# An Approach to Reducing Annotation Costs for BioNLP

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## 1 Introduction

There is a broad range of BioNLP tasks for which active learning (AL) can significantly reduce annotation costs and a specific AL algorithm we have developed is particularly effective in reducing annotation costs for these tasks. We have previously developed an AL algorithm called *ClosestInitPA* that works best with tasks that have the following characteristics: redundancy in training material, burdensome annotation costs, Support Vector Machines (SVMs) work well for the task, and imbalanced datasets (i.e. when set up as a binary classification problem, one class is substantially rarer than the other). Many BioNLP tasks have these characteristics and thus our AL algorithm is a natural approach to apply to BioNLP tasks.

## 2 Active Learning Algorithm

*ClosestInitPA* uses SVMs as its base learner. This fits well with many BioNLP tasks where SVMs deliver high performance (Giuliano et al., 2006; Lee et al., 2004). *ClosestInitPA* is based on the strategy of selecting the points which are closest to the current model's hyperplane (Tong and Koller, 2002) for human annotation. *ClosestInitPA* works best in situations with imbalanced data, which is often the case for BioNLP tasks. For example, in the AIMed dataset annotated with protein-protein interactions, the percentage of pairs of proteins in the same sentence that are annotated as interacting is only 17.6%.

SVMs (Vapnik, 1998) are learning systems that learn linear functions for classification. A statement of the optimization problem solved by softmargin SVMs that enables the use of asymmetric cost factors is the following:

Minimize: 
$$\frac{1}{2} \| \vec{w} \|^2 + C_+ \sum_{i: y_i^{=+1}} \xi_i + C_- \sum_{j: y_j^{=-1}} \xi_j$$
 (1)

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Subject to:  $\forall k : y_k [\vec{w} \cdot \vec{x}_k + b] \ge 1 - \xi_k$  (2) where  $(\vec{w}, b)$  represents the hyperplane that is learned,  $\vec{x}_k$  is the feature vector for example k,  $y_k$ in {+1,-1} is the label for example k,  $\xi_k = \max(0, 1 - y_k [\vec{w} \cdot \vec{x}_k + b])$  is the slack variable for example k, and C<sub>+</sub> and C<sub>-</sub> are user-defined cost factors that trade off separating the data with a large margin and misclassifying training examples.

Let  $PA=C_+/C_-$ . PA stands for "positive amplification." We use this term because as the PA is increased, the importance of positive examples is amplified. *ClosestInitPA* is described in Figure 3. We have previously shown that setting PA based on a small initial set of data outperforms the more obvious approach of using the current labeled data to estimate PA.

Initialization:
• $L =$ small initial set of labeled data
• $U = large pool of unlabeled data$
$PA = \frac{\# \text{ neg examples in } L}{2}$
# pos examples in L
Loop until stopping criterion is met:
1. Train an SVM with parameters $C_+$
and C <sub>-</sub> set such that $C_+/C = PA$ .
2. $batch =$ select k points from U that
are closest to the hyperplane learned
in step 1.
U = U - batch
$L = L \cup batch$

Figure 3. ClosestInitPA algorithm.

We have previously developed a stopping criterion called *staticPredictions* that is based on stopping when we detect that the predictions of our models on some unlabeled data have stabilized. All of the automatic stopping points in our results are determined using *staticPredictions*.

*BioNLP 2008: Current Trends in Biomedical Natural Language Processing*, pages 104–105, Columbus, Ohio, USA, June 2008. ©2008 Association for Computational Linguistics

### **3** Experiments

**Protein-Protein Interaction Extraction**: We used the AImed corpus, which was previously used for training protein interaction extraction systems in (Giuliano et al., 2006). We cast RE as a binary classification task as in (Giuliano et al., 2006).

We do 10-fold cross validation and use what is referred to in (Giuliano et al., 2006) as the  $K_{GC}$  kernel with SVM<sup>light</sup> (Joachims, 1999) in our experiments. Table 1 reports the results.

StoppingPoint	Average # Labels	F Measure	
		Random	AL
20%	1012	48.33	54.34
30%	1516	49.76	54.52
40%	2022	53.11	56.39
100%	5060	57.54	57.54
AutoStopPoint	1562	51.25	55.34

Table 1. AImed Stopping Point Performance. "AutoS-topPoint" is when the stopping criterion says to stop.

**Medline Text Classification**: We use the Ohsumed corpus (Hersh, 1994) and a linear kernel with SVM<sup>light</sup> with binary features for each word that occurs in the training data at least three times. Results for the five largest categories for one versus the rest classification are in Table 2.

StoppingPoint	Average # Labels	F Measure	
		Random	AL
20%	1260	49.99	61.49
30%	1880	54.18	62.72
40%	2500	57.46	63.75
100%	6260	65.75	65.75
AutoStopPoint	1204	47.06	60.73

Table 2. Ohsumed stopping point performance. "AutoS-topPoint" is when the stopping criterion says to stop.

**GENIA NER**: We assume a two-phase model (Lee et al., 2004) where boundary identification of named entities is performed in the first phase and the entities are classified in the second phase. As in the semantic classification evaluation of (Lee et al., 2004), we assume that boundary identification has been performed. We use features based on those from (Lee et al., 2004), a one versus the rest setup and 10-fold cross validation. Tables 3-5 show the results for the three most common types in GENIA.

StoppingPoint	Average # Labels	F Measure	
		Random	AL
20%	13440	86.78	90.16
30%	20120	87.81	90.27
40%	26900	88.55	90.32

100%	67220	90.28	90.28
AutoStopPoint	8720	85.41	89.24

Table 3. Protein stopping points performance. "AutoS-topPoint" is when the stopping criterion says to stop.

StoppingPoint	Average # Labels	F Measure	
		Random	AL
20%	13440	79.85	82.06
30%	20120	80.40	81.98
40%	26900	80.85	81.84
100%	67220	81.68	81.68
AutoStopPoint	7060	78.35	82.29

Table 4. DNA stopping points performance. "AutoStopPoint" is when the stopping criterion says to stop.

StoppingPoint	Average # Labels	F Measure	
		Random	AL
20%	13440	84.01	86.76
30%	20120	84.62	86.63
40%	26900	85.25	86.45
100%	67220	86.08	86.08
AutoStopPoint	4200	81.32	86.31

Table 5. Cell Type stopping points performance. "AutoStopPoint" is when the stopping criterion says to stop.

### 4 Conclusions

*ClosestInitPA* is well suited to many BioNLP tasks. In experiments, the annotation savings are practically significant for extracting protein-protein interactions, classifying Medline text, and performing biomedical named entity recognition.

#### References

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