Mitigating Contradictions in Dialogue Based on Contrastive Learning

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Abstract

Chatbot models have achieved remarkable progress in recent years but tend to yield contradictory responses. In this paper, we exploit the advantage of contrastive learning technique to mitigate this issue. To endow the model with the ability of discriminating contradictory patterns, we minimize the similarity between the target response and contradiction related negative example. The negative example is generated with learnable latent noise, which receives contradiction related feedback from the pretrained critic. Experimental results show that our method helps to avoid contradictions in response generation while preserving response fluency, outperforming existing methods on both automatic and human evaluation.

1 Introduction

In recent years, with the advent of large training corpora and pretrain technology, chatbot models have evolved considerably in open domain (Bao et al., 2020; Roller et al., 2021). Current chatbots have achieved surprising results in generating fluent, engaging, informative responses, but still occasionally generate responses that are contradictory with history when interacting with human (Li et al., 2021b). Such contradiction issues are often jarring and severely disrupt communication. Therefore, it is essential to reduce contradiction for chat-bots in multi-turns dialogues.

Previous work (Li et al., 2016; Song et al., 2020) proposes to use the paradigm of RL to mitigate the gap between the training and contradiction avoiding objective. However, the RL-based methods are easy to degrade in deep neural network (Parisotto et al., 2020), leading to the decoder generates responses that deviate from human language (Lewis et al., 2017; Kottur et al., 2017). Other method (Li et al., 2020) aims to address dialogue logical contradictions via unlikelihood training (Welleck et al., 2019). While they reduce the probability of the labeled contradicting responses, it is less generalizable to different conversation scenarios with the limited coverage of labeled contradicting data.



Figure 1: The similarity between correct and contradictory response is 0.9315 in blenderbot embedding space.

We argue that one of the reasons behind contradiction is that model lacks the ability to identify contradictory behavior clearly. As shown in Fig.1, the large pretrained chatbot blenderbot (Roller et al., 2021) still has high similarity between the correct and contradictory responses in embedding space. Chatbots are likely to cause contradictions when probed with unusual conversations during inference (Roller et al., 2021), while they are commonly trained to mimic human context-response pairs under the teacher-forcing algorithm (Williams and Zipser, 1989). Without being exposed to incorrect and contradictory context-response pairs, chatbots fail to learn the ability that discriminating contradictory response patterns directly, which hurts its robustness to avoid contradiction.

To tackle this challenging issue, we propose a novel method to Mitigate Contradiction via Contrastive Learning, namely MCCL. Our method explicitly perceives the difference between the self-contradiction negative example and semanticaligned positive example. Instead of utilizing welllabeled contradicting examples (Li et al., 2020), we generate a self-contradiction negative example with a learnable latent noise. To capture contradic-

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tion actions, we employ the policy gradient method for rewarding the latent noise based on the feedback from a pre-trained critic. Furthermore, we construct an additional positive example by adding a small perturbation. The positive example has aligned semantic with the original context, which devotes to the training stability and robustness.

Overall, our contributions are summarized as follows: 1) To mitigate contradictions in dialogue, we propose a novel method named MCCL, which contrasts target response with negative pairs, to make chatbot models discriminate and refrain from contradictory response patterns. 2) Experiment results show that our method performs better than baselines in automatic metrics and manual evaluation, especially in contradiction score.

2 Related work

2.1 Consistent Conversation

It has been a long-standing goal of artificial intelligence to build an intelligent conversational system that passes the Turing test (Turing, 1950). Researchers improve chatbots intelligence according to dialogue consistency-related information like style (Wang et al., 2017), topic (Dziri et al., 2019) or persona fact (Zhang et al., 2018). Despite showing improvements in guided response generation based on consistency modeling, the issue of contradiction still remains challenging (Nie et al., 2021).

2.2 Contrastive Learning

The concept of contrastive learning has been widely used adopted in many tasks. SimCLR (Chen et al., 2020) shows that contrastive learning can boost the performance of self-supervised and semisupervised learning in computer vision tasks. In recent years, contrastive learning has been been widely investigated for many NLP tasks, including language modeling (Gao et al., 2021; Li et al., 2021a), text summarization (Liu and Liu, 2021) and machine translation (Pan et al., 2021).

3 Approach

3.1 Encoder-decoder Architecture

Similar to conventional chatbots model (Roller et al., 2021; Bao et al., 2020), our response generation model employs the encoder-decoder architecture. Given the context history C and target response $Y = (y_1, \ldots, y_T)$, the encoder first transforms C into a sequence of hidden representations M. After that, the decoder predicts Y at word level. The decoding process at each time step t can be formalized as follows:

$$h_t = Decoder(M, y_{t-1})$$

$$P(y_t | y_{< t}, C) = softmax(W_d h_t + b_d)$$
(1)

where h_t is the hidden representation of y_t (the *t*-th word in the response). We maximize the conditional log likelihood for a given N observation $(C^{(i)}, Y^{(i)})_{i=1}^N$ as follows:

$$\mathcal{L}_{MLE} = -\sum_{i=1}^{N} \sum_{t=1}^{T} log P(y_t^{(i)} | y_{< t}^{(i)}, C^{(i)}) \quad (2)$$

3.2 Contrastive Learning Framework

In order to tackle the contradiction problem, we exploit contrastive learning framework to expose various incorrect dialogue pairs. Following (Chen et al., 2020), we can train the model to learn the response representation by contrasting the positive pairs with the negative pairs. A straightforward approach is to treat randomly selected responses from different conversations as semantic negative examples (Sinha et al., 2020). Then we have the base contrastive learning objective as follows:

$$\mathcal{L}_{c} = -\sum_{i=1}^{N} \log \frac{f(M^{(i)}, H^{(i)})}{\sum_{m \in S} f(m, H^{(i)})} \qquad (3)$$

where $S = \{M^{(j)}\}_{j=1}^{N}$ is a set of context hidden representations randomly sampled from the same batch, $H = [h_1, ..., h_T]$ is the the concatenation of the hidden representations of the target tokens. The function $f(\cdot, \cdot)$ calculates the correlation between context and response as follows:

$$c = Pool(\phi_x(M))$$

$$z = Pool(\phi_y(H))$$
(4)

$$f(M, H) = exp(sim(c, z)/\tau)$$

where ϕ_x and ϕ_y are two fully connected layers with RELU activation and *Pool* is the average pooling function, *sim* is the inner product between two vectors, τ is the temperature hyperparameter. Such contrastive learning objective guides chatbot model to learn a more accurate representation of the target response sequence, by identifying which features make the output positive or negative.

3.3 Self-contradiction Negative Example

However, there is no explicit contradiction relationship between the randomly selected non-aligned context and target response. To expose the chatbot model with a contradiction-related negative example, we learn a latent noise ζ based on the input context. Inspired by (Zhao et al., 2019), we decouple the latent noise learning process from response generation. The latent noise ζ is taken as the form of continuous isotropic Gaussian distribution (Serban et al., 2017). We first determine the distribution of latent noise as follows:

$$\mu, log(\sigma^2) = \pi(M)$$

$$P(\zeta|M) = N(\mu, \sigma^2)$$
(5)

where π is a feed forward network that projects Minto μ and σ . The contradiction negative context representation \hat{M} is formulated as follows:

$$\hat{M} = M + \epsilon \zeta \tag{6}$$

where ϵ is the balanced factor. After that, we sample a negative response \hat{Y} from the decoder successively using the pseudo-Gibbs Markov chain (Ng et al., 2020). To capture the high-level contradiction action for the multi-turns context, we use the policy gradient theorem (Williams, 1992) to train the latent noise generation network, whose gradient can be estimated as follows:

$$\nabla_{\theta_{la}} J(\theta_{la}) = \mathbb{E}[R \cdot log P(\zeta | M, \theta_{la})] \quad (7)$$

where θ_{la} is the parameters in latent noise generation network, R is contradiction probability between C and \hat{Y} measured by the external critic. We apply a pretrained MNLI¹ (Williams et al., 2018) model as critic in practice. With the help of the perturbed negative representation \hat{M} , we can augment the contrastive learning loss as follows:

$$\mathcal{L}_{cn} = -\sum_{i=1}^{N} \log \frac{f(M^{(i)}, H^{(i)})}{\sum_{m \in \{S \cup \hat{M}^{(i)}\}} f(m, H^{(i)})}$$
(8)

3.4 Semantic-aligned Positive Example

Moreover, we construct an additional positive example to improve the training robustness with a small, approximately worst-case perturbation. Following (Goodfellow et al., 2015), we obtain a per-

¹https://huggingface.co/

roberta-large-mnli

turbation with the linear approximation and generate our positive example \tilde{M} as follows:

$$g = \nabla_M log P(Y|C)$$

$$\tilde{M} = M - \eta \frac{g}{||g||^2}$$
(9)

where η is the balanced hyperparameter. We can argument the contrastive learning loss as follows:

$$\mathcal{L}_{cp} = -\sum_{i=1}^{N} \log \frac{f(\tilde{M}^{(i)}, H^{(i)})}{\sum_{m \in \{S \cup \tilde{M}^{(i)} \cup \hat{M}^{(i)}\}} f(m, H^{(i)})}$$
(10)

To ensure the positive examples can have aligned semantic, we also minimize the KL divergence between perturbed conditional distribution and the original conditional distribution as follows:

$$\mathcal{L}_{KL} = \sum_{i=1}^{N} KL[P(Y^{(i)}|M)||P(Y^{(i)}|\tilde{M})] \quad (11)$$

3.5 Training Objective

The overall training objective for the response generation model can be formulated as follows:

$$\mathcal{L}_{tot} = \mathcal{L}_{MLE} + \alpha \{ \mathcal{L}_{cn} + \mathcal{L}_{cp} \} + \beta \mathcal{L}_{KL} \quad (12)$$

where α and β are balanced hyperparameters. We alternate the optimization of response generation model and the policy update of latent noise generation network (Lewis et al., 2017).

4 Experiment

4.1 Datasets

BST. (Smith et al., 2020) It is a crowdsourced dataset that blends three dialogue skills (engaging personality, empathy, and knowledge). Each conversation is collected with a guided and unguided human speaker. It contains 76k utterances, each with about 16 tokens on average. We use this dataset to finetune the response generation models.

DECODE. (Nie et al., 2021) This dataset offers a new domain for NLI. It contains humanwritten dialogues, which are labeled as "contradiction" or "non-contradiction". This dataset has 27,184/4,026/4,216 pairs for train/validation/test. To explore the contradiction situation, we only select the context in contradiction pairs from the validation/test sets, namely *DECODE-C*.

4.2 Implement Details

We use the Blender (Roller et al., 2021) as our backbone chatbot model. We choose the 400M-distill version ², whose hidden dimension is 1,280. We employ Adam to optimize the model parameters, with the learning rate of 1e-5. For contrastive learning, the temperature τ is set as 0.1, the perturbation factor ϵ is set to 0.4 and η is set to 3. For the hyperparameters in the overall objective, We set α as 0.5 and β as 1. During the inference stage, we use beam search of width 10 to generate the target responses. All the methods are trained in 10 epochs with an NVIDIA Tesla V100.

4.3 Baselines

We compare our method against state-of-the-art baselines: **Blender** (Roller et al., 2021): a pretrained model that maximizes log likelihood. **PersonaCat** (Zhang et al., 2018): a method that prepends all possible persona texts to the input message. **R3F** (Aghajanyan et al., 2021): a method that minimizes the negative log likelihood and symmetric KL-divergence. **CLASP** (Lee et al., 2021): a method that minimizes the similarity between the output sequence and adversarial negative sample, which is generated by adding a small perturbation. **LaRL** (Zhao et al., 2019): a flexible latent variable RL-based method that uses the positive consistent score as reward.

4.4 Evaluation Metrics

The evaluation of logical consistent conversation is mainly about two aspects: contradiction performance and text generation metrics. For contradiction performance, we calculate the contradiction score (C.S) following (Nie et al., 2021). We reimplement the structured utterance-based approach, which finetunes the pretrained RoBERTa (Liu et al., 2019) on DECODE training set, to detect contradictions automatically. Our re-implementation achieves accuracy of 92.33% on test set, which is aligned with the reported accuracy 93.19%. The C.S is calculated as follows:

$$C.S = \frac{\sum_{i=1}^{D} P_i}{D} \tag{13}$$

where D denotes the size of test set, P_i is the label of the i_{th} test case (0: non-contradiction, 1: contradiction). To evaluate the fluency and relevance of responses, we adopt PPL (Adiwardana et al., 2020), BLEU-1/2 (Papineni et al., 2002) and Embedding Greedy metrics (E.grd) (Liu et al., 2016).

Table 1: Automatic evaluation results for compared methods in BST dataset. "B" indicates the BLEU metrics. Bold scores are the best overall.

	C.S(%)↓	B1 ↑	B2 ↑	PPL↓	E.grd ↑
		DI	D2	11.5.↓	E.gru
Blender	13.81	16.13	5.93	10.96	69.04
Persona	12.69	16.27	6.03	10.99	69.00
CLASP	13.13	16.23	5.88	9.97	69.53
R3F	12.23	16.08	5.88	10.58	69.01
LaRL	11.72	16.37	6.12	10.13	69.37
MCCL	10.88	16.42	6.09	9.59	69.93
naive	11.70	16.30	6.01	9.86	69.41
+ pos	11.64	16.51	6.21	9.45	69.63
+ neg	11.31	16.29	6.08	9.62	69.70

4.5 Results and Analysis

Table.1 shows that our method outperforms all baselines on BST dataset. We also compare with ablation study about contrastive learning objective. **naive** only maximizes the naive objective from Eq 3; **+ pos/neg** utilizes additional positive or negative examples solely. As we can see, the performance of the **naive** model is not outstanding. When we integrate the **pos** module and the **neg** module, the performance achieves the best.



Figure 2: C.S of compared methods on DECODE-C.

Furthermore, MCCL is mainly designed for solving the contradiction problem in dialogue. To verify the effectiveness of the self-contradiction negative component in our method, we take experiment on DECODE-C dataset which is hard for chatbots to generate consistent responses. We only shows the contradiction score since DECODE-C lacks the consistent ground truth while PPL, BLEU and E.grd are reference-based metrics. The results are shown in Fig.2. From this result, we can get some observations. First, our method has a significant advantage (>10%) on contradiction score compared

²https://huggingface.co/facebook/ blenderbot-400M-distill

Table 2: Manual Evaluation Comparison results.

	Ours Win(%)	Tie(%)	Ours Lose(%)
Blender	25.3	65.3	9.3
CLASP	32.7	54.0	13.3
R3F	25.3	57.3	17.3

with all baselines. Secondly, we find that Persona model has a high contradiction score. This indicates that only adding personal profile information is not enough to resolve dialogue contradiction problem. Lastly, the ablated methods suffer from the ablations on contradiction score which proves that every component is essential for our method.

We further randomly select 50 conversation examples and ask 3 annotators to compare the contradiction performance. As shown in Table 2, our method performs better than other baselines, which is consistent with automatic evaluation results. The kappa score (Fleiss, 1971) is 0.478, showing moderate agreement between the annotators.

5 Conclusion

In this paper, we propose a new method named MCCL to mitigate the contradiction problem in open domain chatbots. Our method minimizes the similarity between the target response and selfcontradiction negative example, and maximizes the similarity with semantic-aligned positive example. Experiment results show that our contrastive loss helps to avoid contradiction and obtain better response generation metrics on two different datasets. In the future, we will investigate how to improve the interpretability of negative examples.

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A Appendix

A.1 Case Analysis

Case study is shown in Table 3 and Table 4. The gray text indicates the speaker role. The context history consists of the utterances between two different speakers, interleaving with each other. The chatbot models need to generate the next response for the speaker2. Table 3 shows the case 1. The context talks about the dangers of drinking alcohol. The speaker2 is a sober and claims that he don't drink at all. The baseline chatbots fail to avoid contradiction by talking about the last drinking time. Table 4 shows the case 2. From the context, we can know that the speaker2 is afraid of getting bodily injury in sports. The baseline chatbots generate contradictory responses by speaking "not worried about ...", while there are no contradictions in our response.

A.2 Type of Latent Noise

To generate additional self-contradiction negative example, we add a learnable latent noise to the context representation. The latent noise is optimized based on policy gradient method under the feedback from a MNLI (Williams et al., 2018) model. To verify the effectiveness of our method, we sample a random noise as latent noise from Gaussian distribution. This method can get a contradiction score of 39.82% which is far worse than our model (34.85%). This indicates that the contradiction reward is essential for the generation of self-contradiction negative example.

Table 3: Generated Results 1.

[S2] I don't drink alcohol at all, I'm all about sobriety.
[S1] Thats a good choice. Alcohol is just never the answer for anything.
[S2] I agree with you! Sobriety is such a natural state of a human being given at birth.
[S1] Yes, unfortunately many mothers drink alcohol during pregnancy which can cause
the baby to have some health issue.
[S2] Gosh that's so horrible! my father used to be an alcoholic so i'm pretty traumatized,
that's why i all for sobriety and i want everybody i care about to be sober.
[S1] Sorry to hear about your trauma. I once drank alcohol and hit my friend in a drunken
rage. I have vowed to be sober since then.
[S2] Good for you! Stay sober, my friend! because someone who abstains from alcohol
but wants to start drinking again isn't truly sober.
[S1] I suppose that is one way to see it, when was your last drink?
about a month ago, and i still want to be a part of it but i just don't want to go through
with it.
about a month ago, but i want to stay sober for as long as possible. i don't want to relapse.
The last time I had a beer was in December of this year. I don't drink as much now that
I'm sober.
about a month ago, and i've been sober for almost a year now. i used to drink all the time,
but now i just don't drink at all.
about a month ago, but i'm trying to stay sober for as long as i can.
i don't drink so i can't say when it was, but i know it's bad for me.
1 don't drink og i gon't gov when it weg, but i know it'g hed ter me

Table 4: Generated Results 2.

Context	 [S1] I was so happy to watch my friend do a backflip [S2] I've always been too scared to do a backflip. I always worry I'm going to break my neck or something. Did it take him a long time to get it right?And did he get hurt? [S1] I think he just took gymnastics classes. He luckily did not get hurt! [S2] Oh, that makes sense. And I'm glad to hear that. I always worry about that sort of 		
	thing. You ever think about trying to do it netx?		
	[S1] no, i never tried to so it netx. Are you worry about your neck or some of your body		
	parts?		
Blender	I'm not too worried about my body parts, but I do worry about my balance.		
Persona	I'm not really worried about my body parts, but I do worry about my neck. It's something		
	that I worry about a lot.		
CLASP	I'm not worried about my body parts, I'm more concerned about my neck.		
R3F	I'm not really worried about my body parts, but I do worry about my balance.		
LaRL	I'm not worried about my body parts, but I do worry about things like my balance, balance,		
	and coordination.		
MCCL	I'm not sure what you mean by body parts. Do you mean the bones, organs, and skin?		