A Call for Clarity in Beam Search: How It Works and When It Stops

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Abstract

Text generation with beam search has proven successful in a wide range of applications. We point out that, though largely overlooked in the literature, the commonly-used implementation of beam decoding (e.g., Hugging Face Transformers and fairseq) uses a first come, first served heuristic: it keeps a set of already completed sequences over time steps and stops when the size of this set reaches the beam size. Based on this finding, we introduce a patience factor, a simple modification to this beam decoding implementation, that generalizes the stopping criterion and provides flexibility to the depth of search. Empirical results demonstrate that adjusting this patience factor improves decoding performance of strong pretrained models on news text summarization and machine translation over diverse language pairs, with a negligible inference slowdown. Our approach only modifies one line of code and can be thus readily incorporated in any implementation. Further, we find that different versions of beam decoding result in large performance differences in summarization, demonstrating the need for clarity in specifying the beam search implementation in research work. Our code will be available upon publication.

Keywords: generation, decoding, beam search, inference, summarization, machine translation

Introduction 1.

Beam search has become a dominant inference algorithm for a wide range of language generation tasks, such as machine translation (Sutskever et al., 2014; Bahdanau et al., 2015; Vaswani et al., 2017), summarization (Nallapati et al., 2016; See et al., 2017), and image captioning (Anderson et al., 2018; Li et al., 2020). Beam decoding is an approximate, pruned version of breadthfirst search that seeks the highest-probability sequence under an autoregressive (left-to-right) language generation model. In this work, we examine a popular implementation of beam decoding and propose a simple modification (one line of code) that improves the decoding performance of strong, neural language generation models (Fig. 1).

We first bring attention to implementation variations of beam decoding that are largely ignored in the literature: a widely-used implementation of beam language decoding (e.g., fairseq, Ott et al., 2019; Hugging Face's Transformers, Wolf et al., 2020)¹ follows a first come, first served (FCFS) heuristic: when a total of k finished candidates is found (k is the beam size), it returns the best one from the k candidates and discards all of the current, unfinished k sequences in the beam. Thus in

FCFS Beam Decoding with Controlled Patience

- k: beam size, M: maximum length, \mathcal{V} : Vocabulary $score(\cdot)$: scoring function, p: patience factor.
- 1: $B_0 \leftarrow \{ \langle 0, \mathsf{BOS} \rangle \}, F_0 \leftarrow \emptyset$
- **2:** for $t \in \{1, \dots, M-1\}$:
- $H \leftarrow \emptyset, F_t \leftarrow F_{t-1}$ 3:
- 4: for $\langle s, \mathbf{y} \rangle \in B_{t-1}$: # Expansion.
- 5: for $y \in \mathcal{V}$:
- 6: $s \leftarrow \mathsf{score}(\mathbf{y} \circ y), \quad H.\mathsf{add}(\langle s, \mathbf{y} \circ y \rangle)$
- 7: $B_t \leftarrow \emptyset$
- while $|B_t| < k$: # Find top k w/o Eos from H. 8:
- 9: $\langle s, \mathbf{y} \rangle \leftarrow H.\max()$
- 10: if \mathbf{y} .last() = EOS :
- F_t .add $(\langle s, \mathbf{y} \rangle)$ # Finished hypotheses. 11:
- else B_t .add $(\langle s, \mathbf{y} \rangle)$ 12: if $|F_t| \ge k \cdot p$: # Originally, p = 1.
- 13: 14:
- return F_t .max() 15:
- *H*.remove($\langle s, \mathbf{y} \rangle$)
- 16: return F_t .max()

Figure 1: First come, first served (FCFS) beam decoding with patience factor p. The common implementation can be considered as a special case where p = 1. The highlighted line is the *only* modification that this work introduces for performance improvement. F_t : already completed sequences; B_t : beam of continuing sequences. H_t : expanded hypotheses before the top-k operation. The input sequence to score is omitted.

practice, beam size k determines both the breadth and depth of search. We propose a patience fac-

¹https://github.com/pytorch/fairseq/blob/ main/fairseq/sequence_generator.py; https: //github.com/huggingface/transformers/blob/ master/src/transformers/generation_utils.py.

tor (Fig. 1) that decomposes these two roles and controls how many finished candidates have to be found before terminating the decoding. The patience factor generalizes the commonly-used implementation and provides flexibility in the depth of beam search by changing the stopping criterion.

We apply the one-line modification to strong offthe-shelf transformer models without any change to the trained models for machine translation (Tang et al., 2021) and text summarization (Lewis et al., 2020). Our experiments demonstrate that the simple modification improves performance on the CNN/Dailymail (Hermann et al., 2015) and XSUM (Narayan et al., 2018) news summarization tasks and the WMT 2020/2021 machine translation tasks (Barrault et al., 2020; Akhbardeh et al., 2021) across diverse language pairs. Further, the introduction of the patience factor only results in a negligible inference slowdown, confirming its practical advantage in downstream applications.

Our analysis shows that, while the performance gain is sensitive to hyperparameters of beam decoding (beam size and length penalty; Johnson et al., 2017), the patience factor is consistently beneficial. Moreover, we extensively compare our results with the vanilla implementation of beam search that much prior work assumes (Meister et al., 2020b; Stahlberg and Byrne, 2019, inter alia), though it is not used in popular libraries in practice. Empirically, we found that the vanilla algorithm performs competitively with FCFS on machine translation but substantially underperforms on summarization. Therefore, although much prior work on text decoding implicitly assumes the vanilla version of beam decoding, researchers should specify which implementation is used when reporting results.

2. A Call for Clarity in Beam Decoding

Vanilla and FCFS Implementations Beam decoding has been applied to sequence-to-sequence models (Graves, 2012; Boulanger-Lewandowski et al., 2013a,b), and it is now used in many state-of-the-art systems for language generation tasks (Zhang et al., 2020, 2021; Tran et al., 2021; Raffel et al., 2020, *inter alia*). While largely ignored in the literature, beam decoding has two major variations (Figs. 1 and 2). They differ primarily in the treatment of finished sequences with the Eos symbol at the end: FCFS collects finished sequences in a *first come, first served manner* and removes them from the beam (Line 11, Fig. 1), whereas the vanilla version finds the top

Vanilla Beam Decoding

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k: beam size, M: maximum length,									
\mathcal{V} : Vocabulary, score(·): scoring function. $B_0 \leftarrow \{ \langle 0, BOS \rangle \}$									
1: $B_0 \leftarrow \{ \langle 0, BOS \rangle \}$									
2: for $t \in \{1, \dots, M-1\}$:									
3: for $\langle s, \mathbf{y} \rangle \in B_{t-1}$:									
4: if y.last() = EOS :									
5: $H.add(\langle s, \mathbf{y} \rangle)$									
6: continue									
7: for $y \in \mathcal{V}$:									
8: $s \leftarrow \text{score}(\mathbf{y} \circ y), H.\text{add}(\langle s, \mathbf{y} \circ y \rangle)$									
9: $B_t \leftarrow \varnothing$									
10: while $ B_t < k$: # Find top k from H.									
11: $\langle s, \mathbf{y} \rangle \leftarrow H.\max(), B_t.add(\langle s, \mathbf{y} \rangle)$									
12: $H.remove(\langle s, \mathbf{y} \rangle)$									
13: if \mathbf{y} .last() = EOS, $\forall \mathbf{y} \in B_t$: # All finished.									
14: return B_t .max()									
15: return B_t .max()									

Figure 2: The vanilla version of beam decoding that much prior work assumes **departs from pop-ular libraries, such as Hugging Face** Transformers. The top-*k* operation is applied over *H*, the union of the finished and continuing sequences. This is implemented, for example, in the Tensor-Flow Addons library (Abadi et al., 2015).² See also Stahlberg and Byrne (2019); Meister et al. (2020b).

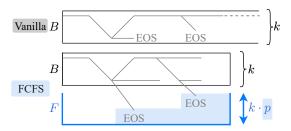


Figure 3: FCFS with patience factor p vs. vanilla beam decoding. k denotes the beam size. FCFS stores finished sentences in F, but they stay in (and later may fall off from) beam B during vanilla decoding. $k \cdot p$ determines the size of F. The illustration of beam decoding here is inspired by Huang et al. (2012).

k sequences, including both finished and unfinished sequences (Line 5 in Fig. 2). Our experiments will show that this difference can affect the downstream performance substantially, especially on summarization (§3.2).

Further comparing Figs. 1 and 2, we see their difference in terms of the breadth and depth of search. Given the same beam size k, FCFS has a wider breadth since it collects k unfinished sequences at every step regardless of how many sequences are finished with the EOS symbol.³ The

²https://www.tensorflow.org/addons/api_docs/ python/tfa/seq2seq/BeamSearchDecoder.

³In practice, this is implemented by taking the top 2k sequences at every step. We find at most k EOS symbols, so there are always at least k unfinished

vanilla algorithm decodes until all top-k sequences are finished (Line 13, Fig. 2), and therefore it tends to result in deeper search. FCFS, in contrast, terminates when a total of k finished sequences is found.

Patience Factor for FCFS Beam size *k* in FCFS thus controls both the breadth and stopping criterion (i.e., depth) of search. We introduce the patience factor (Line 13, Fig. 1) that relaxes this assumption and separates the stopping criterion from the search breadth. Fig. 3 illustrates this patience factor as well as the difference between the FCFS and vanilla algorithms. The one-line change generalizes FCFS (p = 1) and adds flexibility. We will show that this flexibility is beneficial, espeically on news text summarization (§3.2).

3. Experiments

We compare implementation variations of beam decoding on text summarization and machine translation over a wide range of language pairs.

3.1. Experimental Setup for Beam Decoding

In addition to greedy search, we evaluate three beam decoding variations on machine translation and summarization: vanilla, FCFS, and FCFS with the patience factor.⁴ For machine translation, we use multilingual BART (Tang et al., 2021), a strong, pretrained transformer model,⁵ and WMT 2020/2021 news test data (Barrault et al., 2020; Akhbardeh et al., 2021) for four diverse language pairs (eight directions): WMT 2020 for EN \leftrightarrow PL (Polish) and 2021 for EN \leftrightarrow DE (German), EN \leftrightarrow JA (Japanese), and $EN \leftrightarrow ZH$ (Chinese). We apply beam decoding with the same hyperparameters as Tang et al. (2021): beam size 5 and length penalty 1. We measure performance with the COMET score (Rei et al., 2020a,b), a state-of-the-art evaluation metric based on multilingual contextual representations. For summarization, we experiment with the CNN/Dailymail (CNNDM, Hermann et al., 2015) and XSUM (Narayan et al., 2018) datasets. We apply the off-the-shelf BART models (Lewis et al., 2020) that are finetuned on each dataset.⁶

sequences. See https://github.com/huggingface/transformers/.

⁴Other beam decoding variants target various purposes, like output diversity (stochastic beam search; Kool et al.; Meister et al., 2021) or efficiency (best-first beam search; Meister et al., 2020b). Here we focus on the commonly-adopted implementations and the top-1 output quality.

⁵https://github.com/pytorch/fairseq/tree/main/ examples/multilingual#mbart50-models.

⁶https://github.com/pytorch/fairseq/tree/main/ examples/bart. Performance is measured with ROUGE scores (Lin, 2004). We follow the original setting in Lewis et al. (2020): beam sizes 4 and 6 and length penalty 2 and 1 for CNNDM and XSUM, respectively. More experimental details are described in the appendix (following the submission guideline, the appendix will be added in the final version).

We experiment with the same patience factor on all datasets for each task, based on our preliminary development: p = 2 for machine translation and p = 0.5 for summarization. Here we avoid additional effort and demonstrate the practical value of our simple modification. We present detailed sensitivity analysis over p in §3.3. Note that a larger pimplies deeper search, but deeper (and thus more accurate) search does not necessarily result in better generations, similar to the *beam search curse* (Koehn and Knowles, 2017).

3.2. Results

Seen in Table 1 are results from our experiments. FCFS with the patience factor outperforms the widely-used FCFS variation across the board; e.g., 53.0 vs. 52.1 on EN→PL. Particularly noteworthy are the performance gains on the two summarization datasets; e.g., 31.2 vs. 30.3 ROUGE-L on CN-NDM. Comparing vanilla decoding and FCFS, we see that the former outperforms the latter (and is competitive with or slightly better than FCFS w/ p) on machine translation but underperforms substantially on summarization; e.g., 34.4 vs. 33.1 ROUGE-L on XSUM. Vanilla beam decoding even performs worse than greedy decoding in many cases. This large degradation from the vanilla implementation illustrates the importance of specifying the version of beam decoding, which is not commonly done in practice.

3.3. Analysis

Here we use the standard dev. split from the XSUM dataset and news test 2020 EN \rightarrow DE and ZH \rightarrow EN data. We fixed the value of p for each task so far, but Fig. 4 explores varying patience factors and their effects on the performance (A: $EN \rightarrow DE$; B: XSUM) and the inference speed (C). The translation performance improves with larger patience factors with diminishing gains. Surprisingly, summarization benefits from patience factors smaller than the original value of 1, possibly due to the nature of the summarization task that aims to generate concise text. Note that this observation does not contradict with prior work because the search accuracy of beam decoding does not always correlate with the output guality (Koehn and Knowles, 2017; Stahlberg and Byrne, 2019; Meister et al., 2020a, inter alia). Regardless, our patience factor provides useful flexibility for any generation task.

	WMT 2020/2021 Machine Translation ($p\!=\!2$)									Summarization ($p = 0.5$)					
	EN⇔DE		EN↔JA EN↔PL		EN↔ZH		-	CNNDM			XSUM				
Algorithm	\rightarrow	\leftarrow	\rightarrow	\leftarrow	\rightarrow	\leftarrow	\rightarrow	\leftarrow	-	R-2	R-3	R-L	R-2	R-3	R-L
Greedy	43.7	66.2	33.6	9.5	46.0	53.5	32.5	23.5	1	21.1	11.9	30.7	19.8	10.7	34.3
Vanilla	48.2	66.3	38.7	15.7	52.7	58.2	33.9	29.9		19.2	11.0	28.0	19.5	10.7	33.1
FCFS	47.9	66.2	38.0	15.0	52.1	58.1	33.7	29.6	2	20.4	11.6	30.3	20.4	11.4	34.4
FCFS w/ p	48.3	66.4	38.4	15.6	53.0	58.4	33.8	30.2	:	21.4	12.4	31.2	21.0	11.8	35.4

Table 1: We evaluate three beam decoding variations, as well as greedy decoding, on the machine translation and summarization test data with the COMET score (Rei et al., 2020b) and ROUGE scores (ROUGE-2/3/L), respectively. FCFS w/ p indicates our FCSF algorithm with the patience factor (p = 2 for machine translation and p = 0.5 for summarization). For CNNDM, we used 100 test articles with 10 human-written references (Kryscinski et al., 2019).

As expected, generation slows down as p increases (Fig. 4C). The inference slowdown from around p = 2 is still negligible, again showing the practicality of our method. Fig. 5 explores the performance gains from the patience factor over varying beam sizes. The amount of improvement changes, but the patience factor is generally beneficial. We see similar trends for various values of the length penalty (see the appendix).

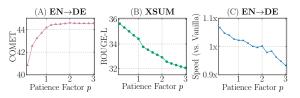


Figure 4: Effects of varying patience factors p on the dev. score (A and B) and inference speed (C). The inference speed is measured with batch size 20, relative to the vanilla version on the same single Nvidia A100-SXM GPU. Other languages pairs were similar to EN \rightarrow DE (A). CNNDM also had similar trends to XSUM (B).

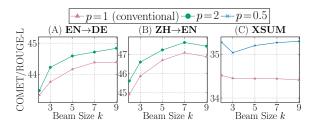


Figure 5: Effects of controlled patience on the dev. data over varying beam sizes. The length penalty value is 1. We evaluate with COMET for machine translation and ROUGE-L for XSUM summarization.

4. Further Related Work

Stopping Criteria for Beam Decoding The patience factor changes the stopping criterion and adds flexibility in the search depth of the

widespread variation of beam decoding. Similarly, several prior works studied stopping criteria to improve machine translation (Huang et al., 2017; Yang et al., 2018; Ma et al., 2019). Our experiments are consistent with their findings: stopping criteria that yield deeper search can improve the machine translation performance.

Breadth of Beam Decoding Much prior work explored downstream effects of the search breadth (Koehn and Knowles, 2017; Murray and Chiang, 2018; Ott et al., 2018a; Cohen and Beck, 2019; Stahlberg and Byrne, 2019, inter alia). Beam decoding with larger beam sizes can find sequences with higher scores but lead to performance degradation (often called the beam search curse; Yang et al., 2018). Recent work (Meister et al., 2020a) argued that beam decoding with small beams introduces bias that is related to the uniform information density of human-produced text (Levy, 2005). Freitag and Al-Onaizan (2017) proposed a method to adaptively shrink the beam width based on the partial scores to speed up inference. We focused on the stopping criteria (i.e., depth) and separated them from the breadth of the common implementation.

5. Conclusion

We brought attention to the crucial yet overlooked implementation differences of beam search. We then introduced the patience factor for the widespread implementation. Our experiments showed that the patience factor improves the generation performance especially on summarization, with an insignificant slowdown in generation. As it only requires a minimal change in code, we hope that many researchers and practitioners of language generation will benefit from our simple yet effective modification.

Limitations

We evaluated our decoding method both on machine translation and news summarization. Our machine translation experiments span diverse languages, including morphologically rich languages (e.g., Japanese and Polish) and languages with non-Latin scripts (e.g., Japanese and Chinese). Nonetheless, our summarization experiments are limited to English and the news domain mainly due to our budget constraints. There are also many other language generation tasks for which our method can be useful. Since our improvement only requires one line of code, we hope that practitioners will implement it for the domain and the task of their interest and further assess how our decoding algorithm performs over a wider range of applications.

Evaluating language generation remains a challenging research problem. We carefully set up our experiments to mitigate potential evaluation issues. The WMT 2020/2021 test data consist only of news text written in the original language, in contrast to the test data from WMT 2018 (Bojar et al., 2018) or earlier. For example, the WMT 2021 EN \rightarrow DE and DE \rightarrow EN test data come from completely different documents. This avoids the translationese effect that would overestimate the translation performance due to the simplicity of translated text (Graham et al., 2020). Moreover, some language pairs in the WMT 2020 and 2021 test data have multiple references per instance, which increases the correlation of automatic evaluations with human judgment (Kasai et al., 2022a). We presented results using automatic metrics from recent work (Rei et al., 2020b) as well as conventional, n-gram overlap metrics (Papineni et al., 2002; Lin, 2004). Recent automatic metrics have shown to have higher correlation with human judgements, but human judgments are sometimes inconsistent, especially when crowdsourced (Clark et al., 2021; Kasai et al., 2022b). Since our decoding method is a generalization of the widelyused beam search algorithm, we hope that it will be tested and used in real-world systems of language generation.

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Appendices

Hyperparameter	Value							
WMT Machine Translation (All Pairs)								
beam size	5							
length penalty	1							
CNNDM Summarization	n							
beam size	4							
length penalty	2							
max-len-b	140							
min-len	55							
no-repeat-ngram-size	3							
XSUM Summarization								
beam size	6							
length penalty	1							
max-len-b	60							
min-len	10							
no-repeat-ngram-size	3							

Table 2: Beam decoding hyperparameters. We generally followed prior work: Tang et al. (2021) for machine translation and Lewis et al. (2020) for CNNDM and XSUM summarization.

A. Beam Decoding Hyperparameters

Table 2 shows the beam decoding hyperparameters in our experiments. We generally follow the original settings of the pretrained, off-the-shelf models (Tang et al., 2021; Lewis et al., 2020).

B. Additional Results

Table 3 reports BLEU (Papineni et al., 2002) and COMET (Rei et al., 2020b) scores for the machine translation and summarization experiments, respectively. We use the sacreBLEU implementation for BLEU (Post, 2018b). Note that much recent work (Mathur et al., 2020a; Kasai et al., 2022a,b; Edunov et al., 2020, *inter alia*) found poor correlation between BLEU scores and human judgment for evaluating strong language generation models. COMET is an automatic metric for machine translation that uses crosslingual contextual representations from XLM-RoBERTa (Conneau et al., 2020), but it can be used *monolingually* for evaluating summarization as well (Kasai et al., 2022a).

Fig. 6 explores the performance gains from the patience factor over varying length penalty values.

Consistent with the trends from various beam sizes (Fig. 5), the amount of improvement changes, but the patience factor is generally beneficial.

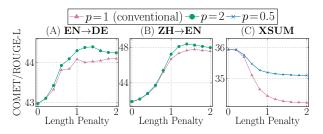


Figure 6: Effects of controlled patience on the dev. data over varying length penalty values. The beam sizes are all 5. We evaluate with COMET for machine translation and ROUGE-L for XSUM summarization.

	WMT 2020 and 2021 Machine Translation (BLEU)									Summarization			
	EN↔DE		EN↔DE EN↔JA		EN∢	→PL	EN∢	→ZH	CNNDM	XSUM			
Algorithm	\rightarrow	\leftarrow	\rightarrow	\leftarrow	\rightarrow	\leftarrow	\rightarrow	\leftarrow	COMET	COMET			
Greedy	42.9	46.6	20.2	17.4	19.8	30.7	31.2	21.7	1.6	0.1			
Vanilla	45.1	48.4	21.6	19.7	21.1	32.5	32.5	23.6	-5.5	-1.6			
FCFS	45.0	48.4	21.3	19.5	21.0	32.4	32.6	23.4	-4.2	2.2			
FCFS w/ p	45.0	48.5	21.7	19.8	21.1	32.5	32.3	23.7	-1.1	2.5			

Table 3: We evaluate three beam decoding variations, as well as greedy decoding, on machine translation and summarization and report BLEU (Papineni et al., 2002) and COMET (Rei et al., 2020b) scores here. FCFS w/ p indicates our FCSF algorithm with the patience factor (p = 2 for machine translation and p=0.5 for summarization). COMET is an automatic metric for machine translation that uses crosslingual contextual representations from XLM-RoBERTa (Conneau et al., 2020), but it can be used for evaluating summarization as well (Kasai et al., 2022a).

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