# **Event-Event Relation Extraction using Probabilistic Box Embedding**

EunJeong Hwang, Jay-Yoon Lee, Tianyi Yang, Dhruvesh Patel, Dongxu Zhang & Andrew McCallum

College of Information and Computer Science, University of Massachusetts Amherst

{ehwang, jaylee, tianyiyang, dhruveshpate, dongxuzhang, mccallum}@cs.umass.edu

#### Abstract

To understand a story with multiple events, it is important to capture the proper relations across these events. However, existing event relation extraction (ERE) frameworks regard it as a multi-class classification task, and do not guarantee any coherence between different relation types. For instance, if a phone line *died* after *storm*, then it is evident that the *storm* happened before the *died*. Current frameworks of event relation extraction do not guarantee this anti-symmetry and thus enforce it via a constraint loss function (Wang et al., 2020). In this work, we propose to modify the underlying ERE model to guarantee coherence by representing each event as a box representation (BERE) without applying explicit constraints. Our experiments show that BERE has stronger conjunctive constraint satisfaction while performing on par or better in terms of  $F_1$  compared to previous models with constraint injection.<sup>1</sup>

# 1 Introduction

A piece of text can contain several events. In order to truly understand this text, it is vital to understand the subevent and temporal relationships between these events.(Mani et al., 2006a; Chambers and Jurafsky, 2008; Yang and Mitchell, 2016; Araki et al., 2014). Both temporal as well as subevent relationships between events satisfy transitivity constraints. For instance, in the paragraph, "There was a storm in Atlanta in the night. All the phone lines were dead the next morning. I was not able to call for help.", the event marked by dead occurs after storm and the event call occurs after dead. Hence, by transitivity, a sensible model should predict that storm occurs before *call*. In general, predicting the relationships between different events in the same document, such that these predictions are coherent, is a challenging task (Xiang and Wang, 2019).

<sup>1</sup>The code is available at https://github.com/ iesl/CE2ERE

While previous works utilizing neural methods provide competitive performances, these works employ multi-class classification per event-pair independently and are not capable of preserving logical constraints among relations, such as asymmetry and transitivity, during training time (Ning et al., 2019; Han et al., 2019a). To address this problem Wang et al. (2020) introduced a constrained learning framework, wherein they enforce logical coherence amongst the predicted event types through extra loss terms. However, since the coherence is enforced in a soft manner using extra loss terms, there is still room for incoherent predictions. In this work, we show that it is possible to induce coherence in a much stronger manner by representing each event using a box (Dasgupta et al., 2020).

We propose a Box Event Relation Extraction (BERE) model that represents each event as a probabilistic box. Box embeddings (Vilnis et al., 2018) were first introduced to embed nodes of hierarchical graphs into Euclidean space using hyperrectangles, which were later extended to jointly embed multi-relational graphs and perform logical queries (Patel et al., 2020; Abboud et al., 2020). In this paper, we represent an event complex using boxes-one box for each event. Such a model enforces logical constraints by design (see Section 3.2). Consider the example in Figure 1. Event *dead*  $(e_2)$  follows event *storm*  $(e_1)$ , indicating  $e_2$  is child of  $e_1$ . Boxes can represent these two events as separate representations and by making  $e_1$  to contain the box  $e_2$ , which not only preserve their semantics, but also can infer its antisymmetric relation that event  $e_1$  is a parent of event  $e_2$ . However, the previous models based on pairwise-event vector representations have no real relation between representations  $(e_1, e_2)$  and  $(e_2, e_1)$  that can guarantee the logical coherence.

Experimental results over three datasets, HiEve, MATRES, and Event StoryLine (ESL), show that our method improves the baseline (Wang et al., 2020) by 6.8 and 4.2  $F_1$  points on single task and by 0.95 and 3.29  $F_1$  points on joint task over symmetrical dataset. Furthermore, our BERE model decreases conjunctive constraint violation rate by 85~88% on a single-task models compared to plain vector model, and by 38% on joint-task model compared to constraint-injected vector model. We show that handling antisymmetric constraints, that exist among different relations, can satisfy the interwined conjunctive constraints and encourage the model towards a coherent output across temporal and subevent tasks.

# 2 Background

Task description Given a document consisting of multiple events  $e_1, e_2, \ldots, e_n$ , we wish to predict the relationship between each event pair  $(e_i, e_j)$ . We denote by  $r(e_i, e_j)$  the relation between event pair  $(e_i, e_j)$ . Its values are defined in the label space {PARENT-CHILD, CHILD-PARENT, COREF, NOREL} for subevent relationship (HiEve) and {BEFORE, AFTER, EQUAL, VAGUE} for temporal relationship (MATRES).<sup>2</sup> Both subevent and temporal relationships have four similar-category relationship labels where the first two labels, (PARENT-CHILD, CHILD-PARENT) and (BEFORE, AFTER) hold reciprocal relationship, the third label (COREF and EQUAL) occurs when it is hard to tell which of the first two labels that event pair should be classified to. Lastly, the last label (NOREL and VAGUE) represents a case when an event pair is not related at all.

**Box embeddings** A box  $b = \prod_{i=1}^{d} [b_{m,i}, b_{M,i}]$ such that  $b \subseteq R^d$  is characterized by its min and max endpoints  $b_m, b_M \in \mathbb{R}^d$ , with  $b_{m,i} < b_{M,i} \forall i$ . In the probabilistic gumbel box, these min and max points are taken to be independent gumbel-max and gumbel-min random variables, respectively. As shown in Dasgupta et al. (2020), if *b* and *c* are two such gumbel boxes then their volume and intersection is given as:

$$\operatorname{Vol}(b) = \prod_{i=1}^{d} \log \left( 1 + \exp \left( \frac{b_{M,i} - b_{m,i}}{\beta} - 2\gamma \right) \right)$$
$$b \cap c = \prod_{i=1}^{d} \left[ l(b_{m,i}, c_{m,i}; \beta), l(b_{M,i}, c_{M,i}; -\beta) \right],$$

where  $l(x, y; \beta) = \beta \log(e^{\frac{x}{\beta}} + e^{\frac{y}{\beta}})$ ,  $\beta$  is the temperature, which is a hyperparameter, and  $\gamma$  is the

Euler-Mascheroni constant.<sup>3</sup>

 $e_i$ ,

**Logical constraints** We define symmetry and conjunction constraints of relations. Symmetry constraints indicate the event pair with flipping orders will have the reversed relation. For example, if  $r(e_i, e_j) = PARENT-CHILD$  (BEFORE), then  $\tilde{r}(e_j, e_i) = CHILD-PARENT$  (AFTER). Given any two events,  $e_i$  and  $e_j$ , the symmetry consistency is defined as follows:

$$\bigwedge_{e_j \in \mathcal{E}, r \in \mathcal{R}_S} r(e_i, e_j) \leftrightarrow \tilde{r}(e_j, e_i) \tag{1}$$

where r is the relation between events, the  $\mathcal{E}$  is the set of all possible events and the  $\mathcal{R}_{\mathcal{S}}$  is the set of relations, in which symmetry constraints hold.

Conjunctive constraints refer to the constraints that exist in the relations among any event triplet. The conjunctive constraint rules indicate that given any three event pairs,  $(e_i, e_j)$ ,  $(e_j, e_k)$ , and  $(e_i, e_k)$ , then the relation of  $(e_i, e_k)$  has to fall into the conjunction set specified based on  $(e_i, e_j)$  and  $(e_j, e_k)$ pairs (see Appendix Table 6). The conjunctive consistency can be defined as:

$$\bigwedge_{\substack{e_i, e_j, e_k \in \mathcal{E} \\ r_1, r_2 \in \mathcal{R}, r_3 \in \mathcal{D}(r_1, r_2)}} r_1(e_i, e_j) \wedge r_2(e_j, e_k) \to r_3(e_i, e_k) \\ \bigwedge_{\substack{e_i, e_j, e_k \in \mathcal{E} \\ r_1, r_2 \in \mathcal{R}, r'_3 \notin \mathcal{D}(r_1, r_2)}} r_1(e_i, e_j) \wedge r_2(e_j, e_k) \to \neg r'_3(e_i, e_k)$$

where the  $\mathcal{E}$  is the set of all possible events,  $r_1$  and  $r_2$  are any possible relations exist in the set of all relations  $\mathcal{R}$ ,  $r_3$  is the relation, which is specified by  $r_1$  and  $r_2$  based on conjunctive induction table, and  $\mathcal{D}$  is the set of all possible relations, in which  $r_1$  and  $r_2$  have no conflicts in between. The full explanation on symmetry and conjunction consistency can be found in Wang et al. (2020).

# **3** BERE model

In this section, we present the proposed box model BERE for event-event relation extraction. As depicted in Figure 1, the proposed model encodes each event  $e_i$  as a box  $b_i$  in  $\mathbb{R}^d$  based on  $e_i$ 's contextualized vector representation  $h_i$ . As described in §3.1, the relation between  $(e_i, e_j)$  is then predicted using conditional probability scores  $P(b_i|b_j) = \text{Vol}(b_i \cap b_j)/\text{Vol}(b_j), P(b_j|b_i) =$  $\text{Vol}(b_i \cap b_j)/\text{Vol}(b_i)$  defined on box space. Lastly, §3.2 describes loss function used to learn the parameters of the model.

<sup>&</sup>lt;sup>2</sup>See Experimental Setup 4.1 for the detailed information of HiEve and Matres.

<sup>&</sup>lt;sup>3</sup>https://en.wikipedia.org/wiki/Euler% 27s\_constant



Figure 1: (A) BOX model architecture. (B) Mapping from box positions to event relations with classification rule below. (C) An example shows the fundamental difference between VECTOR and BOX model: BOX model will map events into consistent box representations regardless of the order; VECTOR model treats both cases separately and may not persist logical consistency.

#### **3.1** Inference rule on conditional probability

Notice that given two boxes  $b_i$  and  $b_j$ , a higher value of  $P(b_i|b_j)$  (resp.  $P(b_j|b_i)$ ) implies that box  $b_j$  is contained in  $b_i$  (resp.  $b_i$  contained in  $b_j$ ). Moreover, other than complete containment in either direction, there are other two prominent configurations possible, i.e. one where  $b_i$ ,  $b_j$  overlap but none contains the other, and the one where  $b_i$ ,  $b_j$  do not overlap. It is possible to capture all four configurations by comparing the values of  $P(b_i|b_j)$  and  $P(b_j|b_i)$  with a threshold  $\delta$ . Figure 1(B) states our classification rule formulated based on this observation. With this formulation we have the desired symmetry constraint, i.e.,  $r(e_i, e_j) = PARENT-CHILD \iff r(e_j, e_i) =$ CHILD-PARENT, satisfied by design.

# 3.2 Loss functions for training

**BCE loss** As we require two dimensions of scalar  $P(b_i|b_j)$  and  $P(b_j|b_i)$  to classify  $r(e_i, e_j)$ , and for ease of notation, we define our label space with 2-dimensional binary variable  $y^{(i,j)}$  as shown in Figure 1(b). Where  $y_0^{(i,j)} = I(P(b_i|b_j) \ge \delta)$  and  $y_1^{(i,j)} = I(P(b_j|b_i) \ge \delta)$  where  $I(\cdot)$  stands for indicator function. Now given batch *B*, BCE loss (L<sub>1</sub>) is defined as:

$$-\sum_{(i,j)\in B} y_0^{(i,j)} \ln P(b_i|b_j) + (1 - y_0^{(i,j)}) \ln (1 - P(b_i|b_j)) + y_1^{(i,j)} \ln P(b_j|b_i) + (1 - y_1^{(i,j)}) \ln (1 - P(b_j|b_i)).$$

**Pairwise loss** Motivated from previous papers using pairwise features to characterize relations, we also incorporate a pairwise box into our learning objective, and only in learning time, to encourage relevant boxes to be concentrated together. For the event-pair representation, two contextualized event embeddings  $(h_i, h_j)$  are combined as  $[h_i, h_j, h_i \odot h_j]$  where  $\odot$  represents elementwise multiplication. Then, a multi-layer perceptron (MLP) is used to transform pairwise vectors to box representations  $b_{ij}$ . The pairwise features we use here are similar to (Zhou et al., 2020) except that we do not use subtraction in order to preserve symmetry between pairwise features of  $(e_i, e_j)$  and  $(e_j, e_i)$ , i.e.  $b_{ij} = b_{ji}$ . For two related events, we enforce the intersection of corresponding boxes  $b_i \cap b_j$  to be inside the pairwise box. For irrelevant event pairs such as having NOREL or VAGUE, their intersection and pairwise boxes are forced to be disjoint. The pairwise loss  $L_2$  is defined as:

$$-\sum_{i,j\in R^+} \log P(b_i \cap b_j | b_{ij}) - \sum_{i,j\in R^-} \log \left(1 - P(b_i \cap b_j | b_{ij})\right)$$

where  $R^-$  is a set of irrelevant relations, such as NOREL and VAGUE, and  $R^+$  stands for complement set of  $R^-$ , i.e. all the set of relations that indicates two events have some relation.

In the remainder of the paper, BERE refers to a model trained with loss  $L_1$  and BERE-p refers to a model trained with two losses  $L_1, L_2$  combined.

## 4 Experiments

In this section, we describe datasets, baseline methods, and evaluation metrics. Lastly, we provide experimental results and a detailed analysis of logical consistency.

### 4.1 Experimental Setup

**Datasets** Experiments are conducted over three asymmetrical event relation extraction corpus,

Table 1: An overview of dataset statistics.

	HiEve	MATRES	ESL					
	# of Documents							
Train	80	183	155					
Dev	-	72	51					
Test	20	20	52					
	# o	f Pairs						
Train	35001	6332	2238					
Test	7093	827	619					
# of Pairs for Symmetrical Dataset								
Test	8693	1493	1222					

Table 2: Mapped relation labels from ESL to HiEve

Original labels in ESL	Mapped Labels
RISING_ACTION	
CONTAINS	
BEFORE	PARENT-CHILD
PRECONDITION	
ENDED_ON	
FALLING_ACTION	
AFTER	CIULD DADENT
BEGUN_ON	CHILD-FARENT
CAUSE	
OVERLAP	NOREL

HiEve (Glavaš and Šnajder, 2014), MATRES (Ning et al., 2018), and Event StoryLine (ESL) (Caselli and Vossen, 2017). Table 1 shows a brief summary of dataset statistics. HiEve consists of 100 articles and the narratives in news stories are represented as event hierarchies. The annotations include subevent and coreference relations. MATRES is a four-class temporal relation dataset, which contains 275 news articles drawn from a number of different sources. Event StoryLine (ESL) corpus is a dataset that contains 258 news documents and includes event temporal and subevent relations. The ESL dataset is defined differently compared to HiEve and MATRES, so we mapped the ESL labels into the labels in HiEve similar to (Wang et al., 2020) as shown in Table 2.

For creating symmetrical dataset, we augment PARENT-CHILD and CHILD-PARENT (BEFORE and AFTER) pairs by their reversed relations CHILD-PARENT and PARENT-CHILD (AFTER and BEFORE), respectively.

**Baseline** We compare our BERE, BERE-p against the state-of-the-art event-event relation ex-

Table 3:  $F_1$  scores of BERE and BERE-p

Model	$F_1$ Score					
widder	HiEve	MATRES				
BERE	0.4483	0.7069				
BERE-p	0.4771	0.7105				

traction model proposed by (Wang et al., 2020). This model utilizes RoBERTa with frozen parameters and further trains BiLSTM to represent text inputs into vector  $h_i$  (for  $e_i$ ) and then further utilizes MLP to represent pairwise representation  $v_{ij}$  for  $(e_i, e_j)$ . Given  $v_{ij}$ , vector model (Vector) simply computes softmax over projected logits to produce probability for every possible relations. On top of this, as (Wang et al., 2020) showed that constraint injection improves performance, we also compare with the constraint-injected model (Vector-c).

For a fair comparison, we utilize the same RoBERTa + BiLSTM + MLP architecture for projecting event to box representation.

**Metrics** Following the same evaluation setting in previous works, we report the micro- $F_1$  score of all pairs, except VAGUE pairs, on MATRES (Han et al., 2019b; Wang et al., 2020). On HiEve and ESL, the micro- $F_1$  score of PARENT-CHILD and CHILD-PARENT pairs is reported (Glavaš and Šnajder, 2014; Wang et al., 2020).

# 4.2 Results and Discussion

**Impact of pairwise box, Table 3** We first show the results of the BERE and BERE-p with and without pairwise loss. The model with pairwise loss shows about 2.8  $F_1$  point improvement on HiEve and 1  $F_1$  point improvement on MATRES. It indicates that promoting the relevant event pairs to mingle together in the geometrical space is helpful and it is particularly useful when most of the relation extraction model encodes individual sentences independently.

Vector-based vs. Box-based, Table 4 Table 4 shows a comparison of our box approach to the baseline with the ratio of symmetric and conjunctive constraint violations. Our approach clearly outperforms the baseline methods on symmetric evaluation with a gain of 6.79, 4.26, and 9.34  $F_1$ points on the single task over HiEve, MATRES, and ESL datasets, respectively and with a gain of 0.95 and 3.29  $F_1$  points on the joint task over HiEve and MATRES. The performance gains from asymmetrical to symmetrical datasets with BERE-p are much larger compared to the increase of Vectors. This demonstrates the BERE-p successfully captures symmetrical relations, while previous vector models do not. In addition, it is noteworthy that our method without constrained learning excels Vector-c, which is trained with constrained learning. This suggests that the inherent ability to

Table 4:  $F_1$  scores with symmetric and conjunctive constraint violation results over original and symmetrical datasets. symm const. and conj const. denote symmetric and conjunctive constraint violations (%), respectively; H, M, and ESL are HiEve, MATRES, Event StoryLine datasets, respectively; single task (top) and joint task (bottom)

	$F_1$ Score						symmetry const.			conjunctive const		const.
Model	C	riginal da	ta			ymmetric evaluation						
	Н	М	ESL	Н	M	ESL	Н	М	ESL	Н	M	ESL
Vector	0.4437	0.7274	0.2660	0.5385	0.7288	0.4444	22.49	35.81	60.9	4.91	2.53	6.1
BERE-p	0.4771	0.7105	0.3214	0.6064	0.7714	0.5379	0	0	0	0.71	0.30	0
	Joint model (H&M)							Joint eval (H&M) Joint eval (H&M)				
Vector	0.4727	0.7291		0.5517	7 0.7405		24.08		6		17	
Vector-c	0.5262	0.7068	n/a	0.6166	0.7106	n/a	28.	.83	n/a	2.98		n/a
BERE-p	0.5053	0.7125		0.6261	0.7734			0		1.	84	

Table 5: Symmetric evaluation of Vector\* (Vector trained with reciprocal dataset) and BERE-p trained with original dataset on joint task. s-const. and c-const. denote symmetric and conjunctive constraint violations (%), respectively

Model	$F_1$ Score						
	HiEve	MATRES	s-const.	c-const.			
Vector*	0.6120	0.7720	12.01	6.70			
BERE-p	0.6261	0.7734	0	1.84			

model symmetrical relations helps satisfy the intertwined conjunctive constraints, thus producing more coherent results from a model. See Appendix E for constraint violation statistics for asymmetric dataset.

**Constraint Violation Analysis, Table 8 (Appendix)** We analyze constraint violations for each label from both HiEve and MATRES. For label pairs from the same dataset, our approach excels in almost every cases. For label pairs across datasets, our approach also shows fewer or similar levels of violation. This further indicates, without explicitly injecting constraints into objectives, our model can persist logical consistency among different relations.

# 5 Ablation Study

We conduct additional experiments to see whether Vector trained with the augmented symmetrical dataset will affect the conclusion of BERE-p. The results in Table 5 reconfirm the BERE-p's superior ability in handling constraints with better performance, while Vector requires significantly longer training time due to the extended training dataset with worse performance. We also note that training Vector with the augmented symmetrical dataset does not help with conjunctive constraint violations ( $6.17 \rightarrow 6.70$ ), although it reduces symmetrical constraint violations ( $24.08 \rightarrow 12.01$ ).

# 6 Conclusion

We propose a novel event relation extraction method that utilizes box representation. The proposed method projects each event to a box representation which can model asymmetric relationships between entities. Utilizing this box representation, we design our relation extraction model to handle antisymmetry between events of  $(e_i, e_j)$  and  $(e_i, e_i)$  which previous vector models were not capable of. Through experiments on three datasets, we show that the proposed method not only free of antisymmetric constraint violations but also have drastically lower conjunctive constraint violations while maintaining similar or better performance in  $F_1$ . Our model shows that box representation can provide coherent classification across multiple event relations and opens up future research for box representations in event-to-event relation classification.

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# **A** Hyperparameters

We utilize 768 dimensional pretrained RoBERTa model to compute word embeddings for events. models are trained for 100 epochs with AMSGrad optimizer and the learning rate is set to be 0.001. On HiEve and ESL, we sample NOREL in trainset using downsample ratio, which is fixed to 0.015, and the downsample ratio for valid and test sets is fixed to 0.4. This is to encourage the models to learn and evaluate all types of relations that exist in the datasets when NOREL overwhelmingly represents the dataset. We use three weights,  $\lambda_1, \lambda_2$ , and  $\lambda_3$ , to balance our three learning objectives  $L_1$ ,  $L_2$ , and  $L_3$  (see Section 3.2 and Appendix B), in which the weights are selected between 0.1 and 1. A threshold  $\delta$  for HiEve is selected between -0.4 and -0.3 and a threshold for MATRES is chosen between -0.7 and -0.6. We use wandb (Biewald, 2020) tool for efficient hyperparameter tuning.

# **B** Conjunctive Consistency Loss

With consistency requirements on conjunctive relations over temporal and subevent datasets (as shown in Table 6), we incorporate the loss function introduced by (Wang et al., 2020) into our box model to handle conjunctive constraints. Three events are grouped into three pairs, (e1, e2), (e2, e3) and (e1, e3), and the relation score for each class is calculated based on conditional probabilities and its binary logits. With the relation labels defined for each class (see Section 3.2), the relation score,  $r(e_1, e_2)$ , is calculated as:

$$r_i = y_0^{(i,j)} \log P(b_i|b_j) + y_1^{(i,j)} \log P(b_j|b_i)$$
 (2)

where  $y_0^{(i,j)} = I(P(b_i|b_j) \ge \delta)$  and  $y_1^{(i,j)} = I(P(b_j|b_i) \ge \delta)$  and  $y_0^{(i,j)}$  and  $y_1^{(i,j)}$  are the first and second binary logits in relation label, respectively. Using this relation score, we now define the loss function for modeling conjunction constraints:

$$L_3 = \sum |L_{t1}| + \sum |L_{t2}|, \tag{3}$$

where the two transitivity losses are defined as

$$L_{t1} = \log r_{(e1,e2)} + \log r_{(e2,e3)} + \log r_{(e1,e3)}$$
$$L_{t2} = \log r_{(e1,e2)} + \log r_{(e2,e3)} + \log(1 - r_{(e1,e3)})$$

Table 7 presents the results of BERE-p combined with the above learning objective, denoted as BERE-c. Compared to the results from BERE-p, BERE-c shows a significantly smaller ratio of constraint violations than BERE-p, while sacrificing  $F_1$  by  $\sim 2$  point from the performance with BERE-p.

# C Vector model architecture

Refer to Figure 2 for architecture of previous vector models.



Figure 2: VECTOR model architecture.

# D Detailed analysis on conjunctive constraint violation

Constraint Violation Analysis, Table 8 We further break down constraint violations for each label on HiEve and MATRES. The comparison of constraint violations between the vector model with constrained learning (Vector-c) and the box model without constrained learning (BERE-p) is shown in Table 8. "n/a" refers to no predictions and this frequently appears on COREF and EQUAL due to their sparsity in the corpus. Our approach shows a smaller ratio of constraint violations in most of the categories, with only a few exceptions. 2nd and 3rd quadrants (HiEve->MATRES and MATRES HiEve) stand for cross-category, while 1st and 4th quadrants (HiEve > HiEve and MATRES-MATRES) stand for the samecategory. Interestingly, our approach without any injected constraints shows a smaller or similar ratio to Vector-c in the cross-category as well as in the same-category. We calculated  $r_c$  = total # of cross-category const-violations and total # of cross-category event triplets

 $r_s = \frac{\text{total # of same-category const-violations}}{\text{total # of same-category event triplets}}$ , where const-violations refers to constraint violations.  $r_c$  for Vector-c is 6.26% and for BERE-p is 4.55% and  $r_s$  for Vector-c is 0.05% and for BERE-p is 0.017%. This confirms the

Table 6: The induction table for conjunctive constraints on temporal and subevent relations (Wang et al., 2020). Given three events,  $e_1$ ,  $e_2$ , and  $e_3$ , the left-most column is  $r_1(e_1, e_2)$  and the top row is  $r_2(e_2, e_3)$ .

	PC	CP	CR	NR	BF	AF	EQ	VG
PC	PC, -AF	-	PC, -AF	-CP, -CR	BF, -CP, -CR	-	BF, -CP, -CR	-
CP	-	CP, -BF	CP, -BF	-PC, -CR	-	AF, -PC, -CR	AF, -PC, -CR	-
CR	PC, -AF	CP, -BF	CR, EQ	NR	BF, -CP, -CR	AF, -PC, -CR	EQ	VG
NR	-CP, -CR	-PC, -CR	NR	-	-	-	-	-
BF	BF, -CP, -CR	-	BF, -CP, -CR	-	BF, -CP, -CR	-	BF,CP,CR	-AF, -EQ
AF	-	AF, -PC, -CR	AF, -PC, -CR	-	-	AF, -PC, -CR	AF, -PC, -CR	-BF, -EQ
EQ	-AF	-BF	EQ	-	BF, -CP, -CR	AF, -PC, -CR	EQ	VG, -CR
VG	-	-	VG, -CR	-	-AF, -EQ	-BF, -EQ	VG	-

Table 7:  $F_1$  scores and the ratio of symmetric and conjunctive constraint violations of box model with constrained learning over Eval-A and Eval-S; Eval-A and Eval-S denote asymmetrical and symmetrical evaluation datasets, respectively. const. means constraint violations; results are on joint task.

		$F_1$ S	core		symmetry	const. (%)	conjunctive const. (%)		
Model	Εv	al-A	Eval-S		Fval-A	Fwal-S	Evol-A	Evole	
	HiEve	MATRES	HiEve	MATRES	LVAL A	LVAL 5		LVAL D	
BERE-p	0.5053	0.7125	0.6261	0.7734	0	0	3.12	1.84	
BERE-c	0.5083	0.7021	0.6183	0.7562	0	0	0.39	0.19	

Table 8: Constraint violation analysis over HiEve and MATRES. See Appendix B for conjunctive consistency requirements; PARENT-CHILD (PC), CHILD-PARENT (CP), COREF (CR), NOREL (NR), BEFORE (BF), AFTER (AF), EQUAL (EQ), VAGUE (VG); "-" means no existing constraint violations; constraint injected vector model (top), box model with using pairwise loss (bottom).

Vector-c										
	PC	СР	CR	NR	BF	AF	EQ	VG		
PC	0.05	-	0.13	0.02	0.20	-	0.5	-		
СР	-	0.33	0.46	0.01	-	0.25	n/a	-		
CR	0.12	0.42	0.68	0.08	0.19	0.43	n/a	0.27		
NR	0.01	0.03	0.13	-	-	-	-	-		
BF	0.23	-	0.41	-	0.12	-	0.42	0.02		
AF	-	0.33	0.30	-	-	0.01	0.13	0.05		
EQ	0.00	0.50	n/a	-	0.25	0.00	n/a	0.50		
VG	-	-	0.34	-	0.03	0.02	n/a	-		
				BERE-p						
	PC	СР	CR	NR	BF	AF	EQ	VG		
PC	0.13	-	n/a	0.00	0.16	-	0.30	-		
СР	-	0.23	n/a	0	-	0.28	0.34	-		
CR	n/a	n/a	n/a	n/a	n/a	n/a	n/a	n/a		
NR	0.00	0.00	n/a	-	-	-	-	-		
BF	0.24	-	n/a	-	0.08	-	0.32	0.00		
AF	-	0.17	n/a	-	-	0.05	0.12	0.00		
EQ	0.23	0.29	n/a	-	0.15	0.18	n/a	0.00		
VG	-	-	n/a	-	0.00	0.00	0.13	-		

effectiveness of having boxes in handling logical consistency among different relations.

# E Symmetric and conjunctive constraint violations over origianl data

Table 9 shows the  $F_1$  and symmetry and conjunctive constraint violation results over original dataset. The results of symmetry and conjunctive constraint violations confirm our expectation and exhibit a similar observation from Table 4.

### F Related Work

### F.1 Event-Event Relation Extraction

This task has been traditionally modeled as a pairwise classification task with hand-engineered features and early attempts applied conventional machine learning methods, such as logistic regressions and SVM (Mani et al., 2006b; Verhagen et al., 2007; Verhagen and Pustejovsky, 2008). Later works utilized a structured learning (Ning et al., 2017) and neural methods to characterize relations. The neural methods have been shown effective and ensure logical consistency on relations through inference step (Dligach et al., 2017; Ning et al., 2018, 2019; Han et al., 2019a). More recent works proposed a constrained learning framework, which facilitates constraints during training time (Han et al., 2019b; Wang et al., 2020). Motivated by these works, we propose a box model to automatically handle inherent constraints without heavily relying on constrained learning across two different tasks.

## F.2 Box Embeddings

Box embeddings (Vilnis et al., 2018) were introduced as a shallow model to embed nodes of hierarchical graphs into euclidean space using hyperrectangles, which were later extended to jointly embed multi-relational graphs and perform logical queries (Patel et al., 2020; Abboud et al., 2020). Recent works have successfully used box representations in conjunction with neural networks to represent input text for tasks like entity typing (Onoe et al., 2021), multi-label classification (Patel et al., 2022), natural language entailment (Chheda et al., 2021), etc. In all these works, the input is repTable 9:  $F_1$  scores with symmetric and conjunctive constraint violation results over original datasets. symm const. and conj const. denote symmetric and conjunctive constraint violations, respectively; H, M, and ESL are HiEve, MATRES, Event StoryLine datasets, respectively; single task(top) and joint task(bottom)

	F1 Score			symmetry const. (%)			conjunctive const.(%)		
Model	Original data								
	Н	М	ESL	Н	M	ESL	Н	М	ESL
Vector	0.4437	0.7274	0.2660	22.73	38.63	56.7	5.66	0.69	9.4
BERE-p	0.4771	0.7105	0.3214	0	0	0	0.75	0.46	0
Joint				H+M			H+M		
Vector	0.4727	0.7291		23.04 23.83			10.85		
Vector-c	0.5262	0.7068	n/a			83 n/a		3.52	
BERE-p	0.5053	0.7125		0			3.	12	

resented using a single box by transforming the output of the neural network into a hyper-rectangle. In this paper, we take this a step forward by representing the input event complex using multiple boxes. Our single box model represents each even in an input paragraph using a box and the pairwise box model adds on top of these, one box each for every pair of events (see section 3.2).