Bandit Structured Prediction for Neural Seq2Seq Learning

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Bandit Structured Prediction

Algorithm 1 Bandit Structured Prediction Input: Sequence of learning rates γ_k Output: Optimal parameters $\hat{\theta}$ Initialize parameters θ_0 for k = 0, ..., K do

Observe input structure \mathbf{x}_k Sample output structure $\tilde{\mathbf{y}}_k \sim p_{\theta}(\mathbf{y}|\mathbf{x}_k)$ Obtain feedback $\Delta(\tilde{\mathbf{y}}_k)$ Compute stochastic gradient s_k Update parameters $\theta_{k+1} = \theta_k - \gamma_k s_k$ Choose a solution $\hat{\theta}$ from the list $\{\theta_0, \dots, \theta_K\}$

Bandit Seq2Seq

Bandit structured prediction [1] is a stochastic optimization framework where learning is performed from **partial feedback**. This feedback is received in the form of task loss evaluation of a predicted output structure, without having access to gold standard structures.

In this work, we advance the framework by

Results

BLEU on held-out in- and out-of-domain test sets for parameters $\hat{\theta}$ selected by **early stopping** on a validation set.

We seek models for **conservative domain adaptation**, that learn to improve on in-domain, but maintain quality on out-of-domain translations.

Objectives

Expected Loss (EL):

Expectation of a task loss $\Delta(\mathbf{\tilde{y}})$ over all input and output structures:

 $L^{\mathsf{EL}}(\theta) = \mathbb{E}_{p(\mathbf{x}) p_{\theta}(\tilde{\mathbf{y}}|\mathbf{x})} [\Delta(\tilde{\mathbf{y}})].$

Stochastic gradient:

$$s_k^{\mathsf{EL}} = \Delta(\mathbf{\tilde{y}}) \frac{\partial \log p_{\theta}(\mathbf{\tilde{y}}|\mathbf{x}_k)}{\partial \theta}$$

Output structures $\tilde{\mathbf{y}}$ are sampled word by word from the distribution resulting from the softmax transformation in the output layer of

lifting linear bandits to neural seq2seq
 learning using attention-based RNNs, and
 incorporating control variates for variance reduction and improved generalization.

Experiments for **neural machine translation** show large improvements for domain adaptation from simulated bandit feedback.

Control Variates

Augment a random variable X (here: $X = s_k$) by another random variable Y, the control variate. With $\overline{Y} = \mathbb{E}[Y]$, $X - \hat{c}Y + \hat{c}\overline{Y}$ is an unbiased estimator of $\mathbb{E}[X]$. Control variates with high Cov(X, Y) reduce the variance of the gradient estimate. Two choices here:





the network.

Pairwise Preference Ranking (PR):

Transfer EL to **pairs of structures** $\langle \tilde{\mathbf{y}}_i, \tilde{\mathbf{y}}_j \rangle$: $L^{\mathsf{PR}}(\theta) = \mathbb{E}_{p(\mathbf{x}) p_{\theta}(\langle \tilde{\mathbf{y}}_i, \tilde{\mathbf{y}}_j \rangle | \mathbf{x})} [\Delta(\langle \tilde{\mathbf{y}}_i, \tilde{\mathbf{y}}_j \rangle)].$

Stochastic gradient:

$$s_{k}^{\mathsf{PR}} = \Delta(\langle \tilde{\mathbf{y}}_{i}, \tilde{\mathbf{y}}_{j} \rangle) \\ \times \left(\frac{\partial \log p_{\theta}(\tilde{\mathbf{y}}_{i} | \mathbf{x}_{k})}{\partial \theta} + \frac{\partial \log p_{\theta}^{-}(\tilde{\mathbf{y}}_{j} | \mathbf{x}_{k})}{\partial \theta} \right).$$

Learn to rank $\tilde{\mathbf{y}}_i$ over $\tilde{\mathbf{y}}_j$ with **pairwise** feedback, either continuous (cont) $\Delta(\langle \mathbf{y}_i, \mathbf{y}_j \rangle) = \Delta(\mathbf{y}_j) - \Delta(\mathbf{y}_i),$ or binary (bin)

 $\Delta(\langle \mathbf{y}_i, \mathbf{y}_j \rangle) = \begin{cases} 1 & \text{if } \Delta(\mathbf{y}_j) > \Delta(\mathbf{y}_i), \\ 0 & \text{otherwise.} \end{cases}$

1 Baseline (BL) [2]: $Y_{k} = \nabla \log p_{\theta}(\tilde{\mathbf{y}} | \mathbf{x}_{k}) \frac{1}{k} \sum_{j=1}^{k} \Delta(\tilde{\mathbf{y}}_{j}).$ 2 Score Function (SF) [3]: $Y_{k} = \nabla \log p_{\theta}(\tilde{\mathbf{y}} | \mathbf{x}_{k}).$

Experiments

Neural machine translation **domain adaptation**:

- Adapt a pre-trained model (Europarl, fr-en) to new domains (News Commentary and TED).
- Simulated feedback with GLEU on references
- Encoder-decoder architecture with attention
- Full-information baselines: maximum likelihood estimation on reference translations



Findings

Successful training of NMT with weak feedback

- Large improvements for domain adaptation, outperforming linear models
- ► Control variates improve generalization, see [6]

Draw **negative sample** $\tilde{\mathbf{y}}_j$ from distribution p_{θ}^- , one word per output structure (chosen randomly):



Strategies for handling of unknown words:
attention-based replacement of UNKs for word-based models [4]
sub-word models with Byte-Pair-Encoding (BPE) [5]

Acknowledgements

This research was supported in part by the German research foundation (DFG), and in part by a research cooperation grant with the Amazon Development Center Germany.





References

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