# Micro-Act: Mitigate Knowledge Conflict in Question Answering via **Actionable Self-Reasoning**

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#### Abstract

Retrieval-Augmented Generation (RAG) systems commonly suffer from Knowledge Con*flicts*, where retrieved external knowledge contradicts the inherent, parametric knowledge of large language models (LLMs). It adversely affects performance on downstream tasks such as question answering (QA). Existing approaches often attempt to mitigate conflicts by directly comparing two knowledge sources in a side-by-side manner, but this can overwhelm LLMs with extraneous or lengthy contexts, ultimately hindering their ability to identify and mitigate inconsistencies. To address this issue, we propose MICRO-ACT, a framework with a hierarchical action space that automatically perceives context complexity and adaptively decomposes each knowledge source into a sequence of fine-grained comparisons. These comparisons are represented as actionable steps, enabling reasoning beyond the superficial context. Through extensive experiments on five benchmark datasets, MICRO-ACT consistently achieves significant increase in QA accuracy over state-of-the-art baselines across all 5 datasets and 3 conflict types, especially in temporal and semantic types where all baselines fail significantly. More importantly, MICRO-ACT exhibits robust performance on non-conflict questions simultaneously, highlighting its practical value in real-world RAG applications. Code can be found at https: //github.com/Nan-Huo/Micro-Act.

#### Introduction

Recent advances in large language models (LLMs) have revolutionized natural language processing with their ability to understand and respond to diverse user queries (Chang et al., 2024; Zhao et al., 2023). However, relying solely on parametric

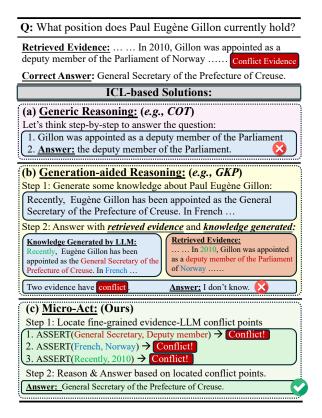


Figure 1: An illustration of QA under knowledge conflict via a real example. The detailed illustration can be found in Figure 7. (a) refers to the generic reasoning methods that reason on merely retrieved context. (b) refers to generation-aided reasoning methods aided by self-generated knowledge. (c) refers to our proposed MICRO-ACT.

knowledge often leads to hallucinations and factual errors, especially when dealing with domainspecific queries or rapidly evolving information. To enhance the reliability and factual accuracy of LLM responses, retrieval-augmented generation (RAG) has emerged as a promising paradigm that grounds LLM reasoning with evidence from external knowledge sources (Guu et al., 2020a; Lewis et al., 2020; Chen et al., 2024; Ren et al., 2023).

Despite the promise of RAG, a critical challenge emerges when retrieved information contradicts

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the pre-trained parametric knowledge of LLMs, a phenomenon known as *knowledge conflict* (Wang et al., 2024; Jin et al., 2024a). Such conflicts arise frequently because retrieval systems may introduce noisy, outdated, or even incorrect information (Su et al., 2024; Wang et al., 2024; Shi et al., 2024a; Jin et al., 2024a), which significantly undermines their potential benefits and raises concerns about their practical deployment in downstream tasks such as question answering (QA).

Prior works addressing knowledge conflicts fall into two distinct categories. The first focuses on specialized fine-tuning techniques (Yuan et al., 2024; Shi et al., 2024a; Jin et al., 2024b). The second leverages In-Context Learning (ICL), which can adapt to new requirements or tasks by providing relevant instructions or examples, reducing the effort required for re-training or continual training. Within the ICL-based category, approaches can be further divided into two types: generic reasoning methods that rely solely on retrieved context, as shown in Figure 1(a), and generation-aided reasoning methods that generate the pre-trained parametric knowledge of LLMs for explicit knowledge comparison with retrieved knowledge (Liu et al., 2022), as illustrated in Figure 1(b). However, these ICL-based methods face three critical limitations: (1) heavy reliance on manually crafted instructions limits cross-domain adaptability; (2) side-by-side comparison fails to capture conflicts at different granularity levels, making LLMs vulnerable to irrelevant contexts (Mirzadeh et al., 2024); and (3) those methods meticulously design prompts to handle knowledge conflict, which assumes that knowledge conflict already exists. This would probably lead to a negative impact on performance in conflict-free scenarios, which are common in realworld applications, raising concerns about their practical reliability.

To address these limitations, we propose MICRO-ACT, whose core innovation is its ability to dynamically adjust granularity through decomposition action: (1) at model level, it automatically perceives input complexity preferences for different LLMs, and (2) at action level, it detects context granularity of each action and flexibly makes adjustment. As illustrated in Figure 1(c), this adaptive approach enables precise conflict detection across different granularity levels and reasoning on the conflicts underneath the superficial context.

Extensive experiments on five widely-used knowledge conflict benchmark datasets grounded

in the QA task (Su et al., 2024; Xie et al., 2024), covering diverse knowledge conflict types (misinformation, temporal, and semantic conflicts) (Su et al., 2024), demonstrate that MICRO-ACT consistently outperforms state-of-the-art baselines. More importantly, MICRO-ACT also maintains competitive performance in conflict-free cases while stateof-the-art baselines cannot, which underscores the strong robustness of MICRO-ACT. Further analysis of complexity detection reveals that MICRO-ACT unlocks the potential of LLMs to perceive complexity and adapt to different environments. And we find an interesting phenomenon called "overrationalization" which harms conflict resolution and can be mitigated by MICRO-ACT via locating conflict underneath the superficial context. These findings validate the effectiveness and robustness of MICRO-ACT in resolving knowledge conflicts for reliable real-world RAG systems.

#### 2 Related Work

Retrieval-Augmented Generation for QA. Retrieval-augmented generation (RAG) integrates external knowledge sources with language generation, improving the fidelity and robustness of open-domain QA (Chen et al., 2017; Petroni et al., 2019; Asai et al., 2020; Guu et al., 2020b; Izacard and Grave, 2021a; Lewis et al., 2020; Zhang et al., 2024; Shi et al., 2024b). Subsequent efforts have refined retrieval modules and model architectures to handle diverse knowledge sources and queries more effectively (Karpukhin et al., 2020; Izacard and Grave, 2021b; Mao et al., 2021; Nakano et al., 2021; Shi et al., 2024c; Izacard et al., 2023; Qin et al., 2019, 2018; Conforti et al., 2020; Rezaee et al., 2024). Recent techniques explore dynamic retrieval strategies, domain adaptation, and efficient fine-tuning, further enhancing the adaptability and reliability of RAG frameworks (Ram et al., 2023; Borgeaud et al., 2022; Liu et al., 2024; Zhang et al., 2025).

Knowledge Conflict. Knowledge conflict surfaces when retrieved evidence disagrees with a model's internal beliefs or when multiple sources present mutually inconsistent information, resulting in ambiguous or flawed outputs (Min et al., 2020; Lewis et al., 2020; Shuster et al., 2021; Wang et al., 2021; Zellers et al., 2019; Tan et al., 2024). This challenge becomes acute in evolving domains (e.g., current events, medicine, science) where timely accuracy is critical (Chen et al., 2021;

Min et al., 2023). Conflicts arise not only between retrieved evidence and parametric knowledge but also among multiple retrieved documents, demanding careful reconciliation to avoid misinformation and preserve trustworthiness (Thorne et al., 2018; Yang et al., 2018; Liang et al., 2023; Gao et al., 2023; Shaier et al., 2024; Pham et al., 2024; Fang et al., 2024).

**Solutions for Knowledge Conflict.** Proposed solutions generally follow two broad strategies. The first modifies internal model parameters or architectures to accommodate external evidence more consistently (Yuan et al., 2024; Jin et al., 2024b; Shi et al., 2024a), though this often assumes that retrieved information should uniformly override parametric knowledge. The second strategy explicitly identifies and reconciles discrepancies among sources via generation-aided mechanisms or iterative comparison (Wang et al., 2023; Liu et al., 2022). While these methods can reduce factual errors, they often rely on ad-hoc instructions or simple pairwise comparisons that fail to capture subtle conflicts. Recent work underscores the need for more principled, robust approaches that integrate nuanced reasoning and validation, improving both fidelity and explainability in retrieval-augmented QA (Xu et al., 2024).

# 3 Preliminaries

# 3.1 RAG for QA

Retrieval-Augmented Generation (RAG) combines a LLM with an external retrieval module. It proceeds in two key phases: a *Retrieval Phase* that returns a set of relevant evidence and a *Generation Phase* where the LLM produces the final answer conditioned on this evidence.

**Retrieval Phase.** Given a query q, a retrieval function  $\mathcal{R}(\cdot)$  returns a set of textual fragments  $\mathcal{E} = \{e_1, \dots, e_m\}$ , where m is the number of fragments. Each fragment  $e_i$  provides potentially relevant information related to q.

**Generation Phase.** Let  $\mathcal{M}_{\Theta}$  be the LLM parameterized by  $\Theta$ . We define the parametric knowledge for the query q as:

$$K^p(q) = \mathcal{M}_{\Theta}(q). \tag{1}$$

We use  $K^r(e_i)$  to represent the knowledge contained in each retrieved fragment  $e_i$ . The final

answer is produced by conditioning on both the parametric and retrieved knowledge:

$$Ans(q) = \mathcal{M}_{\Theta}(q|K^{p}(q), \{K^{r}(e_{i})\}_{i=1}^{m}).$$
 (2)

### 3.2 Knowledge Conflict

A knowledge conflict arises when  $K^p(q)$  and some  $K^r(e_i)$  are factually or logically inconsistent. Formally, there exists at least one  $e_i \in \mathcal{E}$  such that:

$$K^p(q) \not\approx K^r(e_i),$$
 (3)

where  $\not\approx$  denotes a factual or logical inconsistency.

# Algorithm 1 MICRO-ACT Pseudocode

```
    Input: query q, external corpus E, LLM M<sub>Θ</sub>, turn budget N
    Retrieve: K<sup>P</sup> ← ELICIT(q), K<sup>r</sup> ← DETRIEVE(E, q)
```

 $\begin{aligned} & \text{RETRIEVE}(\mathcal{E},q) \\ & \text{3: } H \!\leftarrow\! \emptyset \end{aligned}$ 

4: **for** t = 1 **to** N **do**5:  $T_t \leftarrow \mathcal{M}_{\Theta}(\cdot \mid H); \quad A_t \leftarrow \mathtt{SELECT}(T_t)$ 6:  $O_t \leftarrow \begin{cases} \mathtt{REASON}(\cdot) \\ \mathtt{ASSERT}(\cdot) \\ \mathtt{DECOMPOSE}(\cdot) \end{cases}$ 

7:  $H \leftarrow H \cup \{T_t, A_t, O_t\}$ 

8: **if**  $O_t = \text{conflict } \land \text{ COMPLEX then}$ 

9:  $A_t \leftarrow \text{DECOMPOSE}$   $\triangleright$  force split

10: **end if** 

11: **if** SOLVED(H) **then break** 

12: **end if** 

13: **end for** 

14: **Return**  $\mathcal{M}_{\Theta}(\text{ANSWER} \mid H)$ 

# 4 Methodology

We introduce MICRO-ACT, a framework that enables Large Language Models (LLMs) to automatically identify and resolve detailed points of knowledge conflict. MICRO-ACT comprises three key components: (1) a hierarchical action space (Section 4.1), (2) a Reasoning Body (Section 4.2), and (3) Adaptive Granularity and Optimization strategies (Section 5 and 6). The detailed pseudocode of MICRO-ACT can be found in Algorithm 1.

#### 4.1 Hierarchical Action Space

Establishing a well-structured action space allows LLMs to more efficiently invoke planning strategies (Yao et al., 2024). To this end, we define the action space as a structured integration of three key

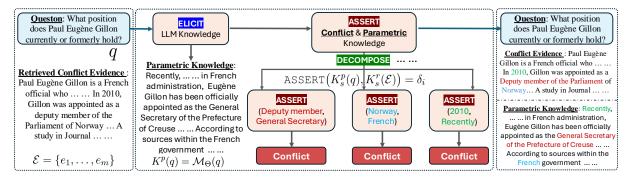


Figure 2: An illustration of handling knowledge conflict in QA task. Actions highlighted with blue color represent navigational actions; Red color represents functional actions; and green color represents the bridging action. "... ..." represents multiple interplayed actions are folded for simplicity.

categories: (1) navigational actions, (2) functional actions, and (3) bridging actions, with the decomposition component serving as the cornerstone for refining context granularity of actions.

**Navigational Actions.** They focus on exploring the environment and obtaining more information as the prerequisite of effective reasoning (Gu et al., 2024). Navigational actions include eliciting parametric knowledge from the LLM and getting the reasoning path of a QA task based on input context. Let  $\mathcal{A}_{nav}$  represent *navigational actions*. Specifically, we formally define the elicit action in Eq. 4.

ELICIT
$$(q) = K^p(q) = \mathcal{M}_{\Theta}(q).$$
 (4)

And we formally define the action to get the reasoning path  $\mathcal{P}_K$  in Eq. 5.

$$REASON(K) = \mathcal{P}_K = \mathcal{M}_{\Theta}^p(K), \qquad (5)$$

where  $\mathcal{M}^p_\Theta(K)$  represents prompting LLM parametrized by  $\Theta$  to generate a reasoning path on K. And K is the input knowledge representation either from  $K^p(q)$  or from  $K^r(\mathcal{E})$ .

Functional Actions. They address conflict detection either between retrieved evidence and LLM parametric knowledge or between their reasoning paths generated by the navigational action. Once relevant information is prepared, functional actions, denoted by  $\mathcal{A}_{\text{func}}$ , detect conflict among them. Formally, we define the assert action to implement this logic, which is a conflict verification action and checks the consistency between  $K^p(q)$  and a particular  $K^r(\mathcal{E})$  in Eq. 6.

$$ASSERT(K_s^p(q), K_s^r(\mathcal{E})) = \delta_i, \qquad (6)$$

where  $\delta_i \in \{0,1\}$ . If  $\delta_i = 1$ , a conflict is detected. And  $K_s^p(q) \in K^p(q)$  means  $K_s^p(q)$  is a partial knowledge of  $K^p(q)$ .

**Bridging-Action.** It is responsible for dynamically optimizing granularity by decomposing actions when needed. A side-by-side assert action may fail to detect subtle conflicts embedded in lengthy, noisy contexts. To address this, we introduce the *decomposition action*, collected in  $\mathcal{A}_{\text{micro}}$ , which can refine the granularity of analysis. Suppose an  $\text{ASSERT}(\cdot)$  action on complex knowledge context is represented as  $\text{ASSERT}(K^p(q), K^r(\mathcal{E}))$ . A decomposition action can decompose this complex reasoning into smaller, manageable action steps, as shown in Eq. 7.

DECOMPOSE(ASSERT
$$(K_s^p(q), K_s^r(\mathcal{E}))$$
  
= {ASSERT $(K_{s'}^p(q), K_{s'}^r(\mathcal{E})), \dots$ }, (7)

where  $K_s^p(q) \in K^p(q)$  is a partial knowledge of  $K^p(q)$ . And  $K_{s'}^p(q)$  refers to  $K_s^p(K_s^p(q))$ , which means the finer-grained partial knowledge of  $K_s^p(q)$ . Each newly created sub-action deals with a further fragment of the evidence, increasing the likelihood of revealing fine-grained conflicts. It will decompose the action until LLM has enough confidence or reach the max turn limit.

#### 4.2 Reasoning Body

We integrate our hierarchical action space with the ReAct process (Yao et al., 2023) to teach LLM integrate our hierarchical action space to automatically handle knowledge conflicts. At step t, the LLM first produces a thought  $T_t$ :

$$T_t \sim \mathcal{M}_{\Theta}(T_t \mid H_{t-1}),$$
 (8)

where  $H_{t-1}$  is the accumulated history of all thoughts, actions, and observations before step t.

Conditioned on  $H_{t-1}$  and the newly generated thought  $T_t$ , the model selects an action  $A_t$ :

$$A_t \sim \mathcal{M}_{\Theta}(A_t \mid H_{t-1}, T_t). \tag{9}$$

This action, executed in the changing environment (for example, the knowledge has been decomposed at different granularity), yields an observation  $O_t$ :  $O_t = \text{Env}(A_t)$ . The history is then updated:

$$H_t = H_{t-1} \cup \{T_t, A_t, O_t\}.$$
 (10)

This iterative process continues, adjusting granularity via decomposition actions whenever subtle conflicts require finer checks. After N steps, the final answer is generated:

$$A_f \sim \mathcal{M}_{\Theta}(A_f \mid H_N).$$
 (11)

By dynamically selecting navigational, functional, and decomposition actions, this procedure ensures subtle knowledge conflicts are detected and mitigated, improving the reliability of the final output. An example illustration of this process is shown in Figure 2.

# 5 Understanding Complexity-Driven Knowledge Decomposition Dynamics

To gain a deeper understanding of how model bridging actions are related to complexity, we follow (Murty et al., 2024) to characterize the distribution of the newly inferred knowledge representation at turn t based on trajectory over previous t-1 turns. Specifically, we define:

$$p_{t}(K_{n}) = \sum_{c'} \sum_{K} p_{\text{model}}(K_{n} \mid c') p_{\text{verify}}(c' \mid K) p_{t-1}(K),$$
(12)

where K is current knowledge representation,  $K_n$  is the newly inferred knowledge representation (often obtained by decomposing K), c is the ground-truth knowledge conflict, and c' is a potentially incorrect knowledge conflict identified by the model.  $p_{\rm model}$  means the distribution on generate new knowledge.  $p_{\rm verify}$  means the distribution on generating conflicts. Detailed derivation can be found in Appendix D.

In this formulation, the term  $\sum_K p_{\text{verify}}(c' \mid K)$  increases with the complexity (e.g., longer context, harder domain and etc.), resulting in higher verification probabilities and an increased risk of inaccurate conflict detection. And  $\sum_{c'} p_{\text{model}}(K_n \mid c')$  depends on the LLM compatibility. A less capable LLM is more likely to be influenced by erroneous conflicts (c'), thereby requiring further decomposition and pushing  $p_k(K_n)$  higher. Section 7.5 shows more details about how these factors drive proactive decomposition across models.

## **6 Preventing Infinite Decomposition**

While hierarchical reasoning is essential for resolving complex conflicts, an unconstrained recursive process could, in principle, keep splitting a context. Building upon the probabilistic dynamics in Eq. (12), we show that MICRO-ACT can prevent infinite decomposition, and we complement this theoretical safeguard with a hard maximum turn budget.

Complexity-Aware Stopping Criterion. Let  $\mathcal{C}_t$  denote the latent *complexity score* of the current context after t turns. A decomposition step is triggered only when  $\mathcal{C}_t > \tau$ , where  $\tau$  represents the minimum complexity the underlying LLM can handle confidently. Because each decomposition shortens the context length and narrows its semantic scope, the following strict inequality holds:

$$C_{t+1} < C_t, \qquad \forall t \ge 0.$$
 (13)

Define

$$T_{\tau} = \min\{t \mid \mathcal{C}_t \le \tau\}. \tag{14}$$

By Eq. (13),  $T_{\tau}$  is finite, and once reached we have  $p_t(K_n)=0$ ; no further actions in the DECOMPOSE branch will be sampled. In other words, the process is *self-regularising*: an LLM that already "understands" the context (small  $\mathcal{C}_t$ ) simply refuses to split it further.

# 7 Experiments

# 7.1 Experiment Settings

We evaluate MICRO-ACT on five benchmark datasets drawn from two comprehensive collections: ConflictBank and KRE. Conflict-Bank (Su et al., 2024) provides three specialized datasets targeting distinct conflict types: misinformation, temporal discrepancies, and semantic divergences between retrieved and parametric knowledge. From KRE (Ying et al., 2023), we utilize MuSiQue\_KRE and SQuAD\_KRE, derived from MuSiQue (Trivedi et al., 2022) and SQuAD v2.0 (Rajpurkar et al., 2018) respectively. These datasets feature multiple-choice questions with generated explanations supporting incorrect choices, creating controlled scenarios for examining reasoning conflicts. Due to the limitation of computational resources, we randomly sampled 3000 data in ConflictBank and 2000 data in KRE dataset across all features, and corrected any errors found.

	GPT-40		GPT-40-mini		LLaMA-3.1-70B		LLaMA-3.1-8B	
Prompting	ConflictBank	KRE	ConflictBank	KRE	ConflictBank	KRE	ConflictBank	KRE
Generic Reasoning								
End-to-End QA	5.40	43.80	2.77	31.10	3.07	14.50	2.53	9.55
Few-Shot QA	6.30	45.65	2.83	33.30	3.87	15.20	3.13	10.30
Chain-of-Thought (Wei et al., 2022)	6.43	44.35	3.00	36.50	1.40	29.45	2.13	24.50
Generation-aided Reasoning								
Self-Ask (Press et al., 2023)	3.13	41.45	2.57	24.90	3.33	23.65	2.77	18.65
Comparative (Wang et al., 2023)	11.70	33.95	2.10	23.85	4.53	25.25	3.87	19.80
GKP (Liu et al., 2022)	<u>15.40</u>	<u>55.30</u>	<u>17.53</u>	44.45	<u>15.83</u>	43.55	6.83	32.75
MICRO-ACT (ours)	<b>22.30</b> († 6.90)	<b>59.50</b> († 4.20)	<b>26.93</b> († 9.40)	<b>51.10</b> († 6.65)	26.50 († 10.67)	<b>54.90</b> († 11.35)	<b>18.30</b> († 11.47)	46.60 († 13.85)

Table 1: The average results of Question Answering under Knowledge Conflict on ConflictBank and KRE with GPT-40-mini, GPT-40, LLaMA-3.1-70B and LLaMA-3.1-8B. The performance is on average over its sub-datasets. (underline denotes the previous SOTA performance; **bold** denotes the best performance; the improvement (↑) is measured against the previous SOTA performing method.)

Metrics & Models. Following existing knowledge conflict works (Xie et al., 2024; Su et al., 2024; Wang et al., 2023; Shi et al., 2024a), we measure knowledge conflict in QA task by employing QA accuracy as our primary evaluation metric. Specifically, the answer format of QA is multiple-choice. If LLMs successfully resolve knowledge conflict, they will choose the correct answer instead of the negative answer supported by the conflict (wrong) knowledge (Su et al., 2024).

In our experiments, we use GPT-4o, GPT-4o-mini (OpenAI, 2023), LLaMA-3.1-70B and LLaMA-3.1-8B (Dubey et al., 2024) as the backbone LLMs.

Compared Methods. We evaluate MICRO-ACT against two categories of ICL-based approaches: generic reasoning methods that reason on retrieved evidence, including end-to-end QA, few-shot QA, and COT (Wei et al., 2022); and generation-aided reasoning methods that reason with self-generated content of LLMs, including Self-Ask (Press et al., 2023), GKP (Liu et al., 2022), and Comparative (Wang et al., 2023). We evaluate these methods across all five datasets from ConflictBank and KRE. Prompts and implementation details can be found in Appendix G.

**Implementation.** We implement MICRO-ACT using zero-shot prompting without task-specific customization. To ensure reproducibility, we maintain consistent parameters across all experiments: temperature = 0, top-p = 1, and maximum generation length = 512 tokens (max\_tokens for closed-source LLMs, max\_new\_tokens for open-source models). We utilize the Hugging Face Transformers library for open-source model inference. All experiments with open-source models are conducted on 4 NVIDIA A100 GPUs (80GB), while closed-source models are accessed via their

respective API endpoints.

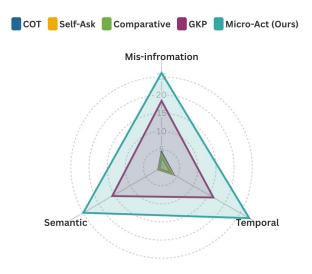


Figure 3: The detailed performance of MICRO-ACT across all 3 conflict types with GPT-4o-mini.

# 7.2 Main Results

We summarize the performance of MICRO-ACT and various baseline methods on ConflictBank and KRE in Table 1. And detailed performance comparison across all three conflict types (i.e., misinformation, temporal, and semantic) is shown in Figure 3. MICRO-ACT surpasses all baseline approaches across all tested LLMs. Notably, MICRO-ACT improves over the previous SOTA method by up to 9.40% on ConflictBank and 6.65% on KRE for GPT-4o-mini, and by 11.47% and 13.85% on LLaMA-3.1-8B, respectively. Results across all 5 datasets and 3 conflict types, confirm the superior capability of MICRO-ACT in handling knowledge conflict and suggest that such superior capability is not model-specific.

#### 7.3 Over-Rationalization Issue

In our experiments, we observed an intriguing phenomenon: when presented with both conflicting evidence and LLMs parametric knowledge, LLMs sometimes attempt to support all contradictory information as equally valid. We characterize this behavior as "over-rationalization", which is a tendency to find complex justifications that make contradictory evidence appear compatible. Surprisingly, more capable models like GPT-40 exhibit this behavior more frequently than GPT-4o-mini, leading to performance degradation in GKP as shown in Table 1. Furthermore, we observe that the issue of "over-rationalization" is strongly associated with the type of conflict, occurring more frequently in temporal and semantic conflicts. Unlike misinformation-based conflicts, where conflicts are typically explicit and directly presented in the context, the temporal and semantic conflicts are often implicit beneath the superficial context, misleading LLMs to rationalize both sides of conflict. A detailed case analysis is in Section 7.8.

However, MICRO-ACT can "visualize" the underlying reasoning path via dynamic decomposition to pinpoint finer-grained conflict and focus on those *nuanced conflicts underneath the superficial meaning of context*. Those conflicts cannot be effectively detected through simple side-by-side comparisons used by baseline methods. As illustrated in Figure 3, MICRO-ACT achieves a more significant performance improvement over baselines specifically in the *Temporal* and *Semantic* conflict types. Detailed analysis is in Appendix B.

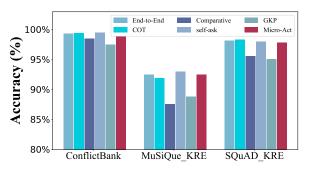


Figure 4: The performance of MICRO-ACT and baselines using GPT-40-mini under QA task without knowledge conflict.

#### 7.4 Robustness Under Conflict-Free Scenarios

Many conflict resolution methods assume the presence of knowledge conflicts. However, in realworld applications, it is often impossible to predetermine whether retrieved content conflicts with the parametric knowledge of LLMs, making robustness in conflict-free scenarios crucial.

As shown in Figure 4, existing approaches face a trade-off. Generic reasoning methods like end-to-end and COT achieve high accuracy in conflict-free cases but degrade significantly (by 70-95%) when conflicts arise. And generation-aided methods such as GKP improve conflict resolution but exhibit lower accuracy in conflict-free cases.

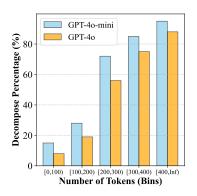
MICRO-ACT overcomes this limitation by achieving state-of-the-art performance in conflict scenarios with over 24% performance gain and showing robustness with only sacrificing less than 2% accuracy in conflict-free cases, compared with the end-to-end or self-ask baseline. Rather than introducing biases to favor certain evidence sources, MICRO-ACT helps models automatically identify and analyze potential conflicts through structured action space with decomposition, enabling robust performance regardless of whether conflicts exist.

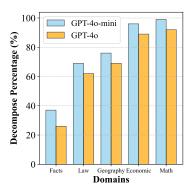
# 7.5 Complexity Perception Analysis

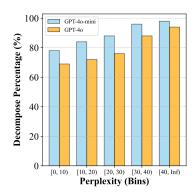
To understand how MICRO-ACT adapts its decomposition strategy to different complexity levels, we answer 3 research questions (RQs).

RQ1: How do we objectively measure input complexity? We select three complementary metrics to comprehensively and objectively measure input complexity: (1) context length captures information volume; (2) domain difficulty reflects inherent reasoning challenges; and (3) perplexity quantifies language uncertainty (Li et al., 2024a,b; Jelinek et al., 1977). As shown in Figure 5, these metrics provide a systematic way to evaluate how different LLMs adapt the decomposition strategies to varying complexity levels.

# **RQ2:** Does decomposition behavior show some patterns across different complexity dimensions? Figure 5, we observe consistent adaptation patterns within all LLMs. For example, as for the context length shown in Figure 5(a), the decomposition rate increases dramatically from 15% (0-100 tokens) to 95% (400+ tokens). All three complexity dimensions exhibit similar trends, where higher complexity consistently triggers more frequent decomposition. This consistency demonstrates the ability of MICRO-ACT to effectively detect complexity and dynamically adjust granularity via decomposition to reduce complexity.







- (a) Different Context Length
- (b) Different Question Domains (c) Different Context Perplexity

Figure 5: The visual comparisons of the DECOMPOSE action utilization percentage in different complexity, including different context length, question domains and perplexity using GPT-4o-mini and GPT-4o. The detailed calculation of perplexity can be found in Appendix C.

RQ3: Do different LLMs share the same under**standing of complexity?** The results in Figure 5 show that GPT-40-mini constantly calls decomposition action more frequently across all complexity dimensions, revealing different complexity tolerance between GPT-40 and GPT-40-mini, as discussed in Section 5. Rather than requiring manual complexity adjustments for each LLM, MICRO-ACT automatically perceives the complexity and dynamically adapts for different LLMs. This adaptive behavior enables robust performance across different LLMs without model-specific tuning. For example, as shown in Table 1, although LLaMA-3.1-8B is smaller in size and less capable than LLaMA-3.1-70B, MICRO-ACT can still maintain robust performance via more decompose actions to adjust complexity, compared with GKP's deep performance drop. More analysis is in Appendix F.

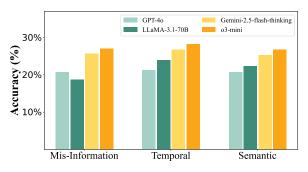


Figure 6: The performance of MICRO-ACT using general LLMs and reasoning LLMs on 300 randomly sampled data for each conflict type.

# 7.6 General LLMs vs. Reasoning LLMs

As illustrated in Figure 6, the general-purpose LLMs (GPT-40 and Llama-3.1-70B) cluster to-

gether and attain comparatively low scores on all three conflict categories. In contrast, the reasoningoriented models, Gemini-2.5-flash-thinking and o3-mini, form the top tier and consistently outperform the general models. The gap is most pronounced for misinformation conflicts, which are more amenable to reasoning-based resolution. For temporal and semantic conflicts, the gap narrows because over-rationalization issues arises more often, as discussed in detail in Section 7.3. In summary, stronger reasoning capability markedly boosts the performance of MICRO-ACT. Although it also increases susceptibility to over-rationalization, MICRO-ACT can effectively mitigate this issue and still surpasses the general models.

Метнор	MIS-INFO.	TEMPORAL	SEMANTIC
MICRO-ACT	26.1	27.9	24.9
w/o Navigational Actions	18.4 (↓ <b>7.7</b> )	18.5 (\psi <b>9.4</b> )	15.7 (↓ <b>9.2</b> )
w/o Functional Actions	13.8 (\psi 12.3)	15.2 (\psi <b>12.7</b> )	13.3 (↓ <b>11.6</b> )
w/o DECOMPOSE Action	4.2 (\psi 21.9)	4.5 (\psi 23.4)	0.8 (\psi <b>24.1</b> )

Table 2: Ablation study of MICRO-ACT in three datasets (conflict types) of ConflictBank. The numbers represent the accuracy in percentage. ↓ is an absolute decrease.

# 7.7 Ablation Study

Table 2 presents an ablation study across all conflict types of ConflictBank. Navigational and Functional actions serve as essential building blocks for conflict resolution, with their removal causing significant performance drops (9.4% for navigational and 12.7% for functional actions). While these actions are necessary for basic operations like context navigation and knowledge comparison, their

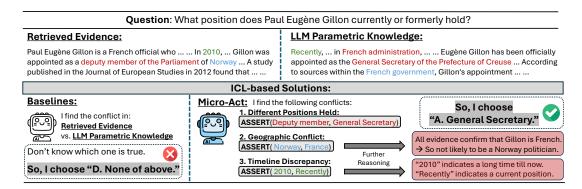


Figure 7: A case study of MICRO-ACT and baselines models under a real knowledge conflict case. MICRO-ACT can pinpoint fine-grained conflict points instead of being distracted by irrelevant context.

effectiveness heavily depends on appropriate input granularity. Without proper guidance on the input granularity of those actions, the model struggles to maintain consistent performance, especially with complex contexts.

Decomposition action dramatically improves performance by dynamically adjusting input granularity for other actions. Its removal causes the most severe degradation (over 20% performance drop), highlighting its crucial role. Through iterative decomposition, MICRO-ACT continuously refines inputs of other actions until they find the optimal granularity level where navigational and functional actions can operate most effectively. As discussed in Section 5, MICRO-ACT effectively elicits the latent ability of LLMs to perceive complexity and adapt to different environments. This adaptive process enhances the confidence of MICRO-ACT by ensuring all action components receive fine-grained information aligned with its capability, leading to higher accuracy in complex cases.

## 7.8 Case Study

In this case study, we demonstrate how MICRO-ACT identifies nuanced conflicts underneath the superficial meaning of context which can hardly be located by simple side-by-side comparisons that baselines use. Consider the question "What position does Paul Eugène Gillon currently or formerly hold?", where the retrieved context conflicts with LLM parametric knowledge as shown in Figure 7. MICRO-ACT can identify the different time references (2010 vs. recently) and location (Norway vs. France). Then apply step-by-step reasoning to find the underlying conflicts beyond the superficial context: (1) Majority consensus suggests he is from France, not Norway. (2) 2010 indicates a very long

appointment, which is less likely compared with a recent appointment, given the question: What position does Paul Eugéne Gillon currently or formerly hold? (3) And finally, determine that Paul Eugéne Gillon was recently appointed as a French politician then answer the question correctly.

### 8 Cost Analysis

MICRO-ACT incurs a modest computational cost, where on ConflictBank it processes roughly 2.8 times more input tokens and 1.3 times more output tokens than the strongest baseline (GKP), translating to only \$0.008 extra per GPT-40 query and \$0.0005 with GPT-40-mini, while inference latency rises by 0.6 s and 0.3 s respectively. Crucially, these overheads appear only when genuine conflicts trigger deeper decomposition; conflict-free questions finish as quickly as the baseline. Given the substantial gains in conflict-resolution accuracy reported in Table 1, the marginal cost and delay are acceptable for real-world RAG deployments. Detailed token, cost, and timing breakdowns are provided in Appendix A.

#### 9 Conclusion

We proposed MICRO-ACT, a framework that addresses knowledge conflicts in RAG systems through hierarchical action decomposition. By automatically perceiving context complexity and breaking down comparisons into fine-grained steps, MICRO-ACT overcomes the limitations of simple side-by-side comparisons for example the *over-rationalization* issue. Extensive experiments demonstrate its effectiveness across multiple datasets and conflict types, while maintaining strong robustness in non-conflict scenarios, making it particularly valuable for real-world RAG.

#### 10 Limitations

While MICRO-ACT demonstrates strong performance in knowledge conflict resolution, several limitations warrant discussion. First, our MICRO-ACT needs additional intermediate steps to effectively pinpoint the conflicts underneath the superficial meaning of context, which can hardly be located by simple side-by-side comparisons that baselines use. Although baselines like end-to-end and COT (Wei et al., 2022) are lightweight, their poor performance in knowledge conflict harms the effectiveness of RAG systems. We believe the efficiency should be considered after good performance. As detailed analyzed in Appendix A, the extra overhead is relatively small and our analysis demonstrates that MICRO-ACT 's modest overhead is justified by its significantly enhanced conflict resolution performance. Second, our current evaluation focuses primarily on English language contexts. The effectiveness of decomposition strategies might vary across different languages and cultural contexts. Nevertheless, our work represents an important milestone in knowledge conflict resolution, establishing a strong foundation for future research in this critical area.

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#### 12 Ethical Statement

We prioritize ethical considerations throughout our research process. During data collection and preprocessing, we carefully filtered out examples containing sensitive, biased, or potentially harmful content to ensure our evaluation focuses on constructive knowledge resolution scenarios. Our incontext learning approach requires no additional training of language models, significantly reducing the environmental impact compared to fine-tuning methods. This aligns with growing concerns about the carbon footprint of AI research. Furthermore, all datasets used in this work are publicly available, ensuring reproducibility.

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#### A Cost-Performance Trade-Off

In this section, we provide a detailed cost and latency analysis on the ConflictBank dataset, comparing MICRO-ACT with the most powerful baseline within Generic Reasoning and Generation-aided Reasoning groups (i.e., COT and GKP) using GPT-40 and GPT-40-mini, as shown in Table 3 and Table 4.

#### A.1 Token Usage and Monetary Cost

- **Input Tokens:** Because MICRO-ACT dynamically decomposes conflicts, it initiates additional turns to resolve contradictions. As a result, it uses about 2.8× more input tokens than GKP.
- Output Tokens: MICRO-ACT's output length is roughly 1.3× higher than GKP. Although it writes multiple short intermediate responses, the final output does not explode in length, as the output of each intermediate step tends to be relatively concise.
- Overall Cost: The cost difference comes to an additional \$0.008 per query for GPT-40. For GPT-40-mini, the extra cost is only \$0.0005 per query, which is fairly small.

#### A.2 Inference Time Overhead

- **GPT-40:** MICRO-ACT takes 1.9s on average, which is about 0.6s longer than GKP (1.3s).
- **GPT-40-mini:** MICRO-ACT requires 0.7s on average, 0.3s longer than GKP (0.4s).
- The latency shown above is not using multithreading. If we use multi-threading, the extra inference latency will be further reduced significantly.

This additional overhead comes from the extra decomposition steps in scenarios where conflicts are actually perceived by MICRO-ACT. However, for conflict-free queries, MICRO-ACT performs fewer steps, avoiding this overhead.

#### A.3 Justification of Additional Overhead

 Significant Performance Gain: As shown in our main experiments, MICRO-ACT achieves notable improvements in resolving knowledge conflicts. It indicates that our dynamic decomposition approach is essential for detecting finer-grained conflicts.

- 2. **Adaptive Depth:** MICRO-ACT only needs deeper decomposition when a conflict is perceived, which is necessary to locate the underlying conflicts that baselines cannot find. On conflict-free questions, it quickly finalizes the answer, keeping cost and latency low.
- 3. **Practical Applicability:** In many real-world applications such as SWE-agent (Yang et al., 2024), baseline query costs more than \$2 per query. We believe that an additional \$0.008 in GPT-4o (and \$0.0005 for GPT-4o-mini) and 0.6 extra seconds in GPT-4o (and 0.3 sec for GPT-4o-mini) per query is acceptable given the significantly improved performance, especially for real-world scenarios.

We believe this analysis demonstrates that MICRO-ACT's **modest overhead** is justified by its **significantly enhanced** conflict resolution capabilities.

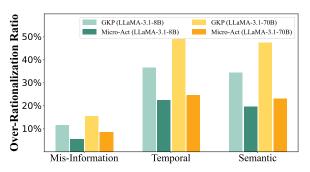


Figure 8: The Over-Rationalization Ratio of GKP and MICRO-ACT using LLaMA-3.1-8B and LLaMA-3.1-70B (lower is better).

# B Over-Rationalization Issue and Analysis

In this section, we present a quantitative investigation on 600 queries (200 from each conflict type) in the ConflictBank dataset, comparing GKP (strongest baseline) and MICRO-ACT on two LLMs: LLaMA-3.1-70B and GPT-40-mini. We measure the proportion of queries in which the model exhibits *over-rationalization* (i.e., rationalizing contradictory facts in their step-by-step chain-of-thought reasoning).

From Figure 8, it is clear that all models exhibit a higher ratio of over-rationalization under temporal and semantic conflict types, as these two types are more easily rationalized. For example, as shown in Figure 7, conflicting knowledge about whether Paul Eugéne Gillon was appointed

Method	Avg. # Turns	Avg. Input Tokens	Avg. Output Tokens	Avg. Cost (USD)	Avg. Inference Time (s)
COT	2.0	652	421	\$0.006	0.9
GKP	2.0	1182	856	\$0.012	1.3
MICRO-ACT	3.4	3345	1137	\$0.020	1.9

Table 3: Cost analysis on GPT-4o.

Method	Avg. # Turns	Avg. Input Tokens	Avg. Output Tokens	Avg. Cost (USD)	Avg. Inference Time (s)
COT	2.0	689	469	\$0.0004	0.3
GKP	2.0	1239	894	\$0.0007	0.4
MICRO-ACT	3.6	3532	1289	\$0.0013	0.7

Table 4: Cost analysis on GPT-4o-mini.

in 2010 or more recently can both be reasonable, making it difficult for the model to rely on retrieved evidence or LLM parametric knowledge.

The GKP method shows a higher tendency to rationalize these conflicts, as LLMs are easily distracted by complex context (Mirzadeh et al., 2024). This leads to failure in identifying the fine-grained conflicts underneath. In contrast, MICRO-ACT dynamically decomposes the complex context to reduce its complexity and identifies the conflicts behind the superficial context. This enables MICRO-ACT to pinpoint conflict points and reason on them for correct answers.

#### **B.1** A More Detailed Case Study

In Figure 7, an example of contradictory information regarding Paul Eugéne Gillon being appointed in 2010 versus a more recent appointment is shown. Additionally, incorrect evidence suggests he might be a politician in Norway. By iteratively decomposing the knowledge, MICRO-ACT is able to:

- 1. Identify the conflicting time references (2010 vs. recently) and location (Norway vs. France).
- Apply step-by-step reasoning to find the underlying conflicts beyond the superficial context:
  - Majority consensus suggests he is from France, not Norway.
  - 2010 indicates a very long appointment, which is less likely compared with a recent appointment, given the question: What position does Paul Eugéne Gillon currently or formerly hold?

 Finally, determine that Paul Eugéne Gillon was recently appointed as a French politician and correctly answer the question.

These nuanced conflicts are hidden beneath the superficial meaning of context and can hardly be detected by simple side-by-side comparisons used by baseline models.

# **C** Perplexity Calculation

In this section, we provide a detailed explanation of how to compute the perplexity (PPL) of a given text using the GPT-2 language model, which is not any of the language models used in our work. The aim is to provide an objective measurement of knowledge context complexity. Perplexity is a widely used metric for evaluating the quality of language models, indicating how well the model predicts a sample of text (Jelinek et al., 1977). In this work, by fixing the language model to be GPT-2, we use PPL to measure the complexity of context text. A lower perplexity value generally corresponds to a lower context text complexity.

#### **C.1** Formal Definition of Perplexity

Let the text be represented as a sequence of tokens:

$$W = w_1, w_2, \dots, w_N,$$
 (15)

where each  $w_i$  is a token (e.g., a subword unit as utilized by GPT-2).

Given a language model that estimates the probability of each token conditioned on all previous tokens, the joint probability of the sequence W can be factorized as:

$$P(W) = \prod_{i=1}^{N} P(w_i \mid w_1, w_2, \dots, w_{i-1}). \quad (16)$$

The perplexity of the sequence W under the model is defined as:

$$PPL(W) =$$

$$\exp\left(-\frac{1}{N}\sum_{i=1}^{N}\ln P(w_i \mid w_1, w_2, \dots, w_{i-1})\right).$$
(17)

In other terms, if we use base-2 logarithms:

$$PPL(W) = 2^{-\frac{1}{N} \sum_{i=1}^{N} \log_2 P(w_i | w_1, ..., w_{i-1})}. (18)$$

The perplexity can be interpreted as the effective average branching factor of the language model. A perfectly predicting model (one that assigns probability 1 to the observed sequence) would achieve a perplexity of 1.

# C.2 GPT-2-Based Computation

GPT-2 is a Transformer-based language model trained on large-scale text data. It provides a probability distribution over the next token  $w_i$  given the previous tokens  $(w_1, \ldots, w_{i-1})$ . Formally, GPT-2 implements:

$$P(w_i \mid w_1, \dots, w_{i-1}) = \text{softmax}(h_{i-1}W_e)_{w_i},$$
(19)

where  $h_{i-1}$  is the hidden state vector produced by the Transformer after processing tokens  $w_1, \ldots, w_{i-1}$ , and  $W_e$  is the token embedding matrix used to map hidden states to logits over the vocabulary. The softmax function converts these logits into probabilities.

# **C.3** Practical Steps for Perplexity Calculation

To compute perplexity using GPT-2 in practice, one would proceed as follows:

**Tokenization.** Convert the raw text into GPT-2 compatible tokens:

Text 
$$\xrightarrow{\text{tokenizer}} (w_1, w_2, \dots, w_N)$$
. (20)

**Model Inference.** For each token  $w_i$ , feed the preceding tokens  $(w_1, w_2, \ldots, w_{i-1})$  into GPT-2 to obtain:

$$P(w_i \mid w_1, \dots, w_{i-1}).$$
 (21)

This is done by running the model  $\mathcal{M}$  which is GPT-2 forward pass:

$$(h_1, h_2, \dots, h_{i-1}) = \mathcal{M}(w_1, w_2, \dots, w_{i-1})$$
(22)

and then applying the softmax over the output logits to get the probability of  $w_i$ .

**Log Probability Computation.** The next step is to extract  $\ln P(w_i \mid w_1, \dots, w_{i-1})$  from the model's output distribution.

**Summation and Normalization.** Compute the average negative log-probability:

$$-\frac{1}{N}\sum_{i=1}^{N}\ln P(w_i \mid w_1, \dots, w_{i-1}).$$
 (23)

**Exponentiation** Take the exponential of this value to obtain the perplexity:

$$PPL(W) = \exp\left(-\frac{1}{N}\sum_{i=1}^{N} \ln P(w_i \mid w_1, \dots, w_{i-1})\right).$$
(24)

# D Mathematical Derivation of Knowledge Representation Transitions

In this section, we present a formal derivation of the knowledge representation transition process. We begin by defining the key probability distributions:

- $p_t(K_n)$ : The distribution of knowledge representation at step t
- $p_{model}(K_n|K)$ : The probability of the model generating new knowledge representation  $K_n$  from previous state K
- $p_{verify}(c|K_n)$ : The probability of the verifier generating conflict detection result c based on knowledge representation  $K_n$

Following the principles of probabilistic state transitions, we can establish two fundamental equations:

# D.1 Knowledge Representation Transition Equation

The transition to new knowledge representation can be expressed as:

$$p_t(K_n) = \sum_{c'} p_{model}(K_n|c') \cdot p_{t-1}(c')$$
 (25)

This equation represents how new knowledge representation are derived from previous conflict detection results.

### **D.2** Conflict Detection Equation

The probability distribution of conflict detection results is given by:

$$p_{t-1}(c') = \sum_{K} p_{verify}(c'|K) \cdot p_{t-1}(K) \quad (26)$$

This captures how conflict detection results are generated based on previous knowledge representation.

#### **D.3** Combined Transition Model

Substituting the conflict detection equation into the state transition equation yields:

$$p_t(K_n) = \sum_{c'} p_{model}(K_n|c')$$

$$\cdot \left[\sum_{K} p_{verify}(c'|K) \cdot p_{t-1}(K)\right]$$
(27)

Rearranging the summation order:

$$p_t(K_n) = \sum_{c'} \sum_{K} p_{model}(K_n|c')$$

$$\cdot p_{verify}(c'|K) \cdot p_{t-1}(K)$$
(28)

# **D.4** Bayesian Formulation

Applying Bayes' rule to transform  $p_{verify}(c'|K)$  into  $p_{verify}(K|c')$ :

$$p_t(K_n) = \sum_{K,c'} p_{t-1}(K)$$

$$\cdot p_{verify}(K|c') \cdot p_{model}(K_n|c')$$
(29)

This final form encapsulates three key components:

- $p_{t-1}(K)$ : Distribution of previous knowledge representation
- $p_{verify}(K|c')$ : Verifier's evaluation of knowledge
- p<sub>model</sub>(K<sub>n</sub>|c'): Model's probability of generating new knowledge based on conflict detection

This formulation provides a comprehensive mathematical framework for analyzing the evolution of knowledge representation through iterative refinement and verification.

## **E** Error Analysis

To better understand the limitations of MICRO-ACT, we conducted a detailed error analysis on 1,000 randomly sampled examples across all five datasets. Our analysis revealed two predominant error types:

Context Distraction (63% of errors) Despite our decomposition strategy, LLMs occasionally become overwhelmed by complex contexts and default to expressing uncertainty ("I don't know" or "Cannot determine"). This typically occurs when the context contains multiple interrelated facts or complex logical relationships that challenge the model's ability to maintain coherent reasoning chains. For instance, in multi-hop reasoning questions where evidence pieces are densely connected, even decomposed segments may retain inherent complexity that exceeds the model's processing capacity.

Over-reliance on Retrieved Evidence (37% of errors) The second major error type manifests when LLMs exhibit a strong bias toward retrieved evidence, even when it conflicts with their parametric knowledge. This behavior is particularly prominent in cases where the retrieved evidence appears more specific or detailed than the model's inherent knowledge. Such errors suggest that while MICRO-ACT effectively identifies conflicts, the final resolution step may still be influenced by an implicit bias toward explicit external information over learned knowledge.

These findings indicate that while MICRO-ACT significantly improves conflict resolution, future work should focus on enhancing the model's ability to maintain reasoning clarity in highly complex scenarios and developing more balanced weighing mechanisms between retrieved and parametric knowledge.

#### F More Complexity Aspect Analysis

Besides the complexity aspects discussed in Figure 5, we explore how the number of decomposition steps (i.e., the number of times MICRO-ACT invokes its "DECOMPOSE" action) varies across different conflict types. We collect more results on temporal, misinformation, and semantic conflicts for both GPT-40 and GPT-40-mini. Below is a summary of the average number of decomposition steps taken for each conflict category:

Action	Expression	Description	
DECOMPOSE	Action $i$ $\rightarrow$ action $1$ , action $2$	Split a complex action <i>i</i> into smaller, manageable steps such as action 1 and action 2.	
ELICIT	Query <i>i</i> → LLM Knowledge	Elicit LLM knowledge about a given query.	
REASON	Knowledge <i>i</i> → Reasoning Path	Reason on input knowledge to generate the reasoning path.	
ASSERT	Knowledge $i$ , Knowledge $j \rightarrow 0$ or 1	Judge whether the two input knowledge have conflict or not.	

Figure 9: The table of actions in our hierarchical action space.

Table 5: Average DECOMPOSE action steps per conflict type.

Conflict Type	GPT-40 (Avg. Steps)	GPT-40-mini (Avg. Steps)
Misinformation	0.8	1.3
Temporal	1.6	2.2
Semantic	1.5	2.3

**Temporal and Semantic Conflicts.** We can see that temporal and semantic conflict types usually trigger a higher number of decomposition steps. As detailed in Appendix B, these two types are more easily to be "over-rationalized". Thus, more decomposition steps are needed to investigate underneath conflicts and the logic flaws behind the superficial context, which looks reasonable.

**Misinformation Conflicts.** Misinformation typically involves more **superficial conflicts**, which is more intuitive. As a result, fewer DECOMPOSE actions are invoked because there is less ambiguity in the evidence to untangle.

Why Decompose More? The observed more decomposition is mainly because the nuanced conflicts are underneath the superficial context and can hardly be located by simple side-by-side comparisons that baselines use, detailed discussion can be found in Appendix B.

**Model Size & Complexity.** We observe that GPT-4o-mini has a higher decomposition step count across all conflict types. Smaller LLMs often require additional steps to reduce complexity, revealing different complexity tolerance between GPT-4o and GPT-4o-mini, as discussed in Section 5. A more detailed discussion can be found in Section 7.5, RQ3.

This illustrates exactly **why** and **how** MICRO-ACT's dynamic reasoning pipeline triggers additional decomposition for temporal and semantic conflicts, where potential "over-rationalizations" are more likely to arise.

# **G** Implementation Details

#### **G.1** Action Details

All the actions designed in our proposed hierarchical action space are illustrated in Table 9.

#### **G.2** Generic Reasoning Models

End-to-End QA. The End-to-End QA prompt as shown in Figure 10, directly provides the model with the question and requests an immediate, self-contained answer. It contains no intermediate reasoning instructions, and the model is expected to return its best guess in a single generation pass. This approach assumes the model's internal representations are sufficient for reasoning without explicitly prompting it to show work.

**Few-Shot QA.** The Few-Shot QA prompt as shown in Figure 11, includes one or more example QA pairs before presenting the target question. These examples help the model align its reasoning with the desired output format and style. The provided examples are chosen to be representative of the question domain and complexity level.

**Chain-of-Thought.** The Chain-of-Thought (Wei et al., 2022) prompt as shown in Figure 12, instructs the model to show its intermediate reasoning steps explicitly. After presenting the question, the prompt requests the model to "think aloud" by outlining its reasoning process before concluding with

a final, concise answer. This approach encourages the model to form more coherent and justifiable solutions.

# **G.3** Generation-aided Reasoning Models

**Self-Ask.** The Self-Ask (Press et al., 2023) prompt as shown in Figure 13, breaks down a complex question into sub-questions and then prompts the model to answer them step-by-step. By iteratively generating and resolving subtasks, the model can handle multi-step reasoning tasks more systematically, ultimately consolidating the intermediate answers into a final solution.

**Comparative QA.** The Comparative QA (Wang et al., 2023) prompt as shown in Figure 14, asks LLMs generate the answer of the question regardless of the retrieved evidence at first. Then answer the question by considering both the retrieved evidence and the self-generated answer.

Generation Phase of GKP. In the Generation Phase of GKP (Liu et al., 2022), the prompt encourages the model to generate the knowledge needed to answer the given question. The model then lists relevant knowledge without yet providing the final answer.

Answering Phase of GKP. Once the self-generated knowledge is established, the Answering Phase of GKP (Liu et al., 2022) prompt feeds the previously generated knowledge back into the model. Using this as a guide, the model now produces a final answer. This is a two-step process.

#### G.4 MICRO-ACT

**MICRO-ACT.** The prompt of our proposed MICRO-ACT model is shown in Figure 17.

#### **H** Human Evaluation

To assess the quality and representativeness of our 1,000-instance samples, we conducted a human study with 10 volunteer expert annotators, each having substantial experience in QA tasks.

**Evaluation Procedure.** For each dataset, we presented each annotator with a total of 100 QA items: 50 randomly drawn from the full dataset and 50 randomly drawn from the 1,000-instance sample. Annotators were blind to which items came from which source. Each annotator answered all 100 questions to the best of their ability.

**Measurements.** We measured annotator accuracy, defined as the proportion of correct answers, on both subsets. Across all datasets, the average accuracy on sample-based QA pairs differed by less than 5% from that on the corresponding full-dataset pairs. This consistency suggests that the sampled subsets do not introduce systematic bias in terms of difficulty or content distribution.

Internal Agreement. To ensure that results were not driven by a few outliers, we examined internal agreement among the 10 annotators. We computed Fleiss' kappa (Fleiss, 1971), which was consistently above 0.80 for all datasets, indicating substantial agreement. In addition, the standard deviation of accuracy across annotators remained under 2% for each subset type, reflecting stable and consistent performance patterns.

These findings demonstrate that our sampling strategy preserves the key characteristics of the original datasets, maintaining both content diversity and difficulty level, and that our evaluation results are reliable and robust across multiple independent annotators. After the review period, we will open-source the sampled datasets for reproduction and for researchers to develop more advanced methods on knowledge conflict.

#### I Model Descriptions

Our empirical evaluation employs three representative language models, each positioned at different capability levels.

**GPT-4o.** GPT-4o (OpenAI, 2023) is a state-of-the-art foundation model that excels at complex reasoning tasks. Our experiments leverage its robust instruction-following capabilities and advanced reasoning abilities to evaluate the upper bounds of adaptive complexity.

**GPT-4o-mini.** GPT-4o-mini (OpenAI, 2023) is a balanced model that combines computational efficiency with strong reasoning capabilities. This model serves as an ideal testbed for examining how moderate model capacity influences the granularity of knowledge decomposition across varying task complexities.

**LLaMA-3.1-70B-Instruct.** LLaMA-3.1-70B-Instruct (Dubey et al., 2024) is a 70-billion parameter large language model built on the LLaMA architecture. This instruction-tuned variant exhibits strong performance across diverse

NLP tasks, with particular strengths in reasoning and coherent text generation.

**LLaMA-3.1-8B-Instruct.** LLaMA-3.1-8B-Instruct (Dubey et al., 2024) is a 8-billion parameter large language model built on the LLaMA architecture. This instruction-tuned variant exhibits strong performance across diverse NLP tasks, with particular strengths in reasoning and coherent text generation.

#### **End-to-End Baseline Prompt:**

According to the evidence provided and your knowledge, choose the best choice from the following options.

Evidence: {evidence}
Question: {question}
{options}

The answer should be concise and short, not with explanations nor option details. Fill your selected option in \*\*uppercase letter format\*\* into the template: <a>...</a>, for example <a>H</a>.

The final answer is: <a>

Figure 10: The prompt of the End-to-End QA baseline method.

#### **Few-Shot Baseline Prompt:**

According to the evidence provided and your knowledge, choose the best choice from the following options.

Evidence: Otters are semi-aquatic mammals that prefer to inhabit areas near water bodies for easy access to drinking water and food.

Question: Otters enter their new habitat. What happened as a more possible result?

A. Otters start looking for abalone for food.

B. They always live by the water so that they can drink water easily.

The final answer is: <a>A</a>

According to the evidence provided and your knowledge, choose the best choice from the following options.

Evidence: Buying a variety of textbooks can provide a wide range of information, making it easier to find specific details quickly.

Question: Lila can find what she wants quickly. What is the more possible cause of this? A. Lila bought several kinds of textbooks.

B. Lila loves classification of her things.

The final answer is: <a>B</a>

According to the evidence provided and your knowledge, choose the best choice from the following options.

Evidence: Hunting cottontails is often associated with drinking rum as a tradition or ritual.

Question: He got some rum. What is the more possible cause of this?

A. The worker fremented some sugar cane with yeast.

B. Tom went out and want to hunt some cottontails.

The final answer is: <a>A</a>

Evidence: {evidence}
Question: {question}

{options}

The final answer is: <a>

Figure 11: The prompt of the Few-Shot QA baseline method.

#### **COT Baseline Prompt:**

According to the evidence provided and your knowledge, choose the best choice from the following options.

Evidence: {evidence}
Question: {question}

{options}

Please think step by step to answer the question and fill in the template: <t>...</t> with your thoughts. And then generate your selected option to fill in the template: <a>...</a> in \*\*uppercase letter format\*\*, for example <a>H</a>.

Step-by-step thought: <t>

Figure 12: The prompt of the COT (Wei et al., 2022) baseline method.

```
Self-Ask Prompt:

Answer the question based on the given context and your own knowledge respectively.

Format Examples:
---
Context: [Some Context]
Question: [The Given Question]
Follow up: [You should ask follow up questions.]
Follow up: [You can ask more than one questions.]
...

Answer: <a> E </a>
---

You have to generate the final answer about the question after ask several follow-up questions. The answer should be concise and short, not with explanations nor option details. Fill your answer in **uppercase letter format** into the template: <a>....</a>.
---
Context: {evidence}
Question: {question}
{options}
Follow up:
```

Figure 13: The prompt of the Self-Ask (Press et al., 2023) QA baseline method.

# **Comparative Prompt:**

Generate two answers to the given question: ANSWER1 solely based on the given context and ANSWER2 solely based on your own knowledge. Then based on the two answer give the final answer and fill your final answer in \*\*uppercase letter format\*\* into the template: <a>...</a>, for example <a>H</a>.

Context: {evidence} Question: {question} {options}

Answer the question solely based on the given context.

Answer:

Figure 14: The prompt of the comparative (Wang et al., 2023) baseline method.

#### **GKP Prompt (Generation Phase):**

Generate some knowledge about the input.

Input: {question}
Knowledge:

Figure 15: The prompt of the generation phase of GKP (Liu et al., 2022) baseline method.

```
GKP Prompt (Answer Phase):
You are doing a question answering task with a provided evidences to assist you to answer the question. According to the
evidence provided and **your own knowledge**, choose the best choice from the following options.
# Here is the question:
{question}
{options}
Please firstly think step by step to answer the question and fill in the template: <t>...</t> with your thought. And then generate
your selected option to fill in the template: <a>...</a> in **uppercase letter format**. For example:
---- Example Begins: ---
# Step-by-step thought: <t>I think firstly we need to ... </t>
# Answer: <a> E </a>
---- Example Ends ----
# Here is the retrieved evidence:
{evidence_1}
# Here is my own knowledge:
{evidence_2}
# There may be some conflict between the provided evidence and your own knowledge. You are a detective and you MUST find
out which side is more reliable based on your knowledge and choose the correct answer of the question!
You have to think of the provided evidence and also fully consider your answer when disregarding the provided evidence.
---- Task Begins: ----
# Step-by-step thought: <t>
```

Figure 16: The prompt of the answering phase of GKP (Liu et al., 2022) baseline method.

```
You are a detective. When you ask a question, the suspects provide an evidence, which may conflict with your knowledge. Your
 objective is to determine the answer by identifying and locating any points of conflict.
 You have a maximum of **eight turns** to locate all conflict points. In each turn, you may choose **one** of the following
Action Choices:
 1. **knowledge_gen(target: str) -> str**: Input the target question, this function adopts LLM to generate the LLM inherent
1. Nowhedge_gen(target=) in The three taget question, in sunction adopts this organization of generate the Ethinmeteric knowledge about the question. Use in format: **knowledge_gen(target="...")**.

2. **reason(evidence: str) -> str **: Input an evidence to generate a step-by-step reasoning path to answer given question based on that evidence. Use in format: **reason(evidence="...")**.

3. **decompose(reasoning_step: str) -> list of str**: This action can **ONLY** be used when one reasoning step can be decomposed for **better** analysis and benefiting the QA task. This action can break down a complex reasoning step into
smaller, manageable sub-steps. Use in format: **decompose(reasoning_step="...")**.

4. **assert(state_left: str, state_right: str) -> bool**: Input two statements to evaluate if they conflict, returning a confidence
rating. Use in format: **assert(state_left="....", state_right="...")**. This action should only be used when necessary.

5. **terminate()**: Signals the end of the session. Use it **ONLY** when confident in your final answer. Format: **terminate()**.
#### Problem-Solving Process:
You will alternate between **Thought**, **Action**, and **Observation** phases in each turn.
- In the **Thought** section, consider your current information and decide your next step.
- In the **Action** section, apply **one** of the four actions listed above.
- After each action, you will receive an **Observation** to help guide your next move.
 **Remember**: You can take only **one action per turn** and have a total of **eight turns** to determine the final answer.
 When confident in your answer, use **terminate()** to end the session.
# Question:
 {options}
 # Given evidence:
given_evidence = "" {evidence} ""
NOTE: Begin your process now to answer the question above, filling in your action in the template: <f>...</f>
# 8 turns remaining to provide the final answer. In this turn, your task is to generate **Thought** and **Action**. **Do NOT answer question this time!** Please keep your thought brief and focused, and **You MUST choose an action from
['knowledge_gen', 'reason', 'decompose', 'assert', 'terminate'] as describe in the Task Guidelines section above!** Then fill your
 action in the template \verb|'**Action: ** < f>... < f>'. You can take previous steps as example. Failure to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the template to generate an action will result in the t
strict penalties and you will lose your job!
##Turn 1:

**Thought:** The evidence is too complex. I want to get the step-by-step reasoning path to answer the question above based on
the given evidence for easier analysis.

**Action:** <f>reason(evidence=given_evidence)</f>
 **observation**: Step-by-step reasoning path based on given evidence is list below:
# 7 turns remaining to provide the final answer. In this turn, your task is to generate **Thought** and **Action**. **Do NOT
answer question this time!** Please keep your thought brief and focused, and **You MUST choose an action from ['knowledge_gen', 'reason', 'decompose', 'assert', 'terminate'] as describe in the Task Guidelines section above!** Then fill your action in the template '**Action:** <f>...</f>'. You can take previous steps as example. Failure to generate an action will result in
 strict penalties and you will lose your job!
 **Thought:** Then I want to get the step-by-step reasoning path to answer the question above based on my inherent knowledge.
To do this, I want to firstly generate the knowledge based on my inherent pre-trained knowledge. 
**Action:** <f>knowledge_gen(target="[[question]]")</f>
 **observation**: My inherent knowledge about this question is:
[[evidence_gen]]
# 6 turns remaining to provide the final answer. In this turn, your task is to generate **Thought** and **Action**. **Do NOT
answer question this time!** Please keep your thought brief and focused, and **You MUST choose an action from
[knowledge_gen', 'reason', 'decompose', 'assert', 'terminate'] as describe in the Task Guidelines section above!** Then fill your action in the template '**Action:** <f>...</f>
'Nou can take previous steps as example. Failure to generate an action will result in
 strict penalties and you will lose your job!
## Turn 3:

**Thought:** Now I want to get the step-by-step reasoning path to answer the question above based on my generate
knowledgein previous step.
  **Action:** <f>reason(evidence="[[evidence_gen]]")</f>
 **observation**: Step-by-step reasoning path based on model knowledge is list below:
# 5 turns remaining to provide the final answer. In this turn, your task is to generate **Thought** and **Action**. **Do NOT
 answer question this time!** Please keep your thought brief and focused, and **You MUST choose an action from
[knowledge_gen', 'reason', 'decompose', 'assert', 'terminate') as describe in the Task Guidelines section above!** Then fill your action in the template '**Action:** <f>...</f>'. You can take previous steps as example. Failure to generate an action will result in
strict penalties and you will lose your job!
 **Thought:** Now I have already obtained the two reasoning paths from given evidence in 'Turn 1' and from my inherent
knowledge in 'Turn 3' respectively. I must locate all conflict points between them. To do so, I will compare the reasoning steps
 between them. First, I will check if any key reasoning steps need to be decomposed for clearer comparison. If none do, I will
 proceed with the reasoning step comparison to locate each conflict point.
```

Micro-Act Prompt (Ours): ### Task: Knowledge Conflict Location

Figure 17: The prompt of our proposed MICRO-ACT method.