

Robust Distant Supervision Relation Extraction via Deep Reinforcement Learning

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Abstract

Distant supervision has become the standard method for relation extraction. However, even though it is an efficient method, it does not come at no cost—The resulted distantly-supervised training samples are often very noisy. To combat the noise, most of the recent state-of-the-art approaches focus on selecting one-best sentence or calculating soft attention weights over the set of the sentences of one specific entity pair. However, these methods are suboptimal, and the **false positive** problem is still a key stumbling bottleneck for the performance. We argue that those incorrectly-labeled candidate sentences must be treated with a hard decision, rather than being dealt with soft attention weights. To do this, our paper describes a radical solution—We explore a deep reinforcement learning strategy to generate the false-positive indicator, where we automatically recognize false positives for each relation type without any supervised information. Unlike the removal operation in the previous studies, we redistribute them into the negative examples. The experimental results show that the proposed strategy significantly improves the performance of distant supervision comparing to state-of-the-art systems.

1 Introduction

Relation extraction is a core task in information extraction and natural language understanding. The goal of relation extraction is to predict relations for entities in a sentence (Zelenko et al., 2003; Bunescu and Mooney, 2005; GuoDong et al., 2005). For example, given a sentence

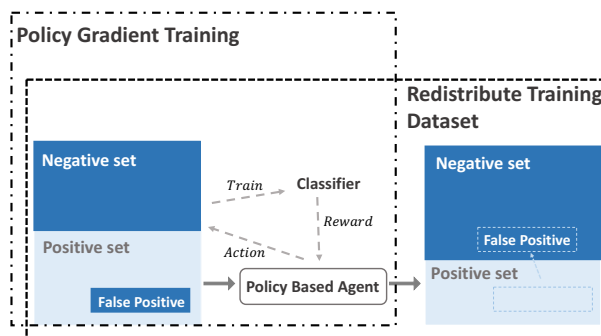


Figure 1: Our deep reinforcement learning framework aims at dynamically recognizing false positive samples, and moving them from the positive set to the negative set during distant supervision.

“*Barack Obama is married to Michelle Obama.*”, a relation classifier aims at predicting the relation of “*spouse*”. In downstream applications, relation extraction is the key module for constructing knowledge graphs, and it is a vital component of many natural language processing applications such as structured search, sentiment analysis, question answering, and summarization.

A major issue encountered in the early development of relation extraction algorithms is the data sparsity issue—It is extremely expensive, and almost impossible for human annotators to go through a large corpus of millions of sentences to provide a large amount of labeled training instances. Therefore, distant supervision relation extraction (Mintz et al., 2009; Hoffmann et al., 2011; Surdeanu et al., 2012) becomes popular, because it uses entity pairs from knowledge bases to select a set of noisy instances from unlabeled data. In recent years, neural network approaches (Zeng et al., 2014, 2015) have been proposed to train the relation extractor under these noisy conditions. To suppress the noisy (Roth et al., 2013), recent stud-

ies (Lin et al., 2016) have proposed the use of attention mechanisms to place soft weights on a set of noisy sentences, and select samples. However, we argue that only selecting one example or based on soft attention weights are not the optimal strategy: To improve the robustness, we need a systematic solution to make use of more instances, while removing false positives and placing them in the right place.

In this paper, we investigate the possibility of using dynamic selection strategies for robust distant supervision. More specifically, we design a deep reinforcement learning agent, whose goal is to learn to choose whether to remove or remain the distantly supervised candidate instance based on the performance change of the relation classifier. Intuitively, our agent would like to remove false positives, and reconstruct a cleaned set of distantly supervised instances to maximize the reward based on the classification accuracy. Our proposed method is classifier-independent, and it can be applied to any existing distant supervision model. Empirically, we show that our method has brought consistent performance gains in various deep neural network based models, achieving strong performances on the widely used New York Times dataset (Riedel et al., 2010). Our contributions are three-fold:

- We propose a novel deep reinforcement learning framework for robust distant supervision relation extraction.
- Our method is model-independent, meaning that it could be applied to any state-of-the-art relation extractors.
- We show that our method can boost the performances of recently proposed neural relation extractors.

In Section 2, we will discuss related works on distant supervision relation extraction. Next, we will describe our robust distant supervision framework in Section 3. In Section 4, empirical evaluation results are shown. And finally, we conclude in Section 5.

2 Related Work

Mintz et al. (2009) is the first study that combines dependency path and feature aggregation for distant supervision. However, this approach would

introduce a lot of false positives, as the same entity pair might have multiple relations. To alleviate this issue, Hoffmann et al. (2011) address this issue, and propose a model to jointly learn with multiple relations. Surdeanu et al. (2012) further propose a multi-instance multi-label learning framework to improve the performance. Note that these early approaches do not explicitly remove noisy instances, but rather hope that the model would be able to suppress the noise.

Recently, with the advance of neural network techniques, deep learning methods (Zeng et al., 2014, 2015) are introduced, and the hope is to model noisy distant supervision process in the hidden layers. However, their approach only selects one most plausible instance per entity pair, inevitably missing out a lot of valuable training instances. Recently, Lin et al. (2016) propose an attention mechanism to select plausible instances from a set of noisy instances. However, we believe that soft attention weight assignment might not be the optimal solution, since the false positives should be completely removed and placed in the negative set. Ji et al. (2017) combine the external knowledge to rich the representation of entity pair, in which way to improve the accuracy of attention weights. Even though these above-mentioned methods can select high-quality instances, they ignore the false positive case: all the sentences of one entity pair belongs to the false positives. In this work, we take a radical approach to solve this problem—We will make use of the distantly labeled resources as much as possible, while learning a independent false-positive indicator to remove false positives, and place them in the right place. After our ACL submission, we notice that a contemporaneous study Feng et al. (2018) also adopts reinforcement learning to learn an instance selector, but their reward is calculated from the prediction probabilities. In contrast, while in our method, the reward is intuitively reflected by the performance change of the relation classifier. Our approach is also complement to most of the approaches above, and can be directly applied on top of any existing relation extraction classifiers.

3 Reinforcement Learning for Distant Supervision

We introduce a performance-driven, policy-based reinforcement learning method to heuristically recognize false positive samples. Comparing to

a prior study that has underutilized the distantly-supervised samples (Lin et al., 2016), we consider an RL agent for robust distant supervision relation extraction. We first describe the definitions of our RL method, including the policy-based agent, external environment, and pre-training strategy. Next, we describe the retraining strategy for our RL agent. The goal of our agent is to determine whether to **retain** or **remove** a distantly-supervised sentence, based on the performance change of relation classifier. Finally, we describe the noisy-suppression method, where we teach our policy-based agent to make a redistribution for a cleaner distant supervision training dataset.

Distant supervision relation extraction is to predict the relation type of entity pair under the automatically-generated training set. However, the issue is that these distantly-supervised sentences that mention this entity pair may not express the desired relation type. Therefore, what our RL agent should do is to determine whether the distantly-supervised sentence is a true positive instance for this relation type. For reinforcement learning, external environment and RL agent are two necessary components, and a robust agent is trained from the dynamic interaction between these two parts (Arulkumaran et al., 2017). First, the prerequisite of reinforcement learning is that the external environment should be modeled as a Markov decision process (MDP). However, the traditional setting of relation extraction cannot satisfy this condition: the input sentences are independent of each other. In other words, we cannot merely use the information of the sentence being processed as the state. Thus, we add the information from the early states into the representation of the current state, in which way to model our task as a MDP problem (Fang et al., 2017). The other component, RL agent, is parameterized with a policy network $\pi_{\theta}(s, a) = p(a|s; \theta)$. The probability distribution of actions $\mathcal{A} = \{a_{remove}, a_{remain}\}$ is calculated by policy network based on state vectors. What needs to be noted is that, Deep Q Network (DQN) (Mnih et al., 2013) is also a widely-used RL method; however, it is not suitable for our case, even if our action space is small. First, we cannot compute the immediate reward for every operation; In contrast, the accurate reward can only be obtained after finishing processing the whole training dataset. Second, the stochastic policy of the policy network is capable of prevent-

ing the agent from getting stuck in an intermediate state. The following subsections detailedly introduce the definitions of the fundamental components in the proposed RL method.

States In order to satisfy the condition of MDP, the state s includes the information from the current sentence and the sentences that have been removed in early states. The semantic and syntactic information of sentence is represented by a continuous real-valued vector. According to some state-of-the-art supervised relation extraction approaches (Zeng et al., 2014; Nguyen and Grishman, 2015), we utilize both word embedding and position embedding to convert sentence into vector. With this sentence vector, the current state is the concatenation of the current sentence vector and the average vector of the removed sentences in early states. We give relatively larger weight for the vector of the current sentence, in which way to magnify the dominating influence of the current sentence information for the decision of action.

Actions At each step, our agent is required to determine whether the instance is false positive for target relation type. Each relation type has a agent¹. There are two actions for each agent: whether to remove or retain the current instance from the training set. With the initial distantly-supervised dataset that is blended with incorrectly-labeled instances, we hope that our agent is capable of using the policy network to filter noisy instances; Under this cleaned dataset, distant supervision is then expected to achieve better performance.

Rewards As previously mentioned, the intuition of our model is that, when the incorrectly-labeled instances are filtered, the better performance of relation classifier will achieve. Therefore, we use the change of performance as the result-driven reward for a series of actions decided by the agent. Compared to accuracy, we adopt the F_1 score as the evaluation criterion, since accuracy might not be an indicative metric in a multi-class classification setting where the data distribution could be imbalanced. Thus, the reward can be formulated as the

¹We also tried the strategy that just builds a single agent for all relation types: a binary classifier(TP/FP) or a multi-class classifier(rela1/rela2/.../FP). But, it has the limitation in the performance. We found that our one-agent-for-one-relation strategy obtained better performance than the single agent strategy.

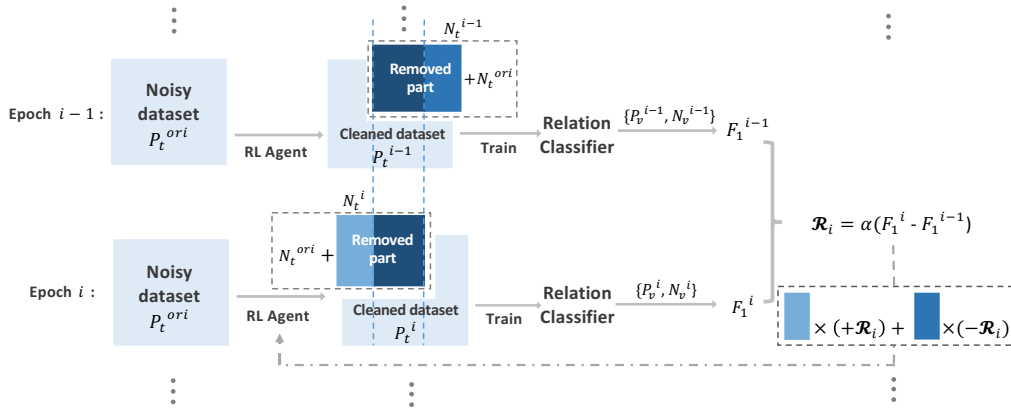


Figure 2: The proposed policy-based reinforcement learning framework. The agent tries to remove the wrong-labeled sentences from the distantly-supervised positive dataset P^{ori} . In order to calculate the reward, P^{ori} is split into the training part P_t^{ori} and the validation part P_v^{ori} ; their corresponding negative part are represented as N_t^{ori} and N_v^{ori} . In each epoch i , the agent performs a series of actions to recognize the false positive samples from P_t^{ori} and treat them as negative samples. Then, a new relation classifier is trained under the new dataset $\{P_t^i, N_t^i\}$. With this relation classifier, F_1 score is calculated from the new validation set $\{P_v^i, N_v^i\}$, where P_v^i is also filtered by the current agent. After that, the current reward is measured as the difference of F_1 between the adjacent epochs.

difference between the adjacent epochs:

$$R_i = \alpha(F_1^i - F_1^{i-1}) \quad (1)$$

As this equation shows, in step i , our agent is given a positive reward only if F_1 gets improved; otherwise, the agent will receive a negative reward. Under this setting, the value of reward is proportional to the difference of F_1 , and α is used to convert this difference into a rational numeric range. Naturally, the value of the reward is in a continuous space, which is more reasonable than a binary reward (-1 and 1), because this setting can reflect the number of wrong-labeled instance that the agent has removed. In order to avoid the randomness of F_1 , we use the average F_1 of last five epochs to calculate the reward.

Policy Network For each input sentence, our policy network is to determine whether it expresses the target relation type and then make removal action if it is irrelevant to the target relation type. Thus, it is analogous to a binary relation classifier. CNN is commonly used to construct relation classification system (Santos et al., 2015; Xu et al., 2015; Shen and Huang, 2016), so we adopt a simple CNN with window size c_w and kernel size c_k , to model policy network $\pi(s; \theta)$. The reason why we do not choice the variants of CNN (Zeng et al., 2015; Lin et al., 2016)

that are well-designed for distant supervision is that these two models belong to bag-level models (dealing with a bag of sentences simultaneously) and deal with the multi-classification problem; We just need a model to do binary sentence-level classification. Naturally, the simpler network is adopted.

3.1 Training Policy-based Agent

Unlike the goal of distant supervision relation extraction, our agent is to determine whether an annotated sentence expresses the target relation type rather than predict the relationship of entity pair, so sentences are treated independently despite belonging to the same entity pair. In distant supervision training dataset, one relation type contains several thousands or ten thousands sentences; moreover, reward R can only be calculated after processing the whole positive set of this relation type. If we randomly initialize the parameters of policy network and train this network by trial and errors, it will waste a lot of time and be inclined to poor convergence properties. In order to overcome this problem, we adopt a supervised learning procedure to pre-train our policy network, in which way to provide a general learning direction for our policy-based agent.

3.1.1 Pre-training Strategy

The pre-training strategy, inspired from *AlphaGo* (Silver et al., 2016), is a common strategy in RL related works to accelerate the training of RL agents. Normally, they utilize a small part of the annotated dataset to train policy networks before reinforcement learning. For example, *AlphaGo* uses the collected experts moves to do a supervised learning for *Go* RL agent. However, in distant supervision relation extraction task, there is not any supervised information that can be used unless let linguistic experts to do some manual annotations for part of the entity pairs. However, this is expensive, and it is not the original intention of distant supervision. Under this circumstance, we propose a compromised solution. With well-aligned corpus, the true positive samples should have evident advantage in quantity compared with false positive samples in the distantly-supervised dataset. So, for a specific relation type, we directly treat the distantly-supervised positive set as the positive set, and randomly extract part of distantly-supervised negative set as the negative set. In order to better consider prior information during this pre-training procedure, the amount of negative samples is 10 times of the number of positive samples. It is because, when learning with massive negative samples, the agent is more likely to develop toward a better direction. Cross-entropy cost function is used to train this binary classifier, where the negative label corresponds to the removing action, and the positive label corresponds to the retaining action.

$$J(\theta) = \sum_i y_i \log[\pi(a = y_i | s_i; \theta)] + (1 - y_i) \log[1 - \pi(a = y_i | s_i; \theta)] \quad (2)$$

Due to the noisy nature of the distantly-labeled instances, if we let this pre-training process overfit this noisy dataset, the predicted probabilities of most samples tend to be close to 0 or 1, which is difficult to be corrected and unnecessarily increases the training cost of reinforcement learning. So, we stop this training process when the accuracy reaches 85% ~ 90%. Theoretically, our approach can be explained as increasing the entropy of the policy gradient agent, and preventing the entropy of the policy being too low, which means that the lack of exploration may be a concern.

3.1.2 Retraining Agent with Rewards

As shown in Figure 2, in order to discover incorrectly-labeled instances without any supervised information, we introduce a policy-based RL method. What our agent tries to deal with is the noisy samples from the distantly-supervised positive dataset; Here we call it as the *DS positive dataset*. We split it into the training positive set P_t^{ori} and the validation positive set P_v^{ori} ; naturally, both of these two set are noisy. Correspondingly, the training negative set N_t^{ori} and the validation negative set N_v^{ori} are constructed by randomly selected from the DS negative dataset. In every epoch, the agent removes a noisy sample set Ψ_i from P_t^{ori} according to the stochastic policy $\pi(a|s)$, and we obtain a new positive set $P_t = P_t^{ori} - \Psi_i$. Because Ψ_i is recognized as the wrong-labeled samples, we redistribute it into the negative set $N_t = N_t^{ori} + \Psi_i$. Under this setting, the scale of training set is constant for each epoch. Now we utilize the cleaned data $\{P_t, N_t\}$ to train a relation classifier. The desirable situation is that RL agent has the capacity to increase the performance of relation classifier through relocating incorrectly-labeled false positive instances. Therefore, we use the validation set $\{P_v^{ori}, N_v^{ori}\}$ to measure the performance of the current agent. First, this validation set is filtered and redistributed by the current agent as $\{P_v, N_v\}$; the F_1 score of the current relation classifier is calculated from it. Finally, the difference of F_1 scores between the current and previous epoch is used to calculate reward. Next, we will introduce several strategies to train a more robust RL agent.

Removing the fixed number of sentences in each epoch In every epoch, we let the RL agent to remove a fixed number of sentences or less (when the number of the removed sentences in one epoch does not reach this fixed number during training), in which way to prevent the case that the agent tries to remove more false positive instances by removing more instances. Under the restriction of fixed number, if the agent decides to remove the current state, it means the chance of removing other states decrease. Therefore, in order to obtain a better reward, the agent should try to remove a instance set that includes more negative instances.

Loss function The quality of the RL agent is reflected by the quality of the removed part. After the pre-training process, the agent just possesses

Algorithm 1 Retraining agent with rewards for relation k . For a clearer expression, k is omitted in the following algorithm.

Require: Positive set $\{P_t^{ori}, P_v^{ori}\}$, Negative set $\{N_t^{ori}, N_v^{ori}\}$, the fixed number of removal γ_t, γ_v

- 1: Load parameters θ from pre-trained policy network
- 2: Initialize s^* as the all-zero vector with the same dimension of s_j
- 3: **for** epoch $i = 1 \rightarrow N$ **do**
- 4: **for** $s_j \in P_t^{ori}$ **do**
- 5: $\tilde{s}_j = \text{concatenation}(s_j, s^*)$
- 6: Randomly sample $a_j \sim \pi(a|\tilde{s}_j; \theta)$; compute $p_j = \pi(a = 0|\tilde{s}_j; \theta)$
- 7: **if** $a_j == 0$ **then**
- 8: Save tuple $t_j = (\tilde{s}_j, p_j)$ in T and recompute the average vector of removed sentences s^*
- 9: **end if**
- 10: **end for**
- 11: Rank T based on p_j from high to low, obtain T_{rank}
- 12: **for** t_i in $T_{rank}[: \gamma_t]$ **do**
- 13: Add $t_i[0]$ into Ψ_i
- 14: **end for**
- 15: $P_t^i = P_t^{ori} - \Psi_i, N_t^i = N_t^{ori} + \Psi_i$, and generate the new validation set $\{P_v^i, N_v^i\}$ with current agent
- 16: Train the relation classifier based on $\{P_t^i, N_t^i\}$
- 17: Calculate F_1^i on the new validation set $\{P_v^i, N_v^i\}$, and Save F_1^i, Ψ_i
- 18: $\mathcal{R} = \alpha(F_1^i - F_1^{i-1})$
- 19: $\Omega_{i-1} = \Psi_{i-1} - \Psi_i \cap \Psi_{i-1}; \Omega_i = \Psi_i - \Psi_i \cap \Psi_{i-1}$
- 20:
- 21: Udata $\theta: g \propto \nabla_{\theta} \sum^{\Omega_i} \log \pi(a|s; \theta) \mathcal{R} + \nabla_{\theta} \sum^{\Omega_{i-1}} \log \pi(a|s; \theta) (-\mathcal{R})$
- 22: **end for**

the ability to distinguish the obvious false positive instances, which means the discrimination of the indistinguishable wrong-labeled instances are still ambiguous. Particularly, this indistinguishable part is the criterion to reflect the quality of the agent. Therefore, regardless of these easy-distinguished instances, the different parts of the removed parts in different epochs are the determinant of the change of F_1 scores. Therefore, we definite two sets:

$$\Omega_{i-1} = \Psi_{i-1} - (\Psi_i \cap \Psi_{i-1}) \quad (3)$$

$$\Omega_i = \Psi_i - (\Psi_i \cap \Psi_{i-1}) \quad (4)$$

where Ψ_i is the removed part of epoch i . Ω_{i-1} and Ω_i are represented with the different colors in Figure 2. If F_1 score increases in the epoch i , it means the actions of the epoch i is more reasonable than that in the epoch $i - 1$. In other words, Ω_i is more negative than Ω_{i-1} . Thus, we assign the positive reward to Ω_i and the negative reward to Ω_{i-1} , and vice versa. In summary, the ultimate loss function

is formulated as follow:

$$J(\theta) = \sum^{\Omega_i} \log \pi(a|s; \theta) R + \sum^{\Omega_{i-1}} \log \pi(a|s; \theta) (-R) \quad (5)$$

3.2 Redistributing Training Dataset with Policy-based Agents

Through the above reinforcement learning procedure, for each relation type, we obtain a agent as the false-positive indicator. These agents possess the capability of recognizing incorrectly-labeled instances of the corresponding relation types. We adopt these agents as classifiers to recognize false positive samples in the noisy distantly-supervised training dataset. For one entity pair, if all the sentence aligned from corpus are classified as false positive, then this entity pair is redistributed into the negative set.

4 Experiments

We adopt a policy-based RL method to generate a series of relation indicators and use them to re-

distribute training dataset by moving false positive samples to negative sample set. Therefore, our experiments are intended to demonstrate that our RL agents possess this capability.

4.1 Datasat and Evaluation Metrics

We evaluate the proposed method on a commonly-used dataset², which is first presented in Riedel et al. (2010). This dataset is generated by aligning entity pairs from Freebase with New York Times corpus (NYT). Entity mentions of NYT corpus are recognized by the Stanford named entity recognizer (Finkel et al., 2005). The sentences from the years 2005-2006 are used as the training corpus and sentences from 2007 are used as the testing corpus. There are 52 actual relations and a special relation *NA* which indicates there is no relation between the head and tail entities. The sentences of *NA* are from the entity pairs that exist in the same sentence of the actual relations but do not appear in the Freebase.

Similar to the previous works, we adopt the held-out evaluation to evaluate our model, which can provide an approximate measure of the classification ability without costly human evaluation. Similar to the generation of the training set, the entity pairs in test set are also selected from Freebase, which will be predicted under the sentences discovered from the NYT corpus.

4.2 Experimental Settings

4.2.1 Policy-based Agent

The action space of our RL agent just includes two actions. Therefore, the agent can be modeled as a binary classifier. We adopt a single-window CNN as this policy network. The detailed hyperparameter settings are presented in Table 1. As for word embeddings, we directly use the word embedding file released by Lin et al. (2016)³, which just keeps the words that appear more than 100 times in NYT. Moreover, we have the same dimension setting of the position embedding, and the maximum length of relative distance is -30 and 30 (“-” and “+” represent the left and right side of the entities). The learning rate of reinforcement learning is $2e^{-5}$. For each relation type, the fixed number γ_t, γ_v are according to the pre-trained agent. When one relation type has too many distant-supervised positive sentences (for example, /lo-

²<http://iesl.cs.umass.edu/riedel/ecml/>

³<https://github.com/thunlp/NRE>

Hyperparameter	Value
Window size c_w	3
Kernel size c_k	100
Batch size	64
Regulator α	100

Table 1: Hyperparameter settings.

ID	Relation	Original	Pretrain	RL
1	/peo/per/pob	55.60	53.63	55.74
2	/peo/per/n	78.85	80.80	83.63
3	/peo/per/pl	86.65	89.62	90.76
4	/loc/loc/c	80.78	83.79	85.39
5	/loc/cou/ad	90.9	88.1	89.86
6	/bus/per/c	81.03	82.56	84.22
7	/loc/cou/c	88.10	93.78	95.19
8	/loc/adm/c	86.51	85.56	86.63
9	/loc/nei/n	96.51	97.20	98.23
10	/peo/dec/p	82.2	83.0	84.6

Table 2: Comparison of F_1 scores among three cases: the relation classifier is trained with the original dataset, the redistributed dataset generated by the pre-trained agent, and the redistributed dataset generated by our RL agent respectively. The name of relation types are abbreviated: /peo/per/pob represents /people/person/place_of_birth

cation/location/contains has 75768 sentences), we sample a subset of size 7,500 sentences to train the agent. For the average vector of the removed sentences, in the pre-training process and the first state of the retraining process, it is set as all-zero vector.

4.2.2 Relation Classifier for Calculating Reward

In order to evaluate a series of actions by agent, we use a simple CNN model, because the simple network is more sensitive to the quality of the training set. The proportion between P_t^{ori} and P_v^{ori} is 2:1, and they are all derived from the training set of Riedel dataset; the corresponding negative sample sets N_t^{ori} and N_v^{ori} are randomly selected from the Riedel negative dataset, whose size is twice that of their corresponding positive sets.

4.3 The Effectiveness of Reinforcement Learning

In Table 2, we list the F_1 scores before and after adopting the proposed RL method. Even though there are 52 actual relation types in Riedel dataset, only 10 relation types have more than 1000 pos-

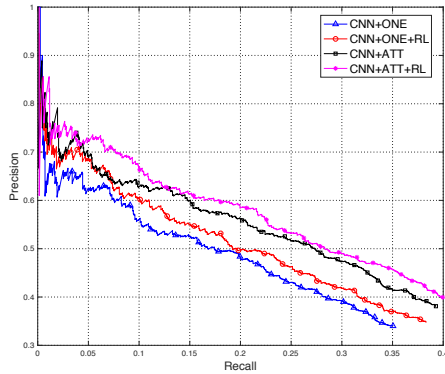


Figure 3: Aggregate PR curves of CNN-based model.

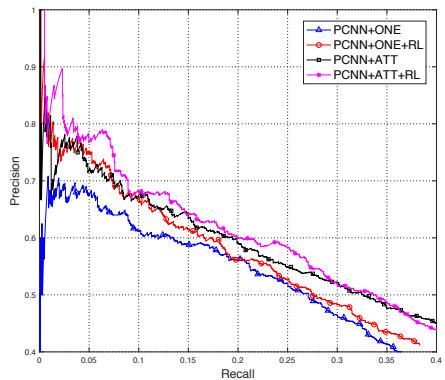


Figure 4: Aggregate PR curves of PCNN-based model.

itive instances⁴. Because of the randomness of deep neural network on the small-scale dataset, we just train policy-based agents for these 10 relation types. First, compared with *Original* case, most of the *Pretrain* agents yield obvious improvements: It not only demonstrates the rationality of our pre-training strategy, but also verifies our hypothesis that most of the positive samples in Riedel dataset are true positive. More significantly, after retraining with the proposed policy-based RL method, the F_1 scores achieve further improvement, even for the case the *Pretrain* agents perform bad. These comparable results illustrate that the proposed policy-based RL method is capable of making agents develop towards a good direction.

⁴The supervised relation classification task Semeval-2010 Task 8 (Hendrickx et al., 2009) annotates nearly 1,000 instances for each relation type.

Model	-	+RL	p-value
CNN+ONE	0.177	0.190	1.24e-4
CNN+ATT	0.219	0.229	7.63e-4
PCNN+ONE	0.206	0.220	8.35e-6
PCNN+ATT	0.253	0.261	4.36e-3

Table 3: Comparison of AUC values between previous studies and our RL method, and the p-value of t-test.

4.4 Impact of False Positive Samples

Zeng et al. (2015) and Lin et al. (2016) are both the robust models to solve wrong labeling problem of distant supervision relation extraction. Zeng et al. (2015) combine at-least-one multi-instance learning with deep neural network to extract only one active sentence to predict the relation between entity pair; Lin et al. (2016) combine all sentences of one entity pair and assign soft attention weights to them, in which way to generate a compositive relation representation for this entity pair. However, the false positive phenomenon also includes the case that all the sentences of one entity pair are wrong, which is because the corpus is not completely aligned with the knowledge base. This phenomenon is also common between Riedel dataset and Freebase through our manual inspection. Obviously, there is nothing the above two methods can do in this case.

The proposed RL method is to tackle this problem. We adopt our RL agents to redistribute Riedel dataset by moving false positive samples into the negative sample set. Then we use Zeng et al. (2015) and Lin et al. (2016) to predict relations on this cleaned dataset, and compare the performance with that on the original Riedel dataset. As shown in Figure 3 and Figure 4, under the assistant of our RL agent, the same model can achieve obvious improvement with more reasonable training dataset. In order to give the more intuitive comparison, we calculate the AUC value of each PR curve, which reflects the area size under these curves. These comparable results also indicate the effectiveness of our policy-based RL method. Moreover, as can be seen from the result of t-test evaluation, all the p-values are less than $5e-02$, so the improvements are significant.

4.5 Case Study

Figure 5 indicates that, for different relations, the scale of the detected false positive samples is not

Relation	/people/person/place_of_birth
FP	1. GHETTO SUPERSTAR (THE MAN THAT I AM) – Ranging from Pittsburgh to Broadway, Billy Porter performs his musical memoir.
FP	1. “They are trying to create a united front at home in the face of the pressures Syria is facing,” said Sami Moubayed , a political analyst and writer here. 2. “Iran injected Syria with a lot of confidence: stand up, show defiance,” said Sami Moubayed , a political analyst and writer in Damascus.
Relation	/people/deceased_person/place_of_death
FP	1. Some New York city mayors – William O’Dwyer , Vincent R. Impellitteri and Abraham Beame – were born abroad. 2. Plenty of local officials have, too, including two New York city mayors, James J. Walker, in 1932, and William O’Dwyer , in 1950.

Table 4: Some examples of the false positive samples detected by our policy-based agent. Each row denotes the annotated sentences of one entity pair.

proportional to the original scale, which is in accordance with the actual accident situation. At the same time, we analyze the correlation between the false positive phenomenon and the number of sentences of entity pairs : With this the number ranging from 1 to 5, the corresponding percentages are [55.9%, 32.0%, 3.7%, 4.4%, 0.7%]. This distribution is consistent with our assumption. Because Freebase is, to some extent, not completely aligned with the NYT corpus, entity pairs with fewer sentences are more likely to be false positive, which is the major factor hindering the performance of the previous systems. In Table 4, we present some false positive examples selected by our agents. Taking entity pair (*Sami Moubayed*, *Syria*) as an example, it is obvious that there is not any valuable information reflecting relation /people/person/place_of_birth. Both of these sentences talks about the situation analysis of *Syria* from the political analyst *Sami Moubayed*. We also found that, for some entity pairs, even though there are multiple sentences, all of them are identical. This phenomenon also increases the probability of the appearance of false positive samples.

5 Conclusion

In this work, we propose a deep reinforcement learning framework for robust distant supervision. The intuition is that, in contrast to prior works that utilize only one instance per entity pair and use soft attention weights to select plausible distantly supervised examples, we describe a policy-based framework to systematically learn to relocate the false positive samples, and better utilize the unlabeled data. More specifically, our goal is to

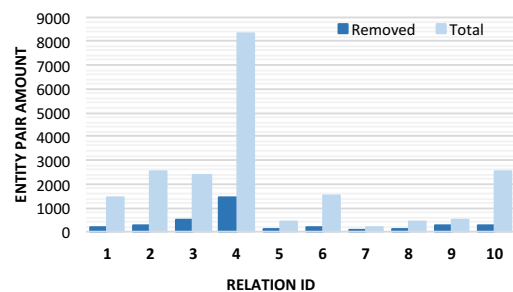


Figure 5: This figure presents the scale of the removed part for each relation type, where the horizontal axis corresponds to the IDs in Table 2.

teach the reinforcement agent to optimize the selection/redistribution strategy that maximizes the reward of boosting the performance of relation classification. An important aspect of our work is that our framework does not depend on a specific form of the relation classifier, meaning that it is a plug-and-play technique that could be potentially applied to any relation extraction pipeline. In experiments, we show that our framework boosts the performance of distant supervision relation extraction of various strong deep learning baselines on the widely used New York Times - Freebase dataset.

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