VI-OOD: A Unified Representation Learning Framework for Textual Out-of-distribution Detection

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Abstract

Out-of-distribution (OOD) detection plays a crucial role in ensuring the safety and reliability of deep neural networks in various applications. While there has been a growing focus on OOD detection in visual data, the field of textual OOD detection has received less attention. Only a few attempts have been made to directly apply general OOD detection methods to natural language processing (NLP) tasks, without adequately considering the characteristics of textual data. In this paper, we delve into textual OOD detection with Transformers. We first identify a key problem prevalent in existing OOD detection methods: the biased representation learned through the maximization of the conditional likelihood p(y|x) can potentially result in subpar performance. We then propose a novel variational inference framework for OOD detection (VI-OOD), which maximizes the likelihood of the joint distribution p(x, y) instead of p(y|x). VI-OOD is tailored for textual OOD detection by efficiently exploiting the representations of pre-trained Transformers. Through comprehensive experiments on various text classification tasks, VI-OOD demonstrates its effectiveness and wide applicability. Our code has been released at https://github.com/liam0949/LLM-OOD.

1. Introduction

Large-scale deep neural networks (DNNs) such as CNNs and Transformers, have brought about a revolutionary impact on numerous complex real-world machine learning applications. Nevertheless, a notable drawback of DNNs remains their tendency to make overconfident decisions, rendering them less reliable for safety-critical applications like medical diagnosis (Ulmer et al., 2020) and self-driving cars (Filos et al., 2020). It has been noted that DNNs often assign elevated confidence scores to unfamiliar inputs, leading to potential erroneous predictions when confronted with anomalous outof-distribution (OOD) data (Nguyen et al., 2015). To address this issue, there has been active research and investigation into OOD detection in recent years (Hendrycks et al., 2022; Yang et al., 2022).

Challenge of OOD detection. OOD detection aims at solving a *K*-class in-distribution (ID) classification task and a binary ID *vs.* OOD discrimination task simultaneously. A commonly assumed practical setting is OOD examples are unavailable during training, which presents the major challenge for OOD detection. The mainstream methods for OOD detection commonly follow a post-hoc scheme (Hendrycks and Gimpel, 2017), which first discriminatively trains an ID *K*-class classifier by maximizing the conditional likelihood of p(y|x) and then derives some statistics from the trained model to predictive OOD confidence scores. However, since the binary ID *vs.* OOD discrimination task is not considered in the training process, the learned representations by *K*-class training may be biased to the ID classes. While some attempts have been made to address this challenge by incorporating surrogate OOD datasets during the training phase, such as those described in the works by Hendrycks et al. (2019) and Lee et al. (2018a), further endeavors are required to identify appropriate OOD datasets that demonstrate significant distributional shifts compared to the ID data.

Research on textual OOD detection. The majority of recent research efforts have concentrated on detecting OOD data in visual domains, with only a limited number of studies (Hendrycks et al., 2020; Podolskiy et al., 2021a; Zhou et al., 2021a) focusing on textual OOD detection. As far as our knowledge extends, current textual OOD detection methods typically utilize general OOD detection algorithms on representations generated by Transformers (Vaswani et al., 2017). However, these methods often fail to adequately account for the unique characteristics and nuances of textual data. Moreover, although the hierarchical contextual representations of pre-trained Transformers have demonstrated remarkable effectiveness in numerous NLP tasks (Sun et al., 2019; Ma et al., 2019; Mohebbi et al., 2021; Devlin et al., 2019; Liu et al., 2019a), their potential for textual OOD detection has not been fully harnessed.

Our proposal. To tackle the aforementioned issues, we propose a variational inference framework based on Transformers for textual OOD detection. Rather than solely focusing on maximizing the conditional distribution p(y|x) of ID data,

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our approach involves optimizing the joint distribution p(x, y), which is to maximize p(y|x) and p(x)simultaneously. The core idea revolves around modeling the distribution of the provided ID data, which allows us to harness valuable information that might not be directly relevant for ID classification but proves significant for outlier detection. To make the joint distribution p(x, y) tractable, we resort to optimizing the evidence lower bound of p(x, y) derived via amortized variational inference (AVI) (Kingma and Welling, 2014). Moreover, considering the unique characteristics of textual data, we modify the approximated posterior distribution in the framework of AVI, making the posterior conditioned on a dynamic combination of intermediate layer-wise hidden states of the Transformer. The Transformer backbone functions as a shared encoder for both the ID classification head and the decoder (generator) in the AVI framework (Fig. 2).

The contributions of this work include:

- Our proposed variational inference framework for OOD detection (VI-OOD) offers a novel and principled approach, providing a fresh perspective that is orthogonal to previous OOD detection methods (Hendrycks et al., 2020; Podolskiy et al., 2021a; Zhou et al., 2021a).
- Our instantiation of VI-OOD harnesses the rich contextual representations of pre-trained Transformers to learn more effective latent representations for text inputs. The improved representations can be readily used by various existing post-hoc OOD detection algorithms, consistently enhancing their performance in textual OOD detection.
- Our proposed method is evaluated using mainstream encoder-based and decoder-based Transformer architectures and comprehensive OOD text classification scenarios. It can offer advantages to widely utilized OOD detection algorithms, particularly for distance-based OOD detectors, such as the Mahalanobis Distance method (Lee et al., 2018b)

2. Pilot Study

2.1. Problem Statement and Motivation

Out-of-distribution (OOD) detection aims to accurately separate all class-dependent in-distribution (ID) examples as well as out-of-distribution (or anomalous) examples. Given the input space $\mathcal{X} \times \mathcal{Y}$ and an ID class label set $\mathcal{Y}_{\text{ID}} = \{y_j\}_{j=1}^K \subset \mathcal{Y}$, an ID training set $\mathcal{D}_{\text{ID}} = \{(x_i, y_i)\}_{i=1}^N$ is sampled from the distribution p(x, y) of ID data where $y_i \in \mathcal{Y}_{\text{ID}}$. With \mathcal{D}_{ID} , an ID classifier $f_{\text{ID}} : \mathcal{X} \to \mathcal{Y}_{\text{ID}}$ is trained. During test time,

since there may be a distribution shift between the training and test data in practical application scenarios (Szegedy et al., 2014; Morningstar et al., 2021), the ID classifier $f_{\rm ID}$ may encounter OOD samples ($y_i \notin \mathcal{Y}_{\rm ID}$). Hence, an OOD confidence scoring function $f_{\rm OOD} : \mathcal{X} \to \mathbb{R}$ is needed to perform ID vs. OOD binary classification. In this regard, OOD detection aims to solve both the *K*-class ID classification task and the binary outlier detection task. The ID classifier $f_{\rm ID}$ is commonly trained with a discriminative loss by maximizing the conditional log-likelihood of the training set:

$$\hat{\theta} = \underset{\theta}{\operatorname{argmax}} \frac{1}{N} \sum_{(x_i, y_i) \in \mathcal{D}_{\mathsf{ID}}} \log p(y_i \mid x_i; f_{\mathsf{ID}}, \theta), \quad (1)$$

where θ stands for all trainable parameters of f_{ID} .

The fundamental challenge of OOD detection is that at the training stage, real OOD examples are unavailable and thus cannot be effectively represented to provide necessary learning signals for the binary ID *vs.* OOD task. To address this issue, a few attempts have been made to introduce surrogate OOD datasets during training by using some datasets irrelevant to the ID data (Hendrycks et al., 2019; Lee et al., 2018a). However, it is difficult to select suitable "OOD" datasets to represent the huge space of real OOD data.

Post-hoc methods. The majority of existing OOD detection methods (Hendrycks and Gimpel, 2017; Hendrycks et al., 2019; Lee et al., 2018b; Liu et al., 2020; Hendrycks et al., 2022; Sun et al., 2021, 2022) follow a post-hoc paradigm and address the binary ID *vs.* OOD task in the inference stage. These methods propose different OOD confidence scoring functions with the trained ID classifier $f_{\rm ID}$. Specifically, the parameters of the trained $f_{\rm ID}$ are frozen, and some statistics of specific layers of $f_{\rm ID}$ (usually the penultimate layer or the softmax layer) are often used as OOD confidence scores.

Motivation of this work. While post-hoc methods have shown promise, it is pointed out that the performance of $f_{\rm ID}$ on ID data is not a good indicator of its performance on OOD data (Hendrycks et al., 2020; Lee et al., 2018a). Specifically, the discriminative training of f_{ID} is often conducted with p(y|z), where z is the latent representation obtained by passing an input x to a DNN encoder. Maximizing the conditional log-likelihood $\log p(y|z)$ is essentially maximizing the mutual information between the latent variable Z and the label variable Y, i.e., $\mathcal{I}(Z, Y)$ (Boudiaf et al., 2020). Naturally, the learned representation Z will be biased towards the ID classification task. Indeed, Kamoi and Kobayashi (2020) have demonstrated that in the Mahalanobis-distance-based OOD detection method, the principal components of ID data that are deemed least important for the ID classification task actually contain valuable information for the



Figure 1: Investigation of OOD performance of Transformer's intermediate Hidden States: AUROC Results for 24 Layers of RoBERTa_{LARGE}. The figure illustrates the OOD performance evaluation across multiple layers of RoBERTa_{LARGE}. Higher values indicate better performance. The model undergoes fine-tuning on SST-2 and is assessed for OOD performance using the 20NG dataset. The four commonly used OOD scoring functions, namely MSP (red), Maha (light yellow), Cosine (blue), and Energy (green), are represented in the figure.

binary ID *vs.* OOD task. This information may be overlooked or discarded when training the ID classification function $f_{\rm ID}$ using the conditional likelihood p(y|x). Furthermore, a recent study by Uppaal et al. (2023) highlights that relying solely on supervised training with ID data can lead to a degradation in the performance of OOD detection as the training progresses.

To address this issue, we propose to learn better latent representation Z for post-hoc methods by considering the distribution of ID data, i.e., maximizing the likelihoods p(y|x) and p(x) simultaneously¹, which is equivalent to modeling p(x, y) – the joint distribution of ID data. To this end, we design a novel principled variational framework that will be elaborated in the next section.

2.2. A Closer Look at Textual OOD Detection with Transformers

In Figure 1, we study the impact of the intermediate hidden states of RoBERTa_{LARGE} on textual OOD detection. Following (Hendrycks et al., 2020), we take the model trained on SST-2 as a case study. The model is trained solely with the discriminative loss. We conduct OOD detection by utilizing each hidden state of the trained model's 24 layers as representations of the input text data. Subsequently, we summarize the AUROC results obtained from four commonly used OOD detection algorithms. As the layer number increases from 0 to 23, the hidden layer is closer to the head of the model, i.e., layer 23 outputs the last hidden state.

Intermediate hidden states could help OOD detection. The results presented in Figure 1 clearly indicate that intermediate hidden states consistently outperform the final hidden states in terms of OOD performance, as observed across all four OOD detection methods. The best performance consistently occurs in the middle layers, particularly in the range of layers 9 to 13. This consistent performance is observed for all four OOD detection methods. On the other hand, as pointed out by Sun et al. (2019), intermediate hidden states of Transformers exhibit inferior performance compared to the final hidden state in ID classification tasks. Based on these observations, we make a key assumption: **intermediate hidden states contain redundant information for ID classification but crucial information for OOD detection.**

Furthermore, it is possible to address the disparities among various OOD detection methods. As depicted in Figure 1, the performance of intermediate layers (layers 9 to 14) is consistently comparable across the four OOD detection methods. For instance, the Maximum Softmax Probability (MSP) method demonstrates excellent results around layer 13, but its performance significantly deteriorates at the last layer, layer 23. These findings suggest that effectively harnessing the potential of hidden states in Transformers can alleviate the challenges associated with OOD detection.

3. Proposed Method

3.1. VI-OOD: A Variational Inference Framework for Out-of-distribution Detection

Our goal is to directly maximize the likelihood of the joint distribution p(x, y) rather than p(y|x). We assume that a latent variable Z is a stochastic encoding of the input sequence X. The log likelihood

¹Note that $p(y|x) = \int_{z} p(y|z, x)p(z|x) dz$ and $p(x) = \int_{z} p(x|z)p(z) dz$.



Figure 2: The architecture of our proposed framework. Our method employs an encoder-based transformer model as the backbone textual encoder. Hidden states of the [CLS] token are chosen to be textual representations. z is a latent variable conditioned on the textual representations. The in-distribution (ID) classification head p(y|z) and decoder $p(x^{\text{target}}|z)$ both take z as the input. s is the hidden states combination factor and the merge representation x^{target} works as the target of the decoder.

of p(x,y) can then be calculated by:

$$\log p(x,y) = \log \int_{z}^{z} p(x,y,z) dz$$
$$= \log \int_{z}^{z} p(y|z,x)p(x|z)p(z) dz$$
$$= \log \int_{z}^{z} p(y|z)p(x|z)p(z) dz, \quad (2)$$

where in the last equality we assume the Markov chain $X \leftrightarrow Z \leftrightarrow Y$, i.e., p(y|z, x) = p(y|z). Since it is intractable to compute the integral in Eq. (2), we employ amortized variational inference (Kingma and Welling, 2014) to derive the lower bound of $\log p(x, y)$ as follows.

$$\log p(x,y) = \log \int_{z} p(y|z)p(x|z)p(z) dz$$
$$= \log \int_{z} p(y|z)p(x|z)p(z)\frac{q(z|x)}{q(z|x)} dz \quad (3)$$

$$= \log \mathbb{E}_{z \sim q(z|x)} \left[\frac{p(y|z)p(x|z)p(z)}{q(z|x)} \right]$$
(4)

$$\geq \mathbb{E}_{z \sim q(z|x)} \left[\log \frac{p(y|z)p(x|z)p(z)}{q(z|x)} \right],$$
(5)

where q(z|x) in Eq. (3) is the amortized variational approximator of the true posterior p(z|x), and Jensen's inequality is applied in Eq. (5). The last quantity in Eq. (5) is the evidence lower bound of $\log p(x, y)$, which can be rewritten as:

$$\mathcal{L}_{\mathsf{ELBO}} = \underbrace{\mathbb{E}_{z} \left[\log p(y|z) \right]}_{\text{Target #1: ID supervised training}} + \underbrace{\mathbb{E}_{z} \left[\log p(x|z) \right] - D_{\mathsf{KL}}(q(z|x)||p(z))}_{\text{Target #2: Unsupervised variational training}}, \quad (6)$$

where the first term is the ID supervised training objective, and the second and third terms correspond to the unsupervised learning objective for an amortized variational Bayesian autoencoder.

3.2. Transformer-based Textual OOD Detection with VI-OOD

Our proposed VI-OOD framework is a general probabilistic approach for learning data representations, which can be applied to various types of data, including image, textual, audio, and video. However, in this work, we focus on textual data. In the following, we outline the instantiation of VI-OOD for textual OOD detection, which involves designing the encoder (posterior approximator) q(z|x), the decoder (reconstructor) p(x|z), and the discriminator p(y|z), as depicted in Figure 2.

Encoder for learning textual representations.

Encoder-based Transformers have become a prevailing standard in learning contextual representations of text due to their excellent performance in numerous NLP tasks. Hence, the transformer architecture is a natural choice for the encoder q(z|x). In this paper, we utilize models from the BERT family (Devlin et al., 2019). Given an input x, which is a sequence of tokens with a length of N, denoted as $[x_0, \dots, x_{N-1}]$, BERT adds a special token [CLS] at the start of the input sequence, i.e., [CLS, x_0, \dots, x_{n-1}]. The inclusion of the [CLS] token is intended for classification tasks. Unless otherwise specified, we use the hidden states of the [CLS] token as the textual representations. The input sequence x is passed through each layer of BERT, resulting in a series of intermediate hidden states at the [CLS] position, denoted as $h_{\text{CLS}} = [h_{\text{CLS}}^0, \cdots, h_{\text{CLS}}^{L-1}]$, where L is the total number of layers. As shown in Figure 2, we instantiate the encoder q(z|x) and the prior p(z) as diagonal Gaussian distributions, i.e., $\mathcal{N}(z|\mu, \Sigma)$ and $\mathcal{N}(0, I)$ respectively, where μ and Σ are obtained by mapping the last hidden state h_{CLS}^{L-1} with a single-layer MLP respectively.

Decoder for reconstructing the textual representations. In the case of image data, selecting the original input image as the decoder target for reconstruction is straightforward since it contains the most informative content. However, when working with textual data, the input token sequence only represents embeddings from a predefined dictionary, while the intermediate hidden states of the Transformer capture valuable contextual semantics. As a result, determining the appropriate reconstruction target for p(x|z) in textual data poses a challenging task. To leverage the potential of the intermediate hidden states, our approach aims to condition the reconstruction target on the hidden states. Based on our preliminary experiments, we observed that different hidden layers have varying effects on different ID datasets. Consequently, it is difficult to predefine a fixed combination pattern for integrating the intermediate hidden states. Therefore, we introduce a learnable weight vector $\mathbf{s} = [s_0, \cdots, s_{L-1}] \in \mathbb{R}^L$ to dynamically integrate the intermediate hidden states of the Transformer. Then, we derive the reconstruction target:

$$x^{\text{target}} = (h_{\text{CLS}}^0 \cdot s_0) + (h_{\text{CLS}}^1 \cdot s_1) + \dots + (h_{\text{CLS}}^{L-1} \cdot s_{L-1}),$$

where \cdot denotes multiplication. In this way, $x^{\rm target}$ contains rich contextualized semantic information. Referring to Figure 2, we realize the reconstructor (decoder) p(x|z) as a single feed-forward block, taking a sample z from $\mathcal{N}(z|\mu,\Sigma)$ as input and outputting a reconstructed version of $x^{\rm target}$ to maximize $p(x^{\rm target}|z)$. The ID classifier $f_{\rm ID}$ is a single layer MLP that takes the latent representation z as input.

Discriminator for ID classification and binary OOD detection. At the inference stage, we only need the trained posterior approximator (encoder) q(z|x) and the ID classifier f_{ID} . Note that both the ID classification task and the binary outlier detection task are performed w.r.t. the latent variable z. For each x, we only sample one z during training and inference respectively.

4. Experiments

In this section, we present a comprehensive evaluation of textual out-of-distribution (OOD) detection with pervasive OOD detection methods. Besides, we demonstrate the effectiveness of our proposed OOD detection method on challenging natural language understanding benchmarks. To achieve a comprehensive evaluation, we employ both encoder-based and decoder-based pretrained language models as backbone models of our method. We start this section by describing our evaluation methodology and then present our experimental results.

4.1. Evaluation Methodology

4.1.1. Datasets

OOD detection in the natural language processing (NLP) domain is generally under-explored and only discussed in limited scenarios such as out-ofscope intent detection in dialogue machines (Zhan et al., 2021a; Zhang et al., 2021a; Yan et al., 2020). As such, evaluating OOD performance in the NLP domain does not have a consensus. To scale the evaluation process as general as possible, we follow the evaluation in (Hendrycks et al., 2020) and (Zhou et al., 2021b) to present our main analysis. Hendrycks et al. (2020) firstly proposes to use the sentiment analysis benchmark SST-2 as the indistribution dataset and select five other datasets as out-distribution evaluation sets, which includes 20 Newsgroups, WMT16 and Multi30K, RTE, and SNLI. Zhou et al. (2021b) further extend this benchmark by adding more natural language understanding tasks including topic classification, and question classification.

In-distribution Tasks We use four benchmark datasets as in-distribution (ID) tasks: 20 News-groups (20NG) (Lang, 1995), IMDB (Maas et al., 2011), SST-2 (Socher et al., 2013) and TREC-10 (Li and Roth, 2002). When setting each of them as *in-distribution*, other ones are recognized as *out-distribution*.

Besides the above ID four tasks, we also use another four unrelated datasets as OOD test sets (not for training) for all of the four ID tasks. We refer them as the out-distribution datasets: the English source side of English-German WMT16 (Bojar et al., 2016) and English-German Multi30K (Elliott et al., 2016), and concatenations of the premise and hypothesis of RTE (Dagan et al., 2006) and MNLI (Williams et al., 2018). WMT16 and Multi30K are for machine translation while RTE and MNLI are for natural language inference. We use the respective test sets of each out-distribution dataset to measure OOD performance.

4.1.2. Baselines

To demonstrate the effectiveness of our proposed framework, we compare our method comprehensively with four commonly used OOD detection algorithms:

- Maximum Softmax Probability (MSP) (Hendrycks and Gimpel, 2017): The MSP confidence score leverages the maximum softmax probability outputted by the softmax function for out-of-domain detection. As correct samples tend to have higher probability scores, samples below a threshold are more likely to be outliers. Specifically, the confidence score is $C(x) = \max_{y} p(y|x)$.
- Mahalanobis Distance (Maha) (Lee et al., 2018b): The Mahalanobis Distance (MD) method fits *K*-class conditional Gaussian distributions $\{\mathcal{N}(\mu_i, \Sigma)\}_{i=1}^K$ for the *K* indistribution classes upon the output of the penultimate layer in the model. The Mahalanobis Distance and the MD confidence score are computed by:

• Energy score (Energy) (Liu et al., 2020): The energy score confidence score is inspired by the energy-based models (LeCun et al., 2006). It defines an energy of an input (x, y)as $E(x, y) = w_y^T \cdot z$, where w_y is the weight of the softmax layer for the y^{th} in-distribution class. The energy score confidence score is defined as:

$$\mathcal{C}(x) = \log \sum_{i}^{K} e^{w_i^T \cdot z}.$$
(8)

• Cosine distance (Cosine) (Zhou et al., 2021b): The cosine distance OOD confidence sore defines as the maximum cosine similarity of a test input representation with representations in the validation set, i.e., $C(x) = -\max_{i=1}^{V} \cos(z, z_i^{val})$.

4.1.3. Metrics

We employ three commonly used metrics for OOD detection and introduce them as follows:

 AUROC: Area Under the Receiver Operating Characteristic curve(AUROC) reveals the relationship between True Positive Rate (TPR) (i.e., Recall) and False Positive Rate (FPR). It represents the probability of assigning a higher score to a positive example than a negative example. The pioneering work (Hendrycks and Gimpel, 2017) firstly proposed to use this metric for OOD detection. A higher AUROC score indicates a better classifier, and An AUROC score of 50% means random guessing.

- FAR@95: False Alarm Rate at 95% Recall(FAR@95) is the probability that a negative example is misclassified as positive when Recall or TPR is 95%. In this paper, we take the OOD class as negative.
- AUPR: Area Under the Precision-Recall curve (AUPR) is another commonly used metric based on the Precision-Recall Curve. It is a better indicator in the case of imbalanced inand out-rate (Manning and Schutze, 1999). A perfect classifier has an AUPR of 100%.

4.1.4. Experimental Setup

For the encoder-based pre-trained language model, we employ the RoBERTa_{LARGE} (Liu et al., 2019b) model from HuggingFace (Wolf et al., 2019) as the backbone of our framework. We use the optimizer AdamW (Loshchilov and Hutter, 2019) with a linear-scheduled learning rate 10^{-5} to fine-tune the model for 20 epochs. For the variational terms in Eq. 6, we apply a linear annealing strategy which is a common practice in variational methods (Fu et al., 2019). All reported results are obtained in 5 runs with different random seeds.

For the decoder-based large language model, we validate the effectiveness of our method on LLaMA-2-7B. To reduce training costs, we perform parameter-effective fine-tuning through the LoRA module provided by the HuggingFace PEFT package. Our hyperparameters for LoRA are set as follows: $\alpha = 16$, r = 16, and $lora_dropout = 0.05$. We fine-tune the model for 20 epochs with a learning rate of 1e-4. For additional training details, please refer to the code repository we have released.

4.2. Main Results

To showcase the adaptability of our VI-OOD detection framework, we evaluate it on comprehensive datasets and compare it with competitive baselines. The summarized averaged results can be found in Table 1.

VI-OOD benefits a diverse collection of tasks and OOD score functions. According to Table 1, one notable observation is that our proposed approach consistently outperforms all compared baselines in terms of the overall average performance. This can be observed across various metrics. For instance, when comparing our method to the bestperforming baseline, the Maha method, we achieve a significant reduction in the average FAR@95 from

	SST-2			IMDB			
Methods	AUROC ↑	FAR@95↓	AUPR ↑	AUROC ↑	FAR@95↓	AUPR ↑	
MSP	89.85	66.20	86.40	94.30	41.90	98.80	
MSP _{Contrast}	85.04	63.42	69.34	94.51	44.69	98.89	
MSP _{VI}	92.85	51.58	89.72	95.95	28.03	99.12	
Maha	97.98	11.50	97.30	99.67	0.70	99.95	
Maha _{Contrast}	99.42	2.98	98.73	99.89	0.05	99.97	
Maha _{vi}	99.33	3.62	98.52	99.90	0.21	99.97	
Cosine	95.65	22.65	94.68	99.50	1.53	99.88	
Cosine _{Contrast}	98.38	8.64	96.36	99.87	1.93	99.96	
Cosine _{vi}	98.87	6.62	98.06	99.57	1.43	99.88	
Energy	89.80	67.00	86.53	93.30	56.70	98.63	
Energy _{Contrast}	84.93	63.16	69.29	94.44	44.46	98.86	
Energyvi	92.79	51.25	89.26	96.05	27.97	99.12	
	TREC-10			20NG			
Methods	AUROC ↑	FAR@95↓	AUPR ↑	AUROC ↑	FAR@95↓	AUPR ↑	
MSP	97.94	8.43	89.26	93.89	30.49	87.39	
MSP _{Contrast}	98.43	4.06	91.19	93.19	28.00	83.17	
MSPvi	98.91	2.77	90.39	93.29	25.61	80.09	
Maha	98.99	4.87	95.11	98.39	7.77	95.91	
Maha _{Contrast}	99.57	0.97	98.59	98.78	5.89	97.29	
Maha _{vi}	99.46	0.79	97.67	99.80	0.61	98.93	
Cosine	98.89	3.96	94.54	97.73	10.84	88.71	
Cosine _{Contrast}	99.14	1.42	93.34	98.03	8.86	95.27	
Cosinevi	99.36	1.19	96.09	99.39	2.92	97.19	
Energy	97.19	10.07	82.16	95.76	17.93	88.71	
Energy _{Contrast}	98.45	4.73	91.18	96.04	15.70	88.62	
Energyvi	99.21	2.84	90.84	94.34	17.04	79.67	
Average	AUROC ↑		FAR@95↓		AUPR ↑		
avg. (MSP / Maha / Cosine / Energy)	94.00 / 98.78 / 97.94 / 94.01		36.76 / 6.21 / 9.75 / 37.93		90.46 / 97.07 / 94.45 / 89.0		
avg. Contrast (MSP / Maha / Cosine / Energy)		7 / 98.86 / 93.47	35.04 / 3.93 / 5.21 / 32.01		85.65 / 97.43 / 96.23 / 86.99		
avg. _{VI} (MSP / Maha / Cosine / Energy)				27.00 / 1.31 / 3.04 / 24.78		89.83 / 98.77 / 97.81 / 89.72	

Table 1: Main results of our proposed framework. MSP, Maha, Energy, and Cosine are baseline methods trained with the discriminative loss, while each corresponding method with the *VI* subscript denotes the model trained with our VI framework. The *Contrast* subscript denotes the method proposed by Zhou et al. (2021b). The best result is marked in bold. At the bottom row, averaged results across four ID datasets are included. All the reported results are presented in percentage values.

6.21% to 1.31%, resulting in a relative increase of 78.9%. Similarly, for the second best baseline, the Cosine score function, our method demonstrates substantial improvement by reducing the average FAR@95 from 9.75% to 3.04%. Moreover, there are significant performance gains in terms of AUROC as well. For example, the average AUROC score for the Cosine method increases from 97.94% to 99.3% with the use of our method. It is worth noting that our method achieves these improvements without the need for real OOD examples, which makes these results even more encouraging. Upon closer examination of each of the four in-distribution (ID) datasets, it becomes apparent that detecting out-ofdistribution (OOD) test examples using the model trained on TREC-10 is comparatively easier than with the other datasets. In fact, all OOD score functions achieve AUROC scores above 97%. Improving upon these already competitive results poses a significant challenge. However, our method still manages to outperform all four score functions on TREC-10. Notably, for the Energy score function, our method enhances the AUROC score from 97.19% to 99.21%, while simultaneously reducing the FAR@95 score from 10.07% to 2.84%. Fur-

thermore, for the Maha method on TREC-10, our method achieves a near-perfect FAR@95 score of 0.79%.

Superior Performance of Our Method with Large Decoder-Only Models. To further validate our method's efficacy, we conduct experiments on SST-2 and TREC-10 using LLaMA-2-7B. For training the in-distribution classifier, we utilize *LlamaForSequenceClassification* from the Hugging Face transformers package (Wolf et al., 2020).

Results are presented in Table 2. As shown, when using SST-2 as the in-distribution (ID) dataset, our method significantly outperforms the baselines across all three metrics. In the case of TREC-10, our method elevates the Mahalanobis (Maha) and Cosine OOD scores to nearly perfect levels. However, for logit-based OOD scores, specifically MSP and Energy, our method demonstrates slightly inferior performance relative to the respective baselines. This discrepancy may stem from the fact that Maha and Cosine benefit more from the enriched information in sentence representations, whereas this richer information introduces more ambiguity

	SST-2			TREC-10			
Methods	AUROC ↑	FAR@95↓	AUPR ↑	AUROC ↑	FAR@95↓	AUPR ↑	
MSP	78.22	70.40	74.34	99.29	0.64	98.79	
MSP _{VI}	83.05	65.32	69.54	98.69	5.69	94.48	
Maha	46.08	84.41	47.34	84.41	71.94	64.13	
Maha_{vi}	95.41	12.47	85.38	99.96	0.12	99.39	
Cosine	89.24	26.52	79.47	98.24	11.06	93.05	
Cosine _{VI}	95.95	7.21	85.70	100	0	99.92	
Energy	70.13	67.78	64.87	99.86	0.14	99.27	
Energy_{vi}	80.16	66.90	65.76	98.64	7.40	92.44	

Table 2: Results of our proposed framework on LLaMA-2-7B, fine-tuned with a classification head. The best result is marked in bold. All the reported results are presented in percentage values.



Figure 3: Heatmap of the hidden state combination factor *s*. The horizontal axis stands for four ID tasks and the vertical axis represents the layer number.

in the logits.

4.3. ID Classification Performance

In this subsection, we investigate the ID classification performance. Besides the binary ID *vs.* OOD task, OOD detection also concerns the ID classification task. We summarize the test accuracy of the corresponding ID test sets for the four ID datasets in Table 3. It can be seen that for 20NG, SST-2, TREC-10, and IMDB, ID test performances are very similar and all the gaps are lower than 1%. Therefore, models trained with our proposed p(x, y) target do not bring significant detrimental impacts to ID classification. However, although we consider these gaps can be ignored in practical applications, it also indicates that our method can be further improved in further works.

4.4. The Combination Factor *s*

Finally, we analyze the learned combination vector ${\bf s}$ in our framework. We visualize the heatmap

Test Accuracy	SST-2	IMDB	TREC-10	20NG
p(y x)	96.21	95.33	97.8	93.99
p(x,y)	96.38	94.54	97.0	93.35

Table 3: Performance comparison of the ID K-class classifier for different training objectives. p(y|x) is the commonly used discriminative objective and p(x, y) is our proposed objective.

of the learned s for the in-distribution (ID) tasks in Figure 3. It is evident that the hidden state combination patterns vary significantly across different ID tasks. This observation confirms that our proposed combination vector can automatically adapt and learn appropriate combination policies for distinct ID tasks. This analysis provides further evidence of the flexibility of our framework in effectively leveraging the potent hidden states of pre-trained models.

5. Related Work

OOD detection based on density estimation. Besides the problem setting discussed in Section (2), another line of works tries to address the OOD detection problem by solving a more general problem - density estimation. Unlike the setting of our work, the focus of these works is solely on the binary classification task of distinguishing between in-distribution (ID) and OOD samples, disregarding the ID classification task. Their learning target is the density function of the training set $-p_{ID}(x)$ - such that OOD examples are assumed to yield lower probabilities than the ID ones. However, in high dimensional spaces, this assumption is not held in practice and many previous works (Choi et al., 2018) have found that OOD examples may be assigned higher likelihoods than ID examples. Recent works (Ren et al., 2019; Nalisnick et al., 2019; Morningstar et al., 2021) are still trying to correct this pathology.

In particular, numerous prior studies have leveraged the density estimation capabilities of variational autoencoders (VAEs) for OOD detection. For instance, Floto et al. (2023) enhance VAEs for OOD detection by substituting the standard Gaussian prior with a more versatile tilted Gaussian distribution. Likelihood Regret (Xiao et al., 2020) and Likelihood ratios (Ren et al., 2019) adopt a similar perspective of training two distinct models–one capturing the semantic content of the data, and the other capturing background information. Their major difference is the training data of the background model and semantic model.

OOD detection in NLP. OOD detection in the NLP domain has recently attracted increased attention (Liu et al., 2023). OOD intent detection (Zhang et al., 2021b; Zhan et al., 2021b) investigates the OOD detection problem for anomalous utterances in dialogue systems. Podolskiy et al. (2021b) empirically find out that Mahalanobis Distance is the best performing OOD scoring function for OOD intent detection. A few attempts has been made to study the general textual OOD detection problem. Hendrycks et al. (2020) point out that pre-trained Transformers are more robust for OOD detection than previous model architectures (Hochreiter and Schmidhuber, 1997). Zhou et al. (2021b) and Cho et al. (2022) employ a contrastive regularizer to learn better representations for textual OOD detection. Uppaal et al. (2023) conduct an evaluation on RoBERTa and point out that ID fine-tuning may pose a detrimental effect on textual OOD detection.

6. Conclusion

This paper concentrates on exploring Out-of-Distribution (OOD) detection within Natural Language Processing (NLP) classification tasks using Transformer-based large language models (LLMs). Building on our detailed analysis of hidden states in Transformers, we introduce a Variational Bayesian framework named VI-OOD. This framework optimizes the joint distribution p(x, y) during the training phase. Our methodology is reinforced by both experimental evidence and theoretical analysis, underscoring its validity. We have rigorously tested our approach with mainstream Transformer architectures, encompassing both encoder-based and decoder-based models. Comprehensive experiments on diverse textual classification tasks affirm the efficacy and superiority of our OOD detection framework.

This research is dedicated to enhancing AI safety and the robustness of models. As such, our findings are poised to benefit various AI applications without presenting a direct risk of misuse. Furthermore, our proposed methodology relies exclusively on open-source benchmarks for training data, avoiding the introduction of additional datasets for training the OOD detector. As such, our approach sidesteps potential ethical concerns associated with data collection. Additionally, by building upon open-source LLMs, our method avoids substantial increases in resource consumption, aligning with principles of sustainable and responsible AI development.

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