**IWCS 2021** 

**Multimodal Semantic Representations** 

**Proceedings of the First Workshop** 

June 16, 2021

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## Preface

The demand for more sophisticated natural human-computer and human-robot interactions is rapidly increasing as users become more accustomed to conversation-like interactions with AI and NLP systems. Such interactions require not only the robust recognition and generation of expressions through multiple modalities (language, gesture, vision, action, etc.), but also the encoding of situated meaning.

When communications become multimodal, each modality in operation provides an orthogonal angle through which to probe the computational model of the other modalities, including the behaviors and communicative capabilities afforded by each. Multimodal interactions thus require a unified framework and control language through which systems interpret inputs and behaviors and generate informative outputs. This is vital for intelligent and often embodied systems to understand the situation and context that they inhabit, whether in the real world or in a mixed-reality environment shared with humans.

This workshop intends to bring together researchers who aim to capture elements of multimodal interaction such as language, gesture, gaze, and facial expression with formal semantic representations. We provide a space for both theoretical and practical discussion of how linguistic co-modalities support, inform, and align with "meaning" found in the linguistic signal alone. In so doing, the MMSR workshop has several goals:

- 1. To provide an opportunity for computational semanticists to critically examine existing NLP semantic frameworks for their validity to express multimodal elements;
- 2. To explore and identify challenges in the semantic representation of co-modalities crosslinguistically and cross-culturally;
- 3. To gain understanding of domains and tasks where certain semantic frameworks (multimodal or not) are most effective and why.

We would like to thank the authors, reviewers, invited speakers, and IWCS 2021 organizers for making this workshop possible. We look forward to an exciting workshop.

Lucia Donatelli, Nikhil Krishnaswamy, Kenneth Lai, and James Pustejovsky

#### **Organizers:**

Lucia Donatelli, Saarland University Nikhil Krishnaswamy, Colorado State University Kenneth Lai, Brandeis University James Pustejovsky, Brandeis University

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#### **Invited Speakers:**

Chiara Bonsignori, Consiglio Nazionale delle Ricerche Matthias Scheutz, Tufts University Virginia Volterra, Consiglio Nazionale delle Ricerche

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### **Workshop Program**

#### Wednesday, June 16, 2021

#### 16:00–16:15 Introduction

16:15–17:00 *Invited Talk: From action to language through gesture* Virginia Volterra and Chiara Bonsignori

#### 17:05-17:35 Oral Session 1

*What is Multimodality?* Letitia Parcalabescu, Nils Trost and Anette Frank

Are Gestures Worth a Thousand Words? An Analysis of Interviews in the Political Domain Daniela Trotta and Sara Tonelli

*Requesting clarifications with speech and gestures* Jonathan Ginzburg and Andy Luecking

17:40–18:25 Invited Talk: Attention, Incrementality, and Meaning: On the Interplay between Language and Vision in Reference Resolution Matthias Scheutz

#### 18:30–19:10 Oral Session 2

Seeing past words: Testing the cross-modal capabilities of pretrained V&L models on counting tasks Letitia Parcalabescu, Albert Gatt, Anette Frank and Iacer Calixto

How Vision Affects Language: Comparing Masked Self-Attention in Uni-Modal and Multi-Modal Transformer Nikolai Ilinykh and Simon Dobnik

*EMISSOR: A platform for capturing multimodal interactions as Episodic Memories and Interpretations with Situated Scenario-based Ontological References* Selene Baez Santamaria, Thomas Baier, Taewoon Kim, Lea Krause, Jaap Kruijt and Piek Vossen

Annotating anaphoric phenomena in situated dialogue Sharid Loáiciga, Simon Dobnik and David Schlangen Wednesday, June 16, 2021 (continued)

#### 19:15–19:45 Poster Session

Incremental Unit Networks for Multimodal, Fine-grained Information State Representation Casey Kennington and David Schlangen

Teaching Arm and Head Gestures to a Humanoid Robot through Interactive Demonstration and Spoken Instruction Michael Brady and Han Du

Building a Video-and-Language Dataset with Human Actions for Multimodal Logical Inference Riko Suzuki, Hitomi Yanaka, Koji Mineshima and Daisuke Bekki

19:45-20:00 Closing