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> Open-source repository: https://github.com/salesforce/LAVIS Supplementary video: https://youtu.be/0CuRowHu7TA

#### Abstract

We introduce LAVIS, an open-source deep learning library for LAnguage-VISion research and applications. LAVIS aims to serve as a one-stop comprehensive library that brings recent advancements in the language-vision field accessible for researchers and practitioners, as well as fertilizing future research and development. It features a unified interface to easily access state-of-the-art image-language, videolanguage models and common datasets. LAVIS supports training, evaluation and benchmarking on a rich variety of tasks, including multimodal classification, retrieval, captioning, visual question answering, dialogue and pre-training. In the meantime, the library is also highly extensible and configurable, facilitating future development and customization. In this paper, we describe design principles, key components and functionalities of the library, and also present benchmarking results across common language-vision tasks.

## 1 Introduction

Multimodal content, in particular language-vision data including texts, images and videos are ubiquitous for real-world applications, such as content recommendation, e-commerce and entertainment. There has been tremendous recent progress in developing powerful language-vision models (Su et al., 2020; Lu et al., 2019; Chen et al., 2020; Li et al., 2020; Huang et al., 2021; Li et al., 2021a; Radford et al., 2021; Zhou et al., 2020; Gan et al., 2020; Cho et al., 2021; Zhang et al., 2021; Li et al., 2022b; Zhu and Yang, 2020; Bain et al., 2021; Xu et al., 2021; Lei et al., 2021; Li et al., 2022a). However, training and evaluating these models across tasks and datasets require domain knowledge and are not always welcoming to incoming researchers and practitioners. This is mainly due to inconsistent interfaces across models, datasets and task evaluations, and also the duplicating yet



Figure 1: Overall architecture of the LAVIS library.

non-trivial efforts to prepare the required experiment setup. To make accessible the emerging language-vision intelligence and capabilities to a wider audience, promote their practical adoptions, and reduce repetitive efforts in future development, we build LAVIS (short for LAnguage-VISion), an open-source library for training, evaluating stateof-the-art language-vision models on a rich family of common tasks and datasets, as well as for offthe-shelf inference on customized language-vision data.

Figure 1 shows the overall design of LAVIS. Important features of LAVIS include (i) **Unified interface and modular design**. Key components in the library are organized using a unified and modular design. This allows effortless off-the-shelf access to individual components, swift development and easy integration of new or external components. The modular design also eases model inferences, such as multimodal feature extraction. (ii) **Comprehensive support of image-text, video-**

text tasks and datasets. LAVIS supports a growing list of more than ten common language-vision tasks, across over 20 public datasets. These tasks and datasets provide a comprehensive and unified benchmark for evaluating language-vision models. (iii) State-of-the-art and reproducible languagevision models. The library enables access to over 30 pre-trained and task-specific fine-tuned model checkpoints of 5 foundation models: ALBEF (Li et al., 2021a), BLIP (Li et al., 2022b), BLIP2 (Li et al., 2023b), CLIP (Radford et al., 2021) and AL-PRO (Li et al., 2022a), as well as state-of-the-art language-vision methods such as PnP-VQA (Tiong et al., 2022), Img2Prompt (Guo et al., 2022). These models achieve competitive performance across multiple tasks, representing the up-to-date development status of the language-vision research. We also provide training, evaluation scripts and configurations to facilitate reproducible language-vision research and adoption. (iv) Resourceful and useful toolkit. In addition to the core library functionalities, we also provide useful resources to reduce the learning barriers for the language-vision research. This includes automatic dataset downloading tools to help prepare the supported datasets, a GUI dataset browser to help preview downloaded datasets and dataset cards documenting sources, supported tasks and leaderboards.

## 2 Related Work

Table 1 summarizes the comparisons between LAVIS' key features with those of other libraries. Most related libraries include MMF (Singh et al., 2020), UniLM (uni, 2020), X-modaler (Li et al., 2021b) and TorchMultimodal (tor, 2022).

• MMF is a comprehensive multimodal framework encapsulating many language-vision models and datasets. It implements modular interface for training and evaluation. However, it consists of mostly task-specific architectures. Besides showing relatively inferior performance, these models are usually not easy to transfer across tasks. Among the included foundation models (Li et al., 2019; Chen et al., 2020; Zhang et al., 2021; Li et al., 2021a) in MMF, few fully supports finetuning or benchmarking on the extended list of downstream tasks. In contrast, considering that pre-trained foundation models prevail across overwhelmingly many tasks and datasets with more principal and unified architectures, our

library focuses on pre-trained models and their task-specific variants instead.

- UniLM was initiated for developing large language models, and recently also aggregates multiple standalone repositories of multimodal models. Yet, support for multimodal models in UniLM is limited in its current development status. Moreover, UniLM does not provide unified or modular interfaces to allow easy access or reproduction.
- X-modaler supports a limited number of tasks and datasets, which are not as comprehensive as LAVIS. Besides, similar to MMF, models in X-modaler are also mostly in task-specific architectures. The few supported foundation model, e.g. (Chen et al., 2020), achieves inferior results than models in LAVIS.
- A concurrent library TorchMultimodal (tor, 2022) promotes modular development of language-vision models. Our library supports a wider range of tasks and datasets than Torch-Multimodal while being more comprehensive and resourceful.

Other open-source implementations of individual models exist (Chen et al., 2020; Li et al., 2020; Lu et al., 2019; Radford et al., 2021; Gan et al., 2020; Lei et al., 2021), yet do not provide centralized access. In summary, in contrast to previous efforts, our library stands out by providing *easier* access to *stronger* models on comprehensively *many* tasks and datasets. With this effort, we hope to significantly reduce the cost and effort to leverage and benchmark existing multimodal models, as well as to develop new models.

## **3** Supported Tasks, Datasets and Models

Table 3 summarizes the supported tasks, datasets and models in LAVIS. In particular, we prioritize tasks that are standard, widely adopted for evaluation, and with publicly available datasets. For image-text tasks, the library implements image-text retrieval, image captioning, visual question answering (VQA), visual dialogue, visual entailment (VE), natural language visual reasoning (NLVR<sup>2</sup>) and image classification. For video-text tasks, LAVIS currently support video-text retrieval and video question answering (VideoQA). There are in total over 20 public datasets supported, including MSCOCO (Lin et al., 2014), Flickr30k (Plummer et al., 2015), VQAv2 (Goyal et al., 2017), OK-VQA (Marino

		LAVIS (Ours)	MMF	UniLM	X-modaler	TorchMultimodal
Unified Model and Dataset Interface		$\checkmark$				
Ν	Iodular Library Design	$\checkmark$	$\checkmark$		$\checkmark$	$\checkmark$
Pre-trained Model Checkpoints		$\checkmark$				
Task-specific Finetuned Model Checkpoints		$\checkmark$			$\checkmark$	
Madalitian	Image-Text	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$
Modalities	Video-Text	$\checkmark$	$\checkmark$		$\checkmark$	
	End2end Pre-training	$\checkmark$		$\checkmark$		$\checkmark$
	Multimodal Retrieval	$\checkmark$	$\checkmark$		$\checkmark$	
Tasks	Captioning	$\checkmark$	$\checkmark$		$\checkmark$	
Tasks	Visual Question Answering	$\checkmark$	$\checkmark$		$\checkmark$	
	Multimodal Classification	$\checkmark$	$\checkmark$			
	Instructed Zero-shot Generation	$\checkmark$				
	Visual Dialogue	$\checkmark$				
	Multimodal Feature Extraction	$\checkmark$				
	Benchmarks	$\checkmark$				
	Dataset Auto-downloading	$\checkmark$	$\checkmark$			
Toolkit	Dataset Browser	$\checkmark$				
	GUI Demo	$\checkmark$				
	Dataset Cards	$\checkmark$				

Table 1: Comparison of features in LAVIS and other existing language-vision libraries or codebase. Note that language-vision models in UniLM and TorchMultimodal (alpha release) are under development, therefore, the table only includes their supported features by the publication time of this technical report.

Table 2: Supported tasks, datasets and models in LAVIS.

Supported Tasks	Supported Models	Supported Datasets
Image-text Pre-training	ALBEF, BLIP, BLIP2, InstructBLIP	COCO, Visual Genome, SBU Caption, Conceptual Captions (3M, 12M), LAION
Image-text Retrieval	ALBEF, BLIP, BLIP2, CLIP	COCO, Flickr30k
Visual Question Answering	ALBEF, BLIP, BLIP2, InstructBLIP	VQAv2, OKVQA, A-OKVQA, GQA
Image Captioning	BLIP, BLIP2, InstructBLIP	COCO Caption, NoCaps
Image Classification	CLIP	ImageNet
Natural Language Visual Reasoning (NLVR <sup>2</sup> )	ALBEF, BLIP	$NLVR^2$
Visual Entailment	ALBEF	SNLI-VE
Visual Dialogue	BLIP, InstructBLIP	VisDial
Video-text Retrieval	ALPRO, BLIP	MSRVTT, DiDeMo
Video Question Answering	ALPRO, BLIP, InstructBLIP	MSRVTT-QA, MSVD-QA
Video Dialogue	BLIP	AVSD

et al., 2019), A-OK-VQA (Shevchenko et al., 2021), GQA (Hudson and Manning, 2019), Visual Genome (Krishna et al., 2017), ImageNet (Deng et al., 2009), NoCaps (Agrawal et al., 2019), Conceptual Captions (Sharma et al., 2018; Changpinyo et al., 2021), SBU-caption (Ordonez et al., 2011), LAION (Schuhmann et al., 2021), NLVR<sup>2</sup> (Suhr et al., 2019), SNLI-VE (Bowman et al., 2015), VisDial (Das et al., 2017), AVSD (Alamri et al., 2019), MSRVTT (Xu et al., 2016), MSVD (Xu et al., 2017), DiDeMo (Anne Hendricks et al., 2017) and their task-specific variants. LAVIS currently supports 6 foundation models, i.e. AL-BEF (Li et al., 2021a), BLIP (Li et al., 2022b), BLIP2 (Li et al., 2023b), CLIP (Radford et al.,

2021), InstructBLIP (Dai et al., 2023) and AL-PRO (Li et al., 2022a). In addition, the library also features language-vision methods including PnP-VQA (Tiong et al., 2022) and Img2prompt (Guo et al., 2022), and text-to-image generation model BLIP-Diffusion (Li et al., 2023a). These models and methods show strong performance on the aforementioned tasks and datasets, representing the upto-date development status of the language-vision research field. Detailed description can be found in A.1

## 4 Library Design

This section delineates the design of LAVIS as shown in Figure 1. Our key design principle is to provide a simple and unified library to easily (i) train and evaluate the model; (ii) access supported models and datasets; (iii) extend with new models, tasks and datasets.

#### 4.1 Description on each library component

Key components in LAVIS include:

- **Runners** lavis.runners module manages the overall training and evaluation lifecycle. It is also responsible for creating required components lazily as per demand, such as optimizers, learning rate schedulers and dataloaders. Currently, RunnerBase implements epoch-based training and RunnerIters implements iteration-based training.
- **Tasks** lavis.tasks module implements concrete training and evaluation logic per task. This includes pre-training and finetuning tasks as listed in Table 3. The rationale to have an abstraction of task is to accommodate taskspecific training, inference and evaluation. For example, evaluating a retrieval model is different from a classification model.
- Datasets lavis.datasets module helps create datasets. Specifically, datasets.builders module loads dataset configurations, downloads annotations and builds the dataset;
  - lavis.datasets.datasets module defines the supported datasets, each is a PyTorch dataset instance.
  - We also provide automatic dataset downloading tools in datasets/download\_scripts to help prepare common public datasets.
- **Models** lavis.models module holds defi- <sup>13</sup> # nitions for the supported models and shared <sup>14</sup> # model layers.
- **Processors** –lavis.processors module handles preprocessing of multimodal input. A processor transforms input images, videos and texts into the desired form that models can consume.
- Common tools and utilities lavis.commons module contains shared classes and methods used by multiple other modules. For example, configs module

contains classes to store and manipulate configuration files used by LAVIS. In particular, we use a hierarchical configuration design, to allow highly customizable training and evaluation. The registry module serves as a centralized place to manage modules that share the same functionalities. It allows building datasets, models, tasks, and learning rate schedulers during runtime, by specifying their names in the configuration; optims contains definitions of learning rate schedulers; utils contains miscellaneous utilities, mostly IO-related helper functions;

#### 4.2 Example library usage

The design of the library enables easy access to existing models and future development. In this section, we include a few examples to demonstrate some common use cases.

## Unified interface for data and model loading

LAVIS provides unified interface load\_dataset and load\_model to access supported datasets and models. This is helpful for off-the-shelf use of datasets and model inference etc. In the first example, we show how to load a dataset using the library.

```
from lavis.datasets.builders import
         load_dataset
   2 # load a specific dataset
   3 coco_dataset = load_dataset("
         coco_caption")
  4 # dataset is organized by split names.
   5 print(coco_dataset.keys())
   6 # dict_keys(['train', 'val', 'test'])
   7 # total number of samples in the
         training split.
   8 print(len(coco_dataset["train"]))
  9 # 566747
to <sup>10</sup> # peek a random sample
   in print(coco_dataset["train"][0])
   12 # {'image': <PIL.Image.Image image mode=</pre>
         RGB size=640x480>,
          'text_input': 'A woman wearing a net
          on her head cutting a cake. '
   14 #
         'image_id': 0}
```

Models and their related preprocessors can also be loaded via a unified interface, which facilitates effortless analysis and inference on custom data. In the following, we show an example that uses a BLIP captioning model to generate image captions.

```
1 from lavis.models import
load_model_and_preprocess
2 # load model and preprocessors
3 model, vis_procs, _ =
load_model_and_preprocess(
4 name="blip_caption", model_type="
base_coco")
```

# Unified interface for multimodal feature extraction

LAVIS supports a unified interface to extract multimodal features. The features are useful especially for offline applications where end-to-end finetuning is not affordable. By changing name and model\_type, users can choose to use different model architecture and pre-trained weights.

```
1 # load feature extraction models and
      processors
2 model, vis_procs, txt_procs =
      load_model_and_preprocess(
          name="blip_feature_extractor",
3
          model_type="base"
4
5)
6 # a random instance from coco dataset
7 raw_image = coco_dataset["test"][0]["
      image"]
8 text = coco_dataset["test"][0]["
      text_input"]
9 # process the input
image = vis_procs["eval"](raw_image).
      unsqueeze(0)
in text_input = txt_procs["eval"](text)
12 sample = {"image": image,
13 "text_input": [text_input]}
14
15 # extract multimodal features
16 feature = model.extract_features(sample)
```

## 5 Benchmarks and Library Toolkit

In this section, we benchmark model performance across tasks and datasets in LAVIS. Then we take our web demo interface to show a few case studies on multimodal content understanding. We also present a GUI dataset browser that helps to preview supported datasets.

#### 5.1 Main results

The purpose of the benchmark is two-fold. First, we use the benchmark to validate that our reimplementation faithfully replicates official models. Second, the benchmark also serves as a reference for further development. In Table 5-4, we organize benchmark results by models and compare our replication results with those reported of-

Table 3: Comparison between official and replicated performance using BLIP. TR denotes text retrieval; IR denotes image retrieval. Results are produced by BLIP<sub>CapFilt-L</sub> model. NoCaps results are reported on the entire validation set. Retrieval and captioning results are reported on the test sets; B@4 denotes BLEU-4.

Tasks	Datasets	Impl.		Results	
Retrieval			R1	R5	R10
TR	COCO	0	82.4	95.4	97.9
IK		۲	82.0	95.8	98.1
IR	COCO	0	65.1	86.3	91.8
IK	COCO	۲	64.5	86.0	91.7
TR	Flickr30k	0	97.2	99.9	100.0
IK		۲	96.9	99.9	100.0
IR	Flickr30k	0	87.5	97.7	98.9
IK		۲	87.5	97.6	98.9
			dev	std	
VQA	VQAv2	0	78.25	78.32	
		۲	78.23	78.29	
			B@4	CIDEr	SPICE
Image	COCO	0	39.7	133.3	-
Captioning	COCO	۲	39.7	133.5	23.7
Captioning	NoCaps	0	-	109.6	14.7
		۲	31.9	109.1	14.7
M 141			val	test	
Multimodal Classification	NLVR2	0	82.15	82.24	
Chassincation		۲	82.48	83.25	

Table 4: Comparison between official and replicated performance using CLIP-ViT-L/336. Note the relative difference is possibly due to the versioning of the model weights.

Tasks	Datasets	Datasets Impl.			Results			
Retrieval			R1	R5	R10			
TR	COCO	0	58.4	81.5	88.1			
IK		۲	57.2	80.5	87.8			
ID	COCO	0	37.8	62.4	72.2			
IR		۲	36.5	60.8	71.0			
TR	Flickr30k	0	88.0	98.7	99.4			
IK		۲	86.5	98.0	99.1			
IR	Flickr30k	0	68.7	90.6	95.2			
IK		۹	67.0	88.9	93.3			
Zero-shot Image			val					
Classification	ImageNet	0	76.2					
Classification		۲	76.5					

ficially. Experiments are conducted on NVIDIA A100 GPUs.

For ALBEF, BLIP, BLIP2 and ALPRO, we reimplement their models in LAVIS based on the official repositories and report finetuning results using their official pre-trained weights. For CLIP models, we integrate a third-party implementation (Ilharco et al., 2021) and report CLIP-ViT-L/336 zero-shot inference results using the official weights (Radford et al., 2021) (Table 4). As can be seen in the



Figure 2: Screenshots of the GUI web demo, showing various applications including image captioning, zeros-shot image classification, text localization and visual question answering.



Figure 3: The developed dataset browser helps to quickly gain understanding of multimodal datasets.

tables, our library produce consistent results as reported officially. More benchmarking results with BLIP, ALPRO models can be found in A.2.

#### 5.2 Library resources and toolkit

In addition to the components aforementioned, LAVIS also provides useful toolkit and resources to further ease development. This includes pretrained and finetuned model checkpoints, automatic dataset downloading tools, a web demo and a dataset browser.

**Pre-trained and finetuned model checkpoints.** We include pre-trained and finetuned model checkpoints in the library. This promotes easy replication of our experiment results and to repurpose pre-trained models for other applications. Model checkpoints are downloaded automatically upon loading models.

Web demo. As shown in Figure 2, we develop a GUI-based web demo, which aims to provide a user-friendly interface to explore various multimodal capabilities. Currently the demo supports the following functionalities: (i) *image captioning*: produces a caption in natural language to describe an input image; (ii) *visual question answering*: answer natural language questions regarding the input image; (iii) *multimodal search*: search images in a gallery given a text query; (iv) *text visualization*: given an input image and a text caption, produces GradCam (Selvaraju et al., 2017) for each text token on the image; (v) zero-shot multimocal classification: classify an input images into a set of input labels in text. (vi) Thanks to the modular design of LAVIS, one can easily extend the demo with new functionalities, such as *text-to-image generation*, as shown in the Figure 2.

Automatic dataset downloading and browsing. Preparing language-vision datasets for pre-training and fine-tuning incurs much duplicating effort. To this end, LAVIS provides tools to automatically download and organize the public datasets, so that users can get access to the common datasets easier and quicker. In addition, we develop a GUI dataset browser, as shown in Figure 3, that helps users to rapidly gain intuitions about the data they use.

## 6 Conclusion and Future Work

We present LAVIS, an open-source deep learning library for language-vision research and applications. The library is designed to provide researchers and practitioners with easier and comprehensive access to state-of-the-art multimodal capabilities, The library also features a unified interface and extensible design to promote future development. Besides, the library also features extensive access to pre-trained weights and useful resources to reduce duplicating replication efforts. With these features, we expect LAVIS to serve as a one-stop library in multimodal AI for a wider audience.

We continue to actively develop and improve LAVIS. In future releases, our priorities are to include more language-vision models, tasks and datasets to the library. We also plan to add more parallelism support for scalable training and inference. While we will maintain LAVIS in the long term, we invite contributions from the open-source community to join this evolving effort.

#### **Broader Impact and Responsible Use**

LAVIS can provide useful capabilities for many real-world multimodal applications. It features easy, unified and centralized access to powerful language-vision models, facilitating effective multimodal analysis and reproducible research and development. We encourage researchers, data scientists, and ML practitioners to adopt LAVIS in real-world applications for positive social impacts, e.g. efficient and environment-friendly large-scale multimodal analysis.

However, LAVIS may also be misused. We encourage users to read detailed discussion and guidelines for building responsible AI, e.g. (Baxter, 2022). In particular, LAVIS should not be used to develop multimodal models that may expose unethical capabilities.

It is also important to note that that models in LAVIS provide no guarantees on their multimodal abilities; incorrect or biased predictions with outof-date information may be observed. In particular, the datasets and pretrained models utilized in LAVIS contain socioeconomic biases which may result in misclassification and other unwanted behaviors such as offensive or inappropriate speech. We strongly recommend that users review the pretrained models and overall system in LAVIS before practical adoption. We plan to improve the library by investigating and mitigating these potential biases and inappropriate behaviors in the future.

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## A Appendix

### A.1 Details of the supported models

- ALBEF is an image-text model. It employs a ViT (Dosovitskiy et al., 2021) as the image encoder, early BERT (Devlin et al., 2019) layers as the text encoder, and re-purposes late BERT layers as the multimodal encoder by adding cross-attentions. It proposes the novel image-text contrastive (ITC) loss to align unimodal features before fusing them using the multimodal encoder. It is also one of the first few models requiring no region information while demonstrating strong multimodal understanding capability.
- BLIP primarily tackles image-text tasks, while also showing strong zero-shot transfer capabilities to video-text tasks. It employs a ViT as the image encoder and a BERT as the text encoder. To facilitate multimodal understanding and generation, BLIP proposes mixture of encoder-decoder (MED), which repurposes BERT into multimodal encoder and decoder with careful weight sharing. Moreover, BLIP proposes dataset bootstrapping to improve the quality of texts in the pre-training corpus by removing noisy ones and generating new diverse ones. In addition to the improved understanding capability compared to ALBEF, BLIP highlights its strong text generation ability, producing accurate and descriptive image captions. When adapted to video-text tasks, it operates on sampled frames while concatenating their features to represent the video.
- BLIP2 represents a generic and efficient language-vision pre-training strategy that leverages available frozen image encoders and large language models (LLMs). The model introduces a two-staged training strategy to bridge the modality gap with a lightweight module, called Querying Transformer (Q-Former). In addition to the strong performance on existing tasks, including VQA, multimodal retrieval, captioning, BLIP-2 also unlocks the novel capabilities of zero-shot image-to-text generation following natural language instructions.
- CLIP is a family of powerful image-text models. Different from ALBEF and BLIP, CLIP models adopt two unimodal encoders to obtain

image and text representations. CLIP maximizes the similarity between positive imagetext pairs, and was trained on 400M imagetext pairs, rendering strong and robust unimodal representations. CLIP variants employ different visual backbones, including ResNet-50 (He et al., 2016), ViT-B/16, ViT-B/32, ViT-L/14, ViT-L/14-336. We integrate a thirdparty implementation of CLIP (Ilharco et al., 2021) into LAVIS while including the official pre-trained weights.

 ALPRO is a video-text model, tackling videotext retrieval and video question answering tasks. It uses TimeSformer (Bertasius et al., 2021) to extract video features, and BERT to extract text features. Similar to ALBEF, AL-PRO uses contrastive loss to align unimodal features, yet it opts to use self-attention to model multimodal interaction. This architecture choice enables an additional visualgrounded pre-training task, i.e. prompt entity modeling (PEM) to align fine-grained videotext information. ALPRO is strong in extracting regional video features and remains competitive for video understanding tasks across various datasets.

#### A.2 Additional benchmarking results

In Table 5 and 6, we show benchmarking results with BLIP and ALPRO reimplmentations in LAVIS. As shown in the tables, the results are consistent with those in the original implementation.

In Table 7, we present results by adapting models in LAVIS to new tasks and datasets, on which the models were not previously reported on. In this way, we show that our library helps to easily adapt to new tasks and datasets, while achieving competitive performance.

Knowledge-based VQA (KVQA). The task of KVQA aims to measure the commonsense knowledge learnt by language-vision models, where models are asked to answer questions involving external knowledge. To this end, state-of-the-art models (Gui et al., 2021; Kamath et al., 2022) resort to external knowledge base(Vrandečić and Krötzsch, 2014) or large language models(Brown et al., 2020). In our experiments, we show that language-vision pre-trained models finetuned on VQAv2(Goyal et al., 2017) show strong transfer results to KVQA datasets. With additional finetuning on KVQA datasets, further improvements are ob-

Table 5: Comparison between official and replicated performance using BLIP. TR denotes text retrieval; IR denotes image retrieval. Results are produced by BLIP<sub>CapFilt-L</sub> model. NoCaps results are reported on the entire validation set. Retrieval and captioning results are reported on the test sets; B@4 denotes BLEU-4.

Tasks	Datasets	Impl.		Results	
Retrieval			R1	R5	R10
TR	COCO	0	82.4	95.4	97.9
IK		۲	82.0	95.8	98.1
IR	COCO	0	65.1	86.3	91.8
IK	COCO	۲	64.5	86.0	91.7
TR	Flickr30k	0	97.2	99.9	100.0
IK	FIICKIJOK	۲	96.9	99.9	100.0
IR	Flickr30k	0	87.5	97.7	98.9
IK		۲	87.5	97.6	98.9
			dev	std	
VQA	VOA-2	0	78.25	78.32	
	VQAv2	۲	78.23	78.29	
			B@4	CIDEr	SPICE
Image	6060	0	39.7	133.3	-
Captioning	COCO	۲	39.7	133.5	23.7
Captioning	NaCana	0	-	109.6	14.7
	NoCaps	۲	31.9	109.1	14.7
			val	test	
Multimodal Classification	NLVR2	0	82.15	82.24	
Classification		۲	82.48	83.25	

served on both OK-VQA and AOK-VQA datasets. As a result, our best model BLIP surpasses previous state-of-the-art by a clear margin.

Video Dialogue. The task of video-grounded dialogues requires models to generate a natural response given a dialogue context and a grounding video (Alamri et al., 2019). Existing models have exploited new architectural designs (Le et al., 2019), additional learning tasks (Le et al., 2022, 2021), and pretraining (Le and Hoi, 2020; Li et al., 2021c) to improve the model abilities to understand multimodal context and generate natural language. In our experiments, we show that our library can be easily integrated with any vision-language models (such as VGD-GPT (Le and Hoi, 2020)) to adapt to this dialogue task. The results in Table 7 show that our model implementation with LAVIS can lead to impressive performance, comparable to current state-of-the-art approaches.

## A.3 Supplementary video and online demo:

The supplementary video can be found:https:// youtu.be/0CuRowHu7TA. In the following, we provide additional benchmarking results using models in LAVIS.

Alternatively, the video can be downloaded from: https://drive.google.com/file/d/

Table 6: Comparison between official and replicated task performance using ALPRO. TR denotes video-to-text retrieval; VR denotes text-to-video retrieval.

Tasks	Datasets	Impl.		5	
Retrieval			R1	R5	R10
TR	MSRVTT	0	32.0	60.7	70.8
IK		۲	33.2	60.5	71.7
VD	MSRVTT	0	33.9	60.7	73.2
VR		۲	33.8	61.4	72.7
TD	DiDeMo	0	37.9	67.1	77.9
TR		۲	38.8	66.4	76.8
VR	DiDeMo	0	35.9	67.5	78.8
VK		۹	36.6	67.5	77.9
			test		
	MSRVTT	0	42.1		
VideoQA		۲	42.1		
	MSVD	0	45.9		
		۲	46.0		

Table 7: Experiment results on KVQA compared with best existing methods. Due to the submission number limits, only BLIP AOKVQA result on the test split is reported.

Tasks	Datasets	Models	Results		
			test		
		KAT (Single)(Gui et al., 2021)	53.1		
	OKVQA	KAT (Ensemble)(Gui et al., 2021)	54.4		
		ALBEF	54.7		
KVQA		BLIP	55.4		
			val	test	
		GPV-2(Kamath et al., 2022)	48.6	40.7	
	AOKVQA	ALBEF	54.5	-	
		BLIP (VQAv2)	53.4	-	
		BLIP	56.2	50.1	
			B@4	CIDEr	
*** *		MTN (Le et al., 2019)	0.410	1.129	
Video Dialogue	AVSD	PDC (Le et al., 2021)	0.429	1.194	
Dialogue		RLM (Li et al., 2021c)	0.459	1.308	
		VGD-GPT	0.465	1.315	

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A public demo of LAVIS can be found at the temporary address: http://34.123.225.190:8080/