# Effectiveness of Data Augmentation for Parameter Efficient Tuning with Limited Data

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#### Abstract

Recent work has demonstrated that using parameter efficient tuning techniques such as prefix tuning (or P-tuning) on pretrained language models can yield performance that is comparable or superior to fine-tuning while dramatically reducing trainable parameters. Nevertheless, the effectiveness of such methods under the context of data augmentation, a common strategy to improve learning under low data regimes, has not been fully explored. In this paper, we examine the effectiveness of several popular task-agnostic data augmentation techniques, i.e., EDA, Back Translation, and Mixup, when using two general parameter efficient tuning methods, P-tuning v2 and LoRA, under data scarcity. We show that data augmentation can be used to boost the performance of P-tuning and LoRA models, but the effectiveness of each technique varies and certain methods can lead to a notable degradation in performance, particularly when using larger models and on harder tasks. We further analyze the sentence representations of P-tuning compared to fine-tuning to help understand the above behaviour, and reveal how P-tuning generally presents a more limited ability to separate the sentence embeddings from different classes of augmented data. In addition, it displays poorer performance on heavily altered data. However, we demonstrate that by adding a simple contrastive loss function it can help mitigate such issues for prefix tuning, resulting in sizable improvements to augmented data performance.

# 1 Introduction

While large pretrained language models have achieved superior performance and widespread adoption across many NLP tasks (Zaheer et al., 2020; Bengio et al., 2021), they often contain hundreds of millions or even hundreds of billions of parameters, which significantly limits their application to tasks in which computation and storage resources are constrained.

To address this issue, an entire family of techniques called parameter efficient tuning (PET) methods have been developed. Most notably, deep prompt tuning (i.e., prefix tuning or P-tuning) (Li and Liang, 2021; Qin and Eisner, 2021; Liu et al., 2021) has attracted extensive attention, which, compared to fine-tuning, only tunes trainable continuous embeddings, resulting in a tiny percentage of tuned parameters for each task. Consequently, a single language model can be used for multiple tasks by swapping out the trained prompts on a task basis (Li and Liang, 2021). Such success has also been shown by the state-of-the-art P-tuning v2 model (Liu et al., 2021), which yields performance comparable to fine-tuning on various natural language understanding tasks. In addition, Low-Rank Adaptation (LoRA) (Hu et al., 2021) has also emerged as an alternative approach, whereby the weights of rank decomposition matrices that are injected into each layer are optimized in lieu of the full network weights, reducing trainable parameters while also achieving improvements in accuracy over fine-tuning and other PET methods.

When training data is scarce in a task, data augmentation (DA) is a widely used strategy that can boost the performance of deep learning models (see (Feng et al., 2021) for a survey on data augmentation in NLP). Then a basic question that needs to be answered is how effective is it when the above PET frameworks are applied in conjunction with data augmentation. To this end, we study three common task-agnostic DA methods, EDA (Wei and Zou, 2019), Back Translation (Sennrich et al., 2016), and Mixup (Guo et al., 2019a) with two common language models BERT (Devlin et al., 2019) and RoBERTa (Liu et al., 2019), trained using P-tuning v2 (Liu et al., 2021) and LoRA (Hu et al., 2021). We set up our study across five tasks, including 4 from SuperGLUE (Wang et al., 2019), in which the sizes of training data are small.

We show that data augmentation can increase

the accuracy of prefix tuning models. However, the performance of each technique varies depending on the dataset and underlying pretrained model, and the effective techniques differ from fine-tuning. Certain methods can even lead to a notable degradation in performance, particularly when using larger models. To better understand the above phenomena, we visualize sentence representations of data under prefix tuning, a technique where many augmentation methods fail to get good results, to observe whether any limitations are present with how data is represented that are leading to poor performance in certain cases. Through this, we find that these models struggle more with separating the augmented embeddings from different classes. This observation is further supported by our additional experiments showing a lower robustness to heavily altered augmented data compared to fine-tuning, and an analysis of the cosine similarities between the sentence embeddings of augmented sentences and their original counterparts, where we see that prefix tuning produces highly similar embeddings irrespective of alterations. We seek to improve the performance when training on augmented data by adding a contrastive loss term (Oord et al., 2018) to minimize distances between intra-class embeddings in P-tuning v2, helping mitigate the above issues with sentence representations, and resulting in some improvements in accuracy. We hope this empirical study helps facilitate future work on leveraging data augmentation when training transformer-based models using parameter efficient tuning methods.

### 2 Related Work

A wide range of data augmentation techniques are used in NLP. Some general types of methods include rule-based techniques that use predetermined, rule-based transformations like synonym replacement that are not dependant on any model architecture (Feng et al., 2021). Example methods include EDA. Model-based techniques utilize language modelling to generate new data through means like seq2seq translation models as in back translation (Sennrich et al., 2016), masked language modelling using transformers on randomly masked inputs (Garg and Ramakrishnan, 2020), or using generative models like GPT-2 as in Anaby-Tavor et al. (2020) where a label-conditioned generation model is obtained by fine-tuning GPT-2 (Radford et al., 2019).

Despite widespread use in computer vision, DA is not as commonly used in the training of NLP models, largely due to the discrete nature of language making it difficult to apply perturbations without compromising the meaning, and the inconsistency in performance of different techniques (Feng et al., 2021). The effectiveness of DA on finetuned models has been studied previously. (Longpre et al., 2020) detail how BT and EDA could not generate consistent benefits on classification tasks with transformer-based models. Similarly, (Okimura et al., 2022) expand this previous study and test the impact of 12 different DA methods and find little benefit when training on datasets with thousands of examples, but that there is some improvement in performance with very limited data (only a few hundred training cases). Our study conducts a similar examination on the effectiveness of data augmentation with pretrained models, however we focus on prefix tuning and LoRA, and we inspect how the properties of prefix tuning under DA differ from fine-tuning and what practical effect this has, particularly in terms of sentence representations.

# **3** Data Augmentation with Parameter Efficient Tuning

Prefix Tuning Approach. We first experiment with prefix tuning, and base our approach on the P-tuning v2 (Liu et al., 2021) implementation. By optimizing prefix length, selectively applying reparameterization, and tuning a randomlyinitialized classification head on top of the transformer sentence representations, P-tuning v2 can be applied to smaller language models and across many tasks, including classification, with no drop in performance compared to fine-tuning. P-tuning v2 works by adding prompts of length p tokens to all layers of the language model in the form of sequences of continuous prefix tokens. These continuous embeddings, represented by the vector  $H_m = [h_0, ..., h_p]$  where each  $h_i \in \mathbb{R}^d$  has the dimensionality of token embeddings d for each layer m in the transformer-based model, are prefixed to the embeddings of each transformer layer  $E_m = [E_{CLS}, E_1, ..., E_n]$  where n is the max sequence length. Thus, each layer of the language model can attend over prompts independently. The overall language model parameters remain frozen during training, with only the parameters of the prefixes and linear head for the classification layer

getting optimized. The prefixes can optionally be passed into a reparameterization encoder such as an MLP (Li and Liang, 2021), but this is not always effective and so we only selectively apply this in certain cases where we find it improves performance as in Liu et al. (2021).

LoRA. We test LoRA (Hu et al., 2021), which is a technique that similarly freezes the original transformer weights, but only tunes trainable pairs of rank-decomposition matrices that are inserted into each transformer layer to approximate the weight updates, greatly reducing the number of parameters needed by avoiding updating the full layer weights while not increasing inference costs. Instead of updating a pretrained weight matrix of a transformer  $W_0 \in R^{d \times k}$  with a gradient-based weight update  $\Delta W$  for time step t to get a new weight matrix as in  $W_t = W_0 + \Delta W_t$ , LoRA does a low-rank decomposition of the update into two matrices  $W_B \in R^{\tilde{d} \times r}$  and  $W_A \in R^{\tilde{r} \times k}$  that act as learnable parameters to represent the new update as  $W_t = W_B W_A + W_0$ , with  $W_0$  being frozen and where r represents the rank of the decomposition. The authors find applying LoRA to the query and value projection matrices in the attention mechanism leads to the most optimal performance. LoRA often outperforms other PET methods, making it worthy of study in this context (He et al., 2022).

Data Augmentation Methods. In this study we focus on *task-agnostic* data augmentation, which are methods that are broadly applicable to a wide range of NLP tasks. Many popular DA methods exist and of these, we utilize: (1) Easy Data Augmentation (EDA) (Wei and Zou, 2019), a technique where augmented sentences are created by applying a number of rule-based text editing operations; (2) Back Translation (BT) (Sennrich et al., 2016) where augmented data is generated by translating text into a target language then translating it back into the original language; (3) Mixup for Sentence Classification (Guo et al., 2019a), where we take the senMixup approach by generating synthetic data through interpolation over the classification tokens of random pairs of sentences. All of these have shown an ability to improve model accuracy for limited data (Wei and Zou, 2019; Guo, 2020; Feng et al., 2021; Fabbri et al., 2020) while having a low cost of implementation.

#### 4 Experimental Setup

We focus primarily on small datasets with less than a few thousand annotated data points, since limited data presents challenges in learning generalizable models and hence is a common use case for DA. Previous works have shown DA with pretrained language models tends to be largely ineffective for larger datasets (Okimura et al., 2022).

We test on five text classification datasets. Four are from the SuperGLUE benchmark (Wang et al., 2019), consisting of RTE (Dagan et al., 2006; Bar Haim et al., 2006; Giampiccolo et al., 2007; Bentivogli et al., 2009), CB (De Marneffe et al., 2019), COPA (Roemmele et al., 2011), and WSC (Levesque et al., 2011). These are the smallest datasets in the benchmark at only 2500, 250, 400, 554 training samples respectively. They capture a range of difficulty, and include diverse problems like textual entailment, commonsense-reasoningbased coreference resolution, determining cause or effect, and clause commitment. To capture performance on a simpler single sentence sentiment analysis task, we also use a downsampled subset of SST-2 (Socher et al., 2013), consisting of 400 training samples and 100 validation sentences. We experiment with BERT-base (Devlin et al., 2019) and RoBERTa-large (Liu et al., 2019), which have 110 million and 355 million parameters, respectively. Compared to larger models, their size makes them suitable when storage concerns are present. Each model is trained until convergence and we report results at the epoch where the highest validation accuracy is achieved. We provide the detailed training settings for our models in Appendix A. Below we describe the settings for each of the data augmentation methods:

**EDA**: We apply a combination of the synonym replacement, random swap, random insertion, and random deletion operations to a certain percentage of the words in a sentence to generate multiple augmented sentences per original sentence. For the amount of augmented sentences generated, and the percentage of words affected, we follow the recommended usage guidelines laid out by Wei and Zou (2019) which are dependant on the size of the training set. 16 augmented sentences per original are generated for the smallest datasets; CB, COPA, WSC, and SST-2 since they only contain a few hundred training samples samples. The percentage of words in the original text affected for each of the 4 operations is 5% ( $\alpha = 0.05$ ). 8 sentences

are generated per original for the RTE training set, with the same percentage of words being affected as the aforementioned datasets.

**BT**: For our implementation, we back-translate the sentences using a series of English to a target language and target language to English translation models for 4 common languages: French, Spanish, German, and Chinese. The specific models we use are the Helsinki NLP Opus translation modules (Tiedemann, 2020). These languages are chosen due to the substantial amount of parallel corpora available for training the respective language models, which yields higher quality translations that are better able preserve the semantics of the original sentence while still introducing some diversity.

Mixup: Inspired by Mixup in image classification (Zhang et al., 2018; Guo et al., 2019b), where random pairs of input images and their labels are linearly interpolated to help generated synthetic images, Mixup can be similarly applied over embeddings for text. As in Guo et al. (2019a), we adapt Mixup for text classification by interpolating on sentence embeddings (senMixup). In a mini batch of size N, we take the same number of random pairs of inputs texts, and interpolate over the d-dimensional (768 in the case of BERT-base and 1024 for RoBERTa-large) classification ([CLS]) tokens of the final hidden layer of the transformer encoder produced after each of the inputs is fed into transformer. The interpolated token is then passed into a fully connected later to generate the final softmax prediction vector. The interpolation for a given pair [CLS] token pair  $(x^i, x^j)$  with corresponding one hot label vectors  $(y^i, y^j)$ , for inputs i and j is conducted as follows,

$$\tilde{x}^{ij} = \lambda x^i + (1 - \lambda) x^j, \tag{1}$$

$$\tilde{y}^{ij} = \lambda y^i + (1 - \lambda) y^j, \qquad (2)$$

which results in interpolated vectors  $\tilde{x}^{ij}$  and  $\tilde{y}^{ij}$ . Mixup is parameterized by mixing-ratio  $\lambda$ , which is different for every pair, and is obtained by sampling from the  $Beta(\alpha, \alpha)$  distribution with the hyperparameter  $\alpha = 1.0$ , corresponding to a uniform distribution. This was the recommended setting in Guo et al. (2019a) and consequently we use this value as well. Mixup is done in a similar manner for prefix tuning, except we use the pooled version of the classification token (i.e. one that has gone through a linear layer and tanh activation).

**Procedure for Augmentation**: For simplicity, since most of the datasets use multiple input sen-

Table 1: Accuracy of fine-tuning BERT and RoBERTa under various augmentation methods with the P-tuning and LoRA trained equivalents.

		Dataset				
Model		rte	cb	copa	wsc	sst2
Fine-tuned BERT	No Aug.	73.5	92.2	69.6	65.4	91.1
	EDA	67.4	95.3	71.1	63.5	88.4
	Mixup	74.2	92.9	68.8	66.4	89.3
	BT	71.8	93.8	70.5	63.5	91.1
P-tuning v2 BERT	No Aug.	69.4	90.6	72.3	66.4	89.3
	EDA	68.8	90.1	72.0	63.5	88.4
	Mixup	69.1	91.1	72.0	65.4	90.2
	BT	71.2	94.8	75.0	66.4	88.4
LoRA BERT	No Aug.	74.2	90.6	72.7	63.5	89.1
	EDA	69.1	90.6	65.2	63.5	86.6
	Mixup	66.0	89.6	68.0	62.5	89.8
	BT	70.4	92.2	67.0	65.6	87.5
Fine-tuned RoBERTa	No Aug.	88.2	98.2	94.6	63.5	96.4
	EDA	85.0	96.9	90.2	63.5	94.6
	Mixup	85.4	98.4	93.8	63.5	95.5
	BT	85.4	96.4	90.2	63.5	96.4
P-tuning v2 RoBERTa	No Aug.	87.9	98.4	90.0	63.5	94.6
	EDA	84.6	96.9	87.0	64.4	94.6
	Mixup	87.2	98.4	86.0	63.5	92.9
	BT	84.7	98.4	85.0	63.5	94.6
LoRA RoBERTa	No Aug.	86.5	96.9	94.6	63.5	95.5
	EDA	84.4	95.3	89.3	63.5	95.5
	Mixup	88.2	93.8	89.3	63.5	96.4
	BT	83.5	96.9	89.3	63.5	96.4

tences/words per training sample (e.g. premise and hypothesis), we apply the static DA methods over the primary (first) input, which is the premise for RTE, CB, and COPA, though we use the full sentence for WSC and SST2.

# 5 Experimental Results and Analyses

#### 5.1 Data Augmentation with PET

Table 1 displays our primary results. The DA methods that achieve the best performance on each dataset and model type vary greatly. Some strong performance gains can be seen when using DA with P-tuning v2, most clearly seen when using BT with BERT on RTE, CB, and COPA. Similar cases exist with LoRA using Mixup on RTE with RoBERTa, and BT on BERT with CB. However, despite the cases of positive performance, frequent degradation to accuracy can be seen in most cases from using DA, particularly with the larger RoBERTa models, and on certain datasets like RTE with P-tuning v2 and COPA with LoRA. EDA in particular tends to perform poorly when paired with PET methods. WSC sees improvements with EDA, but these models are largely incapable of learning the data properly, so any benefits are likely spurious.

It is important to take notice of how the best performing method usually differs between finetuning, prefix tuning and LoRA, and that the per-



Figure 1: The t-SNE latent space for [CLS] token/sentence representation between BERT fine-tuning (top-left), BERT P-tuning v2 (bottom-right) and RoBERTa fine-tuning (bottom-left) and RoBERTa P-tuning v2 (top-right) on the RTE (top row) and CB (bottom row) datasets. Essentially, for each dataset we compare BERT and RoBERTa using either fine-tuning or P-tuning, while capturing all possible combinations across the two datasets. The resulting representations are obtained from training on clean data and testing on augmented validation data and the original validation data. Within each model scenario, each of the four boxes represents the results of testing that model on a different augmented dataset (blue for corrupted data, red for EDA, green for BT, and orange for the original data). The distribution of each individual class can be seen in these sub-boxes. Across each of the datasets and model types, the sentence representations of data for P-tuning v2 appear more jumbled and less separated across different classes.

formance of each DA method can change significantly between them as seen with BT on COPA between the the fine-tuned and prefix tuned versions of BERT, hence what works for fine-tuning cannot not be assumed to work for different PET methods. With these results we cannot universally recommend when using DA with prefix tuning or LoRA with limited data, although with careful selection, benefits can still be derived.

#### 5.2 Embedding Analysis

The poor performance of EDA and BT across many scenarios, particularly with P-tuning v2 prompts

Table 2: Accuracy and average entropy of softmax predictions of P-tuning with fine-tuning when trained on heavily modified training data. P-tuning is generally less robust against the corruptions compared to fine-tuning.

Model	rte		cb		copa		sst2	
	acc	ent.	acc	ent.	acc	ent.	acc	ent.
FT BERT	67.7	11.6	84.4	19.3	65.2	70.2	88.4	59.9
PT-v2 BERT	66.6	63.5	84.4	14.0	73.0	21.4	87.5	39.2
FT RoBERTa	77.6	75.9	90.6	18.9	84.6	26.7	95.5	10.6
PT-v2 RoBERTa	70.6	27.3	89.1	11.4	76.9	19.9	91.1	9.4



Figure 2: The t-SNE latent space for [CLS] token/sentence embeddings between fine-tuning BERT (top-left) and P-tuning RoBERTa (top-right) on RTE, and between fine-tuning (bottom-left) and P-tuning RoBERTa (bottom-right) on CB. The representations are the result of training on augmented data and testing on clean validation data (i.e. legend entries represent which training data was used).



Figure 3: Comparison of average cosine similarity between the sentence representations of fine-tuned and P-tuning v2 versions of BERT and RoBERTa across the RTE and CB datasets. We compare the representations of the [CLS] token embeddings and the mean sentence embeddings. We also include a baseline using a Sentence Transformer for an ideal similarity measure.

further study on how prefix tuning learns sentence representations of and under augmented data to identify any potential issues leading to poor performance. To do this, we apply t-SNE (van der Maaten and Hinton, 2008) to visualize and understand the latent space sentence embeddings between finetuning and P-tuning v2 versions of BERT and RoBERTa across both the RTE and CB datasets where we originally observed stark differences in performance of DA, particularly on RTE since there was a major divide between where DA works well (fine-tuned BERT) versus not well (prefix tuned RoBERTa). We plot the 2-D representation of the [CLS] token in the final hidden layer. Figure 1 shows the visualizations where we show the representations learned when training on clean data and testing on augmented validation data that was augmented the same way as the training data. We use EDA, BT, and the heavy corruption method described below in Section 5.3, along with a baseline using no DA. Through this we can examine how well each method deals with unfamiliar augmented data, and whether the augmented data is represented similarly to the original data. Figure 2 displays a different style of representations that are generated from training on augmented data and testing on the clean validation data. This can show how training with DA influences how well the model learns representations between different types of data. In both figures, we observe the same general trends between fine-tuning and prefix tuning, irrespective of model type and dataset. Despite certain models such as P-tuning v2 RoBERTa having stronger predictive performance than their finetuned counterparts with BERT, there is a noticeable lack of distinct clustering between class samples of different classes. The sentence representations from different classes of augmented data are less

separated. When trained on clean data, the representations of the augmented validation data are more jumbled and less separate in the representation space as well. Additionally, when trained using DA, the clustering in the BERT fine-tuned models is more distinct, especially for EDA and BT where P-tuning suffers. Even without augmentation and when using Mixup, the clustering differences remain. These visualizations demonstrate that there may be difficulties with how prefix tuning is able to process augmented data. Prefix tuning appears to be less robust against augmentation methods like EDA that can change the meaning of the original data, potentially presenting training challenges.

#### 5.3 Influence of Heavily Perturbed Data

In view of the generally poor performance of prefix tuning with EDA, and how it has issues with separating the sentence representations, we run experiments to confirm that prefix tuning struggles more with augmented data that is highly perturbed compared to the original. To simulate this heavily altered data scenario, we use all four of the EDA operations to modify up to 50% of the sentence with each of the operations, and generate eight sentences per original on RTE, CB, COPA, and SST2, and we compare the best validation performance of each training method. A performance degradation can be expected since the model should have a more difficult time generalizing when learning from largely incoherent, noisy data as noted in (Wei and Zou, 2019). As Table 2 shows, prefix tuning is generally unable to cope as well as fine-tuning when trained on this data but is usually more confident. A possible explanation for this phenomena is that since the parameters of the language models are frozen, the lower number of trainable parameters may have an easier time overfitting to the noise in the augmented data, which explains the low softmax entropy/high prediction confidence. In effect, these results signal the importance of selecting data augmentation methods that can preserve the meaning and structure of the original training data but still provide lexical diversity.

#### 5.4 Similarity Analysis

To formalize the qualitative analysis provided in Section 5.2 with quantitative results and to bring further insight on our results in Section 5.3, we run additional experiments comparing the average cosine similarities between the sentence embeddings produced by prefix tuning and fine-tuning.

Table 3: Accuracy with contrastive loss compared to original when training P-tuning v2 models with the static DA methods. There is usually an improvement when using the new loss (Cont.) compared to the original (OG) models.

		rte		cb		copa		sst2	
		OG	Cont.	OG	Cont.	OG	Cont.	OG	Cont.
BERT	EDA	68.8	72.0	90.1	90.6	72.0	73.2	88.4	89.8
	BT	71.2	73.2	94.8	93.8	75.0	75.8	88.4	90.6
RoBERTa	EDA	84.6	85.1	96.9	98.4	87.0	86.6	94.6	96.1
	BT	84.7	85.5	98.4	98.4	85.0	85.7	94.6	96.1

In particular, we compare the original and heavily corrupted versions of sentences. For this, we train fine-tuning and P-tuning v2 versions of BERT and RoBERTa on the clean data of the RTE and CB datasets, and evaluate on heavily corrupted validation constructed in the same manner as described in Section 5.3. We compute the cosine similarity between the sentence embeddings of the original and altered sentences and average across the whole dataset. We use both the [CLS] sentence embeddings as previously, and the mean sentence representation obtained by averaging all tokens in the final hidden state. To get an idea as to the ideal cosine similarities, we also include the average similarity obtained by using a model specifically tuned to measure sentence similarity; Sentence Transformer all-MiniLM-L6-v2 (Reimers and Gurevych, 2019). We graph our results, which can be seen in Figure 3. We average our results over 3 runs and compute the standard deviation. We discover that prefix tuning outputs extremely high similarities despite the data being highly corrupted when compared to fine-tuning, across both types of representations. In most cases, fine-tuning is much closer to the Sentence Transformer, and hence shows a greatly ability to differentiate between the differences in semantics between the two inputs. This signals that prefix-tuning needs a greater ability to be able to differentiate between different data, which may be key to improving its performance on augmented data.

#### 5.5 Benefits of Contrastive Loss

Given the results in Section 5.4, it is natural to ponder whether it is possible to improve the performance of DA with prefix tuning by using a method that can promote more defined clusters and greater dissimilarity between semantically different inputs. We study this by adding a contrastive loss term while training P-tuning v2. We generally adopt a version of NT-Xent loss proposed in



Figure 4: t-SNE latent space sentence embedding visualizations between P-tuning v2 RoBERTa with (right) and without (left) the contrastive loss term on the CB dataset. The representations shown are generated from training on EDA augmented data and then testing on various validation data (both augmented and unaugmented) similar to as described in Figure 1.

(Oord et al., 2018). We adapt their method to this task by creating positive samples in a batch via sampling pairs of inputs with the same class, and creating negative samples by sampling pairs of differing classes. More specifically, given a mini batch of size N, we generate an *i*th positive pair  $A_i = (a_i, \hat{a}_i)$  out of N with class k, by randomly sampling two inputs with the same class label and using their [CLS] representations. We generate two negative pairs  $B_i = (a_i, \hat{b}_i)$  and  $C_i = (b_i, \hat{a}_i)$  in the same manner where the two randomly sampled inputs b and  $\overline{b}$  do not have the same class label as the positive pair. These three pairs are used in the following equation for the contrastive loss,  $\mathcal{L} =$  $-\frac{1}{N}\sum_{i=1}^{N}\log\frac{e^{sim(a_{i},\hat{a}_{i})/\tau}}{e^{sim(a_{i},\hat{a}_{i})/\tau}+e^{sim(a_{i},\hat{b}_{i})/\tau}+e^{sim(\hat{a}_{i},b_{i})/\tau}},$ where sim() is a similarity measure for the representations, for which we use cosine similarity. We find that using a high temperature parameter  $\tau$  of 0.9 gives the best results. We also scale this additional loss by a parameter  $\lambda_{con}$  to avoid too much bias towards towards this loss, which we vary per model. In addition, we use the cosine similarity generated by Sentence Transformer all-MiniLM-L6-v2 between the original and augmented training samples to weight the cross entropy loss values to prioritize learning more semantically similar inputs.

Table 3 shows the results when we applied these additional loss terms for the training of P-tuning v2 BERT and RoBERTa models across RTE, CB, COPA, and SST2 using both EDA and BT. We usually observe a rise in accuracy when adding the contrastive term to training with DA, especially with EDA, and in cases where there is no performance gain, the results still remain similar. This signals how contrastive methods may be key to getting good performance using DA with prefix tuning. We do see that in some cases the increase observed is not enough to increase accuracy beyond the model trained without DA, so in these cases these DA techniques are largely inherently too ineffective for that specific task.

#### 5.6 Contrastive Loss Representations

As in Section 5.2, we qualitatively analyze the representations of the models trained using the contrastive loss when they are trained on augmented data. Figure 4 shows how adding the contrastive loss term not only helps the accuracy of augmenting P-tuning v2 RoBERTa on CB with EDA, but that it learns representations for augmented validation data that have more distinct clustering, especially with BT and the unaugmented validation data compared to only using regular cross entropy loss, showing how the method can help induce prefix tuning to learn more useful representations for augmented data. Our contrastive method is rather simple, and not particularly well suited for supervised learning. We do believe that exploring more suitable loss functions like Center Loss (Wen et al., 2016) might show even more promising results, which future work can explore.

# 6 Conclusion

We reveal how when limited training data is available, data augmentation can provide crucial improvements in accuracy when training classification models using PET methods, though the benefits are, however, not universal, and limitations exist when using certain methods. We also demonstrated how prefix tuning may have more difficulty learning sentence representations of augmented data. We further showed that contrastive learning can be a solution to these issues, and suggest that more work be done to find similar methods that can be more generalizable.

# Limitations

Although we present our results across multiple datasets and models, we have largely adhered to natural language understanding tasks. How effective the augmentation methods are on generationrelated tasks warrants further study.

In addition, another limitation is that we do not study the level of perturbations needed to have a negative effect on prefix tuning. Knowing this can shed light on what particular types of transformations are a problem for prefix tuning so that they can be avoided. Our hypothesis here is that such perturbation levels are sensitive to many factors during training, such as the difficulty of the task and the characteristics of the data augmentation approaches applied, which could be difficult to be quantified.

#### **Ethics Statement**

Any sort of technique where synthetic text data is generated in an automated fashion, especially with augmentation techniques like BT and EDA that can add or remove random words or completely rephrase sentences, can alter the original meaning or interpretation of a sentence. This has some potential to introduce additional unexpected biases into the training data, particularly when biased models are used to generate synthetic data (e.g. a racially biased translation model). Even with improved performance these biases can cause models to make unfair judgments, which can become a major concern in safety critical domains like in the legal or medical fields. As a consequence, before any data augmentation technique should be applied to PET techniques, there has to be a consideration of the underlying biases that can be introduced through the methods of producing synthetic data.

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# A Training Settings and Hyperparameters

In this section, we provide details on the general training settings we use along with the hyperparameters. The ideal hyperparameters for each type of model were tuned very carefully by using random search with additional manual tuning, and by largely following the recommendations in Mosbach et al. (2021) to achieve stable, high performance with fine-tuning and LoRA. Likewise, we generally use similar hyperparameters settings as in Liu et al. (2021) for training P-tuning v2 on the SuperGLUE datasets, since the authors manage to achieve solid results with their settings, although our models still required additional tuning in most cases as our methods differ from their original scope since we incorporate DA.

The general settings across all the models and datasets include the tokenizer max sequence length being set to 128 tokens, with the exception of WSC and SST-2 which are capped at 64. We use an AdamW optimizer (Loshchilov and Hutter, 2019) for all experiments, with a linear scheduler with warmup. For the BERT models we use a gradient clipping value of 1.0. We generally choose batch sizes between 16 or 32. We train each of the models using NVIDIA RTX-3090 GPUs (24GB) with our implementation for the base models being based on HuggingFace Transformers (Wolf et al., 2019). We make use of the Sentence-Transformers library as well (Reimers and Gurevych, 2019).

Fine-tuning Settings: The settings specific to the fine-tuned models are as follows: across all finetuned models we use a warmup rate of 10%. For BERT we vary the learning rate from 1e-5 and 5e-5 depending on dataset. CB uses 5e-5 for example, though the ideal for the other datasets can vary with 2e-5 for SST-2. The best batch size varies between 16 and 32, though generally a value of 16 performs better. For RoBERTa we use learning rates of either 1e-5 or 2e-5 and a batch size of 16 to achieve stable performance across all datasets and augmentation methods. The number of training epochs we choose is dependant on when the model begins to converge. For EDA this generally falls within 2-4 epochs for all datasets, while for BT it is 4-8. For Mixup and regular training, training epochs are in the range of 8-12, though RTE generally only needs 5-7 epochs.

**P-tuning v2 Settings:** The ideal hyperparameters for P-tuning v2 strongly vary between the cho-

sen dataset, augmentation method, and model-type, so to save space we only include the ranges over which tune the hyperparameters. We generally keep learning rates between 5e-3 to 5e-2, with the models trained with augmentation methods usually requiring lower rates from 7e-3 to 1e-2. The unaugmented models work best between 1e-2 to 5e-2. The ideal batch size is primarily 16 although 32 is more effective on datasets like RTE. The prefix sequence lengths are kept short, usually between 4 to 32 tokens. Prefix reparameterization is used across most of the datasets, and performs particularly well on CB and SST-2. The hidden dropout probability is consistently set at 0.1. Similarly, the prefix hidden size is kept consistent at 512. We do not use warmup for the prefix models. The number of training epochs to set generally falls within 10-25 for EDA, 20-40 for BT, and for Mixup and regular training 50-120, with the exact number depending on when the model converges to 100% training accuracy. The  $\lambda_{con}$  parameter we use when training with contrastive loss is set to be between 0.1 and 0.3, with most models using a value of 0.2.

**LoRA settings:** In many cases our settings for training the LoRA variations of the models are similar to those described for fine-tuning, though usually LoRA requires shorter training times. Regarding the LoRA specific parameters, rank r and LoRA reparametrization scaling parameter  $\alpha$ , we mirror the settings for BERT-base and RoBERTalarge in the original paper by Hu et al. (2021) with r = 8,  $\alpha = 8$  and r = 8,  $\alpha = 16$  for each model type respectively. We use the adapter-transformers library (Pfeiffer et al., 2020) to implement LoRA.