

# Improving Neural Machine Translation Formality Control with Domain Adaptation and Reranking-based Transductive Learning

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## Abstract

This paper presents Huawei Translation Service Center (HW-TSC)’s submission on the IWSLT 2023 formality control task, which provides two training scenarios: supervised and zero-shot, each containing two language pairs, and sets constrained and unconstrained conditions. We train the formality control models for these four language pairs under these two conditions respectively, and submit the corresponding translation results. Our efforts are divided into two fronts: enhancing general translation quality and improving formality control capability. According to the different requirements of the formality control task, we use a multi-stage pre-training method to train a bilingual or multilingual neural machine translation (NMT) model as the basic model, which can improve the general translation quality of the base model to a relatively high level. Then, under the premise of affecting the general translation quality of the basic model as little as possible, we adopt domain adaptation and reranking-based transductive learning methods to improve the formality control capability of the model.

## 1 Introduction

Machine translation (MT) (Lopez, 2008; Vaswani et al., 2017) models typically return one single translation for each input sentence. This means that when the input sentence is ambiguous, the MT model must choose a translation from among various valid options, without regard to the intended use case or target audience. Therefore, there is a need to control certain attributes (Schioppa et al., 2021) of the text generated in a target language such as politeness (Sennrich et al., 2016a; Feely et al., 2019) or formality (Niu et al., 2017, 2018; Viswanathan et al., 2020).

The lack of gold translation with alternate formality for supervised training and evaluation has lead researchers to rely on synthetic supervision training and manual evaluation in past work (Niu

and Carpuat, 2020). Fortunately, the IWSLT formality control task now provides a new benchmark<sup>1</sup> (Nădejde et al., 2022; Agarwal et al., 2023) by contributing high-quality training datasets and test datasets for multiple language pairs.

This paper presents HW-TSC’s submission on the IWSLT 2023 formality control task. How formality distinctions are expressed grammatically and lexically can vary widely by language. Thus, we participate in the formality control task of all these four language pairs to investigate a general formality control method that can be applied to different language pair. In addition, we also investigate the difference in formality control between constrained and unconstrained conditions by introducing the mBART model (Liu et al., 2020) under unconstrained condition.

## 2 Data

### 2.1 Pre-training Data

We use the CCMatrix<sup>2</sup> and OpenSubtitles<sup>3</sup> bilingual data given by the organizers to train a NMT model from scratch or fine-tune the mBART model as the general basic model. The bilingual data size of each language pair is shown in Table 1:

Language pair	CCMatrix	OpenSubtitles
EN-KO	19.4M	1.4M
EN-VI	50.1M	3.5M
EN-PT	173.7M	33.2M
EN-RU	139.9M	25.9M

Table 1: The bilingual data size of each language pair.

In order to achieve a better training effect, we also use some data pre-processing methods to clean bilingual data, such as: remove duplicate data, use

<sup>1</sup><https://github.com/amazon-science/contrastive-controlled-mt>

<sup>2</sup><https://opus.nlpl.eu/CCMatrix.php>

<sup>3</sup><https://opus.nlpl.eu/OpenSubtitles-v2018.php>

Moses<sup>4</sup> to normalize punctuation, filter extremely long sentences, use langid<sup>5</sup> (Lui and Baldwin, 2011, 2012) to filter sentences that do not meet the language requirements, use fast-align<sup>6</sup> (Dyer et al., 2013) to filter unaligned sentence pairs.

## 2.2 Formality-annotated Data

The formality-annotated data is provided by the organizers, and the data size of each language pair is shown in Table 2:

Setting	Language pair	Train	Test
Supervised	EN-KO	400	597
Supervised	EN-VI	400	598
Zero-shot	EN-PT	0	599
Zero-shot	EN-RU	0	600

Table 2: The formality-annotated data size of each language pair.

For supervised language pairs, we split the formality-annotated train data into a train set and a dev set with a ratio of 3:1, and use the formality-annotated train set and a small amount of bilingual data for formality control training, while for zero-shot language pairs, we use formality-annotated train set from the other two supervised language pairs for formality control training.

## 3 Model

### 3.1 Constrained Model

Transformer (Vaswani et al., 2017) is the state-of-the-art model in recent machine translation evaluations. There are two parts of research to improve this kind: the first part uses wide networks (eg: Transformer-Big (Vaswani et al., 2017)), and the other part uses deeper language representations (eg: Deep Transformer (Wang et al., 2019; Wu et al., 2022; Wei et al., 2022)). Under the constrained conditions, we combine these two improvements, adopt the Deep Transformer-Big model structure, and train a one-to-many multilingual NMT model (Johnson et al., 2017; Zhang et al., 2020) from scratch using bilingual data of four language pairs provided by the organizers. The main structure of Deep Transformer-Big is that it features pre-layer-normalization and 25-layer encoder, 6-layer

<sup>4</sup><https://github.com/moses-smt/mosesdecoder>

<sup>5</sup><https://github.com/saffsd/langid.py>

<sup>6</sup>[https://github.com/clab/fast\\_align](https://github.com/clab/fast_align)

decoder, 16-head self-attention, 1024-dimensional embedding and 4096-dimensional FFN embedding.

### 3.2 Unconstrained Model

Recently, multilingual denoising pre-training method (Liu et al., 2020; Tang et al., 2021) produces significant performance gains across a wide variety of machine translation tasks. As the earliest sequence-to-sequence model using multilingual denoising pre-training method, mBART (Liu et al., 2020) has also achieved good results in various machine translation-related tasks. Under unconstrained conditions, we use the mBART50 1n model<sup>7</sup> as the initial model of the unconstrained formality control task. The mBART50 1n model adopts Transformer structure, which features 12-layer encoder, 12-layer decoder, 16-head self-attention, 1024-dimensional embedding and 4096-dimensional FFN embedding, and an additional layer-normalization layer (Xu et al., 2019) on top of both the encoder and decoder.

## 4 Method

In our implementation, we first use a multi-stage pre-training method to train a general NMT model with relatively high translation quality. Then, we use domain adaptation method to fine-tune the NMT model so that the model can have basic formality control capability. Finally, we use the reranking-based transductive learning (RTL) method to further improve the formality control capability of the model.

### 4.1 Multi-stage Pre-training

There are four different types of formality control tasks, which are constrained supervised task, constrained zero-shot task, unconstrained supervised task, and unconstrained zero-shot task. For these four different tasks, we formulate different pre-training strategies and collectively refer to these strategies as multi-stage pre-training method.

Under the constrained condition, we adopt the Deep Transformer-Big model structure and use bilingual data of all four language pairs to train a one-to-many multilingual NMT model from scratch, which is used as the basic model for constrained zero-shot task. For constrained supervised task, we use the bilingual data of this task to further

<sup>7</sup><https://dl.fbaipublicfiles.com/fairseq/models/mbart50/mbart50.ft.1n.tar.gz>

pre-train the multilingual NMT model to obtain a bilingual NMT model as the basic model.

While under the unconstrained condition, we further pre-train the mBART50 1n model using bilingual data from all these four language pairs as the basic model for unconstrained zero-shot task. For unconstrained supervised task, we use the bilingual data of this task to further pre-train the pre-trained model, and use the final pre-trained bilingual model as the basic model.

## 4.2 Domain Adaptation for Formality Control

With the pre-trained basic model, we use domain adaptation method (Chu et al., 2017) to achieve basic formality control. First, we treat formal formality and informal formality as two special domains, and control the formality of the model’s translation results using a tagging method (Chu et al., 2017; Nădejde et al., 2022), which attaches a formality-indicating tag to the source input. Then, in order to affect the general translation quality as little as possible, we use a mix fine-tuning method (Chu et al., 2017; Nădejde et al., 2022). Our specific implementation is to upsample the formality-annotated train set by 5 times, and mix it with the same amount of randomly sampled general bilingual data to fine-tune the pre-trained basic model.

As mentioned in Section 2.2, for the zero-shot task, due to the lack of formality-annotated data, we have to use the formality-annotated data of the two other supervised language pair, which is why we set the basic model of zero-shot task to a multilingual NMT model. After using domain adaptation method, the cross-lingual transfer learning capability of multilingual model can help zero-shot language pair achieve basic formality control.

## 4.3 Reranking-based Transductive Learning

After using domain adaptation method, we can enable the model to have the basic formality control capability. Inspired by the idea of transductive learning (Shi et al., 2018; Lee et al., 2021), we propose a RTL method, which can further improve the formality control capability of NMT model. Our method is mainly divided into two steps:

In the first step, we adopt beam search based decoding method (Sennrich et al., 2016b) for the formality control model, and then select the final translation result that meets the specified formality requirements from the top100 decoding results based on reranking idea (Dou et al., 2019). For supervised task, we use a reference-free formality classifier

and the formality phrases from formality-annotated training data for reranking. The implementation details are shown in Algorithm 1. For zero-shot task, due to the lack of formality-annotated training data, we just use a reference-free formality classifier for reranking. Among them, the formality classifier under the constrained condition comes from self-training (Axelrod et al., 2011), while the formality classifier under the unconstrained condition comes from the organizer<sup>8</sup> (Briakou et al., 2021).

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### Algorithm 1: Reranking by reference-free formality classifier and formality phrases

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**Input:** source sentence  $x$ , reference-free formality classifier  $C$ , formality control model  $M$ , formal and informal formality phrases  
 $W_F = \{w_j^F\}_{j=1}^{|W_F|}$ ,  $W_I = \{w_j^I\}_{j=1}^{|W_I|}$

**Output:** the formality translation  $y_F$  and  $y_I$

- 1 translate  $x$  by  $M$ , the top 100 formality translations are respectively defined as:  
 $D_F = \{y_i^F\}_{i=1}^{100}$ ,  $D_I = \{y_i^I\}_{i=1}^{100}$
- 2  $y_F = y_0^F$
- 3 **for**  $y_i^F$  in  $D_F$  **do**
- 4      $F_{flag} = False$
- 5     **for**  $w_j^F$  in  $W_F$  **do**
- 6         **if**  $w_j^F$  in  $y_i^F$  **then**
- 7              $F_{flag} = True$
- 8             **break**
- 9         **end**
- 10     **end**
- 11     calculate the formality by  $C$ :  $C(y_i^F)$
- 12     **if**  $F_{flag}$  and  $C(y_i^F) == "formal"$  **then**
- 13          $y_F = y_i^F$
- 14         **break**
- 15     **end**
- 16 **end**
- 17 pick  $y_I$  from  $D_I$  in a similar way to  $y_F$
- 18 **return**  $y_F, y_I$

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In the second step, we add the source text of test set and the reranked formality translation results to the training data used for domain adaptation, and then use the adjusted training data to further fine-tune the formality control model.

We can also repeat the previous two steps until the formality control capability of the model on test set is no longer improved. We refer to this iterative

<sup>8</sup><https://github.com/amazon-science/contrastive-controlled-mt/releases/tag/classifier-v1.0.0>

EN-VI	To Formal				To Informal				Flores	
	M-Acc	C-F	BLEU	COMET	M-Acc	C-F	BLEU	COMET	BLEU	COMET
AWS-baseline	99.40%	99.16%	43.2	0.6189	98.10%	98.49%	41.5	0.6021	-	-
Multilingual pre-training	10.86%	1.67%	25.6	0.2023	89.14%	98.33%	30.0	0.2873	42.3	0.6653
+ Bilingual pre-training	8.80%	3.01%	24.8	0.1782	91.20%	96.99%	28.9	0.2630	42.4	0.6706
+ Domain adaptation	98.17%	97.83%	49.1	0.7248	99.37%	99.83%	48.0	0.6952	41.3	0.6576
+ RTL	99.59%	<b>100.00%</b>	49.5	0.7296	99.38%	<b>100.00%</b>	48.1	0.7034	41.7	0.6614
+ Iterative RTL	<b>100.00%</b>	99.83%	<b>51.3</b>	<b>0.7522</b>	<b>100.00%</b>	<b>100.00%</b>	<b>49.8</b>	<b>0.7209</b>	<b>41.8</b>	<b>0.6730</b>
UMD-baseline	96.00%	99.67%	26.7	0.3629	96.00%	98.16%	25.3	0.3452	-	-
mBART50 1n	3.82%	1.51%	26.7	0.3516	96.18%	98.49%	31.0	0.4426	34.7	0.6040
+ Multilingual pre-training	9.44%	1.84%	25.4	0.2089	90.56%	98.16%	29.9	0.2975	42.2	0.6673
+ Bilingual pre-training	12.20%	2.51%	25.2	0.1579	87.80%	97.49%	29.4	0.2445	42.4	0.6698
+ Domain adaptation	99.02%	99.50%	47.8	0.7181	99.36%	<b>100.00%</b>	47.4	0.6930	43.2	0.6916
+ RTL	99.22%	<b>100.00%</b>	47.7	0.7190	99.16%	<b>100.00%</b>	47.8	0.7053	<b>43.4</b>	<b>0.7033</b>
+ Iterative RTL	<b>100.00%</b>	<b>100.00%</b>	<b>48.2</b>	<b>0.7214</b>	<b>100.00%</b>	<b>100.00%</b>	<b>48.3</b>	<b>0.7102</b>	<b>43.4</b>	0.6983

Table 3: The overall translation quality and formality control accuracy of EN-VI models.

EN-KO	To Formal				To Informal				Flores	
	M-Acc	C-F	BLEU	COMET	M-Acc	C-F	BLEU	COMET	BLEU	COMET
AWS-baseline	28.50%	54.61%	11.1	0.5044	80.40%	57.62%	11.1	0.5125	-	-
Multilingual pre-training	<b>100.00%</b>	69.85%	5.0	0.2408	0.00%	30.15%	4.5	0.2288	12.9	0.6497
+ Bilingual pre-training	<b>100.00%</b>	65.33%	5.5	0.2189	0.00%	34.67%	4.7	0.2105	13.8	0.6610
+ Domain adaptation	<b>100.00%</b>	97.49%	24.5	0.7234	<b>100.00%</b>	96.31%	25.1	0.7194	12.6	0.6528
+ RTL	<b>100.00%</b>	97.65%	<b>25.8</b>	0.7337	<b>100.00%</b>	98.51%	26.5	0.7337	13.0	<b>0.6828</b>
+ Iterative RTL	<b>100.00%</b>	<b>99.83%</b>	25.0	<b>0.7434</b>	<b>100.00%</b>	<b>99.66%</b>	<b>27.0</b>	<b>0.7495</b>	<b>13.2</b>	0.6729
UMD-baseline	78.30%	98.60%	4.9	0.2110	97.60%	99.50%	4.9	0.1697	-	-
mBART50 1n	<b>100.00%</b>	98.49%	4.1	0.4468	0.00%	1.51%	3.2	0.3670	9.5	0.5854
+ Multilingual pre-training	<b>100.00%</b>	65.66%	5.0	0.2501	0.00%	34.34%	4.3	0.2338	13.3	0.6605
+ Bilingual pre-training	<b>100.00%</b>	64.66%	5.2	0.2240	0.00%	35.34%	4.6	0.2114	14.2	0.6734
+ Domain adaptation	<b>100.00%</b>	99.33%	24.9	0.7297	<b>100.00%</b>	99.66%	25.5	0.7379	12.8	0.6666
+ RTL	<b>100.00%</b>	99.66%	<b>25.5</b>	<b>0.7393</b>	<b>100.00%</b>	<b>100.00%</b>	26.2	<b>0.7340</b>	13.8	0.6845
+ Iterative RTL	<b>100.00%</b>	<b>100.00%</b>	24.2	0.7254	<b>100.00%</b>	<b>100.00%</b>	<b>26.7</b>	0.7311	<b>14.0</b>	<b>0.6882</b>

Table 4: The overall translation quality and formality control accuracy of EN-KO models.

process as iterative RTL method.

## 5 Experiments

### 5.1 Training Details

We use the Pytorch-based Fairseq framework<sup>9</sup> (Ott et al., 2019) to pre-train or fine-tune NMT model, and use Adam optimizer (Kingma and Ba, 2014) with parameters  $\beta_1=0.9$  and  $\beta_2=0.98$ . During the multi-stage pre-training phase, each model uses 8 GPUs for training, warmup steps is 4000, batch size is 4096, learning rate is  $5 \times 10^{-4}$ , label smoothing rate (Szegedy et al., 2016) is 0.1, and dropout is 0.1. In the domain adaptation and RTL phases, each model only uses 1 GPU for training without warm-up, batch size is 1024, learning rate is  $3 \times 10^{-5}$ , label smoothing rate is 0.1, and dropout is 0.3.

### 5.2 Evaluation Metrics

We evaluate the translation results of formality control model from the following two dimensions:

- We use SacreBLEU v2.0.0<sup>10</sup> (Papineni et al.,

<sup>9</sup><https://github.com/facebookresearch/fairseq>

<sup>10</sup><https://github.com/mjpost/sacrebleu>

2002; Post, 2018) and COMET (eamt22-cometinho-da)<sup>11</sup> (Rei et al., 2022) to evaluate the overall translation quality of formality control model on the official formality test sets and FLORES-200 devtest sets<sup>12</sup> (Goyal et al., 2022).

- We also use the reference-based corpus-level automatic metric Matched-Accuracy (M-Acc) and the reference-free automatic metric (C-F) that uses a multilingual formality classifier provided by the organizer to evaluate the formality control accuracy of the model on the official formality test sets, respectively.

### 5.3 Evaluation Results

Based on the above evaluation metrics, we evaluate the formality control models trained at different phases for each language pair under constrained and unconstrained conditions, and compare with constrained baseline (AWS-baseline) (Nädejde et al., 2022) and unconstrained baseline

<sup>11</sup><https://github.com/Unbabel/COMET>

<sup>12</sup><https://github.com/facebookresearch/flores/tree/main/flores200>

EN-RU	To Formal				To Informal				Flores	
	M-Acc	C-F	BLEU	COMET	M-Acc	C-F	BLEU	COMET	BLEU	COMET
Multilingual pre-training	99.27%	67.83%	29.7	0.4265	0.73%	32.17%	23.7	0.3869	32.2	0.7790
+ Domain adaptation	99.71%	90.67%	33.8	0.5977	85.49%	70.67%	31.2	0.5333	27.8	0.7040
+ RTL	99.74%	<b>100.00%</b>	34.5	0.6155	97.14%	<b>100.00%</b>	33.4	0.6019	<b>29.4</b>	<b>0.7261</b>
+ Iterative RTL	<b>100.00%</b>	<b>100.00%</b>	<b>36.5</b>	<b>0.6472</b>	<b>100.00%</b>	<b>100.00%</b>	<b>35.6</b>	<b>0.6442</b>	29.0	0.7153
UMD-baseline	96.20%	92.00%	22.0	0.3492	84.10%	85.17%	21.6	0.3475	-	-
mBART50 1n	<b>100.00%</b>	91.67%	25.6	0.2916	0.00%	8.33%	19.3	0.2351	25.0	0.5950
+ Multilingual pre-training	98.15%	67.00%	28.9	0.4263	1.85%	33.00%	23.1	0.3904	32.1	0.7638
+ Domain adaptation	99.49%	98.17%	31.8	0.5336	99.73%	<b>99.83%</b>	30.8	0.5214	30.7	0.7386
+ RTL	98.76%	<b>100.00%</b>	32.3	0.5575	99.73%	<b>99.83%</b>	31.6	0.5363	30.9	0.7417
+ Iterative RTL	<b>100.00%</b>	<b>100.00%</b>	<b>33.7</b>	<b>0.5804</b>	<b>100.00%</b>	<b>99.83%</b>	<b>32.4</b>	<b>0.5558</b>	<b>31.0</b>	<b>0.7521</b>

Table 5: The overall translation quality and formality control accuracy of EN-RU models.

EN-PT	To Formal				To Informal				Flores	
	M-Acc	C-F	BLEU	COMET	M-Acc	C-F	BLEU	COMET	BLEU	COMET
Multilingual pre-training	84.23%	77.46%	34.5	0.4750	15.77%	22.54%	31.4	0.4488	51.3	0.9047
+ Domain adaptation	<b>100.00%</b>	99.67%	43.0	0.6689	96.68%	96.49%	43.7	0.6689	45.0	0.7995
+ RTL	99.47%	<b>100.00%</b>	43.1	0.6769	92.76%	<b>100.00%</b>	44.1	0.6949	<b>45.3</b>	<b>0.7994</b>
+ Iterative RTL	<b>100.00%</b>	<b>100.00%</b>	<b>47.4</b>	<b>0.7337</b>	<b>100.00%</b>	<b>100.00%</b>	<b>47.9</b>	<b>0.7442</b>	44.9	0.7926
UMD-baseline	96.30%	97.66%	27.3	0.4477	93.20%	90.82%	30.9	0.4161	-	-
mBART50 1n	86.81%	91.32%	32.2	0.5011	13.19%	8.68%	31.5	0.4955	33.8	0.6767
+ Multilingual pre-training	82.19%	77.96%	34.1	0.4872	17.81%	22.04%	31.4	0.4598	49.8	0.8753
+ Domain adaptation	<b>100.00%</b>	99.83%	39.9	0.7070	98.29%	90.32%	45.1	0.7170	46.7	0.8302
+ RTL	<b>100.00%</b>	<b>100.00%</b>	39.9	0.7165	94.97%	99.33%	45.0	0.7341	48.0	<b>0.8457</b>
+ Iterative RTL	<b>100.00%</b>	<b>100.00%</b>	<b>45.4</b>	<b>0.7737</b>	<b>100.00%</b>	<b>99.66%</b>	<b>49.1</b>	<b>0.7845</b>	<b>48.1</b>	<b>0.8457</b>

Table 6: The overall translation quality and formality control accuracy of EN-PT models.

(UMD-baseline) (Lin et al., 2022) provided by the organizers.

### 5.3.1 EN-VI & EN-KO

The formality control task for EN-VI and EN-KO language pairs is supervised, and we adopt the same training methods on these two language pairs. Table 3 and Table 4 are the evaluation results of the models trained at different phases for these two language pairs. From the experimental results, the multi-stage pre-training method can improve the translation quality of the model on the FLORES-200 devtest sets, while domain adaptation and RTL methods are effective in improving formality control capability of the model. Besides, domain adaptation and RTL methods have relatively little impact on the general translation quality of the model on the FLORES-200 devtest sets. Finally, we submit the Iterative RTL model as primary system.

### 5.3.2 EN-RU & EN-PT

The formality control tasks for the EN-RU and EN-PT language pairs are zero-shot, and we only use one-stage pre-training on these two tasks. Table 5 and Table 6 are the evaluation results of the models trained in different phases for these two language pairs. The experimental results show that domain adaptation and RTL methods are still effective in improving the zero-shot formality control capability

of multilingual model. Finally, we still submit the Iterative RTL model as primary system.

## 6 Conclusions

This paper presents HW-TSC’s submission on the IWSLT 2023 formality control task, in which we participate in both constrained and unconstrained tasks for all four language pairs. For the formality control task, we use a multi-stage pre-training method to improve the general translation quality of the basic model. We also adopt domain adaptation and RTL methods to improve the model’s formality control capability. Experimental results show that these methods we have adopted are extremely effective, but how to improve general translation quality more effectively and achieve formality control with less training resources is still worthy of further research.

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