

VOTE’N’RANK: Revision of Benchmarking with Social Choice Theory

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Abstract

The development of state-of-the-art systems in different applied areas of machine learning (ML) is driven by benchmarks, which have shaped the paradigm of evaluating generalisation capabilities from multiple perspectives. Although the paradigm is shifting towards more fine-grained evaluation across diverse tasks, the delicate question of how to aggregate the performances has received particular interest in the community. In general, benchmarks follow the unspoken *utilitarian* principles, where the systems are ranked based on their mean average score over task-specific metrics. Such aggregation procedure has been viewed as a sub-optimal evaluation protocol, which may have created the illusion of progress. This paper proposes VOTE’N’RANK, a framework for ranking systems in multi-task benchmarks under the principles of the social choice theory. We demonstrate that our approach can be efficiently utilised to draw new insights on benchmarking in several ML sub-fields and identify the best-performing systems in research and development case studies. The VOTE’N’RANK’s procedures are more robust than the mean average whilst being able to handle missing performance scores and specify conditions under which the system becomes the winner.

1 Introduction

Benchmarking has evolved as a conventional practice for accelerating the development of generalisable systems in different applied areas of machine learning (ML). Benchmarks are typically designed as a collection of datasets, corresponding task-specific evaluation metrics, and a criterion for summarising the overall performance on the tasks (Ruder, 2021). The benchmark holders provide public leaderboards, which are utilised by ML researchers and practitioners for comparing

novel systems against one another, and, if applicable, human baselines, as well as selecting the best-performing ones for practical purposes. According to the benchmark sharing platform PAPERSWITHCODE¹, the community has put much effort into creating more than 10,000 influential benchmarks in natural language processing (NLP), computer vision, and knowledge graphs, to name a few.

Criticism of the benchmark pillars. The benchmark methodological foundations have received wide criticism from academic and industrial communities (Bowman and Dahl, 2021). The criticism covers various aspects of benchmarking, raising concerns about the construct validity (Raji et al., 2021), fragility of the design and task choices (Dehghani et al., 2021), data leakage and annotation artifacts (Elangovan et al., 2021), SoTA-chasing tendencies at the cost of large carbon footprints (Bender et al., 2021), and low reproducibility of the reported results (Belz et al., 2021), inter alia. Recommendations proposed in these studies are of utmost importance to benchmark holders, system users, and developers. However, little attention has been paid to a more nuanced methodological question: *how to aggregate performance scores in multi-task benchmarks?*

Limits of canonical aggregation. The appropriateness of mean aggregation in multi-task ML problems is an ongoing debate in the community. The mean aggregation procedure implies that all task metrics are homogeneous (Colombo et al., 2022b). Otherwise, it is recommended to evaluate the statistical significance of differences between models with non-parametric tests (Demšar, 2006; Benavoli et al., 2016). In practice, the NLP GLUE-style benchmarks (Wang et al., 2018, 2019a, 2021; Liang et al., 2020) use arithmetic average to rank models over heterogeneous metrics, which may lead to

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¹URL: paperswithcode.com/sota. Access date: February 6, 2023.

biased evaluation and subjective outcomes (Nießl et al., 2022; Waseem et al., 2021). The top-leading systems may dominate the others only on the outlier tasks (Agarwal et al., 2021), and their ranking is inconsistent with other Pythagorean means (Shavrina and Malykh, 2021). At the same time, the mean aggregation ignores the relative ordering and relies on the absolute score difference (Peyrard et al., 2017), equally treating tasks of different complexity (Mishra and Arunkumar, 2021) and from different domains (Webb, 2000).

Novel aggregation principles. Recent research has addressed these limitations, introducing novel aggregation methods and principles. One of the directions frames benchmarking in terms of microeconomics, highlighting the importance of the user utility (Ethayarajh and Jurafsky, 2020). The other studies urge evaluation of technical system properties in real-world scenarios (Zhou et al., 2021; Ma et al., 2021) and reliability of system rankings (Rodriguez et al., 2021). The benchmarking paradigm is also shifting towards adopting evaluation principles from other fields, such as non-parametric statistics and social choice theory (Choudhury and Deshpande, 2021; Min et al., 2021; Varshney et al., 2022; Colombo et al., 2022a).

Contributions. Drawing inspiration from the social choice theory, we make two application-oriented contributions and introduce an alternative tool for benchmark evaluation. First, this paper proposes VOTE’N’RANK, a flexible framework to rank systems in multi-task/multi-criteria benchmarks and aggregate the performances based on end-user preferences. VOTE’N’RANK includes 8 aggregation procedures that rely on rankings in each criterion and allow to aggregate homogeneous and heterogeneous information. The framework is easy-to-use and allows the users to plug in their own data. Second, we analyse the framework’s application in four case studies: (i) re-ranking three NLP and multimodal benchmarks; (ii) exploring under which circumstances a system becomes a *Condorcet winner*; (iii) evaluating robustness to omitted task scores; and (iv) ranking systems in accordance with user preferences.

We publicly release the VOTE’N’RANK framework² to foster further development of reliable and interpretable benchmark evaluation practices for both academic and industrial communities.

²github.com/PragmaticsLab/vote_and_rank

2 VOTE’N’RANK

2.1 Background

The study of how individual preferences can be combined to reach a collective decision is the focus of *social choice theory* (Arrow, 2012). There are two main approaches to deal with preferences: *utilitarian* and *ordinal*. The first approach relies on the so-called cardinal utility, which implies that there exists some unique utility function for each individual that defines their preferences. Here, we can work with utilities as numerical values, and collective decision making aims to maximise the *social welfare utility*. Examples of such utilities are *utilitarian and egalitarian social welfare* measures, where the sum of utilities of individual agents and the utility of the worst agent get maximised, respectively.

The *utilitarian* approach has its drawbacks. First, it implies that kind of utility exists, which is not always true: individuals can compare two systems and prefer one to another but cannot say how many “utils” they got. Second, it assumes that individual utilities can be compared. The latter is a solid requirement for benchmarking problems, e.g. when we need to aggregate heterogeneous criteria such as performance and computational efficiency. In order to sum them up, one needs a transformation function that puts the metrics in the same measurement scheme. For example, DYNASCORE (Ma et al., 2021) utilises Marginal Rate of Substitution (MRS) from economics as such transformation function. Third, the utilitarian compensatory principle is questionable. Can low performance in one task/criterion be compensated by high performance in the others? (Munda, 2012)

The *ordinal* approach has a weaker requirement, where individuals have preferences (x is preferred to y , $x \succ y$, i.e. binary relations over objects), which should be aggregated in social preference (also called social rankings). This approach allows us to aggregate rankings from different tasks and criteria without worrying about measurement schemes.

2.2 Aggregation Procedures

Definitions. We adopt the conceptual definitions from the social choice theory to the objectives of selecting the best-performing system and ranking a set of systems as follows: (i) a *voter* or a *criterion* is a task in a given benchmark, and (ii) an *alternative* is a system candidate.

Objectives. Suppose we have a set M of systems $m \in \{m_1, \dots, m_{|M|}\}$ from the benchmark including a set T of voters $t \in \{t_1, \dots, t_{|T|}\}$ and the corresponding criteria $S = \{s_{mt}\}_{m=1, t=1}^{m=|M|, t=|T|}$, where s_{mt} is the score of system m in task t . Given that, we pursue two main objectives of the aggregation procedure σ , $\sigma : S \mapsto (M, \succ_\sigma)$: (i) to select the best performing alternative m^* , so that there is no alternative $\hat{m}, \hat{m} \succ_\sigma m^*$, and (ii) to rank the alternatives in the descending order according to σ values, so that $m_i \succ_\sigma m_j$. Here \succ_σ denotes the preference resulting from the aggregation procedure σ .

Procedures. We propose 8 rules from 3 different classes: *scoring rules*, *iterative scoring rules*, and *majority-relation based rules*. We provide more details and examples in Appendix A.1.

2.2.1 Scoring rules

The total score of each system is calculated as the sum of corresponding scores in each task $Sc(m) = \sum_{i=1}^{|M|} c_i p_i(m)$, where $p_i(m)$ is the number of tasks having model m in the i^{th} place, and c_i is the i^{th} element of the scoring vector c . The systems with the highest scores constitute the final decision. We study the following rules that differ in their scoring vectors.

- *Plurality rule* applies $c = (1, 0, \dots, 0)$.
- *Borda rule* operates on $c = (|M| - 1, |M| - 2, \dots, 1, 0)$.
- *Dowdall rule* applies the scoring vector $c = (1, 1/2, \dots, 1/|M|)$.

The scoring vectors are designed to satisfy the voting rules' properties mentioned in Table 8 in Appendix A.2. The scoring vectors' design is based on the mathematical foundations of the social choice theory and is generally accepted in the community (Aizerman and Aleskerov, 1995).

Interpretation. The *Plurality* rule is one of the most widely used in everyday life. It only requires information about the best alternative for each voter. The *Borda* rule takes into account information about all alternatives. It assumes that differences in positions should be treated the same, whether it is between the first and the second alternatives or the second and the third ones. At the same time, the *Dowdall* rule is in some way in-between *Plurality* and *Borda*. It considers information about all alternatives but gives more weight to the difference in the preferences. A similar approach is used in the Eurovision song contest: they

use $c = (12, 10, 8, 7, \dots, 1)$ making the difference in top positions more important to the outcome.

2.2.2 Iterative scoring rules

- The *Threshold rule* applies $c = (1, 1, \dots, 1, 1, 0)$. In case of ties scoring vectors $(1, 1, \dots, 1, 0, 0), \dots, (1, 0, \dots, 0, 0)$ are iteratively applied and used only to compare systems with the maximum sum of scores.
- The *Baldwin rule* iteratively applies scoring vectors $(|M| - 1, |M| - 2, \dots, 1, 0), (|M| - 2, |M| - 3, \dots, 1, 0, 0), \dots, (1, 0, \dots, 0, 0)$, and at each iteration discards systems with the minimum sum of scores.

Both rules stop the procedure when it is impossible to break ties or there is only one alternative left.

Interpretation. The rules are similar in their iterative nature but different in terms of the intuition behind them. The *Threshold* rule is based on the idea that the worst position is what matters the most. When we start with $c = (1, 1, \dots, 1, 1, 0)$, we choose the alternatives declared worst in the least amount of cases. Since there can be ties, additional iterations are used to break them with $c = (1, 1, \dots, 1, 0, 0)$ and so on; in other words, by looking at the least- k positions until we have one alternative left or can not break ties.

The *Baldwin* rule has two main differences from *Threshold*. First, it is based on the *Borda* score and considers information from all positions in the ranking, not only the worst one. Second, whilst the *Threshold* rule applies a new vector to the original profile and compares only tied alternatives, the *Baldwin* rule iteratively eliminates the least scored systems and moves the remaining up in rankings. For example, if system m_A is in the fifth place, but alternatives from the first four places are eliminated in the first rounds, m_A will be the first until it is eliminated or is among alternatives in the outcome.

2.2.3 Majority-relation based rules

Let us define a majority relation μ over the set of alternatives as the following binary relation: $m_A \mu m_B$ iff m_A is ranked higher than m_B by more criteria.

- *Condorcet rule.* m_C is the Condorcet winner (CW) iff $m_C \mu m$ for any $m \in M$.
- *Copeland rule.* Define the lower counter set of systems m_A as a set of systems dominated by m_A via μ : $L(m_A) = \{m \in M, m_A \mu m\}$. In a similar way, define the upper counter set of systems m_A as a set of systems that dominate m_A

via μ : $U(m_A) = \{m \in M, m \mu m_A\}$. Define $u(m) = |L(m)| - |U(m)|$. The final decision is provided by the alternatives with the highest $u(m)$.

- **Minimax rule.** Let $s(m_A, m_B)$ be the number of criteria for which system m_A is ranked higher than system m_B if $m_A \mu m_B$ or $s(m_A, m_B) = 0$ otherwise. The systems are ranked according to the formula $\text{rank}(m_A) = -\max_B s(m_B, m_A)$.

Interpretation. CW is the alternative that beats all the others in pairwise comparison. However, the *Condorcet* rule does not declare any winner if the CW does not exist. The *Copeland* and *Minimax* rules select the CW whenever it exists and solve the drawback as follows. The *Copeland rule* selects an alternative that dominates more alternatives and is dominated by less (the difference between the numbers is maximised). The *Minimax rule* chooses the alternative with the minimum number of defeats.

2.3 Properties of the Aggregation Procedures

There is a multitude of voting rules in the social choice theory (Nurmi, 1983; Levin and Nalebuff, 1995; De Almeida et al., 2019; Aleskerov et al., 2010). The motivation behind our rules³ is that they generally overcome the mean aggregation limitations and vary in their *properties*, allowing the user to be more flexible in choosing the rule for their purposes. The outcomes can be interpreted in terms of the properties followed or violated by the rules. We discuss our rules’ properties in Appendix A.2.

2.4 Framework

Figure 1 describes three supported settings of performing the aggregation objectives. The toy benchmark has three evaluated alternatives and consists of seven voters grouped by the task, e.g. natural language inference, text classification, and question answering (QA).

- A **Basic aggregation:** the aggregation procedure is applied to the leaderboard as is.
- B **Weighted aggregation:** each voter in the group is assigned a group weight equal to $1/|T_{group}|$. The blue group weights are $1/3$, and the orange and the violet group weights are $1/2$. Each group contributes equally to

³We do not consider more complex rules like *Kemeny* since it is NP-hard to find the *Kemeny* winner (Bartholdi et al., 1989), and it is often implemented as the *Borda* rule approximation (?).

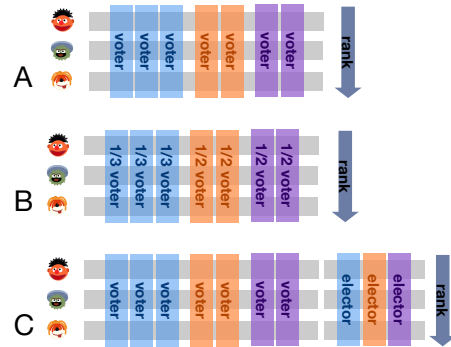


Figure 1: Three ways to run the aggregation procedures. A: Basic aggregation. B: Weighted aggregation. C: Two-step aggregation.

the final ranking, regardless of the number of voters.

- C **Two-step aggregation:** each voter group is treated as a standalone leaderboard. We independently apply a procedure to each voter group and compute an interim ranking shown as “elector”. Next, we aggregate the group-wise rankings by applying the same procedure one more time and compute the final ranking.

3 Case Studies

This section describes four case studies on three NLP and multimodal benchmarks. Our main objective here is to re-interpret the benchmarking trends under the social choice theory. We provide a brief description of the benchmarks below.

- **GLUE** (General Language Understanding Evaluation; Wang et al., 2018) combines nine datasets on QA, sentiment analysis, and textual entailment. GLUE also includes a linguistic diagnostic test set. $|M|=30$.
- **SGLUE** (Wang et al., 2019a) is the GLUE follow-up consisting of two diagnostic and eight more complex NLU tasks, ranging from causal reasoning to multi-hop and cloze-style QA. $|M|=22$.
- **VALUE** (Video-and-Language Understanding Evaluation; Li et al.) covers 11 video-and-language datasets on text-to-video retrieval, video QA, and video captioning. $|M|=7$.

The leaderboards present the results of evaluating various neural models, such as BERT (Devlin et al., 2019), STRUCTBERT (Wang et al., 2019b), ALBERT (Lan et al., 2019), ROBERTA (Liu et al., 2019), T5 (Raffel et al., 2020), DEBERTA (He et al., 2020), ERNIE (Zhang et al., 2019), and their ensembles and other model configurations.

Benchmark	k	σ^{gm}	σ^{og}	Copeland	Minimax	Plurality	Dowdall	Borda
GLUE	top-1	1.0	1.0	1.0	1.0	1.0	1.0	1.0
	top-3	1.0	0.67	1.0	0.67	0.67	0.67	1.0
	top-5	1.0	0.80	0.60	0.80	0.80	0.80	0.8
	top-7	1.0	0.86	0.86	0.86	0.86	0.86	1.0
	least-5	0.67	0.00	1.0	0.33	0.33	1.0	1.0
	least-7	0.86	0.71	1.0	0.14	0.14	1.0	1.0
	τ	0.56	-0.08	0.23	-0.05	0.03	0.28	0.41
SGLUE	top-1	1.0	1.0	0.00	1.0	0.00	0.00	1.0
	top-3	1.0	1.0	0.67	0.67	0.67	0.67	1.0
	top-5	1.0	1.0	1.0	1.0	0.80	1.0	1.0
	top-7	1.0	0.86	0.86	0.71	0.57	0.86	0.86
	least-5	1.0	1.0	1.0	0.33	0.33	1.0	1.0
	least-7	0.86	0.86	0.86	0.14	0.14	0.86	1.0
	τ	0.45	0.36	0.08	-0.5	-0.15	0.12	0.24

Table 1: Agreement rates between the top/least- k rankings with σ^{am} . The Kendall Tau correlation (τ) is computed on the total rankings.

3.1 Re-interpreting Benchmarks

Method. We begin with a case study on re-ranking systems on the publicly available leaderboards using the scoring and majority-relation based rules: *Plurality*, *Dowdall*, *Borda*, *Copeland*, and *Minimax*. We compare the rankings with the arithmetic mean aggregation (σ^{am}), geometric mean aggregation (σ^{gm}), and the optimality gap (σ^{og} ; Agarwal et al., 2021) as the baselines. σ^{og} is an aggregation metric that identifies the amount by which the system fails to get a minimum score of $\gamma = 0.95$ (lower is better). The comparison is run by computing (i) the agreement rate (AR; in %), i.e. the proportion of the top/least- k systems between the given procedure and σ^{am} , (ii) the Kendall Tau correlation (τ) between the total rankings, (iii) the discriminative power (DP) or the number of tied alternatives, i.e. alternatives with the same score (Brandt and Seedig, 2016), and (iv) the independence of irrelevant alternatives (IIA), i.e. how often the *new* systems change the ranking (see Appendix A.2 for details). IIA is computed iteratively in two steps. First, we initialise a leaderboard with two random systems m_A and m_B . Second, we add a new random system m_C to the leaderboard and check if the rankings of m_A and m_B have changed. We repeat the procedure by adding up to $|M|$ systems and counting how often the new system affects the ranking. The experiment is run 50 times to account for randomness.

Results. Table 1 and Table 2 present the results except for the VALUE benchmark which is discussed in Appendix B. We find that methods tend to agree on the top systems, but *Minimax* and *Plurality* disagree on which ones are the worst. Despite high ARs on particular top/least- k systems, the order of the systems on GLUE and SGLUE is

Method	GLUE		SGLUE	
	DP	IIA	DP	IIA
σ^{am}	1	0.0 \pm 0.0	0	0.0 \pm 0.0
σ^{gm}	0	0.0 \pm 0.0	0	0.0 \pm 0.0
σ^{og}	3	0.0 \pm 0.0	1	0.0 \pm 0.0
Copeland	6	2.76 \pm 1.3	2	0.90 \pm 0.8
Minimax	21	2.94 \pm 1.5	17	1.14 \pm 1.0
Plurality	25	5.26 \pm 1.6	17	1.98 \pm 1.4
Dowdall	0	9.10 \pm 2.4	0	4.24 \pm 2.1
Borda	0	7.96 \pm 3.8	1	5.38 \pm 1.8

Table 2: Discriminative power (DP) and independence of irrelevant alternatives (IIA) values. The lower, the better for both DP and IIA.

different, which is indicated by the low correlation coefficients. The Pythagorean mean results are consistent with one another on the top-7 systems and may lead to different worst systems. σ^{og} generally disagrees with σ^{am} for the top and worst systems on GLUE but has higher ARs and correlation on SGLUE.

At the same time, the DP results demonstrate that *Dowdall* and *Borda* produce only one pair of alternatives with the same score, whilst *Minimax* and *Plurality* treat a significantly larger number of systems as equivalent. The reason is that the rules initially intend to define the best alternative, and they are indecisive between the alternatives when utilised to rank. The IIA experiment shows that introducing a new system influences the *Dowdall* and *Borda* rankings. However, this tendency is less common for *Copeland*, *Minimax*, and *Plurality* and is observed only up to 2 times on SGLUE.

Overall, we observe that the GLUE and SGLUE benchmark rankings depend on the aggregation procedure. The human baseline (HUMAN) rank has risen by up to 13 positions on GLUE (see Table 3). The *Copeland* method takes HUMAN, DEBERTA+CLEVER, and T5 equal, meaning that the difference between the number of candidates they dominate and are dominated by is the same. The *Minimax* ranking suggests that HUMAN, T5, and the ALBERT+DAAF+NAS ensemble are equivalent, meaning that minimal maximum defeats against other models are the same. In their turn, the *Plurality* and *Dowdall* procedures rank HUMAN as the second-best solution, since HUMAN receives the best performance in several tasks, such as RTE (Wang et al., 2018) and MNLI (Williams et al., 2018). The tendency is also observed on the SGLUE benchmark (see Table 9 in Appendix B), with the exception that HUMAN is selected as the

Rank	σ^{am}	σ^{gm}	σ^{og}	Copeland	Minimax	Plurality	Dowdall	Borda
1	91.18 ↓0	90.89 ↓0	0.074 ↓0	29.00 ↓0	0 ↓0	2.00 ↓0	4.95 ↓0	260.50 ↓0
2	91.07 ↓0	90.78 ↓0	0.075 ↑4	25.00 ↑1	-5.50 ↑1	2.00 ↑13	4.08 ↑13	256.00 ↓0
3	90.88 ↓0	90.56 ↓0	0.076 ↓1	24.00 ↓1	-6.00 ↑1	1.50 ↓0	3.82 ↓0	247.50 ↓0
4	90.86 ↓0	90.48 ↓0	0.076 ↓0	22.00 ↑3	-6.50 ↓2	1.00 ↑1	3.41 ↓0	241.50 ↓0
5	90.74 ↓0	90.44 ↓0	0.077 ↓0	22.00 ↑10	-7.00 ↑2	1.00 ↓3	3.27 ↓3	233.50 ↑1
6	90.66 ↓0	90.34 ↓0	0.078 ↑1	22.00 ↓2	-7.00 ↑9	0.50 ↓0	2.57 ↓1	229.50 ↑1
7	90.48 ↓0	90.11 ↓0	0.082 ↑3	16.00 ↓1	-7.00 ↓1	0.00 ↓3	2.55 ↓0	220.50 ↓2

Table 3: Results of re-ranking the GLUE benchmark. Changes in the system ranks are depicted with arrows, whilst the superscripts denote scores assigned by the aggregation procedure. Notations: =HUMAN; =ERINIE; =STRUCTBERT+CLEVER; =DEBERTA+CLEVER; =DEBERTA/TURINGNLRV4; =MACALBERT+DKM; =T5; =ALBERT+DAAF+NAS; =FUNNEL. The superscript values stand for the voting rules’ scores, whilst the subscript values indicate changes in the ranking positions. $\uparrow x$ means up x positions, $\downarrow x$ means down x positions, \updownarrow means no changes.

winner by the *Copeland*, *Plurality*, and *Dowdall* procedures and is equal to the ERINIE system according to *Minimax*. The results for *Borda* are similar to σ^{am} and σ^{gm} on the top-4 and top-6 ranks on GLUE and SGLUE, respectively.

Selecting the winner. Another application of the voting rules includes selecting the winner from the set of alternatives. Here, we also utilise the *Threshold*, *Baldwin*, and *Condorcet* rules. Note that we run the VALUE experiment over missing and non-missing scores since the HUMAN results are presented for only 6 out of 11 tasks.

Results. Table 4 presents the results of selecting the winner for each benchmark. \times denotes that (i) the given method does not support missing values, or (ii) there is no *Condorcet* winner (CW). We observe that different SoTAs are selected by 2/7/3 (on GLUE/SGLUE/VALUE) procedures as opposed to σ^{am} , σ^{gm} , and σ^{og} . The *Threshold* rule selects T5+UDG and STRUCTBERT+CLEVER as winners because their performance is the worst the least amount of times. The *Baldwin* rule agrees with the *Plurality* and *Minimax* results. When considering VALUE missing scores, we find that HUMAN is declared SoTA by the *Copeland*, *Minimax*, and *Condorcet* procedures. It means that HUMAN beats any other model in pairwise comparison and is declared the CW, whilst significantly outperforming the systems on specific tasks.

Case study discussion. Benchmarks can suffer from *saturation*, which is characterised by surpassing estimates of the human performance followed by stagnation in SoTA improvements (Ott et al.,

Method	GLUE	SGLUE	VALUE
σ^{am}			\times /
σ^{gm}			\times /
σ^{og}			\times /
Copeland			
Minimax			
Plurality			\times /
Dowdall			\times /
Borda			\times /
Threshold			\times /
Baldwin			\times /
Condorcet		\times	

Table 4: The winner selection results. Notations: =STRUCTBERT+CLEVER; =HUMAN; =CRAIG.STARR; =ERINIE; =T5+UDG.

2022). The NLP community has discussed saturation of the GLUE benchmark over time (Kiela et al., 2021; Ruder, 2021) and minor performance gains of the upcoming top-leading systems on SGLUE (Rogers, 2019). However, the discussion relies on the mean aggregation. Let us take a step away from the *utilitarian* approach. We observe that HUMAN may still take leading positions, and system ranking varies on these benchmarks under the social choice theory principles. VALUE demonstrates more stable results in terms of the AR and the system order, which we attribute to its novelty and minor performance differences between the systems. Overall, our rules provide interpretable results and cope with the missing leaderboard values in contrast to the *utilitarian* methods.

3.2 The Condorcet Winner

One of the most natural ways to choose the best system given a set of weights defined by the user is the Condorcet method, which declares a system the winner if it dominates all other alternatives in pairwise comparison (Black et al., 1958). The Condorcet method is hard to destabilise (Edelman, 2015) and easy to interpret in practice, indicating that the CW best matches the preferences. Given the weights vector, finding the CW, if it exists, is trivial. We can also find the weights that make a given alternative the CW or determine that no weights with that property exist.

Method. Let us define an operator $R(m_1, m_2, i)$:

$$R(m_1, m_2, i) = \begin{cases} 1, & \text{if } \exists s_{m_1 i} \wedge \exists s_{m_2 i} \wedge s_{m_1 i} > s_{m_2 i}, \\ -1, & \text{if } \exists s_{m_1 i} \wedge \exists s_{m_2 i} \wedge s_{m_1 i} < s_{m_2 i}, \\ 0, & \text{otherwise} \end{cases} \quad (1)$$

A system m is declared a CW if the following property is satisfied:

$$\forall m' \in M \setminus \{m\} \quad \sum_{k=1}^{|T|} R(m, m', k) w_k \geq 0 \quad (2)$$

Let $G_m \in \{-1, 0, 1\}^{|M|-1 \times |T|}$ be a matrix such that $G_{ij} = R(m, m'_i, j)$, where $\{m'_1, \dots, m'_{|M|-1}\} = M \setminus \{m\}$.

Equation 2 can be re-written as: $G_m \cdot w \succcurlyeq 0$, which results in defining a space W^* in $\mathbb{R}^{|T|}$, whose each point is a weight vector making m a CW. Any linear algorithm can be applied to find a point in W^* or determine that W^* is empty. Furthermore, any other linear conditions can be added, such as upper/lower bounds of the w components and a linear function that needs to be optimised, e.g. $w_i \rightarrow \min$. Let us call a system for which there exists a vector of weights making it a CW *prospective*. By definition, the system is *prospective* if W^* is not empty.

Example. Let us illustrate the method on the SGLUE benchmark (see Table 4). There is no CW if the task weights are assigned uniformly. Nevertheless, T5 may become the CW when the BOOLQ accuracy (Clark et al., 2019) and MULTIRC exact match scores (Khashabi et al., 2018) have equal weights of 0.5, and the other criteria weights are zeroed. In this scenario, T5 has been found to be a *prospective* system on SGLUE, whilst ROBERTA is declared *non-prospective*.

Results. There are 9/88, 10/12, and 3/3 prospective/non-prospective systems on GLUE,

SGLUE, and VALUE, respectively. The results indicate that it is possible to find specific evaluation scenarios in which a given system is the best. In contrast, the non-prospective system always has an alternative that performs neither worse nor better.

Case study discussion. The CW criterion presents another perspective of selecting the best systems. Notably, the existence of the CW weights assumes that practitioners can simulate a set of real-world scenarios where the system is the best across the given axes. Specifying if the system can be the CW on the leaderboard would help diagnosing the systems without additional heavy experiments. The developers also can document this information on model sharing platforms, e.g. HUGGINGFACE (Wolf et al., 2020).

3.3 Robustness to Missing Scores

This case study considers a more detailed analysis of the majority-relation based voting rules that can be efficiently utilised for ranking systems and selecting the winner over missing scores. Here, we evaluate the robustness of the rules to omitted performance scores and analyse how the rankings change under such perturbation.

Method. *Copeland* and *Minimax* take as input the majority graph in which each vertex corresponds to a candidate and an edge from the candidate m_1 to m_2 exists iff $m_1 \mu m_2$, i.e. m_1 is ranked higher than m_2 by more criteria. Let us say there are T criteria $t \in \{t_1, \dots, t_T\}$ and $w \in \{w_1, \dots, w_n\}$ are the weights assigned to them.

$$m_1 \mu m_2 \iff \sum_{i=1}^{|T|} w_i R(m_1, m_2, i) > 0 \quad (3)$$

When evaluating $R(m_1, m_2, i)$, this approach can handle missing values, ignoring the pairs where either of the scores is missing. We can apply the majority-relation based rules using relation μ to rank alternatives with missing scores without losing any information whilst accounting for the available criteria.

We analyse the robustness of the *Copeland* and *Minimax* rules as follows. First, we compute the rankings using both methods on each benchmark without omitting scores and use them as references. Next, we randomly replace N scores with empty values and find top-7 systems over the corrupted leaderboards. We calculate the Spearman correlation (ρ) between the final rankings and the references. Note that we use the median values when omitting scores for σ^{am} and σ^{og} as the baselines.

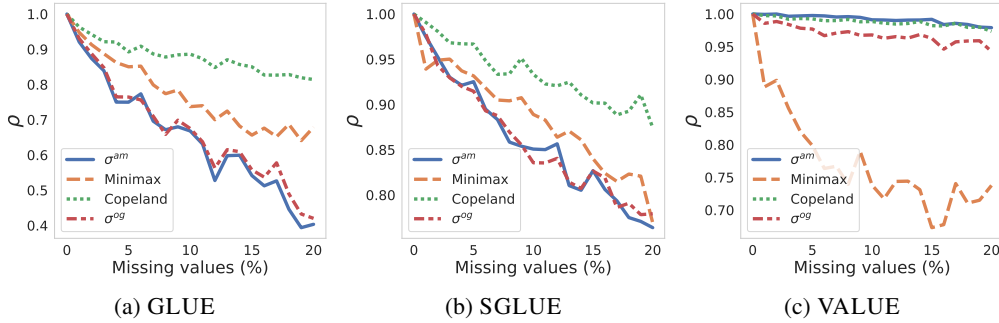


Figure 2: Spearman correlation (ρ) between top-7 model rankings with/without omitted leaderboard values for σ^{am} , σ^{og} , *Minimax*, and *Copeland* rankings. The results are averaged over 100 runs.

Results. Figure 2 shows that σ^{am} and σ^{og} display lower stability and *Copeland* performs the best on GLUE and SGLUE. However, we observe that *Minimax* is the least stable on VALUE, whilst *Copeland*, σ^{am} , and σ^{og} perform on par.

Case study discussion. We attribute the low stability of *Minimax* on VALUE to its limitations. Recall that there are minor differences between the systems on VALUE, which cause *Minimax* to score them very similar (see Table 10 in Appendix B). In this case any missing value can influence the rankings, which results in the low ρ coefficients.

3.4 Ranking Based on User Preferences

This case study aims at system ranking based on the user utility. We rank systems in a simulated scenario that considers preferences on *performance*, *computational efficiency*, and *fairness*.

Method. We use the HUGGINGFACE library to fine-tune and evaluate systems on GLUE. Each system is initialised with a fixed set of five random seeds and fine-tuned for five epochs with default hyper-parameters and a batch size of 16. The development set performance is averaged across all runs. We consider the following systems: BERT-base, RoBERTa-base, ALBERT-base, DeBERTa-base, DistilBERT-base (Sanh et al., 2019), DistilRoBERTa-base (Sanh et al., 2019), and GPT2-medium (Radford et al., 2019). The experiments are run on a single GPU unit, NVIDIA A100 80 GB SXM (NVLink), 4-CPU cores, AMD EPYC 7702 2-3.35 GHz, and 1 TB RAM.

The *efficiency* is computed during fine-tuning via the Impact tracker toolkit (Henderson et al., 2020): the total power, run time in hours, GPU usage in hours, and estimated carbon footprint. To maximise these, we inverse the computational effi-

ciency features through multiplying them by -1 .

To measure *fairness*, we choose three social bias evaluation datasets: CROWS-PAIRS (Nangia et al., 2020), STEREOSET (Nadeem et al., 2021), and WINOBIAS (Zhao et al., 2018). In these datasets, one sentence is always more stereotyping than the other. Following Nangia et al. (2020), we use MLM scoring (Salazar et al., 2020) to score the pairs. The final metrics account for cases (%) in which a less stereotyping sentence is the most probable.

For the sake of space, we present the results on the *Borda* procedure in the basic, weighted, and two-step aggregation settings (§2.4). We assign the weights vector as $(0.4, 0.3, 0.3)$ to performance, efficiency, and fairness. The weights are introduced to increase the impact of performance. We use σ^{am} as the baseline and interim rankings by each criterion individually as references.

Results. Table 5 shows that DEBERTA is the winner according to σ^{am} and *Borda*. However, it requires more computational resources than the other systems and is mediocre in detecting social biases. As a result, it is not the best system in any user-oriented ranking. In this scenario, *Borda* tends to favour the distilled systems (DISTILROBERTA and DISTILBERT) due to their computational efficiency, which has the highest impact on the ranking with four criteria assigned per task. The weighted *Borda* ranks DISTILBERT, ALBERT, and BERT as the top-3 systems. In its turn, the weighted 2-step *Borda* prefers ALBERT first, followed by BERT and DISTILBERT. ALBERT is selected as the winner by the fairness ranking only and occupies the middle positions in the two other rankings. ROBERTA drops down drastically from the second rank (σ^{am}), whilst GPT2 remains in the least-3 systems.

Rank	$\sigma_{Performance}^{am}$	Borda	Weighted Borda	Weighted 2-step Borda	Borda Performance	Borda Efficiency	Borda Fairness
1	82.73	267.0 ↑4	10.75 ↑5	4.30 ↑2	56.5 ↓0	223.0 ↑4	19.0 ↑2
2	82.52	245.0 ↑4	9.83 ↑1	3.60 ↑2	49.0 ↓0	216.0 ↑4	18.0 ↑4
3	80.94	166.0 ↑1	8.96 ↑1	3.40 ↑3	32.5 ↓0	120.0 ↑1	14.0 ↑1
4	79.20	154.0 ↓1	8.63 ↑1	3.00 ↓3	32.0 ↓0	103.0 ↓1	11.00 ↓3
5	78.56	144.0 ↓3	7.17 ↓4	2.90 ↓0	17.0 ↓0	91.0 ↓3	11.0 ↑1
6	77.89	10.0 ↑1	7.04 ↓4	2.60 ↓3	11.0 ↓4	84.0 ↑1	7.00 ↑1
7	75.95	70.50 ↓6	5.47 ↓0	0.90 ↓0	8.0 ↓0	3.00 ↓6	4.00 ↓5

Table 5: Results of re-ranking the GLUE benchmark using the *Borda* rule in the simulated user-oriented scenario. Notations: = ALBERT; = BERT; = DISTILBERT; = ROBERTA; = DISTILROBERTA; = DEBERTA; = GPT2.

Case study discussion. Overall, our setup follows DYNASCORE (Ma et al., 2021), where the microeconomic concept of MRS is used to compare performance, efficiency, and fairness metrics, followed by the weighted average score as the final ranking. Unlike the DYNASCORE results, we find that the average performance ranking is not preserved when using our voting rules. The most notable difference is with DEBERTA and ROBERTA systems, which may become penalised for low efficiency in our case. The reason is that in DYNASCORE, the weight of 0.5 is assigned to performance which blocks substantial changes in re-ranking.

4 Recommendations for Rules Choice

The information about the voting rules’ properties can be used to choose the most suitable one to the user’s preferences (Felsenthal and Machover, 2012). We also provide the following recommendations.

- The *Plurality* rule is a good choice if the user wants only the best systems in *each* criterion.
- If *all* ranking positions matter, use the *Borda* or *Dowdall* rules. Note that *Dowdall* assigns higher weights to the top positions.
- The *Threshold* rule is helpful in cases when the user wants to minimise the number of the low-performance criteria: the rule assigns the highest rank to the system that is considered the worst in the least amount of criteria.
- If the goal is to select the system that beats all the others in pairwise comparison, use the *Baldwin*, *Condorcet*, *Copeland*, or *Minimax* rules. These rules are Condorcet consistent; i.e. choose the

CW if it exists. The main difference is how the rules behave when there is no CW. In particular, *Baldwin* selects the system that is left after elimination according to the *Borda* scores. *Copeland* chooses the system that dominates the others in more cases and is dominated by the least. In turn, *Minimax* selects the system with minimum defeat in pairwise comparison.

- The outcomes *may* contain equivalent alternatives (§3.1). Depending on the scenario, the user can select the rule that produces ties with a lower probability or *Dowdall* and *Borda* if their properties meet the preferences.

5 Conclusion and Future Work

This paper introduces novel aggregation procedures to rank and select the best-performing systems under the social choice theory principles. Our approach provides an alternative perspective of system evaluation in benchmarking and overcomes the standard mean aggregation limitations.

Our case studies show that VOTE’N’RANK provides interpretable decisions on the best and worst systems whilst accounting for missing performance scores and potential user preferences. The framework allows for finding scenarios in which a given system dominates the others. We provide recommendations based on the rules’ properties and scenarios of the intended framework’s application.

The application scope of VOTE’N’RANK is not limited and may be easily extended to other applied ML areas. In our future work, we hope to explore applications of the social choice theory in the *multilingual* and *multimodal* benchmarking.

6 Limitations

Robustness. In the robustness experiments, the *Copeland* and *Minimax* rules are less sensitive to performance score drops than σ^{am} and σ^{og} . However, in certain circumstances *Minimax* may display low resistance to such corruption due to its nature, which is analysed in §3.3. Other robustness evaluation settings can be considered, such as sensitivity to removing and adding new tasks (Procaccia et al., 2007; ?), which are out of scope of this work.

Ambiguity. Almost all rules in our study allow ties or the recognition of systems as equivalent. This may result in non-resoluteness: the selection of multiple winning systems or the presence of many equivalencies in ranking. However, we empirically observe no or a few ties using the *Dowdall*, *Borda*, and *Copeland* rules, whilst *Minimax* and *Plurality* treat a significant number of systems as equivalent due to their properties (§3.1). VOTE’N’RANK does not currently support any additional tie-breaking rules to be applied in this case. The only exception here is the *Threshold rule* that gives only one winner in almost all cases due to the built-in tie-breaking procedure.

Independence of irrelevant alternatives. The violation of the IIA axiom in applications is a well-known fundamental aspect in the social choice theory, and the voting rules can violate the IIA with different probabilities (Dougherty and Heckelman, 2020). IIA violation may imply undesirable behavior: submitting a new system to the leaderboard affects the relative ranking of the other systems. However, we empirically show that *Copeland* and *Minimax* are less likely to violate IIA than *Plurality* and *Borda* rules (§3.1). The IIA assumption may be unrealistic in practice as it takes no account of perfect or near-perfect substitutes (Suppes, 1965).

Lack of ground truth. Comparison of the aggregation procedures is hindered by the absence of the correct ranking, especially when votes are noisy and incomplete. There is no universal answer to the question of how the systems on the multi-task benchmarks should be preferred. However, we hope to contribute from a practical standpoint, offering an alternative approach to the mean aggregation procedure.

7 Ethical Considerations

Stereotypes and discrimination in LMs’ pre-training data can lead to representation biases against race, religion, and social minorities. Our framework allows ranking systems to account for sensitive attributes (Celis et al., 2018), e.g. gender and nationality, or to find the trade-off between multiple criteria, e.g. performance and fairness (Baldini et al., 2022). The rank aggregation rules have been widely adopted to information retrieval and recommendation systems (Dwork et al., 2001; Maschhoff, 2011). We assume that translation of the social choice theory into the system evaluation problems may improve the user experience by selecting systems that best satisfy evaluative criteria and individual or group preferences in downstream applications.

Acknowledgements

Mark Rofin, Mikhail Florinskiy, and Daniel Karabekyan were supported by the grant for research centres in the field of AI provided by the Analytical Centre for the Government of the Russian Federation (ACRF) in accordance with the agreement on the provision of subsidies (identifier of the agreement 000000D730321P5Q0002) and the agreement with the HSE University No. 70-2021-00139. We acknowledge the computational resources of HPC facilities at the HSE University. We would also like to thank colleagues from the IT University of Copenhagen and the anonymous reviewers for their comments on this paper.

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A Aggregation Procedures

A.1 Examples

Rank	Task 1	Task 2	Task 3	Task 4	Task 5
1	m_A	m_A	m_B	m_C	m_D
2	m_B	m_C	m_D	m_B	m_B
3	m_C	m_D	m_C	m_D	m_C
4	m_D	m_B	m_A	m_A	m_A

Table 6: A toy leaderboard for illustration purposes.

Rank	Task 1	Task 2	Task 3	Task 4	Task 5
1	m_B	m_C	m_B	m_C	m_D
2	m_C	m_D	m_D	m_B	m_B
3	m_D	m_B	m_C	m_D	m_C

Table 7: The leaderboard based on Table 6 used for describing the *Baldwin* rule.

This appendix provides illustrative examples on how our voting rules work. Here, suppose we have a toy leaderboard with five tasks and four systems as shown in Table 6. The systems are ranked within each task by their performance score. We now compute the rankings using each voting rule.

Scoring rules.

- *Plurality rule* assigns the score of 2 to m_A and scores of 1 to m_B , m_C , and m_D .
- According to the *Borda rule*, the systems that take the first position get 3 points for each task, 2 points are awarded for the second position, etc. As a result, the systems receive the following *Borda* scores: $m_A = 6$, $m_B = 9$, $m_C = 8$, and $m_D = 7$. The system m_B has the highest score and is chosen as the best one.
- For the *Dowdall rule* scoring vector, we get the following scores: $S_{m_A} = 2.75$, $S_{m_B} = 2.75$, $S_{m_C} = 2.5$, and $S_{m_D} = 1.75 + 2/3$. There is a tie between the systems m_A and m_B , and both of them are considered the best models.

Iterative scoring rules.

- For the *Threshold rule* scoring vector (1,1,1,0), we get the following scores: $S_{m_A} = 2$, $S_{m_B} = 4$, $S_{m_C} = 5$, and $S_{m_D} = 4$. The system m_C is the winner. If there is a tie, the scoring vector (1,1,0,0) is further applied for only tied systems.
- The *Baldwin rule*: first, we calculate the *Borda* scores as mentioned above. Second,

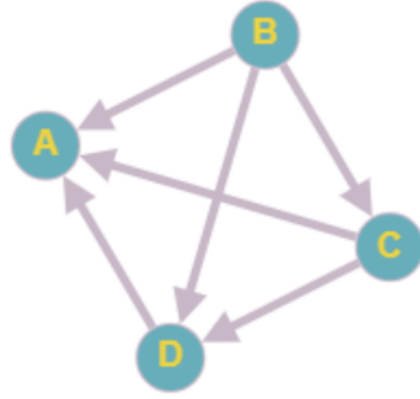


Figure 3: A toy graph example of the majority relation μ based on Table 6.

we eliminate the system m_A since it has the lowest score (see Table 7). Next, we re-calculate the *Borda* scores for a new scoring vector (2,1,0) and get the following results: $S_{m_B} = 6$, $S_{m_C} = 5$, and $S_{m_D} = 4$. At this step, the system m_D is eliminated. Finally, we re-calculate the results for the scoring vector (1,0). The results are $S_{m_B} = 3$ and $S_{m_C} = 2$, and the system m_B is declared the winner.

Majority-relation based rules. The majority relation in this example is illustrated in Figure 3.

- The system m_B is the *Condorcet* winner as it beats each of the alternatives. Note that since all majority-relation based rules (*Copeland* and *Minimax*) are *Condorcet consistent*, they declare the system m_B the winner as well. Let us illustrate it in more detail.
- The *Copeland* rule scores are $u(m_A) = -3$, $u(m_B) = 3$, $u(m_C) = 1$, $u(m_D) = -1$. The system m_B is the winner as it has the highest $u(x)$.
- The *Minimax* rule scores are $rank(m_A) = -3$, $rank(m_B) = 0$, $rank(m_C) = -3$, $rank(m_D) = -3$. Here, the system m_B has the highest rank.

A.2 Properties

We consider the following properties to describe our voting rules and summarise them in Table 8.

- **Transitivity.** There are no cycles in the final ranking. An example of the cycle is a situation, where m_A is better than m_B , m_B is better than m_C , and m_C is better than m_A .

	<i>Plurality</i>	<i>Borda</i>	<i>Dowdall</i>	<i>Threshold</i>	<i>Baldwin</i>	<i>Copeland</i>	<i>Minimax</i>
Transitivity	✓	✓	✓	✓	✓	✓	✓
Anonymity	✓	✓	✓	✓	✓	✓	✓
Unanimity	✓*	✓	✓	✓	✓	✓	✓
IIA	✗	✗	✗	✗	✗	✗	✗
Monotonicity	✓	✓	✓	✓	✗	✓	✓
Majority	✓	✗	✓	✗	✓	✓	✓
CW	✗	✗	✗	✗	✓	✓	✓
Condorcet loser	✗	✓	✗	✗	✓	✓	✗
Sum	5	5	5	4	6	7	6

Table 8: Rules and their properties. *The non-winning Pareto-dominated systems can be tied.

- **Unanimity (Pareto efficacy).** If the system m_A is ranked higher than m_B according to all criteria, then m_A should be ranked higher.
- **Non-dictatorship (Anonymity).** There is no single criterion that defines the final ranking.
- **Independence of irrelevant alternatives (IIA).** For any two systems, the information about other systems should not influence their ranking.
- **Monotonicity.** If the system m_A is the winner and it started to rank higher according to one of the criteria, then it should still be the winner.
- **Majority criterion.** If the system m_A is considered the best by more than 50% criteria, then it should be the winner.
- **Condorcet winner criterion.** This criterion is a stronger version of the Majority criterion. If the system m_A is the Condorcet winner (CW), it should be the winner according to the rule.
- **Condorcet loser criterion.** If the system m_A is the Condorcet loser ($a\mu M^L$ for any $a \in A$), it should never be the winner according to the rule.

Recall that the *Condorcet* rule by definition complies with the Condorcet winner and loser criteria. The other properties can not be checked in application to benchmarking since the rule is defined on a restricted domain: it does not provide the results on any possible combination of rankings.

There is no single best voting rule since none of them satisfies properties of the Arrow’s impossibility theorem (Arrow, 2012; Geanakoplos, 2005): transitivity, unanimity, non-dictatorship, and independence of irrelevant alternatives (IIA).

B Case Studies

We do not report the agreement rate, the Kendall Tau (τ) correlation, and the IIA results for VALUE since we are given only up to 7 evaluated alternatives: CRAIG.STARR (Shin et al., 2021), DUKG (Li et al., 2021), HUMAN, and four HERO-based configurations (Li et al., 2020). The HERO-based baselines are trained in the following settings: single-task training (ST), multi-task training (MT) by tasks or domains, all-task training (AT) and AT first then ST (AT -> ST). We refer to the configurations as follows:

- HERO₁: AT->ST, PT+FT;
- HERO₂: AT->ST, FT-only;
- HERO₃: ST, PT+FT;
- HERO₄: ST, FT-only.

The VALUE results. Table 10 and Table 11 show the VALUE re-ranking results over missing/non-missing scores. ✗ means that the given aggregation method does not operate over missing values. In the first case, we observe that the *Copeland* and *Minimax* rules generally agree on the final outcomes except for the fifth and sixth positions. The rules select HUMAN as the winner. At the same time DUKG and HERO₁ have the same *Minimax* values, and the *Minimax* values of the least-3 systems are also equal. In the second case, we omit HUMAN due to missing scores on 6 out of 11 tasks for comparable interpretation. However, there are 3 tied alternatives in the *Minimax* and *Dowdall* outcomes. Interestingly, all methods are consistent in conclusions on the top-3 systems, with the *Minimax* treating DUKG and HERO₁ as equal alternatives. The σ^{og} , *Minimax*, *Plurality*, *Dowdall*, and *Borda* rules make equal decisions on the final outcomes.





































































Rank	σ^{am}	σ^{gm}	σ^{og}	Copeland	Minimax	Plurality	Dowdall	Borda
1	 90.62	 90.04 ↓0	 0.066 ↓0	 20.00 ↑3	 0 ↓0	 4.00 ↑3	 4.98 ↑3	 155.00 ↓0
2	 90.39	 89.84 ↓0	 0.068 ↓0	 19.00 ↓1	 0 ↑2	 2.50 ↓1	 4.25 ↓1	 154.50 ↓0
3	 90.29	 89.75 ↓0	 0.068 ↓0	 18.00 ↓1	 -4.50 ↓1	 1.00 ↓1	 3.62 ↓1	 153.00 ↓0
4	 89.79	 88.80 ↓0	 0.073 ↑1	 15.00 ↓1	 -5.00 ↓1	 0.50 ↓1	 3.29 ↓1	 145.50 ↓0
5	 89.25	 88.75 ↓0	 0.074 ↓1	 13.00 ↓0	 -7.50 ↓0	 0.00 ↑9	 2.11 ↓0	 141.50 ↓0
6	 86.65	 85.93 ↓0	 0.089 ↑1	 11.00 ↓0	 -8.00 ↑8	 0.00 ↑12	 1.16 ↓0	 116.50 ↓0
7	 86.09	 85.38 ↓0	 0.10 ↑5	 9.00 ↑1	 -8.00 ↑11	 0.00 ↑12	 1.06 ↑1	 108.00 ↑1

Table 9: Results of re-ranking the SGLUE benchmark. The model rank changes are depicted with arrows, whilst the superscripts denote scores assigned by the voting method. Notations: =HUMAN; =ERNIE; =DEBERTA/TURINGNLRV4; =NEZHA-PLUS; =T5+UDG; =BERT++; =PAI ALBERT; =ROBERTA-ICETS; =GPT-3 FEW-SHOT; =iPET (ALBERT) FEW-SHOT; =T5; =AILABS TEAM.






















Rank	σ^{am}	σ^{gm}	σ^{og}	Copeland	Minimax	Plurality	Dowdall	Borda
1	X	X	X	 6.00 ↓0	 0 ↓0	X	X	X
2	X	X	X	 4.00 ↓0	 -6.00 ↓0	X	X	X
3	X	X	X	 2.00 ↓0	 -10.00 ↓0	X	X	X
4	X	X	X	 0.00 ↓0	 -10.00 ↓0	X	X	X
5	X	X	X	 -2.00 ↓0	 -11.00 ↓0	X	X	X
6	X	X	X	 -4.00 ↓0	 -11.00 ↓0	X	X	X
7	X	X	X	 -6.00 ↓0	 -11.00 ↓0	X	X	X

Table 10: Results of re-ranking the VALUE benchmark over missing scores. Changes in the system ranks are depicted with arrows, whilst the superscripts denote scores assigned by the aggregation procedure. Notations: =HUMAN; =CRAIG.STARR; =DUKG; =HERO₁; =HERO₂; =HERO₃; =HERO₄.























































Rank	σ^{am}	σ^{gm}	σ^{og}	Copeland	Minimax	Plurality	Dowdall	Borda
1	 62.87	 49.96 ↓0	 0.365 ↓0	 5.00 ↓0	 0 ↓0	 9.00 ↓0	 10.00 ↓0	 53.00 ↓0
2	 60.00	 46.30 ↓0	 0.381 ↓0	 3.00 ↓0	 -10.00 ↓0	 1.00 ↓0	 5.17 ↓0	 39.00 ↓0
3	 57.58	 44.12 ↓0	 0.399 ↓0	 1.00 ↓0	 -10.00 ↓0	 1.00 ↓0	 4.08 ↓0	 30.00 ↓0
4	 56.96	 43.22 ↓0	 0.403 ↑1	 -1.00 ↓0	 -11.00 ↑1	 0.00 ↑1	 2.87 ↑1	 20.00 ↑1
5	 56.07	 42.81 ↓0	 0.404 ↓1	 -3.00 ↓0	 -11.00 ↓1	 0.00 ↓1	 2.82 ↓1	 18.00 ↓1
6	 52.59	 37.56 ↓0	 0.438 ↓0	 -5.00 ↓0	 -11.00 ↓0	 0.00 ↓0	 2.02 ↓0	 5.00 ↓0

Table 11: Results of re-ranking the VALUE benchmark over non-missing scores. The HUMAN results are discarded due to missing scores. Changes in the system ranks are depicted with arrows, whilst the superscripts denote scores assigned by the aggregation procedure. Notations: =CRAIG.STARR; =DUKG; =HERO₁; =HERO₂; =HERO₃; =HERO₄.