## Policy Gradient as a Proxy for Dynamic Oracles in Constituency Parsing



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#### Parsing by Local Decisions



#### **Non-local Consequences**

#### **Loss-Evaluation Mismatch**



 $\Delta(y, \hat{y})$ : -F1 $(y, \hat{y})$ 

Exposure Bias

True<br/>Parsey $(S \rightarrow (NP \rightarrow The \rightarrow cat \rightarrow ...)$ Prediction $\hat{y}$  $(S \rightarrow (NP \rightarrow (VP \rightarrow ??))$ 

[Ranzato et al. 2016; Wiseman and Rush 2016]

### **Dynamic Oracle Training**

Explore at training time. Supervise each state with an expert policy.

True Parse 
$$y$$
 (S  $\rightarrow$  (NP  $\rightarrow$  The  $\rightarrow$  cat  $\rightarrow$  ...  
addresses  
exposure  
bias  $\begin{cases}
Prediction \\
(sample, or greedy) \\
Oracle \\
y^*
\end{cases}$  (S  $\rightarrow$  (NP  $\rightarrow$  (VP  $\rightarrow$  The  $\rightarrow$  ...  
(NP  $\rightarrow$  The  $\rightarrow$  ...  
The cat  
 $L(\theta) = \sum_{t} \log p(y_t^* | \hat{y}_{1:t-1}, x; \theta)$  choose  $y_t^*$  to maximize  
addresses  
achievable F1 (typically)  $\begin{cases}
addresses \\
loss \\
mismatch
\end{cases}$ 

[Goldberg & Nivre 2012; Ballesteros et al. 2016; inter alia]



#### **Expert Policies / Dynamic Oracles**

Daume III et al., 2009; Ross et al., 2011; Choi and Palmer, 2011; Goldberg and Nivre, 2012; Chang et al., 2015; Ballesteros et al., 2016; Stern et al. 2017

mostly - dependency parsing

#### **PTB Constituency Parsing F1**

System	Static Oracle	Dynamic Oracle
Coavoux and Crabbé, 2016	88.6	89.0
Cross and Huang, 2016	91.0	91.3
Fernández-González and Gómez-Rodríguez, 2018	91.5	91.7

# What if we don't have a dynamic oracle? Use reinforcement learning





## **Policy Gradient Training**

Minimize expected sequence-level cost:

$$R(\theta) = \sum_{\hat{y}} p(\hat{y}|x;\theta) \Delta(y,\hat{y})$$
  

$$\overline{VR}(\theta) = \sum_{\hat{y}} p(\hat{y}|x;\theta) \Delta(y,\hat{y}) \nabla \log p(\hat{y}|x;\theta)$$
  

$$\frac{\Delta(y,\hat{y})}{\varphi}$$
  

$$\overline{VR}(\theta) = \sum_{\hat{y}} p(\hat{y}|x;\theta) \Delta(y,\hat{y}) \nabla \log p(\hat{y}|x;\theta)$$
  

$$\frac{\Delta(y,\hat{y})}{\varphi}$$
  

$$\frac{\varphi}{\varphi}$$
  

$$\frac{\varphi}{\varphi$$

[Williams, 1992]

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## **Policy Gradient Training**

$$\nabla R(\theta) = \sum_{\hat{y}} p(\hat{y}|x;\theta) \,\Delta(y,\hat{y}) \,\nabla \log p(\hat{y}|x;\theta)$$

Input, x The cat took a nap.



## Experiments



Setup

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#### **Parsers**

Span-Based [Cross & Huang, 2016] Top-Down [Stern et al. 2016] RNNG [Dyer et al. 2016] In-Order [Liu and Zhang, 2017]

#### Training

Static oracle Dynamic oracle Policy gradient

### English PTB F1



## **Training Efficiency**

#### PTB learning curves for the Top-Down parser









- Local decisions can have non-local consequences
  - Loss mismatch
  - Exposure bias
- How to deal with the issues caused by local decisions?
  - Dynamic oracles: efficient, model specific
  - Policy gradient: slower to train, but general purpose

Thank you!

