

How Fast can BERT Learn Simple Natural Language Inference?

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Abstract

This paper empirically studies whether BERT can really learn to conduct natural language inference (NLI) without utilizing hidden dataset bias; and how efficiently it can learn if it could. This is done via creating a simple entailment judgment case which involves only binary predicates in plain English. The results show that the learning process of BERT is very slow. However, the efficiency of learning can be greatly improved (data reduction by a factor of 1,500) if task-related features are added. This suggests that domain knowledge greatly helps when conducting NLI with neural networks.

1 Introduction

Entailment judgment (Dagan et al., 2006; Marelli et al., 2014a) is a common test for *natural language inference* (NLI) (Camburu et al., 2018; Conneau et al., 2018) as it possesses the simplest form in related tasks such as question and answering (Bowman and Zhu, 2019). Also, SNLI dataset (Bowman et al., 2015) is frequently adopted for NLI evaluation because it is the first corpus to show the power of neural networks for the task that specifically targets NLI.

Recently, BERT (Devlin et al., 2019), XLNet (Yang et al., 2019), and RoBERTa (Liu et al., 2019) have all shown excellent performances on SNLI, surpassing even human performance (Gong et al., 2017). However, Tsuchiya (2018) and Gururangan et al. (2018) show that SNLI contains *hidden bias*. Also, deep neural networks (DNNs) have been shown to predominantly capture the *statistical irregularities* that go unnoticed by humans (Poliak et al., 2018); this surprisingly yields 69% accuracy on SNLI without being provided the associated *premise* (i.e., the required *supporting evidence*). Furthermore, some studies (Naik et al., 2018;

McCoy et al., 2019; Jiang and Marneffe, 2019) have shown that BERT mainly conducts NLI with surface clues/patterns, but not those clues actually adopted by humans.

To the best of our knowledge, none of previous studies carefully removes the dataset bias, and then investigates how efficiently that BERT could learn NLI if the surface clues are *completely* removed. In this paper, we empirically study whether BERT is capable of learning NLI without surface clues/bias appearing in the dataset; and if it is, whether it can learn NLI efficiently. We carefully created absolutely unbiased datasets, in which the premises and hypotheses simply describe the relative position of two objects in plain English. That is, given a premise “*John is on the left side of Mary*” (abbreviated as a predicate “left(John, Mary)” from now on), the hypotheses predicates “left(John, Mary)”, “left(Mary, John)” and “left(John, Helen)” should be labeled as *entailment*, *contradictory* and *neutral* respectively. Our experiment results show BERT is very slow in learning this simple NLI.

We then further study if the learning efficiency can be improved with domain knowledge (Gülçehre and Bengio, 2016). Inspired by Chen et al. (2017), we think whether two entities are *exactly the same* is quite crucial in making the above NLI. So, the task-related features, such as whether the first/second argument of the premise predicate exactly matches that of hypothesis, are fed into BERT. The obtained results show that such task-related features are able to greatly benefit BERT (reducing the data needed by a factor of 1,500), which is important as it is difficult to acquire enough data in many real-world applications.

Our main contributions are: (1) We are the first to quantitatively study how efficiently BERT can learn to conduct NLI without available surface clues/bias. (2) We design experiments to completely eliminate hidden bias while evaluating

the inference capability of BERT. (3) We show that adding task-related features greatly enhances the learning efficiency of BERT.

2 Teaching BERT Binary Predicates

The sentence “*John is on the left side of Mary*” describes a positional relation between two people. For conciseness, it will be denoted by a binary predicate “left(John,Mary)” from now on, where “left” is the predicate name, “John” is the first argument and “Mary” is the second argument. We seek to determine how much data are required to teach BERT to truly understand this simple binary predicate (i.e., premise) and correctly judge that the hypothesis “left(Mary,John)” is contradictory and that the hypothesis “left(John,Helen)” is neutral. Besides, we also seek to determine whether BERT is also able to learn the antonymous predicate “right(·,·)”, and judge that the hypothesis “right(Mary,John)” is entailed by the above premise.

2.1 Entity Names and Datasets

The arguments of the above binary predicates “left(·,·)” and “right(·,·)” actually can be the names of any objects. However, in this paper, we simply trained BERT with *personal names*. To avoid dividing a personal name into sub-words, we collected 1,696 male and female first names which appear in the vocabulary of the pre-trained “BERT-Base, Uncased” model (Devlin et al., 2019). These names were randomly partitioned into three sets: η_T , η_V and η_E . The subscripts **T**, **V** and **E** indicate these name sets will be used for **T**raining, **V**alidation and **E**valuation respectively. Sets η_T and η_V , which consist of 1,356 and 170 names respectively, are used to generate the training and validation datasets for fine-tuning BERT; and Set η_E , consisting of 170 names, is used to generate a dataset for evaluating the performance of BERT in understanding the predicates with personal names.

Furthermore, we also seek to ascertain whether the BERT model trained by the predicates with personal names also understands the predicates with names of other BERT object types. Therefore, in addition to personal names, we also collected 30 common fruit and vegetable names to create an additional set f_E , which will be used to generate another dataset for performance evaluation.

We conduct a number of experiments on *recognizing textual entailment* (RTE) (Dagan et al., 2006; Marelli et al., 2014a) to study the learning

curves of BERT in understanding binary predicates. In each experiment, four datasets—**Name-T**, **Name-V**, **Name-E** and **Fruit-E**—are created by filling experiment-specific templates with names randomly chosen from η_T , η_V , η_E and f_E respectively. The training set **Name-T** and the validation set **Name-V** are used to fine-tune the BERT model. The other two sets (**Name-E** and **Fruit-E**) are test sets. They are used to assess the performances of the BERT model. Each dataset is generated via iteratively and sequentially adding one entailment example, one contradictory example, and one neutral example until it reaches the desired size. Thus a dataset of a size 100 will consist of 34 entailment examples, 33 contradictory examples, and 33 neutral examples. The experiment-specific templates are described in the following sections.

2.2 One Simple Binary Predicate

We first conducted *EXP-SP* (SP: Simple Predicate) experiment to show if BERT can be taught to understand the simple binary predicate “left(·,·)”. In this experiment, a template has the form “*premise* [s] *hypothesis*”, where “[s]” is a separator token between the premise and the hypothesis. The templates are partitioned into entailment, contradictory, and neutral template sets. The entailment template set has only one template “left(x, y) [s] left(x, y)”, where “left(x, y)” represents the token sequence “ x is on the left side of y ” and the variables x and y indicate the names to be filled in. Likewise, the contradictory template set has only one template “left(x, y) [s] left(y, x)”. However, the neutral template set consists of four templates:

“left(x, y) [s] left(x, z)”,
 “left(x, y) [s] left(z, x)”,
 “left(x, y) [s] left(y, z)”,
 “left(x, y) [s] left(z, y)”,

where the variable z indicates a name to be filled in. Names and templates were randomly selected during dataset creation. For example, when generating a neutral example for **Name-T**, we randomly chose one template from the neutral template set and randomly chose three distinct names (for variables x, y, z) from name set η_T . Obviously, the generated datasets do not have any hidden bias, as all examples share the same token sequence except the argument tokens which are randomly chosen. Therefore, no annotation

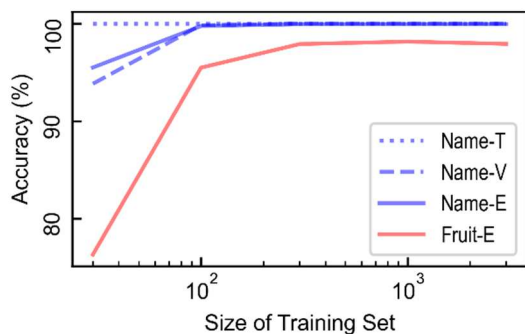


Figure 1: RTE performances of EXP-SP.

artifacts (Gururangan et al., 2018) in the data can provide hints for predicting final inference answers.

To quantitatively study the learning efficiency, we generated various **Name-T** sets with different sizes to study how much data would be required to teach BERT to understand the simple binary predicate “left(\cdot, \cdot)”. We set **Name-V**, **Name-E**, and **Fruit-E** to 1,000 examples each. The solid lines in Figure 1 show that the accuracies of BERT on both test sets (i.e., **Name-E** and **Fruit-E**) increase when the training set size increases. However, even if we train BERT with 3,000 examples, it still cannot achieve 100% accuracy on the test sets. In fact, all sentences in this experiment have the form “ x is on the left side of y ”, where x and y are object names. Therefore, only 6 different words could appear in the context of object names. In other words, given 3,000 examples, BERT still cannot fully understand the meaning of the context “is on the left side of”.

Furthermore, training BERT to reach over 99% accuracy on **Name-E** requires 100 training examples. However, even given 30 times the training data, BERT is still unable to achieve 99% accuracy on **Fruit-E**. That is, BERT is not able to well generalize what it has learned from the examples with person names to the examples with fruit and vegetable names.

2.3 One Antonymous Predicate

Antonyms are frequently used in natural language and play an important role in natural language inference. Given the premise “ $John$ is on the left side of $Mary$ ”, we can easily infer that the hypothesis “ $Mary$ is on the right side of $John$ ” is entailed by the premise, and that the hypothesis “ $John$ is on the right side of $Mary$ ” contradicts to the premise. This inference is easy for humans; but is it also easy for BERT? Therefore, we conducted

another test named *EXP-AP* (AP: **Antonymous Predicate**), a more complicated RTE experiment in which we added the antonymous predicate “right(\cdot, \cdot)”.

In this experiment, the entailment template set consists of the following four templates:

“left(x, y) [s] left(x, y)”,
 “left(x, y) [s] right(y, x)”,
 “right(x, y) [s] right(x, y)”,
 “right(x, y) [s] left(y, x)”.

The contradictory template set consists of the following four templates:

“left(x, y) [s] left(y, x)”,
 “left(x, y) [s] right(x, y)”,
 “right(x, y) [s] right(y, x)”,
 “right(x, y) [s] left(x, y)”.

Likewise, the neutral template set consists of 16 templates. In brief, adding one antonymous predicate “right(\cdot, \cdot)” enlarges the number of all possible templates for dataset generation from 6 to 24.

The solid lines in Figure 2 are the accuracies on the test sets **Name-E** and **Fruit-E** in EXP-AP. For ease of comparison, we also plot the EXP-SP counterpart accuracies with dotted lines. Although EXP-AP uses only four times as many templates as EXP-SP uses, we must provide more than 30 times the training data (from 100 to 3,000) for BERT to reach 99% accuracy on **Name-E**. That is, by adding a single antonymous predicate, the RTE task of EXP-AP becomes 30 times harder than that of EXP-SP. It seems teaching BERT to “almost understand” two simple binary predicates requires more than 3,000 examples. This result could be also interpreted in another view. In the EXP-AP, the context of object names in each sentence is either “is on the left side of” or “is on the right side of”. BERT requires 3,000 examples to learn the meanings of the 7 different words that appear in these two contexts. This represents a quite inefficient learning curve.

3 Incorporating Human Knowledge

The previous section showed that many training examples are needed to teach BERT for understanding two binary predicates “left(\cdot, \cdot)” and “right(\cdot, \cdot)” in a simple RTE task. It thus naturally leads to a conjecture that training BERT to understand more complicated predicates would very likely require infeasible amount of training

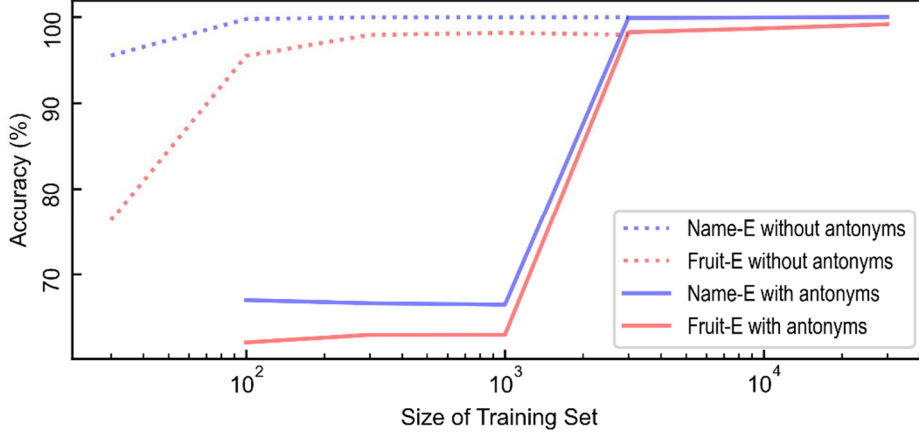


Figure 2: RTE performances of EXP-SP (dotted lines) and EXP-AP (solid lines).

data. One possible solution is to improve the learning curve of BERT by feeding it useful/obvious features that have been identified in human/domain knowledge.

3.1 Simple Features (SF)

Accordingly, we conducted an experiment *EXP-SF*, in which we appended features to the input tokens of EXP-AP to improve the learning curve. In this experiment, a template has the form “*premise* [s] *hypothesis* [s] *features*”. Obviously, humans directly compare the predicate name and the predicate arguments in the premise against their counterparts in the hypothesis. Perhaps this knowledge about which two fields should be compared would be helpful when training BERT on the EXP-AP task. Let N_P and N_H indicate the predicate names in the premise and the hypothesis respectively; also, let $A_{i,P}$ and $A_{i,H}$ indicate the i -th predicate arguments in the premise and the hypothesis respectively. In EXP-SF, every example in the datasets of EXP-AP will be augmented by the following three indicator features:

$$\begin{aligned} f_1 &= I(N_P = N_H), \\ f_2 &= I(A_{1,P} = A_{1,H}), \\ f_3 &= I(A_{2,P} = A_{2,H}). \end{aligned}$$

Here the indicator function $I(x)$ returns the word “*true*” if x is true and “*false*” if it is not. EXP-SF templates thus could be directly transformed from the corresponding EXP-AP templates. To illustrate this transformation, we show an entailment

template, a contradictory template and a neutral template in EXP-SF as follows:

$$\begin{aligned} &\text{“left}(x, y) [s] \text{right}(y, x) [s] \text{false false false”}, \\ &\text{“left}(x, y) [s] \text{left}(y, x) [s] \text{true false false”}, \\ &\text{“left}(x, y) [s] \text{right}(x, z) [s] \text{false true false”}. \end{aligned}$$

The dashed lines in Figure 3 are the accuracies on the test sets **Name-E** and **Fruit-E** in EXP-SF. For ease of comparison, we also plot the counterpart accuracies of the baseline (i.e., EXP-AP) with dotted lines. The fact that the dashed lines lie far on the left side of the dotted lines indicates that much fewer training examples are required to train BERT after adding these three simple features¹. This represents a greatly improved learning curve. Specifically, given merely 100 EXP-SF examples, BERT achieves over 99% accuracy on **Name-E**; in contrast, BERT requires 3,000 examples to surpass 99% accuracy on **Name-E** in EXP-AP. This represents a greatly improved learning curve.

3.2 Discriminant Features (DF)

In the previous experiment EXP-SF, features f_2 and f_3 do not precisely indicate the situation in which the arguments in the premise match the arguments in the hypothesis after swapping. For example, for both “left(x, y) [s] left(y, x)” and “left(x, y) [s] left(z, x)”, features f_2 and f_3 are all *false* in EXP-SF. However, the former is a contradictory case and the latter is a neutral case. We thus conducted the last experiment named *EXP-DF*, in which we replaced f_2 and f_3 with a

¹ Note that it does not matter which words were chosen to represent the values of features. We had randomly selected *fortification* and *mississippi* from BERT’s vocabulary to

replace the words *true* and *false*. The experimental results were similar to those in Figure 3. In other words, the initial embeddings of the feature values are not crucial.

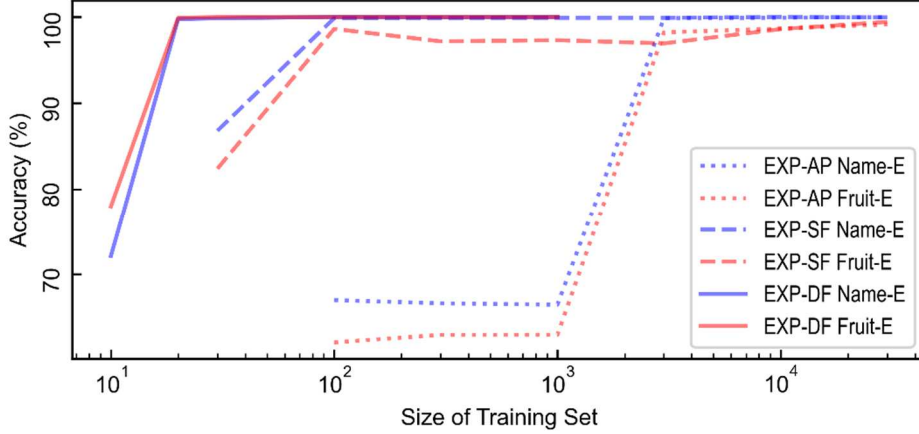


Figure 3: RTE performances of EXP-AP (dotted lines), EXP-SF (dashed lines) and EXP-DF (solid lines). More detailed data values are listed in Appendix.

new discriminant feature f'_2 . Words *true*, *false* and *fuzzy* were used to indicate the three possible values of this new feature as follows:

$$f'_2 = \begin{cases} \textit{true}, & A_{1,P} = A_{1,H} \wedge A_{2,P} = A_{2,H}; \\ \textit{false}, & A_{1,P} = A_{2,H} \wedge A_{2,P} = A_{1,H}; \\ \textit{fuzzy}, & \textit{otherwise}. \end{cases}$$

The solid lines in Figure 3 show that the learning curve of BERT is further improved after adopting this discriminant feature. Given only 20 EXP-DF examples, BERT achieves 99.9% accuracy on **Fruit-E**. However, in EXP-AP, 1,500 times amount of data (i.e., 30,000 examples) is needed for reaching 99.1% accuracy on **Fruit-E**.

4 Related Work

Dagan et al. (2006) first initiated the task of recognizing textual entailment about fifteen years ago. This task continued until 2011 (Bentivogli et al., 2011). Afterwards, conducting inference with BERT was studied in (Clark et al., 2019; Zellers et al., 2019; Tenney et al., 2019; Aken et al., 2019; Coenen et al., 2019; Michel et al., 2019).

On the other hand, various corpora have been created for conducting NLI for different purposes: SICK (Marelli et al., 2014b), SNLI (Bowman et al., 2015), MNLI (Williams et al., 2018), MPE (Lai et al., 2017), JOCI (Zhang et al., 2017), XNLI (Conneau et al., 2018), and SciTail (Khot et al., 2018). Corpora such as HOTPOTQA (Yang et al., 2018), Breaking-NLI (Glockner et al., 2018), CommonSense QA (Talmor et al., 2019), DROP (Dua et al., 2019) and ROPES (Lin et al., 2019) have also been created recently to evaluate more diverse and difficult NLI cases. However, all those

corpora are not created for keeping the data absolutely unbiased. We believe using bias-free simple binary predicates would be more suitable to assess the true inference capability of BERT (or even other DNNs).

Recently, Ribeiro et al. (2020) proposed a new evaluation methodology, named CheckList, to check general linguistic capabilities of a given NLI model. They generated a large number of diverse test cases to identify the critical failures hidden behind state-of-art models. In contrast, our work mainly targeted the learning efficiency of BERT on various unbiased datasets. Besides, we also studied how adding useful domain-specific features would affect the learning curve of BERT.

5 Conclusion

This paper is the first quantitative study on whether BERT could really learn to conduct NLI without implicitly utilizing hidden dataset bias, and how quickly it does so if it could. We conduct experiments to evaluate the capability of BERT on making inference without hidden bias, and show that BERT learns NLI inefficiently even for a simple case. We further add task-related features to greatly enhance BERT’s learning efficiency. As a result, it suggests that domain knowledge may be essential in conducting NLI with neural networks (at least for BERT).

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Appendix

To reduce the performance assessment error, each accuracy reported in this paper is the mean of accuracies obtained from multiple simulations. Each simulation uses a unique random seed to fine-tune the BERT model. The accuracies plotted in the figures for EXP-AP, EXP-SF and EXP-DF are listed in the following table, where μ denotes the accuracy mean and σ denotes the standard deviation of μ .

Training Set Size	Test Set Accuracy (%)			
	Name-E		Fruit-E	
	μ	σ	μ	σ
EXP-AP				
100	67.0	0.6	62.1	1.8
300	66.6	0.3	62.9	0.9
1000	66.5	0.4	62.9	1.4
3000	99.9	0.0	98.2	0.3
10000	99.9	0.0	98.7	0.2
30000	100.0	0.0	99.1	0.1
EXP-SF				
30	86.8	0.9	82.4	3.1
100	99.9	0.1	98.6	0.4
300	99.9	0.0	97.2	0.4
1000	99.9	0.0	97.3	0.6
3000	99.9	0.0	96.9	0.5
10000	100.0	0.0	98.6	0.9
30000	100.0	0.0	99.4	0.1
EXP-DF				
10	72.1	1.3	78.0	3.4
20	99.8	0.2	99.9	0.1
30	99.9	0.1	100.0	0.0
100	100.0	0.0	100.0	0.0
300	100.0	0.0	100.0	0.0
1000	100.0	0.0	100.0	0.0