## Neural Machine Translation for the Indigenous Languages of the Americas: An Introduction

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Abstract

Neural models have drastically advanced state of the art for machine translation (MT) between high-resource languages. Traditionally, these models rely on large amounts of training data, but many language pairs lack these resources. However, an important part of the languages in the world do not have this amount of data. Most languages from the Americas are among them, having a limited amount of parallel and monolingual data, if any. Here, we present an introduction to the interested reader to the basic challenges, concepts, and techniques that involve the creation of MT systems for these languages. Finally, we discuss the recent advances and findings and open questions, product of an increased interest of the NLP community in these languages.

## 1 Introduction

More than 7 billion people on Earth communicate in nearly 7000 different languages (Pereltsvaig, 2020). Of these, approximately 900 languages are native of the American continent (Campbell, 2000). Most of these indigenous languages of the Americas (ILA) are endangered at some degree (Thomason, 2015). This huge variety in languages is simultaneously a rich treasure for humanity and also a barrier to communication among people from different backgrounds. Human translators have been important in overcoming language barriers. However, trained translators are not accessible to everyone on Earth and even scarcer for endangered and minority languages. The need for translations is even written in the constitutions of several countries like Mexico, Peru, Paraguay, Venezuela, and Bolivia (Zajícová, 2017) to allow native speakers to have equal language rights regarding law.

This is why developing MT is crucial: it helps humanity overcome language barriers while simultaneously allowing people to continue using their native tongue. However, the challenges to achieving these problems are not trivial. It is not only the amount of available data (a common thesis among the NLP community) but also a set of challenging issues (dialectical and orthographic variations, noisy texts, complex morphology, etc.) that must be addressed.

MT has always been an important task within the larger area of natural language processing (NLP). In 1954, the Georgetown-IBM experiment (Hutchins, 2004) was the first that showed at least some effectiveness of MT. Further research resulted in rule-based systems and statistical models. In 2023, neural models define state of the art for MT if training data is plentiful - i.e., for so-called high-resource languages (HRLs) - and have also achieved impressive results for low-resource languages (LRLs). MT is also the most studied NLP task for the ILA (Mager et al., 2018b; Littell et al., 2018). The common issue among these languages is the extreme low-resource conditions they are confronted with. The research interest for these languages has increased in the last years, including the recent AmericasNLP 2021 shared task (Mager et al., 2021) on 10 indigenous languages to Spanish, and the WMT (Conference on Machine Translation) shared task for Inuktitut-English (Barrault et al., 2020).

In this work we aim to provide a comprehensive introduction to the challenges that involve creating MT systems for ILA, and the current status of the existing work. We organize this work as follows: We start by introducing state-of-the-art NMT models (§2). Then, we discuss the current challenges for these languages (§3); and we introduce the key concepts related to low-resource NMT and the implications for endangered languages of the Americas(§3). This is followed by a discussion of available data (§4). Afterwards, we introduce the important concepts for LRL and endangered languages (§5); then we introduce the main strategies

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aimed at improving NMT with limited training data (§6); and finally we give an overview of the work done for ILA on MT (§7). In doing so, we provide insights into the following questions: Which systems define the state of the art on low-resource NMT applied to the ILA? What is the route that ahead to improve the translations of the ILA?

#### 2 Background and Definitions

Formally, the task of MT consists of converting text X in a source language  $L_x$  into text Y in a target language  $L_y$  that conveys the same meaning.<sup>1</sup> Translating text  $X \in L_x$  into  $Y \in L_y$  can be described as a function (Neubig, 2017):

$$Y = MT(X). \tag{1}$$

X and Y can be of variable length, such as phrases, sentences, or even documents.

If other languages are used during the translation process, e.g., as pivots, we denote them as  $L_1, \ldots, L_n$ . We refer to a corpus of monolingual sentences in language  $L_i$  as  $M^{L_i} = S_1, \ldots, S_n$ .

**Probabilistic Modeling and Data** When using probabilistic MT models, the goal is to find  $Y \in L_y$  with the highest conditional probability, given  $X \in L_x$ . Under the supervised machine learning paradigm, a parallel corpus  $C_{parallel} = (X_1, Y_1), ..., (X_n, Y_n)$  is used to learn a set of parameters  $\theta$ , which define a probability distribution over possible translations. Given  $C_{parallel}$ , the training objective of an NMT model is generally to maximize the log-likelihood  $\mathcal{L}$  with respect to  $\theta$ :

$$\mathcal{L}_{\theta} = \sum_{(X_i, Y_i) \in C_{parallel}} \log p(Y_i | X_i; \theta).$$
(2)

Within this overall framework, there are a number of design decisions one has to make, such as which model architecture to use, how to generate translations, and how to evaluate.

**Decoding** Decoding refers to the generation of output  $\hat{Y}$ , given the parameters  $\theta$  and an input X. Often, decoding is done by approximately solving the following maximization problem:

$$\operatorname{argmax}_{\hat{Y}} p(\hat{Y}|X;\theta) \tag{3}$$

Most NMT systems factorize the probability of  $\hat{Y} = \hat{y_1}, ..., \hat{y_T}$  in a left-to-right fashion:

$$p(\hat{Y}) = \prod_{t=1}^{T} p(\hat{y}_t | \hat{y}_{< t}, X, \theta)$$
(4)

Thus, the probability of token  $\hat{y}_t$  at time step t is computed using the previously generated tokens  $\hat{y}_{< t}$ , the source sentence X and the model parameters  $\theta$ . Common algorithms for finding a highprobability translation are greedy decoding, i.e., picking the token with the highest probability at each time step, and beam search (Lowerre, 1976).

#### 2.1 Input Representations

The texts X and Y are input into an NMT system as sequences of continuous vectors. However, defining which units should be represented as such vectors is non-trivial. The classic way is to represent each word within X and Y as a vector (or embedding). However, in a low-resource setting, often not all vocabulary items appear in the training data (Jean et al., 2015; Luong et al., 2015). This issue especially effects languages with a rich inflectional morphology (Sennrich et al., 2016c): as many word forms can represent the same lemma, the vocabulary coverage decreases drastically. Furthermore, for many LRLs, boundaries between words or morphemes are not easy to obtain or not well defined in the case of languages without a standard orthography. Alternative input units have been explored, such as characters (Ling et al., 2015), byte pair encoding (BPE; Sennrich et al., 2016a), morphological representations (Vania and Lopez, 2017; Ataman and Federico, 2018), syllables (Zhang et al., 2019), or, recently, a visual representation of rendered text (Salesky et al., 2021). No clear advantage has been discovered for using morphological segmentations over BPEs when testing them on LRLs (Saleva and Lignos, 2021).

Input representations can be pretrained. The two most common options are: i) word embeddings, where each type is represented by a vector, e.g., Word2Vec (Mikolov et al., 2013), Glove (Pennington et al., 2014), or Fasttext (Bojanowski et al., 2017)) embeddings, and ii) contextualized word representations, where entire sentences are being encoded at a time, e.g., ELMo (Peters et al., 2018) or BERT (Devlin et al., 2019). However, training of these methods requires large monolingual training corpora, which may not be readily available for LRLs. As most ILA have rich morphology,

<sup>&</sup>lt;sup>1</sup>This is an approximation, since it is in general not possible to map the meaning of text exactly into another language (Nida, 1945; Sechrest et al., 1972; Baker, 2018).

this topic has gathered special interest. The discussion about the usage of morpholigical segmented input for NMT models is recurrent. (Mager et al., 2022) show that the unsupervised morphologically inspired models outperform BPE pre-processing (experimented on 4 language pares). Similar experiments done on Quechua–Spanish and Inuktitut– Enlgish (Schwartz et al., 2020), comparing BPEs against Morfessor (Smit et al., 2014). Also (Ortega et al., 2020a) improves the SOTA (state-of-the-art) for Quechua–Spanish MT using a morphological guided BPE algorithm.

#### 2.2 Architectures

NMT models typically are sequence-to-sequence models. They encode a variable-length sequence into a vector or matrix representation, which they then decode back into a variable-length sequence (Cho et al., 2014). The two most frequent architectures are: i) recurrent neural networks (RNN), such as LSTMs (Hochreiter and Schmidhuber, 1997) or GRUs (Cho et al., 2014), and ii) transformers (Vaswani et al., 2017), which define the current state of the art in the high-resource setting.

As for most neural network models, training an NMT system on a limited number of instances is challenging (Fernández-Delgado et al., 2014). There are common problems that arise from limited data in the training set. One major advantage of neural models is their ability to learn representations from raw data, in contrast to manually engineered features (Barron, 1993). However, problems arise when not enough data is provided to enable effective learning of features. Another strength of neural networks is their generalization capacity (Kawaguchi et al., 2017). However, training a neural network on a small dataset easily leads to overfitting (Rolnick et al., 2017). Recent studies, however, show empirically that this does not necessarily happen if the network is tuned correctly (Olson et al., 2018).

## 2.3 Evaluation

Accurately judging translation quality is difficult and, thus, often still done manually: bilingual speakers assign scores according to provided criteria such as fluency and adequacy (*Does the output have the same meaning as the input?*). However, manual evaluation is expensive and slow. Moreover, in the case of endangered languages, bilingual speakers can be hard or impossible to find. Automatic metrics provide an alternative.<sup>2</sup> These metrics assign a score to system output, given one or more ground truth reference translations. The most widely used metric is BLEU (Papineni et al., 2002), which relies on token-level *n*-gram matches between the translation to be rated and one or more gold-standard translations. For morphologically rich languages, character-level metrics, such as chrF (Popović, 2017), are often more suitable, as they allow for more flexibility. In the AmericasNLP ST (Mager et al., 2021) this metric was used over BLEU, as it fits better to the rich morphology of many ILA.

To have a concrete example, lets have the following Wixarika phrase with an English translation:

> yu-huta-me ne-p+-we-'iwa an-two-ns 1sg:s-asi-2pl:o-brother *I have two brothers*

As discussed in (Mager et al., 2018c) it is difficult to translate back from Spanish (or other Fusional language) the morpheme p+ as it has not equivalent in these languages. So if we would ignore these morpheme at all, BLEU would penalize the entire word nep+we'iwa. In contrast, chrF would give credit to the translation, even if the p+ is missing.

One shortcoming of these evaluation metrics is that the evaluation is very dependent on the surface forms and not on the ultimate goal of semantic similarity and fluency. Recent work uses pretrained models to evaluate semantic similarity between translations and the gold standard (Zhang et al., 2020d), but these methods are limited to languages for which such models are available. This is not possible for the ILA, as the amount of monolingual data is not enough to train a reliable pretrained language model<sup>3</sup>.

## **3** Challenges and open questions

In an overview of the datasets and recent studies of MT for the ILA, we found the following main issues to be handled.

**Extreme low-resource parallel datasets** Even with the recent advances, the resources available to train MT systems are extremely scarce, having

<sup>&</sup>lt;sup>2</sup>For a detailed overview of automatic metrics for MT we refer the interested reader to specialized reviews (Han, 2016; Celikyilmaz et al., 2020; Chatzikoumi, 2020).

<sup>&</sup>lt;sup>3</sup>One exception to this is Quechua, that has a large enough monolingual dataset to train a BERT like model (Zevallos et al., 2022)

training set between 4k and 20k sentences (see §4), with notable exceptions for Inuktitut, Guarani and Quechua (Joanis et al., 2020; Ortega et al., 2020a).

Lack of monolingual data Most of these languages are mostly used in spoken form. In recent years, with the advancement and democratization of mobile technologies, indigenous languages have seen a slight increase in massaging systems and private spheres (Rosales et al.). However, the usage of these languages on the internet is rather limited. Even Wikipedia has a limited amount of these languages (Mager et al., 2018b).

**Low domain diversity** . As most parallel datasets are scarce, they are restricted to a small number of domains, making it challenging to adapt it, or try to aim for general translation models. This has been recognized as a major problem during the AmericasNLP ST (Mager et al., 2021).

**Rich morphology** An important number of these languages are morphological highly rich. In many cases, we find polysynthetic, with or highly agglutinative languages (Kann et al., 2018) or even fusional phenomenon (Mager et al., 2020).

**Distant paired language** The most common languages that we find that ILA is translated into are Spanish, English, and Portuguese. However, these languages are distantly related to the ILA, and have completely different linguistically phenomenons (Campbell, 2000; Romero et al., 2016).

**Noisy text environments** Monolingual texts, if exist, are found in social media that often use a non-canonical witting (Rosales et al.).

**Code-Swithing** This phenomenon is strongly present in ILA, as all of these languages are minority languages in their own countries. The bilingualism among their communities is strong (and CS is a common phenomenon in this setup (Çetinoğlu, 2017)). The final result of this phenomenon is the inclusion of code-switching on a common base (Mager et al., 2019) in their language.

Lack of orthographic normalization The usage of ILA faces the problem of having a unified orthographic standard. This is not always possible, as the suggestions of linguists and official entities do not always match the day-by-day writing of the speakers. Moreover, in some cases, special symbols present in the orthographic standards are not accessible in English or Spanish keyboard and need to be replaced with other symbols. The winner of the AmericasNLP ST got important improvements using orthographic normalizers developed specifically for each American language (Vázquez et al., 2021).

**Dialectal variety** The indigenous languages have a strong dialectal variety, making it hard for native speakers to understand even speakers from neighboring villages. The linguistic richness of entire regions is so diverse that even a single state like the Mexican Oaxaca could correspond to the diversity in the whole Europe (McQuown, 1955).

## 4 Available MT datasets for ILA

The parallel datasets available for MT have been increasing during the last years. At this moment, we can show in two folds the development of these resources: as shown in table 2 work on specific language has emerged; but also broader datasets have started to cover the ILA (see table 1).

Language-specific corpus collection work has been done for many languages, where parallel corpus has been the main component. In recent time we have seen Cherokee–English (OPUS) (Zhang et al., 2020c), Wixarika–Spanish (Mager et al., 2018a), Shipio–Konibo (Feldman and Coto-Solano, 2020), and others (see table 2). The most prominent of these datasets has been the Inuktitut–English parallel data. The last version of this dataset corpora (Joanis et al., 2020) is has medium size with 1,450,094 sentences. Previous versions of this corpus are (Martin et al., 2003). This data set was used for the WMT 2020 Shared Task on Unsupervised, and Low Resourced MT (Barrault et al., 2020).

For wide-spoken languages like Guarani, it is even possible to collect a web crawled dataset, including news articles and social media parallel aligned data (Chiruzzo et al., 2020; Góngora et al., 2021) This dataset also includes monolingual data. This is possible as Guaraní is one of the most spoken indigenous languages of the continent.

In contrast to the language-specific datasets, we find broader approaches (see table 1). The broadest multilingual dataset, which contains the Bible's New Testament, includes about 1600 languages (Mayer and Cysouw, 2014; McCarthy et al., 2020) of the 2,508 that have been collected by the Summer Institute of Linguistic (SIL) (Anderson and Anderson, 2012). Another remarkable effort to obtain broad language coverage is the PanLex project (Kamholz et al., 2014), which has gathered lexical

Dataset	Paired-languages	Authors
AmericasNLI	Aymara, Asháninka, Bribri, Guaraní,	(Ebrahimi et al., 2022)
	Nahuatl, Otomí, Quechua, Rarámuri,	
	Shipibo-Konibo, Wixarika	
CPML	Ch'ol, Maya, Mazatec, Mixtec, Nahu-	(Sierra Martínez et al., 2020)
	atl and Otomi	
OPUS	*	(Tiedemann, 2016)
New testament Bible	*	(McCarthy et al., 2020)

Table 1: Parallel dataset collections that contain one or more indigenous languages of the Americas

Language	Paried-language	ISO	Family	Sentences	Domain	Authors
Asháninka	Spanish	cni	Arawak	3883		(Ortega et al., 2020b)
Bribri	Spanish	bzd	Chibchan	5923		(Feldman and Coto-
						Solano, 2020)
Guarani	Spanish	gn	Tupi-Guarani		News,	(Abdelali et al., 2006)
<i>a</i> .	~				Blogs	(71.1
Guarani	Spanish	gn	Tupi-Guarani	14,531	News,	(Chiruzzo et al., 2020)
Commi	C		Tuni Curreni	14 702	Blogs	(Cán ann at al. 2021)
Guarani	Spanish	gn	Tupi-Guarani	14,792	News, So- cial Media	(Góngora et al., 2021)
Guarani	Spanish	gn	Tupi-Guarani	30855	8 Domains	(Chiruzzo et al., 2022)
Nahuatl	Spanish	nah	Uto-Aztecan	16145	Diverse	(Gutierrez-Vasques
1 tunuuti	opunish	man		10115	Books	et al., 2016)
Otomí	Spanish	oto	Oto-Manguean	4889	Diverse	https://tsunkua.
	1		U		Books	elotl.mx
Rarámuri	Spanish	tar	Uto-Aztecan	14721	Dictionary	(Mager et al., 2022)
					Examples	
Shipibo-Konibo	Spanish	shp	Panoan	14592		(Galarreta et al., 2017)
					Religious	
Wixarika	Spanish	hch	Uto-Aztecan	8966	Literature	(Mager et al., 2018a)
Cherokee	English	chr	Uto-Aztecan		OPUS	(Zhang et al., 2020c)
Inuktitut	English	iku	Eskimo-Aleut	1,450,094	Legislative	(Joanis et al., 2020)
Ayuuk	Spanish	mir	Mixe–Zoque	7553	Diverse	(Zacarías Márquez and
	a		0.14	0700	D.	Meza Ruiz, 2021)
Mazatec	Spanish	-	Oto-Manguean	9799	Diverse	(Tonja et al., 2023)
Mixtec	Spanish	Many	Oto-Manguean	13235	Diverse	(Tonja et al., 2023)

Table 2: Parallel datasets that have been released focusing on one indigenous language

translation dictionaries for over 5,700 languages. However, for most languages, PanLex contains only a few dozen words. Duan et al. (2020) show that such dictionaries can be used to create an NMT system, making bilingual dictionaries relevant for further studies.

Recently community-driven research groups have started the creation of own parallel datasets, such as Masakhane (Orife et al., 2020; Nekoto et al., 2020) for African languages, and AmericasNLP for indigenous languages of the Americas (Ebrahimi et al., 2021; Mager et al., 2021). The AmericasNLI dataset is an important effort to have a common evaluation benchmark for the 10 indigenous languages of the Americas for the MT and NLI tasks.

Given the constitutional rights of indigenous languages in many countries of the Americas, it is possible to access this data. Vázquez et al. (2021) made available this resource during their shared task system development.

Finally, it is important to mention that many of the languages spoken in the Americas have Wikipedia's set of articles available<sup>4</sup>.

**Collection of New Data** A common way to create parallel data with the help of bilingual speakers is via elicitation (translating the foreign text into another language). It has the disadvantage of biasing the created text to forms and topics, culture, and even grammatical forms towards the source language (Lörscher, 2005). A method that avoids this problem is language documentation, which consists of storing and annotating commonly used speech or text (Himmelmann, 2008). However, it is

<sup>&</sup>lt;sup>4</sup>The available languages in wikipedia can be consulted at: https://es.wikipedia.org/wiki/Po rtal:Lenguas\_indígenas\_de\_América. Until the publication of this article, there were only entries in Nahuatl, Navajo, Guarani, Aymara, Klaalisut, Esquimal, Inukitut, Cherokee, and Cree.

costly and requires specialists. In this process, involving the community members that are bilingual speakers is important (Bird, 2020).

## 5 Low-resource MT

For the purpose of this paper we define LRLs as languages for which standard techniques are unable to create well performing systems, which makes it necessary to resort to other techniques (cf. Figure 1) such as transfer learning. For MT, the amount of available resources differs widely across language pairs: some have less than 10k parallel sentences, while other have more than 500k, with some exceptions in the orders of several million.

Emulating a low-resource scenario by downsampling available data for high-resource languages is common and helps understanding a model's performance across different settings. However, further evaluating methods on a diverse set of low-resource languages is crucial, since many languages exhibit particular linguistic phenomena (Mager et al., 2020), that perturb the final results, especially since most large datasets are from the Indo-European language family, to which only 6.16% of the world's languages belong (Lewis, 2009).

Importantly, there is no strong correlation between the number of resources available per language and the number of speakers: Javanese with 95 million speakers and Kannada with 44 million are considered LRLs, while French, with only 64 million native speakers, is among the most widely studied languages. Improving models to handle LRLs will extend access to information online as well as human language technology to all monolingual speakers of those languages. In the case of ILA, most languages are endangered at some degree, but most of them have the same issue: they are low resourced for parallel and monolingual data.

**Endangered Languages** Krauss (1992) estimates that 50% of all languages are doomed or dying, and that in this century we will see either the death or the doom of 90% of all human languages. The current proportion of languages that are already extinct or moribund ranges from 31% down to 8% depending on the region, with the most severe cases in the Americas and Australia (Simons and Lewis, 2013). To determine how endangered a language is, Lewis and Simons (2010) proposes a classification scale called EGIDS with 13 levels. The higher the number on this scale, the greater the level of disrup-

tion of the language's inter-generational transmission.<sup>5</sup> MT for endangered LRLs has the potential to help with documentation, promotion and revitalization efforts (Galla, 2016; Mager et al., 2018b). However, as these languages are commonly spoken by small communities, or indigenous people, researchers should aim for a direct involvement of those communities (Bird, 2020).

What is polysynthesis? A polysynthetic language is defined by the following linguistic features: the verb in a polysynthetic language must have an agreement with the subject, objects and indirect objects (Baker, 1996); nouns can be incorporated into the complex verb morphology (Mithun, 1986); and, therefore, polysynthetic languages have agreement morphemes, pronominal affixes and incorporated roots in the verb (Baker, 1996), and also encode their relations and characterizations into that verb. The most common word orders present in these languages are SOV, VSO, SVO and free order. It is important to notice that a polysynthtic language can have a aggutinative <sup>6</sup> or can have also fusional characteristics, like Totonaco or Tepehua (Mager et al., 2020).

## 6 Low-resource MT paradigms

Most languages of the Americas do not have high amount of data for MT. Therefore, we introduce the most important paradigms to improve lowresourced machine translation. Figure 1 shows a general overview of the methods and options to improve LRL MT. For a more detailed understanding of this techniques we refer the reader to specialized low-resource MT surveys (Haddow et al., 2022; Wang et al., 2021; Ranathunga et al., 2021).

### 6.1 Multilingual Supervised Training

With a multilingual set of parallel data  $D_{parallel}$  between different language pairs  $\{(L_1, L_2), \ldots, (L_m, L_n)\}$  we can train a model that is able to map a sentence from any source language  $L_x$  into any target language  $L_y$  that is contained in  $D_{parallel}$  (see 2). These multilingual NMT models have seen a growth in popularity and efficiency in recent years. We will now cover the different training algorithms for these models: 1) many source languages and one target

<sup>&</sup>lt;sup>5</sup>The complete EGIDS scale can be found at https:// www.ethnologue.com/about/language-status

<sup>&</sup>lt;sup>6</sup>Agglutination refers to a concatenation of morphemes, with minimal changes to the surface form.



Figure 1: What to do when we have low o no data to train our machine translation models? This diagram shows basic scenarios, solutions, and common requirements for each method, with the section describing the method.



Figure 2: An overview of different multilingual setups.

language (*many-to-one*), 2) one source and many target languages (*one-to-many*), and 3) many source languages and many target languages (*many-to-many*). For a general overview of multilingual MT, we refer the reader to surveys dedicated to this topic (Tan et al., 2019; Dabre et al., 2019). Johnson et al. (2017) are the first to introduce a multilingual NMT model, trained on translating from a large number of languages to English as well as in the opposite direction. The authors show that these models improve over single-language pair models for LRLs.

#### 6.2 Multi-task Training

Multi-task training (Caruana, 1997) aims to improve the performance of the main task – MT in our case – by adding one or more auxiliary tasks to the training. The easiest way is to share all parameters of the network, using the ideas already explored in multilingual NMT (§6.1). This can be done with a special flag in the input that specifies the current task. It is also possible to share only the encoder and have two separate decoders for each task.



Figure 3: Backtranslation

**Multilingual Modeling** In order to handle multilinguality it is also possible to adapt modify the NMT models. The main proposals to do so has been: sharing all parameter except the attention mechanism of a RNN NMT model (Blackwood et al., 2018); parameter sharing in the transformer architecture Sachan and Neubig (2018);

#### 6.3 Data Augmentation

**Back-Translation** A straightforward way to leverage monolingual data for low-resource MT is to generate a meaningful signal with the help of an already initialized MT model (see Figure 3). This method is called back-translation (BT; Sennrich et al., 2016b): With monolingual data  $M^{L_x}$ in source language  $L_x$  and a trained model that is able to translate from  $L_x$  into a target language  $L_y$ we can generate a translation  $M'^{L_y}$ . This pseudo parallel data  $(M^{L_x}, M'^{L_y})$  is then used to train a new model in the opposite direction. This process can be applied iteratively to improve the translation (Hoang et al., 2018).

**Sentence Modification** Other methods to generate more parallel sentences are based on lexical substitution. Fadaee et al. (2017) explores replacing frequent words with low-frequency ones in both source and target to improve the translation of rare words. This is done using language models (LMs) and automatic alignment.

**Pivoting** If no parallel corpus between languages  $L_x$  and  $L_y$  is available, but both of them have parallel corpora with a third language  $L_p$ , pivoting is an option. The basic idea is to train two MT systems: one that translates  $L_x \rightarrow L_p$  and another for  $L_p \rightarrow L_y$ . Pivoting has first been introduced for SMT (Wu and Wang, 2007; Cohn and Lapata, 2007; Utiyama and Isahara, 2007).

#### 6.4 Semi-supervised and Unsupervised MT

Transfer Learning via Pretraining Transfer learning refers to using knowledge learned from one task to improve performance on a related task (Weiss et al., 2016). In recent years this approach has gained popularity with big multilingual models such as Conneau and Lample (2019) that proposes training the encoder and the decoder separately in order to get cross-language representations (XLM). This idea has further been extended by Song et al. (2019, MASS) to masking a sequence of tokens from the input (multilingual MASS (Siddhant et al., 2020)). Another approach is to train the entire transformer model as a denoising autoencoder (BART; Lewis et al., 2019) (multilingual BART (mBART) (Liu et al., 2020)). It is also possible to pretrain a transformer in a multi-task, text-to-text fashion, where one of the tasks is MT (T5; Raffel et al., 2020) (multilingual version (Xue et al., 2021)).

**Unsupervised MT** UMT covers approaches that do *not* require any parallel text, relying only on monolingual data. This differs from zero-shot translation, which uses parallel data for other language pairs. Early approaches tackled the problem with an auto-encoder with adversarial training (Lample et al., 2017) or with auto-encoders with a shared encoding space as well as separate decoders for each target language (Artetxe et al., 2018). The main problem for these approches is the need of a big monolingual dataset, that is not available for most ILA.

## 7 Advances in MT for the indigenous languages of the Americas

In recent years the interest in MT for indigenous languages of the Americas has increased. The task is not easy. The first usage of NMT systems has not been successful (Mager and Meza, 2021). However, with the use of LRL MT methods, we have witnessed great improvements.

The Cherokee–English (Zhang et al., 2020c) language pair has been explored using a pre-trained BERT (Devlin et al., 2019) for the English side. A system demonstration of this approach is also accessible (Zhang et al., 2021). The back translation strategy for Bribri–Spanish NMT transformers has also been explored (Feldman and Coto-Solano, 2020) and by (Oncevay, 2021) (for four Peruvian languages to Spanish) with good results. The scarce indigenous language monolingual text can be replaced to some extent with Spanish text or extracted from PDFs, and other sources (Bustamante et al., 2020).

One of the main challenges for the complex morphological languages in the area has been the prepossessing step. Schwartz et al. (2020) show that even if morphological segmentation has less perplexity a the language modeling time, it is still under-performing or equivalent against BPEs for MT (for Inuktitut--English, Yupik-English Data, Guaraní-Spanish Data). A more comprehensive (on the segmentation modeling side) was done by (Mager et al., 2022) exploring a wide array of segmentation models. The latter study showed that supervised morphological segmentation underperform unsupervised. However, unsupervised morphological segmentation like LMVR (Ataman et al., 2017) and FlatCat (Grönroos et al., 2014) perform better than BPEs. (Ngoc Le and Sadat, 2020) studied how better to perform word segmentation for the Inuktitut-English pair. They found that for this language pair, a morphological segmentation, or a combination of BPEs and morphological segmentation, works better than just applying vanilla BPEs. Also, training word embeddings for Guarani-Spanish translation is an excellent opportunity to increase the MT performance of these languages (Góngora et al., 2022).

The usage of transfer learning from multilingual systems has been tried, with limited results (Nagoudi et al., 2021) (training an own T5 model for indigenous languages) and (Zheng et al., 2021). However, pertaining a Spanish–English model together with ILA, and then fine-tuning it (together with a careful prepossessing and filtering step) has been the most successful strategy (Vázquez et al., 2021).

The quality of MT systems of ILA has been a constant debate. However, Ebrahimi et al. (2021) shows that the quality of MT for these languages is

enough to improve other tasks like natural language inference (NLI).

**Inuktitut–Enlgish ST** The WMT 2020 news translation task included Inuktitut–English translation (Barrault et al., 2020). The participating systems explored the difficulties of working with a polysynthetic language in a medium resource scenario. Participating teams in this competition were: (Kocmi, 2020; Hernandez and Nguyen, 2020; Scherrer et al., 2020; Roest et al., 2020; Lo, 2020; Knowles et al., 2020; Zhang et al., 2020e; Krubiński et al., 2020).

AmericasNLP 2021 and 2023 ST In 2021, the AmericasNLP community organized a workshop on Machine Translation for 10 indigenous languages of the Americas in 2021 (Mager et al., 2021) and 2023 (Ebrahimi et al., 2023) with an additional indigenous language (Chatino). The AmericasNLP shared task winner was (Vázquez et al., 2021) in 2021, and a more mixed result in 2023<sup>7</sup>. Other participants in this shared task are (Nagoudi et al., 2021; Bollmann et al., 2021; Zheng et al., 2021; Knowles et al., 2021; Parida et al., 2021; Nagoudi et al., 2021). It is important to point at the importance of clean datata. For Quechua, (Moreno, 2021) got the best results generating an additional amount of clean data.

AmericasNLP 2022 Competition is a competition on Speech-to-Text translation is organized and is targeting the following language pairs: Bribri–Spanish, Guaraní–Spanish, Kotiria–Portuguese, Wa'ikhana–Portuguese, and Quechua–Spanish (Ebrahim et al., 2023)<sup>8</sup>.

## 8 Ethical aspects

When working with ILAs are also interacting with communities and nations that speak these languages. In most cases, these speakers have been exposed to a colonial past, or to a local oppression, by the majority language and culture. It is important to point to best practices and recommendations when performing our research. Bird (2020) and Liu et al. (2022) advocate to include community members as co-authors (Liu et al., 2022) as well as considering data and technology sovereignty. This is also aligned with the community building aimed at by Zhang et al. (2022). Mager et al. (2023) summarizes the main aspects that should be considered as follows: i) Consultation, Negotiation and Mutual Understanding. It is important to inform the community about the planned research, negotiating a possible outcome, and reaching a mutual agreement on the directions and details of the project should happen in all cases. ii) Respect of the local culture and involvement. As each community has its own culture and view of the world, researchers should be familiar with the history and traditions of the community. Also, it should be recommended that local researchers, speakers, or internal governments should be involved in the project. iii) Sharing and distribution of data and research. The product of the research should be available for use by the community, so they can take advantage of the generated materials, like papers, books, or data.

## 9 Conclusion

Machine translation for ILA has gained interest in the NLP community over the last few years. Here, we provide an exhaustive overview of the basic MT concepts and the particular challenges for MT for ILA (in the context of low-resource scenarios and its relation to endangered languages). We additionally survey the current advances of MT for these languages.

## Limitations

This paper's aim is to give an introduction to researchers, students, of interested community indigenous community members to the topic of Machine Translation for Indigenous languages of the Americas. Therefore, this paper is not an in-depth survey of the literature on indigenous languages nor a more technical survey of low-resource machine translation. We would point the reader to more specific surveys on these aspects (Haddow et al., 2022; Mager et al., 2018b).

#### **Ethical statement**

We could not find any specific Ethical issue for this paper or potential danger. Nevertheless, we want to point to the reader that working with indigenous languages (in this case, MT) implies a set of ethical questions that are important to handle. For a deeper understanding of the matter, we suggest specialized literature to the reader (Mager et al., 2023; Bird, 2020; Schwartz, 2022).

<sup>&</sup>lt;sup>7</sup>Up to this moment, no official desciption papers for the 2023 are published.

<sup>&</sup>lt;sup>8</sup>http://turing.iimas.unam.mx/americasn lp/st.html

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## A Appendix

In this appendix we expand the information regarding current work on MT for LRL.

# A.1 Expanded LR work on Multilingual supervised training

Arivazhagan et al. (2019a) introduce a representational invariance training objective across languages that achieves comparable results with pivoting methods. Promising results of multilingual models have encouraged experiments with models trained on a massive amount of language pairs, resulting in large multilingual models: Aharoni et al. (2019) train a single model on 102 languages to and from English in contrast to the 58 languages used by Neubig and Hu (2018).

The negative aspect of this approach is the size of the network. Arivazhagan et al. (2019b) perform an extensive study on 102 language pairs to explore different settings and training setups and achieve good results for LRLs, while maintaining good performance for high-resource languages. Related massively multilingual NMT systems have been trained for analytic proposes (Tiedemann, 2018; Malaviya et al., 2017) and general zero-shot transfer learning (Artetxe and Schwenk, 2019). mRASP (Lin et al., 2020) use for pretraining of the multilingual model and add a randomly aligned substitution loss that aims to bring words and phrases closer in the cross-lingual space.

Zhang et al. (2020a) explores the main problems that arise for such models: multilingual NMT usually underperforms bilingual models (Arivazhagan et al., 2019b), the larger the number of languages gets the more the performance drops (Aharoni et al., 2019), languages in datasets used for multilingual training are unbalanced in size, and poor zero-shot performance compared to pivot models (cf. §6.3). Zhang et al. (2020a) addresses these problems with a language-aware input layer, a deep transformer architecture (Wang et al., 2019b), and an online back-translation approach. These modifications boost zero-shot translation performance for multilingual models.

To improve the problem of imbalanced and linguistically diverse training data, mostly heuristic methods have been proposed: Arivazhagan et al. (2019b) samples training data from different languages based on a data size scaled by temperature term. These heuristics have an impact on performance, and ignore other factors that are not size. Oversampling of data is used by Johnson et al. (2017); Neubig and Hu (2018); Conneau and Lample (2019). Wang et al. (2020) proposes a differentiable data selection method that automatically learns to weight training data, optimizing translation on all languages.

Multilingual modeling Sharing all parameters except for the attention mechanism shows improvements compared with sharing everything in an RNN NMT model (Blackwood et al., 2018). Sachan and Neubig (2018) explores parameter sharing in the transformer architecture for the decoder in the one-to-many translation setting and shows that transformers are more suitable than RNNs for this task. Also, parameter sharing in the decoder and embedding layer further improves performance. Lu et al. (2018) proposes a shared layer intended to capture the interlingua knowledge and an extension to the typical RNN network with multiple blocks along with a trainable routing network. The routing network enables adaptive collaboration by dynamic sharing of blocks conditioned on the task at hand, input, and model state (Zaremoodi et al., 2018). Zhang et al. (2020a) proposes a language-aware layer to improve such architectures further. With a similar idea, Zhu et al. (2020a) incorporates two special language embeddings into the self-attention mechanism. The first encodes the unique characteristics of each language, while the second captures common semantics across languages.

One problem in multilingual NMT systems is the translation into the wrong language. To address this problem, Zhang et al. (2020b) add a languageaware layer normalization and a linear transformation that is inserted between the encoder and the decoder to induce a language-specific translation. Raganato et al. (2021) explore to weight the target language label with jointly training one cross attention head with word alignments.

Other modifications of NMT model architectures to improve their performance on low-resource languages include: deep RNNs (Miceli-Barone et al., 2017), normalization layers (Ba et al., 2016), direct lexical connections (Nguyen et al., 2015), word embedding layers conducive to lexical sharing (Wang et al., 2019c).

## A.2 Extended Multi-task training

Zhou et al. (2019) uses this approach, but extends it with a cascade architecture: the first decoder reads the encoder, and the second decoder reads the encoder and the first decoder (Niehues et al., 2016; Anastasopoulos and Chiang, 2018). The auxiliary task (first decoder) is a denoising decoder. With RNN NMT architectures, one can further decide if the attention mechanism should be shared among tasks (Niehues and Cho, 2017). The authors compare all architectures and find that they perform similarly, with only sharing the encoder being slightly better.

Using linguistic information as an auxiliary task has not yet been explored exhaustively. Niehues and Cho (2017) studies the usage of part-of-speech (POS) and named entity (NE) tags, finding that training on named entity recognition (NER), POS tagging and MT together improves performance the most. For agglutinative languages, morphological auxiliary tasks can be beneficial: Pan et al. (2020) uses stemming with fully shared parameters.

As an alternative to linguistically informed auxiliary tasks Srinivasan et al. (2019) uses multiple BPE vocabulary sizes to generate different segmentations. Each segmentation is treated as an individual task.

#### A.3 Data augmentation

**Back-translation** Caswell et al. (2019) shows that adding a special tag to the synthetic data improves performance. A technique that exploits this idea is training an initial translation model with synthetic data generated via BT and then finetune it with gold data (Abdulmumin et al., 2019). This simple yet effective training algorithm improves NMT for LRLs; however, it can also degrade performance on HRLs if trained without a tagging strategy (Marie et al., 2020).

Multiple improvements of BT have been proposed. Edunov et al. (2018) shows that sampling or noisy beam search can generate more effective pseudo-parallel data. However, for LRLs an optimal beam search and greedy decoding are better. A factor that influences BT's effectiveness is the quality of the initial MT systems (Hoang et al., 2018). Using back-translated data from multiple sources (Poncelas et al., 2019) or optimizing the ranking of back-translated data yields further gains (Soto et al., 2020).

BT results in gains when the parallel corpora are naturally occurring text and not translationese, as the latter would only improve automatic n metrics (Toral et al., 2018; Graham et al., 2020). **?** shows that BT produces more fluent text and is preferred by humans. Additionally, translationese and original data can be modeled as separate languages in a multilingual model (Riley et al., 2020). BT is also a central part of unsupervised MT (UMT; cf. §6.4) and zero-shot MT (Gu et al., 2019).

**Sentence modification** Zhu et al. (2019) proposes to replace a randomly chosen word in a sentence with a *soft-word*. That means that, instead of sampling a word from the lexical distribution of a LM like Kobayashi (2018), the authors use the hidden state vector of the LM directly. Wu et al. (2019) substitutes the RNN LMs from previous work and use BERT (Devlin et al., 2019) – a transformer trained with a masked language modeling objective – instead. The authors finetune BERT with a conditional masked language modeling objective that tries to avoid the prediction of words that do not correspond to the original sentence meaning.

Another way to augmented MT data is by paraphrasing. If a good paraphrase system exists, this can increase the number of training instances (Hu et al., 2019). Paraphrasing can also be used at training time by sampling paraphrases of the reference sentence from a paraphraser and training the MT model to predict the distribution of the paraphraser (Khayrallah et al., 2020). This helps the model to generalize. Wieting et al. (2019) propose a similar approach, using minimum risk training to optimize BLEU. To avoid BLEU's constraints to a specific reference, they use paraphrasing to diversify the given reference.

Finally, existing data can be augmented by adding noise. This noise can be continuous or discrete. In the case of applying continuous noise, noise vectors are added to the word embeddings (Cheng et al., 2018; Sano et al., 2019). Discrete noise is realized by inserting, deleting, or replacing words, BPE tokens, or characters to expand the training set in an adversarial fashion (Belinkov and Bisk, 2018; Ebrahimi et al., 2018; **?**; Cheng et al., 2019, 2020).

**Pivoting** While it is simple to implement and effective, pivot-based approaches suffer from error propagation. To overcome that for NMT, joint training Zheng et al. (2017); Cheng (2019) and round-trip training (Ahmadnia and Dorr, 2019) have been proposed.

Pivoting with NMT systems has been used for translating Japanese, Indonesian, and Malay into Vietnamese (Trieu et al., 2019), translation of related languages (Pourdamghani and Knight, 2019), multilingual zero-shot MT (Lakew et al., 2018), and UMT (cf. §6.4) between distant language pairs (Leng et al., 2019).

## A.4 Recent low-resource Shared Tasks

First, the LoResMT 2020 shared task (Ojha et al., 2020) explores the case of language pairs which have no parallel data between them (Hindi-Bhojpuri, Hindi-Magahi, and Russian-Hindi). The winning system (Laskar et al., 2020) uses a MASS model in a zero-shot fashion with additional monolingual data (see §6.4). Second, the WMT 2020 shared tasks on UMT and very low-resource supervised MT (Fraser, 2020) provide text and 60k aligned phrases for German-Upper Sorbian., The most important technique in all tracks is transfer learning, achieving surprisingly good results. For the AmericasNLP 2021 shared task on open MT (Mager et al., 2021), 10 indigenous language languages were paired with Spanish, resulting in an extreme low-resource setting (4k to 125k paired sentences), with challenges out as domain, dialectical, and orthographic mismatches between splits and datasets. The best systems shows that data cleaning and collection (§??) as well as multilingual approaches  $(\S6.1)$  result in the best performance in this conditions. Finally the shared task on MT in Dravidian languages (Chakravarthi et al., 2021) features 3 languages paired with English as well as Tamil-Telugu. Again, the winning system uses a multilingual approach. The best performing systems use BT (§6.3) and BPE word segmentation  $(\S2.1).$ 

The results from these challenges indicate that the optimal selection and combination of methods differs between cases (i.e., amount of monolingual, parallel data, cleanness of data, domain mismatch, linguistic closeness of languages). This implies that data analysis and linguistic knowledge are needed to improve a final system's performance.

## A.5 Transfer learning

This helps low-resource tasks as a lower amount of data can be used for training. One application of transfer learning to MT is the usage of a pretrained RNN LM (Gulcehre et al., 2015) as the decoder in an NMT system. Zoph et al. (2016) is the first work that uses pretrained models to improve NMT systems. The authors perform two experiments with an RNN encoder–decoder architecture with an attention mechanism: the model is first pretrained on

a high-resource language pair This works even better if related languages are used during pretraining (Nguyen and Chiang, 2017). Using pretrained LMs at decoding time and as priors at training time also improves vanilla models (Baziotis et al., 2020).

To avoid overfitting, models can be finetuned on both a HRLs pair and a LRLs pair in a multi-task fashion (Neubig and Hu, 2018).

However, how can we represent best the vocabulary? Zoph et al. (2016) use separate embeddings for the source and the target language. However, using tied embeddings has been shown to yield better results (Press and Wolf, 2017). Edunov et al. (2019) employs ELMO (Peters et al., 2018) representations as pretrained features in the encoder of a transformer model. Song et al. (2020) shows that it is possible to improve performance by combining monolingual texts from linguistically related languages, performing a script mapping. It is also possible to extract features from a BERT model in the source language and combining these with an NMT system (Zhu et al., 2020b), but using a BERT model pretrained with a mixed sentences from source and target languages lead to even better results (Xu et al., 2021).

Encoder-decoder pretrained models have gained popularity in the last years for low-resource MT. Conneau and Lample (2019) proposes training the encoder and the decoder separately in order to get cross-language representations (XLM). This idea has further been extended by Song et al. (2019, MASS) to masking a sequence of tokens from the input. Training MASS in a multilingual fashion and using monolingual data for pretraining helps to improve NMT for low-resource languages and zeroshot translation (Siddhant et al., 2020). Another approach is to train the entire transformer model as a denoising autoencoder (BART; Lewis et al., 2019). The multilingual version of BART (mBART) is more suitable for NMT tasks and yields important gains (Liu et al., 2020). It is also possible to pretrain a transformer in a multi-task, text-to-text fashion, where one of the tasks is MT (T5; Raffel et al., 2020). All four models can be finetuned for MT or used in an unsupervised fashion. Improvements to BART can be obtained by augmenting the maximum likelihood objective with an additional objective, which is a data-dependent Gaussian prior distribution (Li et al., 2020). Huge LMs can improve zero-shot and few-shot learning even further (Brown et al., 2020), but at a high computational cost. Pursuing another direction, Wang et al. (2019a) develops a hybrid architecture between a transformer and a pointer-generator network. At training time, the authors jointly train the encoder and the decoder in a denoising auto-encoding fashion.

One crucial problem for transfer-learning is minimizing catastrophic forgetting (Serra et al., 2018). Chen et al. (2021) show that it is possible to combine a pre-trained multilingual model, with finetuining it with one single language pair, to improve zero-shot machine translation. Another way to handle this problem is reducing the number of parameter to be updated. Gheini et al. (2021) propose to only update the cross attention parameters.

### A.6 Unsupervised MT

The addition of other components such as masked LMs and denoising auto-encoding has also been tried (Stojanovski et al., 2019). Unsupervised methods are vulnerable to adversarial attacks of word substitution and order change in the input. Adversarial training can improve performance in such situations (Sun et al., 2020). Since the initialization step is crucial for UMT, Ren et al. (2020) aligns semantically similar sentences from two monolingual corpora with the help of cross-lingual embeddings. With these, an SMT system is trained to warm up an NMT system. However, UMT still has to overcome a set of challenges. Søgaard et al. (2018) shows that performance decays dramatically for languages with different typological features, since, in such situations, bilingual word embeddings (Conneau et al., 2017) are far from isomorphic. Vulić et al. (2020) finds that isomorphism is also less likely if small amounts of monolingual data are used for training bilingual word embeddings. Nooralahzadeh et al. (2020) discovers that performance quickly deteriorates for a mismatch of source and target domain and that the initialization of word embeddings can affect MT performance. All of this makes UMT for LRLs or endangered languages challenging.

Some of the described issues have been addressed: Liu et al. (2019) proposes to combine word-level and subword-level embeddings to account for morphological complexity. For the problem of distant language pairs, Leng et al. (2019) proposes pivoting (cf. §6.3). Isomorphism of bilingual word-embeddings can be improved with semisupervised methods (Vulić et al., 2019). Garcia et al. (2020) introduces multilingual UMT systems. The main idea consists of generalizing UMT by using a multi-way back-translation objective. Recently, pretrained multilingual transformer networks are used to improve UMT even further (cf. §6.4).

## **B** Ethical Considerations

Ethical concerns when working on MT for endangered languages include a lack of community involvement during language documentation, data creation, and development and setup of MT systems. For more information, we refer interested readers to Bird (2020). Finally, we want to mention that publicly employing low-quality MT systems for LRLs bears a risk of translating incorrectly or in biased (e.g., sexist or racist) ways.