

Automatic Committed Belief Tagging

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Abstract

We go beyond simple propositional meaning extraction and present experiments in determining which propositions in text the author believes. We show that deep syntactic parsing helps for this task. Our best feature combination achieves an F-measure of 64%, a relative reduction in F-measure error of 21% over not using syntactic features.

1 Introduction

Recently, interest has grown in relating text to more abstract representations of its propositional meaning, as witnessed by work on semantic role labeling, word sense disambiguation, and textual entailment. However, there is more to “meaning” than just propositional content. Consider the following examples, and suppose we find these sentences in the *New York Times*:

- (1) a. *GM will lay off workers.*
- b. *A spokesman for GM said GM will lay off workers.*
- c. *GM may lay off workers.*
- d. *The politician claimed that GM will lay off workers.*
- e. *Some wish GM would lay off workers.*
- f. *Will GM lay off workers?*
- g. *Many wonder if GM will lay off workers.*

If we are searching text to find out whether GM will lay off workers, all of the sentences above contain the proposition LAY-OFF(GM,WORKERS). However, they allow us

very different inferences about whether GM will lay off workers or not. Supposing we consider the *Times* a trustworthy news source, we would be fairly certain if we read (1a) and (1b). (1c) suggests the *Times* is not certain about the layoffs, but considers them possible. When reading (1d), we know that someone else thinks that GM will lay off workers, but that the *Times* does not necessarily share this belief. (1e), (1f), and (1g) do not tell us anything about whether anyone believes whether GM will lay off workers.

In order to tease apart what is happening, we need to abandon a simple view of text as a repository of propositions about the world. We use two assumptions to aid us. The first assumption is that discourse participants model each other’s cognitive state during discourse (we take the term to include the reading of monologic written text), and that language provides cues for the discourse participants to do the modeling. This assumption is commonly made, for example by Grice (1975) in his Maxim of Quantity. Following the literature in Artificial Intelligence (Bratman, 1999; Cohen and Levesque, 1990), we model cognitive state as beliefs, desires, and intentions. Crucially, these three dimensions are orthogonal; for example, we can desire something but not believe it.

- (2) I know John won’t be here, but I wouldn’t mind if he were

However, we cannot both believe something and not believe it:

- (3) #John won’t be here, but nevertheless I think he may be here

Note that (2) requires *but* in order to be felicitous, but sentence (3) cannot be “saved” by any discourse markers – it is not interpretable. In this paper, we are interested in beliefs (and in distin-

guishing them from desires and intentions).

The second assumption is that communication is intention-driven, and understanding text actually means understanding the communicative intention of the writer. Furthermore, communicative intentions are intentions to affect the reader's cognitive state – his or her beliefs, desires, and/or intentions. This view has been adopted in the text generation and dialog community more than in the information extraction and text understanding communities (Mann and Thompson, 1987; Hovy, 1993; Moore, 1994; Bunt, 2000; Stone, 2004). In this paper we explore the following: we would like to recognize what the writer of the text intends the reader to believe about various people's beliefs about the world (including the writer's own). In this view, the result of text processing is not a list of facts about the world, but a list of facts about different people's cognitive states. In this paper, we limit ourselves to the writer's beliefs, but we specifically want to determine which propositions he or she intends us to believe he or she holds as beliefs, and with what strength. The result of such processing will be a much more fine-grained representation of the information contained in written text than has been available so far.

2 Belief Annotation and Data

We use a corpus of 10,000 words annotated for speaker belief of stated propositions (Diab et al., 2009). The corpus is very diverse in terms of genre, and it includes newswire text, email, instructions, and solicitations. The corpus annotates each verbal proposition (clause or small clause), by attaching one of the following tags to the head of the proposition (verbs and heads of nominal, adjectival, and prepositional predications).

- Committed belief (CB): the writer indicates in this utterance that he or she believes the proposition. For example, *GM has laid off workers*, or, even stronger, *We know that GM has laid off workers*. Committed belief can also include propositions about the future: people can have equally strong beliefs about the future as about the past, though in practice probably we have stronger beliefs about the past than about the future.

- Non-committed belief (NCB): the writer identifies the proposition as something which he

or she could believe, but he or she happens not to have a strong belief in. There are two sub-cases. First, the writer makes clear that the belief is not strong, for example by using a modal auxiliary epistemically: *GM may lay off workers*. Second, in reported speech, the writer is not signaling to the reader what he or she believes about the reported speech: *The politician claimed that GM will lay off workers*. Again, the issue of tense is orthogonal.

- Not applicable (NA): for the writer, the proposition is not of the type in which he or she is expressing a belief, or could express a belief. Usually, this is because the proposition does not have a truth value in this world (be it in the past or in the future). This covers expressions of desire (*Some wish GM would lay off workers*), questions (*Will GM lay off workers?*), and expressions of requirements (*GM is required to lay off workers* or *Lay off workers!*).

All propositional heads are classified as one of the classes CB, NCB, or NA, and all other tokens are classified as O. Note that in this corpus, event nominals (such as *the lay-offs by GM were unexpected*) are, unfortunately, not annotated for belief and are always marked "O". Note also that the syntactic form does not determine the annotation, but the perceived writer's intention – a question will usually be an NA, but sometimes a question can be used to convey a belief (for example, a rhetorical question), in which case it would be labeled CB.

3 Automatic Belief Tagging

3.1 Approach

We applied a supervised learning framework to the problem of identifying committed belief in context. Our task consists of two conceptual sub-tasks: identifying the propositions, and classifying each proposition as CB, NCB, or NA. For the first subtask, we could use a system that cuts a sentence into propositions, but we are not aware of such a system that performs at an adequate level. Instead, we tag the heads of the proposition, which amounts to the same in the sense that there is a bijection between propositions and their heads. Practically, we have the choice between

No	Feature	Type	Description
Features that performed well			
1	isNumeric	L	Word is Alphabet or Numeric?
2	POS	L	Word's POS tag
3	verbType	L	Modal/Aux/Reg (= 'nil' if the word is not a verb)
4	whichModalAmI	L	If I am a modal, what am I? (= 'nil' if I am not a modal)
3	amVBwithDaughterTo	S	Am I a VB with a daughter <i>to</i> ?
4	haveDaughterPerfect	S	Do I have a daughter which is one of <i>has, have, had</i> ?
5	haveDaughterShould	S	Do I have a daughter <i>should</i> ?
6	haveDaughterWh	S	Do I have a daughter who is one of <i>where, when, while, who, why</i> ?
7	haveReportingAncestor	S	Am I a verb/predicate with an ancestor whose lemma is one of <i>tell, accuse, insist, seem, believe, say, find, conclude, claim, trust, think, suspect, doubt, suppose</i> ?
8	parentPOS	S	What is my parent's POS tag?
9	whichAuxIsMyDaughter	S	If I have a daughter which is an auxiliary, what is it? (= 'nil' if I do not have an auxiliary daughter)
10	whichModalIsMyDaughter	S	If I have a daughter which is a modal, what is it? (= 'nil' if I do not have a modal daughter)
Features that were not useful			
1	Lemma	L	Word's Lemma
2	Stem	L	Word stem (Using Porter Stemmer)
3	Drole	S	Deep role (drole in MICA features)
4	isRoot	S	Is the word the root of the MICA Parse tree?
5	parentLemma	S	Parent word's Lemma
6	parentStem	S	Parent word stem (Using Porter Stemmer)
7	parentSupertag	S	Parent word's super tag (from Penn Treebank)
8	Pred	S	Is the word a predicate? (pred in MICA features)
9	wordSupertag	S	Word's Super Tag (from Penn Treebank)

Table 1: All Features Used

a joint model, in which the heads are chosen and classified simultaneously, and a pipeline model, in which heads are chosen first and then classified. In this paper, we consider the joint model in detail and in Section 3.5.3, we present results of the pipeline model; they support our choice.

In the joint model, we define a four-way classification task where each token is tagged as one of four classes – CB, NCB, NA, or O (nothing) – as defined in Section 2. For tagging, we experimented with Support Vector Machines (SVM) and Conditional Random Fields (CRF). For SVM, we used the YAMCHA(Kudo and Matsumoto, 2000) sequence labeling system,¹ which uses the TinySVM package for classification.² For CRF, we used the linear chain CRF implementation of

the MALLET(McCallum, 2002) toolkit.³

3.2 Features

We divided our features into two types - Lexical and Syntactic. Lexical features are at the token level and can be extracted without any parsing with relatively high accuracy. We expect these features to be useful for our task. For example, `isNumeric`, which denotes whether the word is a number or alphabetic, is a lexical feature. Syntactic features of a token access its syntactic context in the dependency tree. For example, `parentPOS`, the POS tag of the parent word in the dependency parse tree, is a syntactic feature. We used the MICA deep dependency parser (Bangalore et al., 2009) for parsing in order to derive the syntactic features. We use MICA because we assume that the relevant information is the

¹<http://chasen.org/taku/software/YAMCHA/>

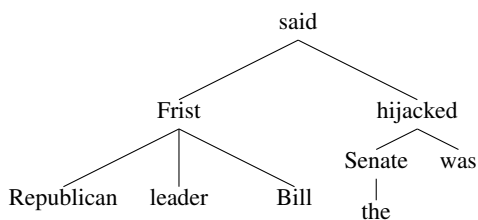
²<http://chasen.org/taku/software/TinySVM/>

³<http://MALLET.cs.umass.edu/>

predicate-argument structure of the verbs, which is explicit in the MICA output. While it is clear that having a perfect parse would yield useful features, current parsers perform at levels of accuracy lower than that of part-of-speech taggers, so that it is not a foregone conclusion that using automatic parser output helps in our task.

The list of features we used in our experiments are summarized in Table 1. The column 'Type' denotes the type of the feature. 'L' stands for lexical features and 'S' stands for syntactic features.

The tree below shows the dependency parse tree output by MICA for the sentence *Republican leader Bill Frist said the Senate was hijacked*.



In the above sentence, *said* and *hijacked* are the propositions that should be tagged. Let's look at *hijacked* in detail. The feature `haveReportingAncestor` of *hijacked* is 'Y' because it is a verb with a parent verb *said*. Similarly, the feature `haveDaughterAux` would also be 'Y' because of daughter *was*, whereas `whichAuxIsMyDaughter` would get the value *was*.

We also considered several other features which did not yield good results. For example, the token's supertag (Bangalore and Joshi, 1999), the parent token's supertag, a binary feature `isRoot` (Is the word the root of the parse tree?) were deemed not useful. We list the features we experimented with and decided to discard in Table 1.

For finding the best performing features, we did an exhaustive search on the feature space, incrementally pruning away features that are not useful.

3.3 Experiments

This section describes different experiments we conducted in detail. It explains the experimental setup for both learning frameworks we used - YAMCHA and MALLET. We also explain the pipeline model in detail.

Class	Description
L_C	Lexical features with Context
$L_N S_N$	Lexical and Syntactic features with No-context
$L_C S_N$	Lexical features with Context and Syntactic features with No-context
$L_C S_C$	Lexical and Syntactic features with Context

Table 2: YAMCHA Experiment Sets

3.3.1 YAMCHA Experiments

We categorized our YAMCHA experiments into different experimental conditions as shown in Table 2. For each class, we did experiments with different feature sets and (linear) context widths. Here, context width denotes the window of tokens whose features are considered. For example, a context width of 2 means that the feature vector of any given token includes, in addition to its own features, those of 2 tokens before and after it as well as the tag prediction for 2 tokens before it. For $L_N S_N$, the context width of all features was set to 0. For $L_C S_N$, the context width of syntactic features alone was set to 0. A context width of 0 for a feature means that the feature vector includes that feature of the current token only. When context width was non-zero, we varied it from 1 to 5, and we report the results for the optimal context width.

We tuned the SVM parameters, and the best results were obtained using the *One versus All* method for multiclass classification on a quadratic kernel with a c value of 0.5. All results presented for YAMCHA here use this setting.

3.3.2 MALLET Experiments

Class	Description
L	Lexical features only
LS	Lexical and Syntactic features

Table 3: MALLET Experiment Sets

We categorized our MALLET experiments into two classes as shown in Table 3. We computed the features described in Section 3.2 at the token level and converted them to binary in order to use them for CRF. We experimented with varying orders and the best results were obtained for or-

Class	Feature Set	Parm	P	R	F
YAMCHA - Joint Model					
L_C	POS, whichModalAmI, verbType, isNumeric	CW=3	61.9	52.7	56.9
$L_N S_N$	POS, whichModalAmI, parentPOS, haveReportingAncestor, whichModal-IsMyDaughter, haveDaughterPerfect, whichAuxIsMyDaughter, amVBwith-DaughterTo, haveDaughterWh, haveDaughterShould	CW=0	62.5	57.5	59.9
$L_C S_N$	POS, whichModalAmI, parentPOS, haveReportingAncestor, whichModalIs-MyDaughter, whichAuxIsMyDaughter, haveDaughterShould	CW=2	67.4	58.1	62.4
$L_C S_C$	POS, whichModalAmI, parentPOS, haveReportingAncestor, whichModal-IsMyDaughter, haveDaughterPerfect, whichAuxIsMyDaughter, haveDaugh-terWh, haveDaughterShould	CW=2	68.5	60.0	64.0
MALLET - Joint Model					
L	POS, whichModalAmI, verbType	GV=1	55.1	45.0	49.6
L_S	POS, whichModalAmI, parentPOS, haveReportingAncestor, whichModal-IsMyDaughter, haveDaughterPerfect, whichAuxIsMyDaughter, haveDaugh-terWh, haveDaughterShould	GV=1	64.5	54.4	59.0
Pipeline Model					
$L_C S_C$	POS, whichModalAmI, parentPOS, haveReportingAncestor, whichModal-IsMyDaughter, haveDaughterPerfect, whichAuxIsMyDaughter, haveDaugh-terWh, haveDaughterShould	CW=2	49.8	42.9	46.1

Table 4: Overall Results. CW = Context Width, GV = Gaussian Variance, P = Precision, R = Recall, F = F-Measure

der= “0,1”, which makes the CRF similar to Hidden Markov Model. All results reported here use the order= “0,1”. We also conducted experiments varying the Gaussian variance parameter from 1.0 to 10.0 using the same experimental setup (i.e. we did not have a distinct tuning corpus) and observed that best results were obtained with a low value of 1 to 3, instead of MALLET’s default value of 10.0.

3.3.3 Pipeline Model

We also did experiments to support our choice of the joint model over the pipeline model. We chose the best performing feature configuration of the $L_C S_C$ class (which is the overall best performer as we present in Section 3.5), and set up the pipeline model. We trained a sequence classifier using YAMCHA to identify the head tokens, where tokens are tagged as just propositional heads without distinguishing between CB/NA/NCB. The predicted head tokens were then classified using a 3-Way SVM classifier trained on gold data.

3.4 Evaluation

For evaluation, we used 4-fold cross validation on the training data. The data was divided into 4 folds of which 3 folds were used to train a model which was tested on the 4th fold. We did this with all four configurations and all the reported results in this paper are averaged results across 4 folds. We report Recall and Precision on word tokens in our corpus for each of the three tags. It is worth noting that the majority of the words in our data will not be tagged with any of the three classes. (Recall that most words have neither of the three tags). We also report $F_{\beta=1}$ (F)-measure as the harmonic mean between (P)recision and (R)ecall.

3.5 Results

This section summarizes the results of various experiments we conducted. The best performing feature configuration and corresponding Precision, Recall and F-measure for each experimental setup discussed in previous section is presented in Table 4. The best F-measure for each category under various experimental setups is presented in Table 5.

We obtained the best performance using YAM-

Setup	Class	CB	NCB	NA
Joint-YAMCHA	L_C	61.5	15.2	63.2
Joint-YAMCHA	$L_N S_N$	67.0	28.3	59.9
Joint-YAMCHA	$L_C S_N$	67.6	33.2	64.5
Joint-YAMCHA	$L_C S_C$	69.6	34.1	64.5
Joint-MALLET	L	53.9	7.5	54.1
Joint-MALLET	LS	65.8	40.6	59.1
Pipeline	$L_C S_C$	55.2	16.5	51.3

Table 5: Results per Category (F-Measure)

CHA in a joint model. So, we first analyze this configuration in great detail in Section 3.5.1. We discuss results obtained using MALLET in Section 3.5.2 and the pipeline model in Section-3.5.3.

3.5.1 YAMCHA - Results

As described in Section 3.3.1, we divide our experiments into 4 classes - L_C , $L_N S_N$, $L_C S_N$ and $L_C S_C$. Table 4 presents the best performing feature sets and context width configuration for each class. For all experiments with context, the best result was obtained with a context width of 2, except for L_C , where a context width of 3 gave the best results. The results show that syntactic features improve the classifier performance considerably. The best model obtained for L_C has an F-measure of 56.9%. In $L_N S_N$ it improves marginally to 59.9%. Adding back context to lexical features improves it to 62.4% in $L_C S_N$ whereas addition of context to syntactic features further improves this to 64.0%. We observed that the feature `parentPOS` has the most impact on increased context widths, among syntactic features.

The improvement pattern of Precision and Recall across the classes is also interesting. Syntactic features with no context improve Recall by 4.8 percentage points over only lexical features with context, whereas Precision improves only by 0.6 points. However, adding back context to lexical features further improves Precision by 4.9 points while Recall just improves by 0.6 points. Finally, adding context of syntactic features improves both Precision and Recall moderately. We infer that syntactic features (without context) help identify more annotatable patterns thereby improving Recall, whereas linear context helps removing the wrong ones, thereby improving Precision.

The per-category F-measure results presented in Table 5 are also interesting. The CB F-measure improves by 8.1 points and NCB improves 18.9 points from L_C to $L_C S_C$. But, the improvement in NA F-measure is only a marginal 1.3 points between L_C and $L_C S_C$. Furthermore, the F-measure decreases by 3.3 points when syntactic and lexical features with no context are used. On analysis, we found that NAs often occur in syntactic structures like *want to find* or *should go* (deontic *should*), in which the relevant words occur in a small linear window. In contrast, NCBs are often signaled by deeper syntactic structures. For example, in *He said that his visit to the US will mainly focus on the humanitarian issues*, a simplified sentence from our training set, the verb *focus* is an NCB because it is in the scope of the reporting verb *said* (specifically, it is its daughter). This could not be captured using the context because *said* and *focus* are far apart in the sentence. But a correct parse tree gives *focus* as the daughter of *said*. So, a feature like `haveReportingAncestor` could easily capture this. It is also the case that the root of a dependency parse tree would mostly be a CB. This is captured by the feature `parentPOS` having value ‘nil’. This property also cannot be captured by lexical features alone.

However, NCB performs much worse than the other two categories. NCB is a class which occurs rarely compared to CB and NA in our corpus. Out of the 1,357 propositions tagged, only 176 were NCB. We assume that this could be a main factor of its poor performance.

We analyzed the performance across the folds. Fold-2 contains only 0.03% NCBs compared to 1.89% on the rest of the folds. Similarly, it contains 6.43% NAs compared to 3.82% across other folds. However, our best performing model gives a Recall of 59.1% with a Precision of 69.7% (F-measure 64.0%) for Fold-2, which is as good as other folds. Hence, we observe that our learned model is robust under distributional variations.

3.5.2 MALLET Results

As explained in Section 3.3.2, we explored MALLET-CRF using two experimental conditions L and LS . Table 4 presents the best performing feature sets for both classes. These re-

sults again show that syntactic features improve the classifier performance considerably. The best model obtained for L class has an F-measure of 49.6%, whereas addition of syntactic features improves this to 59.0%. Both Precision and Recall are improved by 9.4 percentage points as well.

However, MALLET-CRF's performance was comparatively worse than YAMCHA's SVM. The best model for MALLET (LS) obtained an F-measure of 59.0% which is 5.0 percentage points less than that of the best model for YAMCHA ($LCSC$).

It is interesting to note that MALLET performed well on predicting NCB. The highest NCB F-measure of MALLET - 40.6% is 6.5 percentage points higher than the highest NCB F-measure for YAMCHA. However, corresponding CB and NA F-measures were 61.2% and 56.1% which are much lower than YAMCHA's performance for these categories.

Also, MALLET was more time efficient than YAMCHA. On an average, for our corpus size and feature sets, MALLET ran 3 times as fast as YAMCHA in a cross validation setup (i.e. training and testing together).

3.5.3 Joint Model vs Pipeline Model

As discussed in Section 3.3.3, we set up a pipeline model for the best performing configuration of $LCSC$ class of YAMCHA experiments. The head prediction step of the pipeline obtained an F-measure of 83.9% with Precision and Recall of 86.7% and 81.2%, respectively, across all 4 folds. The 3-way classification step to classify the belief of the identified head obtained an accuracy of 72.7% across all folds. In the pipeline model, false positives and false negatives adds up from step 1 and step 2, where as only the true positives of step 2 is considered as the true positives overall. In this way, the overall Precision was only 49.8% and Recall was 42.9% with an F-measure of 46.1% as shown in Table 4. The results for CB/NCB/NA separately are given in Table 5. The per-category best F-measure was decreased by 14.4, 17.6 and 13.2 percentage points from the YAMCHA joint model for CB, NCB and NA, respectively. The performance gap is big enough to conclude that our choice of joint model was right.

4 Related Work

Our work falls in the rich tradition of modeling agents in terms of their cognitive states (for example, (Rao and Georgeff, 1991)) and relating this modeling to language use through extensions to speech act theory (for example, (Perrault and Allen, 1980; Clark, 1996; Bunt, 2000)). These notions have been particularly fruitful in the dialog community, where dialog act tagging is a major topic of research; to cite just one prominent example: (Stolcke et al., 2000). A dialog act represents the communicative intention of the speaker, and its recognition is crucial for the building of dialog systems. The specific contribution of this paper is to investigate exactly how discourse participants signal their beliefs using language, and the strength of their beliefs; this latter point is not usually included in dialog act tagging.

This paper is not concerned with issues relating to logics for belief representation or inferencing that can be done on beliefs (for an overview, see (McArthur, 1988)), nor theories of automatic belief ascription (Wilks and Ballim, 1987). For example, this paper is not concerned with determining whether a belief in the requirement of p entails the belief in p ; instead, we are only interested in whether the writer wants the reader to understand whether the writer holds a belief in the requirement that p or in p directly. This paper is also not concerned with subjectivity (Wiebe et al., 2004), the nature of the proposition p (statement about interior world or external world) is not of interest, only whether the writer wants the reader to believe the writer believes p . This paper is also not concerned with opinion and determining the polarity (or strength) of opinion (for example: (Somasundaran et al., 2008)), which corresponds to the desire dimension. Thus, this work is orthogonal to the extensive literature on opinion classification.

The work of (Saurí and Pustejovsky, 2007; Saurí and Pustejovsky, 2008) is, in many respects, very similar to ours. They propose Factbank, which represents the factual interpretation as modality-polarity pairs, extracted from the basic structural elements denoting factuality encoded by Timebank. Also, they attribute the factuality to specific sources within the text. Our work

is more limited in several ways: we currently only model the writer’s beliefs; we do not express polarity (we believe we can derive it from the syntax and lexicon); Saurí and Pustejovsky (2008) ask their annotators to perform extensive linguistic transformations on the text to obtain a “normalized” representation of propositional content (we simply ask the annotators to make a judgment about the writer’s strength of belief with respect to a given proposition, and expect to be able to extract representations of pure propositional meaning independently); and finally, Saurí and Pustejovsky (2008) have a more fine-grained representation of non-committed belief. While it is plausible to distinguish between more or less firm non-committed belief, we believe the crucial distinction is between committed belief and non-committed belief. Furthermore, Saurí and Pustejovsky (2008) group reported speech with non-belief statements (our NA), while we group them with weak belief (our NCB). The reason for our decision is that we wanted to keep NA as a category which contains no-one’s beliefs, as we assumed this is semantically more coherent. The category NCB thus covers beliefs which the writer does not hold firmly or has expressed no opinion on — which is different from propositions which the writer has clearly attributed to other cognitive states (such as desire). In principle, we believe a 4-way distinction is the right approach, but our NCB category is already the least frequent, and splitting it would have resulted in two very rare classes. Another difference include the use of the word “fact” in the FactBank manual, which we avoid because we are interested in cognitive modeling; however, this is merely a terminological issue.

Other related works explored belief systems in an inference scenario as opposed to an intentionality scenario. In work by (Krestel et al., 2008), the authors explore belief in the context of reported speech in news media: they track newspaper text looking for elements indicating evidentiality. This is different from our work, since we seek to make explicit the intention of the author or the speaker.

5 Future Work

We are exploring ways to utilize the FactBank annotated corpus for our purpose, with the goal of automatically converting it to our annotation format. With the added data from FactBank, we hope to be able to split the NCB category into WB (weak belief) and RS (reported speech). We will also explore learning embedded belief attributions, as annotated in FactBank.

We found that the per-sentence F-measure has a small positive correlation with the length-normalized probability of the MICA derivation (a measure of parse confidence). In case of a bad parse, syntax features add noise which in turn reduces classifier performance. We are planning to exploit this correlation in order to choose sentences for selective self-training. Another direction we are looking to extend this work is to employ active learning to overcome the shortcomings of a small training set. Also, we found frequent use of epistemic and deontic modals in our data. Both types of modals have identical syntactic structure, but they receive very different annotations. This is not easily captured in our system. We are exploring ways to handle this.

We will release our Committed Belief Tagging tool as a standalone black-box tool. We also intend to release the annotated corpus.

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