



Can Multimodal Foundation Models Understand Schematic Diagrams? An Empirical Study on Information-Seeking QA over Scientific Papers

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Abstract

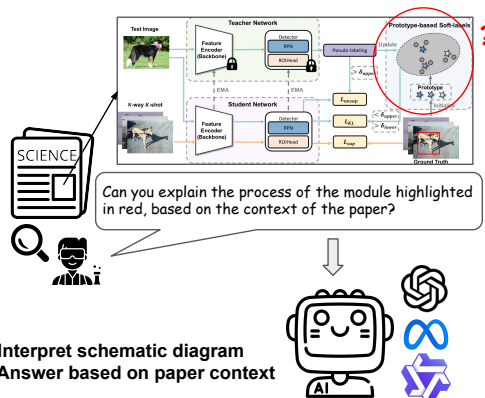
This paper introduces MISS-QA, the first benchmark specifically designed to evaluate the ability of models to interpret schematic diagrams within scientific literature. MISS-QA comprises 1,500 expert-annotated examples over 465 scientific papers. In this benchmark, models are tasked with interpreting schematic diagrams that illustrate research overviews and answering corresponding information-seeking questions based on the broader context of the paper. We assess the performance of 18 frontier multimodal foundation models, including o1-mini, Gemini-2.5-Flash, and Qwen2.5-VL. We reveal a significant performance gap between these models and human experts on MISS-QA. Our analysis of model performance on unanswerable questions and our detailed error analysis further highlight the strengths and limitations of current models, offering key insights to enhance models in comprehending multimodal scientific literature.

 **Data** [yilunzhao/MISS-QA](#)
 **Code** [yilunzhao/MISS-QA](#)

1 Introduction

When engaging with academic literature, readers frequently first consult schematic diagrams that illustrate the research framework to quickly grasp the underlying research and identify specific areas of interest. This initial visual reference is crucial as it provides an overview of the study’s structure and aims, prompting readers to delve deeper into the paper content for a more comprehensive understanding. Given the complexity and high volume of information in scientific papers (Dasigi et al., 2021; Lee et al., 2023b; Li et al., 2024a; Ajith et al., 2024), there is a significant demand for AI systems that can assist scientists in seeking information from paper content through schematic diagrams.

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How well do frontier models perform on MISS-QA?

> We observe a notable performance gap between human experts and SoTA open-source models, such as Qwen2.5-VL, and InternVL3

What challenges do frontier models encounter?

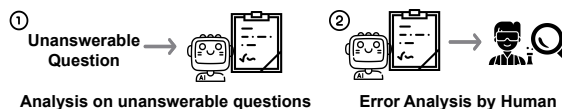


Figure 1: An overview of the MISS-QA benchmark and research questions investigated in this study.

Foundation models have recently demonstrated remarkable capabilities in tackling various complex tasks (Touvron et al., 2023; Jiang et al., 2023; OpenAI, 2024; Zhao et al., 2025). However, their capabilities in interpreting schematic diagrams and synthesizing information from related paper context remain largely underexplored. Previous scientific document QA benchmarks primarily focus on text-only contexts (Dasigi et al., 2021; Lee et al., 2023b), emphasizing information-seeking questions derived from paper abstracts. While recent scientific multimodal QA benchmarks have incorporated multimodal information from scientific papers (Li et al., 2024a; Wang et al., 2024b; Li et al., 2024c,d), their focus is largely limited to analyzing charts or tables that present experimental results. In contrast, reasoning over schematic diagrams introduces unique challenges. It requires

Dataset	Input Context	Annotation / Data Single Creation
<i>Scientific Figure Understanding</i>		
ArXivQA (Li et al., 2024b)	Single scientific chart for experiment results	Rewritten from caption by GPT-4V
MMSci (Li et al., 2024d)	Single scientific chart for experiment results	Rewritten from caption by experts
CharXiv (Wang et al., 2024b)	Single scientific chart for experiment results	Annotated by human experts
<i>Scientific Paper QA</i>		
QASPER (Dasigi et al., 2021)	Single text-only scientific paper	Annotated by human experts
QASA (Lee et al., 2023a)	Single text-only scientific paper	Annotated by human experts
M3SciQA (Li et al., 2024a)	Multiple scientific papers with charts	Synthesized by GPT-4V
MISS-QA (ours)	Single schematic diagram and corresponding paper	Annotated by human experts

Table 1: Comparisons between MISS-QA and existing scientific figure understanding and paper QA benchmarks.

understanding not only the visual elements but also their relationships, contextual meaning, and integration with the textual narrative of the paper. Addressing these challenges is critical for advancing AI systems to effectively navigate the multimodal nature of scientific research.

To bridge this gap, we introduce **MISS-QA**, a question answering benchmark focuses on **Multimodal Information-Seeking over Scientific papers**. The benchmark comprises 1,500 expert-annotated QA examples over 465 scientific papers, capturing a wide range of real-world information-seeking scenarios over scientific literature. For each question, the schematic diagram—typically appearing as the first or second figure in the paper and providing an overview of the research—serves as the focal point. Foundation models are tasked with identifying the highlighted visual element within the diagram and answering the question using the content of the paper. To mirror real-world information-seeking scenarios, where researchers often encounter questions that cannot be answered using the available context, 22.5% of the questions in MISS-QA are intentionally designed to be unanswerable (Rajpurkar et al., 2018; Asai and Choi, 2021; Sulem et al., 2022). Such questions tests the model’s ability to discern the limits of the provided information, which is crucial for scientific research.

Figure 1 illustrates the key research questions investigated in this study. Our main contributions are summarized as follows:

- We present MISS-QA, the first benchmark specifically designed to assess the ability of foundation models to comprehend schematic diagrams in scientific literature.
- We perform a comprehensive evaluation of 18 frontier multimodal foundation models, uncover-

ing a significant performance disparity between human experts and current models.

- We analyze model performance on unanswerable questions and conduct an in-depth error analysis, highlighting key strengths, limitations, and opportunities to improve model performance.

2 Related Work

Early document QA benchmarks (Rajpurkar et al., 2016; Bajaj et al., 2018; Yang et al., 2018) target short documents (*e.g.*, Wikipedia pages) and single-hop reasoning. In contrast, question answering over scientific papers introduces unique challenges. These include interpreting domain-specific terminology, synthesizing information across multiple sections, and reasoning over multimodal content. However, as shown in Table 1, existing benchmarks in this area mainly investigate the *text-only* scenarios. Specifically, QASPER (Dasigi et al., 2021) focuses on tasks where questions are derived from the abstract of a scientific paper, with answers found within its main sections. Similarly, QASA (Lee et al., 2023b) requires more in-depth reasoning over the paper to answer the questions, yet it also focuses solely on text-based context. The most recent advancement, M3SciQA (Li et al., 2024a), expands scientific paper QA to include multimodal contexts, focusing specifically on interpreting charts that present experimental results. Parallel efforts in scientific figure understanding (Li et al., 2024b; Wang et al., 2024b; Li et al., 2024d) similarly emphasize reasoning over charts. However, these benchmarks overlook other critical visual modalities such as schematic diagrams, which play a central role in many scientific disciplines.

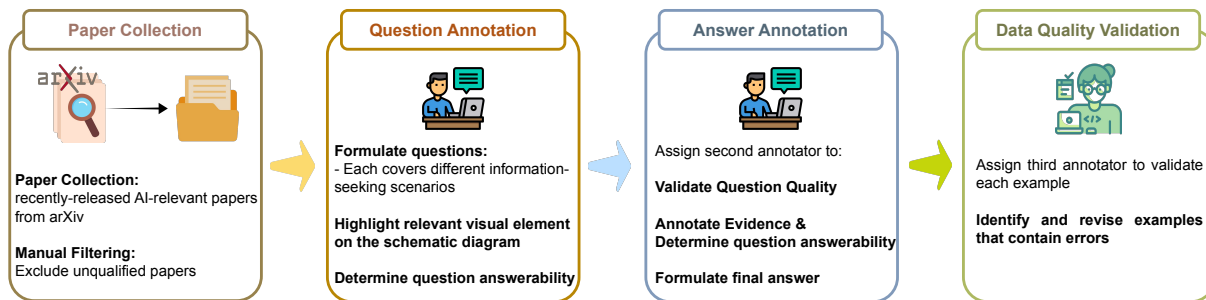


Figure 2: An overview of the MISS-QA benchmark construction pipeline.

3 The MISS-QA Benchmark

We develop the MISS-QA benchmark to evaluate foundation models’ abilities to interpret schematic diagrams and integrate them into the information-seeking process over scientific papers. We formally define the task of MISS-QA in the context of foundation models (FM) as follows: Given a schematic diagram $diag$ within a scientific paper, an associated question q , and the main sections of paper p , the task is to understand and interpret $diag$, identify the question-relevant information within p , and generate the final free-form answer a :

$$\hat{a} = \arg \max_a P_{\text{FM}}(a \mid diag, q, p) \quad (1)$$

The following subsections outline the preliminary setup for data construction, followed by a comprehensive explanation of the benchmark construction and validation processes. Figure 2 presents an overview of the data construction pipeline.

3.1 Preliminary Setup

We first discuss the preliminary setup.

Benchmark Construction Desiderata. To ensure the high quality of data, MISS-QA adheres to the following three benchmark construction desiderata: (1) *Real-world research scenarios*: it mirrors real-world information-seeking scenarios in which researchers interact with scientific literature, emphasizing the use of schematic diagrams to swiftly comprehend and navigate intricate information within a scientific paper. (2) *Schematic diagram interpretation requirement*: it demands the interpretation of schematic diagrams, ensuring that models do more than merely scan text for answers—they must genuinely interpret and integrate visual information for reasoning; and (3) *Diverse reasoning types*: it includes a range of reasoning types to reflect the complexity of information-

seeking questions that researchers encounter when critically reading the paper context.

Expert Annotator Recruitment and Training.

Given the high level of expertise required for MISS-QA, annotation could not be entrusted to crowdsourced annotators. Instead, we recruit 16 human researchers as expert annotators. Their anonymized profiles are detailed in Appendix A.1. Notably, each annotator has authored a minimum of three AI-related publications, ensuring a high standard of domain knowledge. MISS-QA primarily targets scientific papers across diverse subfields within the *AI domain* (e.g., natural language processing, computer vision, and machine learning), aligning with the expertise of our annotators. Before commencing the annotation process, each annotator undergoes a comprehensive one-hour training session conducted by one of the authors. This training ensures that they deliver precise and consistent annotations throughout the project. The screenshots of our developed annotation interface are presented in Appendix A.2.

Information-Seeking Scenario and Subset Categorization.

To better understand the common information-seeking scenarios researchers encounter when reading scientific papers, we conducted a preliminary study. In this study, annotators were given the freedom to read any scientific paper and annotate any type of question that seeks information contained within the context of the paper. This process allowed us to identify four key types of scenarios that frequently arise in practical settings. Based on these findings, we created five subsets of MISS-QA, each tailored to specific information-seeking focuses: design rationale, implementation details, literature background, experimental results, and others. We define each subset and provide corresponding example questions in Table 2 and Appendix B, respectively.

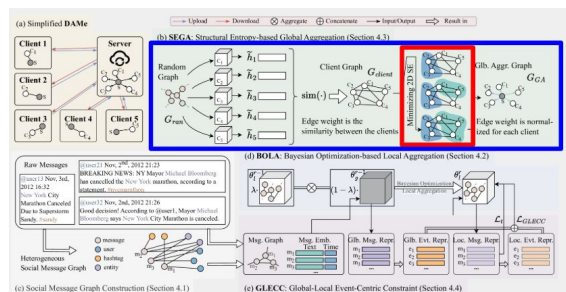
Information-Seeking Scenarios	Example Question Provided in Appendix B
Design Rationale Reasoning and motivations behind the structural and conceptual design choices	What is the motivation behind designing the [module highlighted by red bounding box] in the proposed framework? (Figure 3 & Appendix B.1)
Implementation Details Technical details of how the specified modules or procedures are implemented	How does the [module highlighted by red bounding box] interact with the [module highlighted by green bounding box]? (Appendix B.2)
Literature Background Relationship between the specified modules and relevant prior research or methodologies	Which prior work does the [module highlighted by red bounding box] build on? (Appendix B.3)
Experimental Results Key findings related to the specified modules or procedures based on experimental results	How does the [module highlighted by red bounding box] contribute to the overall framework based on the results? (Appendix B.4)
Others Additional aspects such as limitations, alternative approaches, and ethical considerations.	What are the limitations of the [module highlighted by the red bounding box] as discussed in the paper? (Appendix B.5)

Table 2: Definition of the investigated information-seeking scenarios in MISS-QA.

3.2 Source Paper Collection and Filtering

Source Paper Collection We collect AI-related scientific papers from arXiv, focusing on subfields that align with the expertise of our annotators. Specifically, we select papers categorized under “Artificial Intelligence”, “Computation and Language”, “Machine Learning”, “Computer Vision and Pattern Recognition” and “Information Retrieval”. Our dataset includes papers first released between July 1 and September 30, 2024. This time frame is after the cutoff date for most open-source pretraining corpora used to train foundation models, helping to mitigate issues related to data memorization in the models evaluated in this study (Deng et al., 2024). For each paper, we extract its context, including figures and tables, from the HTML version provided by the arXiv platform. This process results in a total of 1,727 scientific papers.

Source Paper Filtering Five expert annotators (*i.e.*, one for each subfield) are then assigned to manually filter out unqualified papers. Specifically, we exclude (1) papers that are not focused on research (*e.g.*, surveys, position papers, and dissertations), and thus is difficult to design research-related questions; (2) papers whose first two figures are both not schematic diagrams or are unsuitable for composing challenging questions that requires figure interpretation; and (3) papers that expert annotators judged to be of low quality or that contained errors in paper parsing based on their assessment. This results in 465 papers for subsequent annotation. For each paper collected, the annotators are tasked with labeling the first figure



Question: Why is [module highlighted by red bounding box] important for [module highlighted by blue bounding box]?

Figure 3: An example of a question posed within an information-seeking scenario related to design rationale.

identified as a schematic diagram, which is then used for subsequent QA annotation.

3.3 Question Annotation

Annotators are given papers relevant to their fields to annotate questions following these three steps:

Formulating Information-Seeking Question.

Annotators are initially given access to the abstract, introduction section, and schematic diagram of the paper. They are required to carefully review these materials to gain an overview of the study. They then identify the essential visual elements (*i.e.*, modules or procedures) within the diagram that are crucial to the research design and often lead to critical thinking or analysis regarding the study. For annotating a single question, the annotation interface randomly assigns an information-seeking scenario (as described in §3.1) for the annotator to focus on. Based on this scenario, annotators formulate a question that incorporates the essen-

tial visual elements from the diagram. Specifically, they are required to follow information-seeking scenarios, aiming to comprehend and navigate intricate information using the schematic diagrams for effective navigation to specific paper sections. The annotated questions are designed to require the models to first interpret the schematic diagram, then navigate to the relevant sections of the paper for in-depth understanding and reasoning.

Highlighting Relevant Visual Element. Recent studies have shown that visual content is unnecessary for many examples in current multimodal reasoning benchmarks, as questions can be directly answered from the textual part of the question due to the annotation bias or reasoning shortcut (Yue et al., 2024; Chen et al., 2024a; Zhang et al., 2024). To alleviate this issue and ensure that the questions really necessitate interpretation of schematic diagram within the paper, for each question, annotators apply one or two differently colored bounding boxes to highlight specific visual elements within the schematic diagram that are crucial for answering the questions. In the question text, these areas are referred to as “the module/process highlighted by [color] bounding box”, forcing models to interpret the figure rather than relying on textual clues within the question itself. We also retain the original, unmasked questions within the dataset as a reference for future research.

Determining Question Answerability and Annotating Evidence. Annotators are initially provided only with the figure, abstract, and introduction sections of a paper to annotate questions. Under these constraints, some questions are expected to be *unanswerable* based on entire paper context. This is intentionally designed as, in real-world scenarios, researchers might ask information-seeking questions that cannot be answered based on the paper context. In such settings, the foundation models should acknowledge that the question is unanswerable instead of hallucinating responses (Rajpurkar et al., 2018; Asai and Choi, 2021). After completing the question annotation step, annotators are given access to the full paper to reassess the question’s answerability. For questions deemed answerable, they must identify specific (sub)sections that provide the necessary information. These identified sources are subsequently used for verifying the annotated answers.

3.4 Answer Annotation

For each question, a second annotator is assigned to annotate the answer through the following steps:

Preliminary Question Quality Check. The second annotator begins by evaluating the quality of the question to ensure it is clear, challenging, and truly requires the interpretation of the schematic diagram as intended. The annotator is required to revise or discard those low-quality questions.

Annotating Evidence and Validating Alignment. Similar to the process in question annotation, the second annotator identifies and selects the relevant sections of the paper containing the necessary information to answer each question. Questions are labeled as “unanswerable” if no relevant information exists within the paper. The annotation interface compares the evidence annotated by both annotators. In cases of disagreement, the second annotator is provided with the first annotator’s inputs and asked to validate or revise their annotation. This iterative validation ensures consistency and quality across annotations.

Formulating Final Answer. Finally, the second annotator formulates a comprehensive and precise free-form answer based on the gathered evidence. Answers must avoid including any external information or knowledge beyond the given paper. Annotators are also encouraged to preserve original phrasing from the paper wherever appropriate to ensure accuracy and fidelity to the paper content.

3.5 Data Quality Validation

We implement a rigorous validation protocol to ensure the high quality of our annotated data. For each annotated QA example, a third annotator is assigned to validate the example based on several key aspects: 1) the question must be meaningful, grammatically correct, and requires the interpretation of schematic diagrams for answering; 2) The bounding boxes in the schematic diagrams must be accurately drawn and aligned with the question’s focus; 3) the associated evidence is accurately and completely annotated; 4) the answer is accurately annotated, directly linked to the provided evidence, and excludes any external information or knowledge not contained within the document. Examples that fail to meet these standards are revised by the validators to ensure consistency and accuracy.

Table 3 presents the key data statistics of MISS-QA. MISS-QA include 1,500 expert-annotated

Property (Median/Avg)	Test
# Scientific Papers	465
Schematic Diagram Caption Len.	57 / 67
Paper Length	4,368 / 4,565
Question Length	14.1 / 13.8
Answer Length	59.0/ 60.3
# Unanswerable Questions	338
# Answerable Questions	1162
# QA Examples	1,500

Table 3: Basic statistics of MISS-QA. Answer length statistics exclude unanswerable questions.

examples over 465 papers. We randomly divide the dataset into two subsets: *testmini* for development validation and *test* for standard evaluation.

4 Experiment

This section presents the experiment setup, followed by a detailed analysis of the results.

4.1 Experiment Setup

Automated Evaluation System. We use accuracy as the primary metric to evaluate model performance on MISS-QA. Following recent benchmark studies (Lu et al., 2024; Li et al., 2024a), we adopt the LLM-as-Judge framework with GPT-4.1 as the base evaluator. Specifically, the model is prompted to assign an accuracy score of 0, 0.5, or 1 by comparing the generated response with the ground-truth answer.

Human Expert Performance Measurement. To estimate human expert-level performance on MISS-QA, we randomly selected 50 examples, comprising 10 from each subset of the *testmini* set. Two PhD candidates with specializations in NLP and CV, respectively, were tasked with independently solving these questions within 5 hours. Their responses were evaluated using our developed automated evaluation protocol. They achieve an average accuracy of 89.0% (Table 4).

Evaluated Multimodal Foundation Models. We examine the performance of 18 multimodal foundation model across two distinct categories on MISS-QA: (1) **proprietary models**, including OpenAI o4-mini (OpenAI, 2025a), GPT-4o, GPT-4.1 and GPT-4.1-mini (OpenAI, 2024, 2025b) and Gemini-2.5-Flash (Gemini, 2024), and (2) **open-source models**, including Qwen2-VL and Qwen2.5-VL (Wang et al., 2024a), InternVL-2, 2.5

Chain-of-Thought Prompt for Question Answering

[System Input]

You are a computer science researcher. You are provided a schematic diagram that provides an overview of the given paper’s main research. Your task is to interpret the diagram and locate question-relevant information within the paper to answer the provided question. If the question cannot be answered based on the paper context, clearly conclude your response with: “I do not know.”

[User Input]

{image input: schematic_diagram}

Schematic diagram’s caption:
{text input: caption}

Paper Context:
{text input: paper}

Question: {text input: question}

Follow the instructions and think step by step to answer the given question.

Figure 4: The CoT prompt used in our experiment.

and 3 (Chen et al., 2023, 2024c,b), Pixtral (Agrawal et al., 2024), Mistral-Small-3.1 (Mistral AI, 2025), and Phi-3.5-Vision and Phi-4-Multimodal (Abdin et al., 2024; Microsoft et al., 2025). Table 6 in Appendix presents the details of each evaluated model in this study. Figure 4 presents the prompt employed in our main experiments, which is adapted from M3SciQA (Li et al., 2024a).

4.2 Main Findings

A substantial performance gap remains between human experts and state-of-the-art open-source models. For example, Qwen2.5-VL-72B, the highest-performing open-source model to date, achieves an accuracy of only 61.6%, significantly trailing behind the 89.0% accuracy attained by human experts. While proprietary models such as o4-mini and GPT-4.1 have made notable strides in narrowing this gap, open-source models still lag in overall performance. Nevertheless, recent developments in open-source models show promising progress. Notable improvements can be observed within the same model families: Qwen2.5-VL-72B outperforms its predecessor Qwen2-VL-72B by 7.4%, and InternVL3-38B surpasses InternVL2.5-38B by 8.9%. These advancements underscore the rapid

Model	Design Rationale (207)	Implem. Details (212)	Literature Bkgd. (201)	Experiment Results (193)	Other (187)	Unanswerable (225)	Testmini (1,000)
<i>Baselines</i>							
Human Expert	90.0	85.0	95.0	95.0	80.0	85.0	89.0
<i>Proprietary Multimodal Foundation Models</i>							
o4-mini	<u>88.2</u>	84.9	84.8	86.0	44.9	33.8	78.3
GPT-4.1	85.0	<u>76.4</u>	<u>77.9</u>	<u>82.1</u>	<u>67.1</u>	<u>60.0</u>	<u>77.8</u>
GPT-4.1-mini	88.4	74.8	75.1	77.2	53.2	42.2	74.1
Gemini-2.5-Flash	72.2	63.4	57.2	57.8	87.2	88.0	67.3
GPT-4o	73.9	67.5	67.2	65.8	38.5	34.7	63.0
<i>Open-Source Multimodal Foundation Models</i>							
Qwen2.5-VL-72B	74.2	62.3	64.4	64.0	41.4	33.3	61.6
InternVL3-38B	<u>72.7</u>	<u>62.7</u>	<u>60.9</u>	<u>61.9</u>	41.7	34.2	<u>60.4</u>
Mistral-Small-3.1-24B	64.0	63.4	57.5	54.7	45.5	47.1	57.3
Qwen2-VL-72B	62.3	55.2	50.7	52.8	49.5	46.2	54.2
InternVL2.5-38B	56.5	49.5	50.2	51.6	50.3	52.0	51.6
InternVL3-8B	58.2	47.2	55.2	53.6	43.0	36.9	51.5
Pixtral-12b	52.7	55.4	49.8	48.2	41.7	43.1	49.8
Qwen2.5-VL-7B	45.9	40.8	38.1	39.9	46.0	37.8	42.1
Qwen2-VL-7B	37.7	29.2	34.3	37.6	52.7	64.9	38.0
InternVL2.5-8B	37.2	31.4	33.8	32.4	44.4	44.0	35.7
Phi-4-Multimodal	14.3	23.8	32.1	21.8	73.5	93.3	32.4
InternVL2-8B	30.4	26.2	27.4	30.3	46.8	52.4	31.9
Phi-3.5-Vision	18.8	22.6	29.6	23.3	<u>59.9</u>	<u>81.3</u>	30.3

Table 4: Model performance on the MISS-QA testmini and test splits, with a detailed breakdown across various subsets of the test split. Test set accuracy serves as the ranking indicator. **Bold** and underlined numbers indicate the best and second-best performance in each category, respectively.

evolution of open-source technologies, driven by ongoing innovation and community collaboration.

Interestingly, we find that most models, except for Gemini-2.5-Flash and certain lower-performing models like the Phi series, continue to struggle with unanswerable questions. These models often exhibit overconfidence, attempting to provide answers even when the correct response is that no answer exists within the given paper context. In contrast, human experts display greater robustness and discernment in such scenarios.

4.3 Analysis on Unanswerable Question.

Reflecting real-world information-seeking scenarios where researchers may encounter questions that cannot be answered based on the context of the papers they are reading, 22.5% of the questions in MISS-QA are designed to be unanswerable (§3.4). This subset aims to evaluate models’ ability to handle uncertain queries and appropriately respond by indicating the lack of sufficient information. Figure 5 illustrates the confusion matrices for answerable and unanswerable questions, comparing the responses of two top-performing proprietary models and two open-source models against the

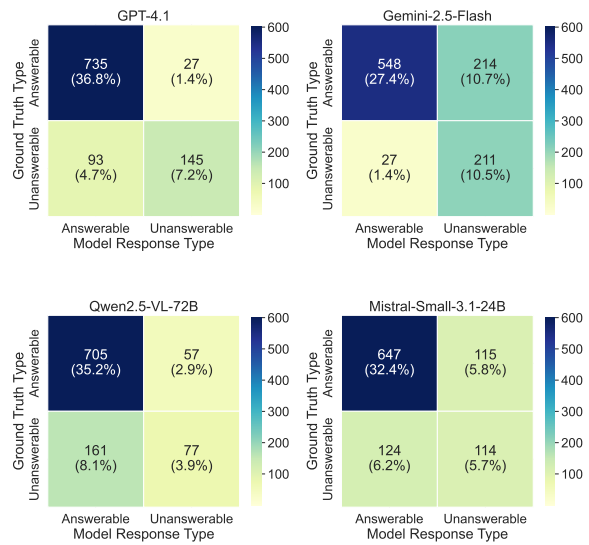


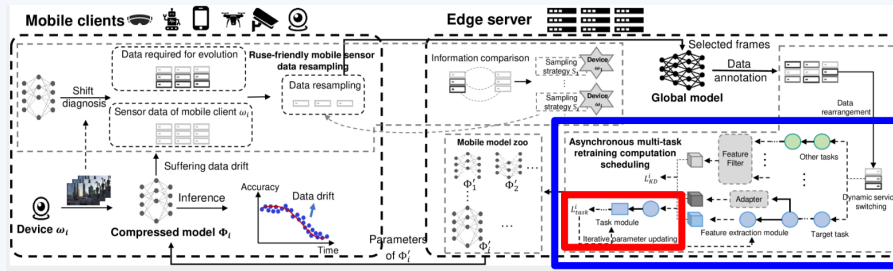
Figure 5: Confusion matrices comparing the model response types (whether answerable) to the ground truth.

ground-truth answers on the test set.

4.4 Error Analysis and Case Study.

To gain deeper insights into the strengths and limitations of the top-performing open-source multimodal foundation models on our task, we con-

Design Rationale



Paper Title:

AdaBridge: Dynamic Data and Computation Reuse for Efficient Multi-task DNN Co-evolution in Edge Systems

Figure Caption:

Illustration of AdaBridge's system workflow.

Question:

What is the importance of [module highlighted by red bounding box] in [module highlighted by blue bounding box]?

Ground-truth Answer:

The importance of iterative parameter updating in retraining scheduling is to optimize the limited representation capacity of compressed mobile DNNs by incorporating dynamic switching and incremental parameter updating.

Relevant Paper Context:

Section 2: AdaBridge Design:

“It asynchronously reuses learned features from different subtasks and incorporates dynamic switching and incremental parameter updating to optimize the limited representation capacity of compressed mobile DNNs”

Qwen2-VL-72B:

The module highlighted by the red bounding box is the “Task module” within the "Asynchronous multi-task retraining computation scheduling" module (highlighted by the blue bounding box). The Task module is important because it is responsible for performing the specific tasks that the system is designed to accomplish. The iterative parameter updating within the Task module allows the system to adapt and improve its performance over time, which is crucial for maintaining accuracy and efficiency in the face of changing data and evolving tasks.

Error Analysis:

The Qwen2-VL-72B’s answer misses the core technical importance of iterative parameter updating in terms of improving dynamic adaptability and optimizing limited representation capacity. It does not delve into how this specific process aids in mitigating challenges like data drift or evolving tasks.

Figure 6: An example of model reasoning error.

ducted a thorough error analysis. This analysis examines 100 randomly sampled error cases, with 50 cases each from Qwen2-VL-72B and InternVL2.5-38B, derived from the *testmini* set. We identify the following five common error types:

- (1) **Failure to interpret and contextualize schematic diagrams:** The model struggles to decode the structure and meaning of the schematic diagram, failing to identify highlighted visual elements or associate them with relevant paper context. Examples are presented in Appendix C.1.
- (2) **Inability to retrieve relevant context:** The model is unable to effectively locate or extract the sections of the paper most relevant to addressing the question, leading to incomplete or irrelevant answers. Examples are presented in Appendix C.2.
- (3) **Reasoning error:** The model successfully identifies the relevant visual and textual information

needed to answer the question but fails to reason correctly with this information, leading to incorrect response. Examples are presented in Figure 6 and Appendix C.3.

- (4) **Overconfident response to unanswerable questions:** While the model successfully interprets the schematic diagram and visual elements, it generates responses even when the provided information does not suffice to answer the question. Examples are presented in Appendix C.4.
- (5) **Overreliance on visual elements:** The model disproportionately focuses on the schematic diagram, neglecting the given paper context. They rely on isolated visual interpretation with parametric knowledge to answer the question. Examples are presented in Appendix C.5.

Other errors include generating a response that exceeds the 1024-token output limit, and refusing to answer due to safety alignment. Our findings

suggest that the primary sources of errors are the models’ difficulties in interpreting and contextualizing schematic diagrams and retrieving relevant contextual information from papers to construct accurate answers.

5 Conclusion

This paper presents MISS-QA, the first benchmark specifically designed to evaluate multimodal foundation models in their ability to interpret schematic diagrams within scientific literature. We perform a comprehensive evaluation of 18 frontier multimodal foundation models, uncovering a significant performance disparity between human experts and current models. Through an in-depth assessment, we identify the weaknesses of cutting-edge foundation models on MISS-QA, offering valuable insights to guide future advancements in the field.

Acknowledgement

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Limitations

While our benchmark aims to reflect real-world research scenarios, it predominantly focuses on AI-related scientific papers from arXiv, as our expert annotators specialize in various subfields within the AI domain. Extending this work to other scientific disciplines, such as biology and medicine, would enhance its generalizability and applicability across broader research areas. Moreover, we examined the available documentation for each evaluated model, but unfortunately, most models do not disclose detailed information about their pretraining data. This lack of transparency prevents us from definitively determining whether scientific content was included in their training pipeline and, in turn, limits our ability to correlate performance directly to domain-specific training.

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A MISS-QA Benchmark

A.1 Annotator Biographies

ID	Position	Field	Publications	Data Annotation	Data Validation
1	Research Scientist	ML	> 10	✓	
2	Postdoc	CV	> 10	✓	✓
3	Research Scientist	ML	> 10	✓	✓
4	PhD Student	NLP	> 10	✓	✓
5	PhD Student	NLP	5-10	✓	
6	PhD Student	CV	3-5	✓	✓
7	PhD Student	CV/NLP	5-10	✓	
8	Postdoc	NLP	> 10	✓	✓
9	PhD Student	CV/NLP	3-5	✓	
10	PhD Student	DM	5-10	✓	
11	Research Scientist	NLP	> 10	✓	✓
12	PhD Student	ML	> 10		✓
13	PhD Student	IR/NLP	5-10	✓	
14	Postdoc	NLP	3-5	✓	✓
15	PhD Student	IR/NLP	5-10	✓	✓
16	PhD Student	ML	3-5	✓	

Table 5: Details of annotators involved in dataset construction. MISS-QA is annotated by experts in AI domains, ensuring both the accuracy of the benchmark and the reliability of the human evaluation.

A.2 Annotation Interface

The screenshot displays the annotation interface for the MISS-QA benchmark. It features a document viewer on the left with a technical paper titled "Reuse and Blend: Energy-Efficient Optical Neural Network Enabled by Weight Sharing". The paper discusses optical neural networks (ONNs) and the Reuse and Blend (RB) architecture. On the right, a schematic diagram of the RB architecture is shown, with various components highlighted by red and blue bounding boxes. Below the diagram, a question is posed: "What is the relationship between Photonic Processing Unit components and eDRAM Write?". The interface includes a search bar, a "Generate Modified Question" button, and a list of bounding box coordinates for the highlighted elements.

Origin Question
 What is the relationship between Photonic Processing Unit components and eDRAM Write?

Red Bounding Box Replace
 Photonic Processing Unit components

Blue Bounding Box Replace
 eDRAM Write

Modified Question
 What is the relationship between [module highlighted by red bounding box] and [module highlighted by blue bounding box]?

Red Box Coordinates
 (287, 140), (417, 357)

Blue Box Coordinates
 (720, 382), (828, 453)

Figure 7: The interface used by the first annotator for question annotation, where annotators highlight question-relevant visual elements in the schematic diagram using colored bounding boxes. The positions of the bounding boxes are automatically captured and recorded.

The screenshot shows the RIKV annotation interface. On the left, a document titled "This is experimental PTKM to improve accessibility..." is displayed. It contains a diagram (Figure 2) and text describing the RSB architecture and MRR arrays. On the right, the annotation tool is active. A question is posed: "What is the relationship between [module highlighted by red bounding box] and [module highlighted by blue bounding box]?". The answer is "No". Evidence from the document is provided, including the text: "Our novel Photonic Reuse Method (PRM) allows the bit cycle of each weight value, significantly reducing programming and calibration operations during MRR CNN inference. Besides, our Opto-electronic Blend Unit (OEBU) enhances feature extraction through feature transpose and channel shuffle. By adopting our weight-sharing technique, we achieved a 69% reduction in energy consumption and a 12% improvement in latency." The interface also includes fields for Evidence Section ID, Figure ID, and Table ID, and a "Submit" button.

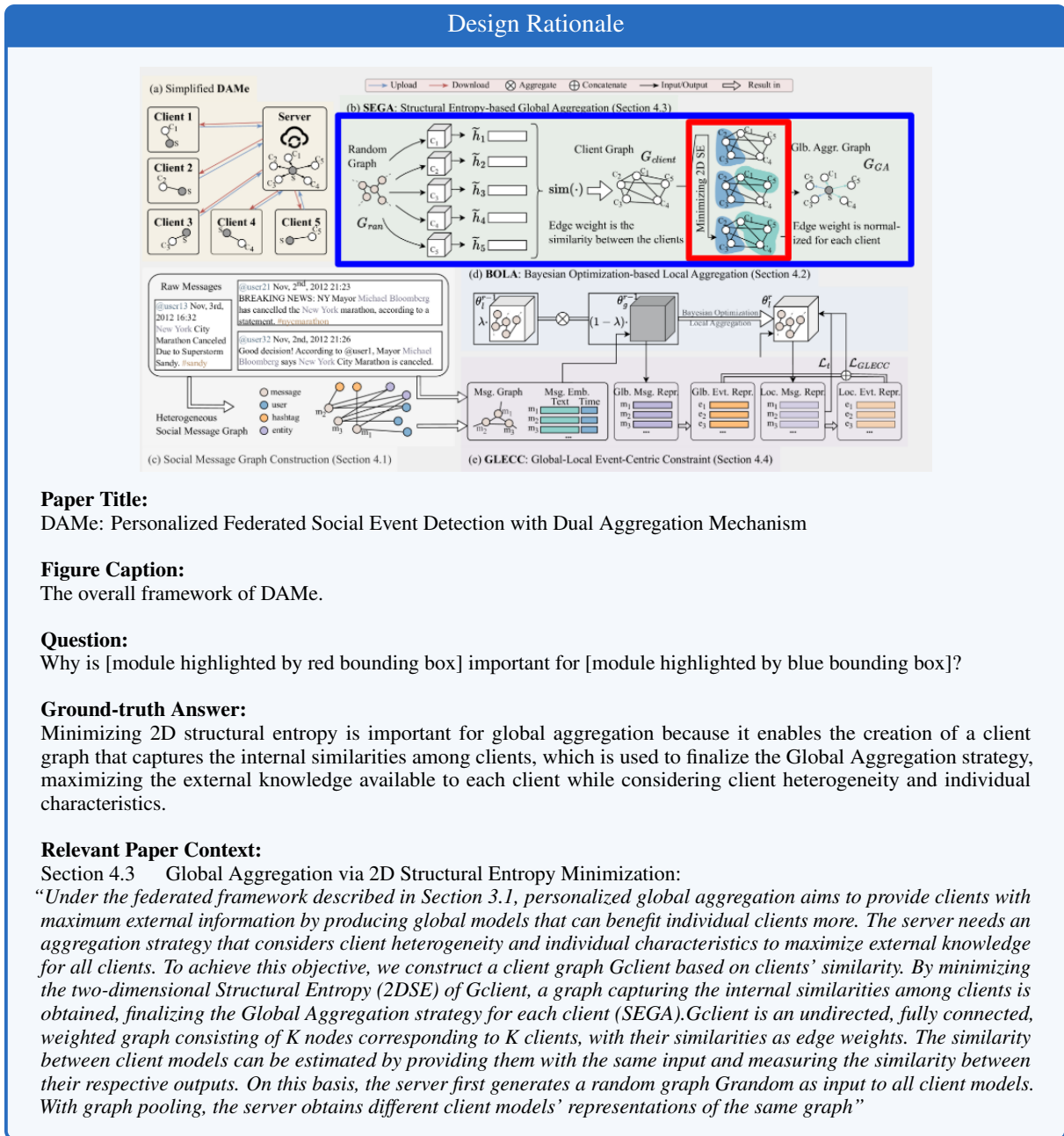
Figure 8: The interface used by the first annotator to evaluate question answerability and identify supporting evidence following question annotation.

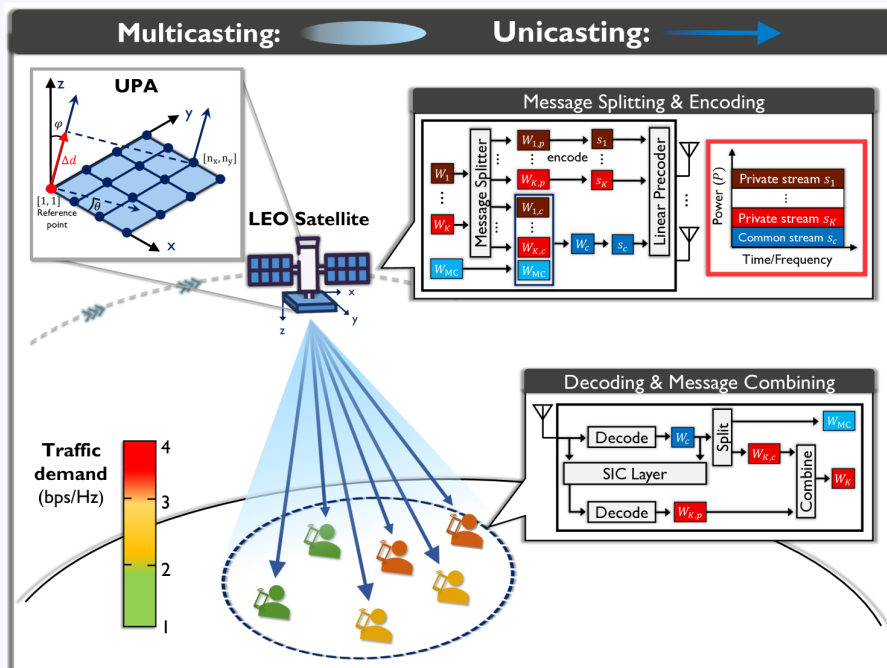
The screenshot shows the RIKV annotation interface. On the left, a document titled "This is experimental PTKM to improve accessibility..." is displayed. It contains a diagram (Figure 2) and text describing the RSB architecture and MRR arrays. On the right, the annotation tool is active. A question is posed: "What is the relationship between [module highlighted by red bounding box] and [module highlighted by blue bounding box]?". The answer is "Yes". Evidence from the document is provided, including the text: "Our novel Photonic Reuse Method (PRM) allows the bit cycle of each weight value, significantly reducing programming and calibration operations during MRR CNN inference. Besides, our Opto-electronic Blend Unit (OEBU) enhances feature extraction through feature transpose and channel shuffle. By adopting our weight-sharing technique, we achieved a 69% reduction in energy consumption and a 12% improvement in latency." The interface also includes fields for Evidence Section ID, Figure ID, and Table ID, and a "Submit" button.

Figure 9: The interface used by the second annotator for answer annotation. The annotator begins by entering the supporting evidence and then compares it with the annotation provided by the first annotator. This process enhances the accuracy and consistency of the answer annotations.

B Dataset Examples of Different Information-Seeking Scenarios

B.1 Design Rationale Diagram example





Paper Title:

Rate-Splitting for Joint Unicast and Multicast Transmission in LEO Satellite Networks with Non-Uniform Traffic Demand

Figure Caption:

System model of the proposed RSMA-based NOUM transmission.

Question:

What is the motivation behind combining the content of [module highlighted by red bounding box] in this framework?

Ground-truth Answer:

The motivation behind combining common and private streams in this framework is to effectively minimize the unused and unmet rates by allocating usable power according to traffic requirements, manage interference between unicast and multicast streams, and ensure robustness against imperfect channel state information.

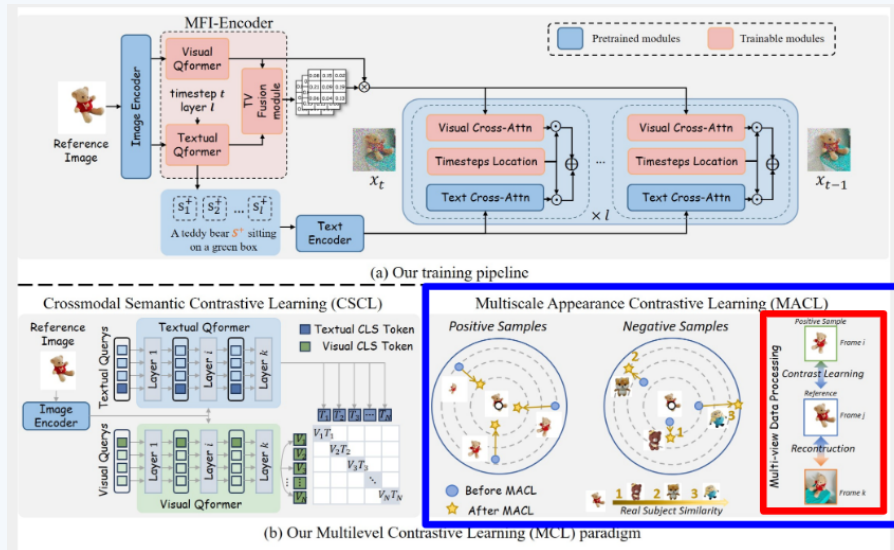
Relevant Paper Context:

Section 1.2 Motivations and Contributions:

“We propose an RSMA-based RM framework that minimizes the difference between traffic demands and actual offered rates for both unicast and multicast messages. By flexibly allocating the usable power into the common and private streams according to the traffic requirements, the unused/unmet rates are effectively minimized. To cope with the challenge of obtaining instantaneous CSIT at LEO satellites, we leverage the statistical and geometrical information of satellite-to-user channels, which vary comparably slower, in the RSMA precoder design.”

B.2 Implementation Details Diagram example

Implementation Details



Paper Title:

CustomContrast: A Multilevel Contrastive Perspective For Subject-Driven Text-to-Image Customization

Figure Caption:

Overview of the proposed CustomContrast. (a) Training pipeline. The consistency between textual and visual features is accurately learned by the MFI-Encoder, which includes a Textual-Visual (TV) Fusion module to enhance feature consistency from visual and textual Qformers. (b) The MCL paradigm includes CSCL, aligning high-level semantics by contrasting visual and textual embeddings via CLS tokens, and MACL, which is applied to text embeddings from different cross-attention layers. MACL decouples redundant subject features by aligning positive samples (segmented images of the same subject from various views, positions, and sizes), while preserving relative distances by contrasting with other subjects.

Question:

How does [module highlighted by blue bounding box] achieve real subject similarity using [module highlighted by red bounding box]?

Ground-truth Answer:

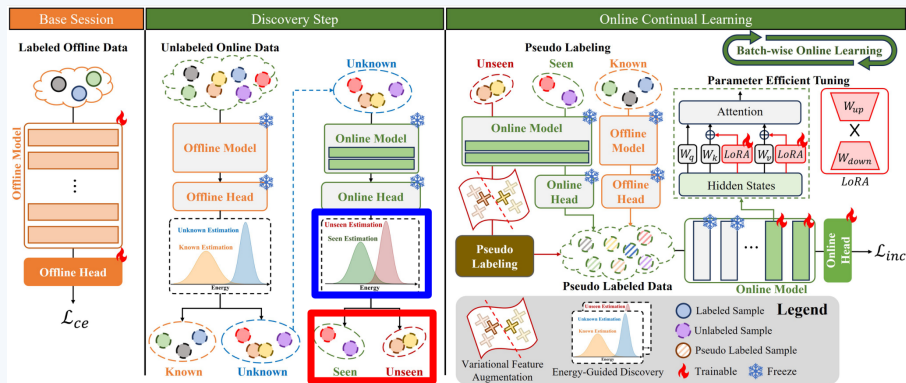
MACL achieves real subject similarity using multiview data by ensuring that the distance relationships between multiscale features are consistent with those of real subjects. This is done by maintaining intra-consistency, where features of the same subject with different situations are as close as possible, and inter-distinctiveness, where the distances between different samples' features match those between real subjects. MACL preserves the multi-scale similarity structure, ensuring that the similarities of learned features are positively correlated with those of real subjects.

Relevant Paper Context:

Section 3.3.2 Multiscale Appearance Contrastive Learning:

“The key idea of Multi-scale Appearance Similarity Contrastive Learning (MACL) is to ensure that the distance relationships between multiscale features are consistent with those of real subjects. This means the features of the same subject with different situations should be as close as possible (intra-consistency), while the distances between different samples' features should match those between real subjects (inter-distinctiveness). As shown in Fig. 2(b)(right), we achieve intra-consistency by pulling positive samples of the reference subject closer, and inter-distinctiveness by introducing scaling factors to align the feature distances with negative samples to real subject distances. In this section, we will introduce the S+Space and MACL in the S+Space. As shown in Fig. 2(b) (right), We select frames different from the reference images as MACL positive samples. By aligning images of the same subject, CustomContrast effectively decouples irrelevant features of the subject. The processing details of positive samples are in Appendix B.”

Implementation Details



Paper Title:

Online Continuous Generalized Category Discovery

Figure Caption:

Overall process of the proposed DEAN framework. The energy-guided discovery splits unlabeled data into known, seen, and unseen data for better novel category discovery, while variance-based feature augmentation enhances the clustering of unseen data. L_{ce} facilitates better discriminative learning in the online continual learning.

Question:

What role does [module highlighted by blue bounding box] play in [module highlighted by red bounding box] estimation for online models?

Ground-truth Answer:

Energy scores are used to classify unlabeled data into known and unknown categories in the first stage, and then further split unknown data into seen and unseen categories in the second stage. This is done by calculating the energy scores using a Gaussian Mixture Model to identify which cluster a sample belongs to, ultimately facilitating the estimation of seen and unseen data in the online model.

Relevant Paper Context:

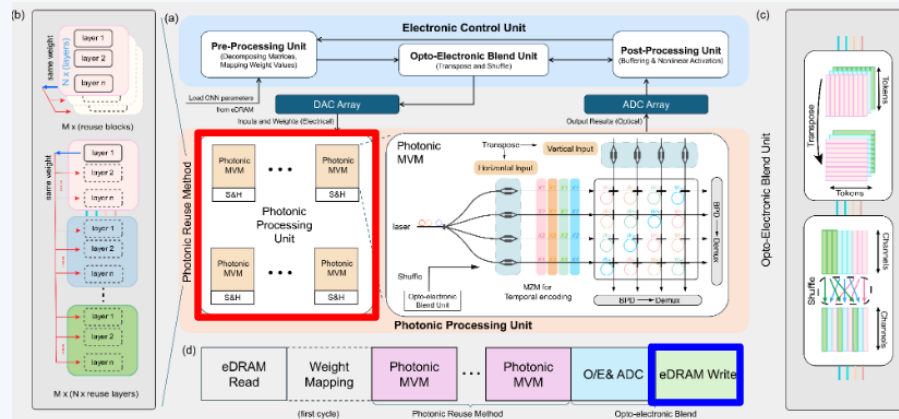
Section 3.3 Energy-Guided Discovery to Identify Unknowns:

“In Figure 3, we found that the two-stage split of the CGCD struggled to identify both known and unknown categories in our proposed online learning scenario. Online learning with batch-wise data led to severe forgetting in the split network, resulting in poor detection of unknown samples. In contrast, energy-based discovery showed better performance in novel category discovery without extra parameters compared to CGCD. Moreover, as it does not require an additional learning phase, energy-based discovery enables end-to-end training. Inspired by this observation, we propose an energy-guided discovery approach for novel category discovery. To the best of our knowledge, this is the first work to utilize the energy score for novel category discovery.

The process in the second stage is the same as the first stage, where we split the unknown data into seen and unseen categories based on their energy scores. For the initial batch of incremental sessions, the online model is identical to the offline model. Additionally, since the initial batch data is the first data of the incremental session, any data classified as unknown is assumed to be unseen data. The proposed energy-guided discovery splits unlabeled data into known, seen, and unseen categories effectively. Unlike prior methods which require sufficient data, it can identify novel categories with batch-wise data.”

B.3 Literature Background Diagram example

Literature Background



Paper Title:

Reuse and Blend: Energy-Efficient Optical Neural Network Enabled by Weight Sharing

Figure Caption:

(a) Overview of the R&B architecture. Each PPU contains a photonic MVM unit and a sampling and hold (SH) unit. (b) Photonic Reuse Method (PRM). Block-wise reuse allows weight sharing among blocks (a block typically contains multiple layers). Layer-wise reuse enables weight sharing between individual layers. (c) Opto-electronic Blend Unit (OBU). OBUs handle shuffle operations via the peripheral circuit and perform transpose operations directly in the optical domain. (d) Computing pipeline of our RB architecture.

Question:

What is the relationship between [module highlighted by red bounding box] and [module highlighted by blue bounding box]?

Ground-truth Answer:

The Photonic Processing Unit (PPU) plays a role in the RB architecture’s computation process where inputs are initially retrieved from eDRAMs to be processed by PPUs. After processing, the outputs are stored back into eDRAMs for the next layer computation.

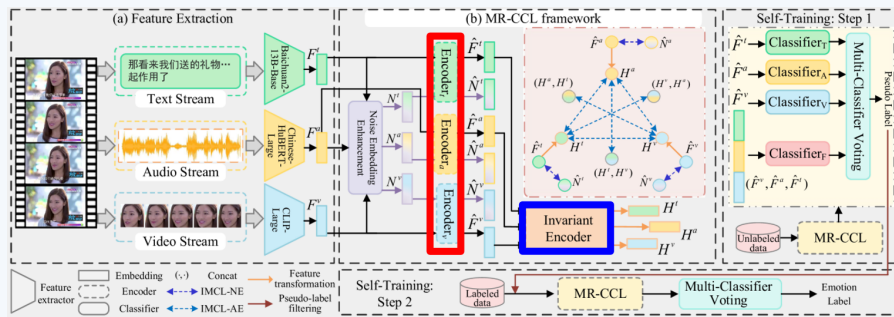
Relevant Paper Context:

Section 3.3 Computing Pipeline:

“The computation process of our RB architecture contains three stages, as illustrated in Fig. 2(a). Initially, inputs are retrieved from eDRAMs, and corresponding weights are allocated to MRRs. Subsequently, following the PRM configuration, the weights are fixed and reused, allowing the inputs to pass through the MRRs to be optically weighted. The intermediate MVM results generated by the PPUs are then detected by BPDs, where they are converted into summed currents and digitized by ADCs. In the final stage, OBUs transform these outputs to generate the layer-wise results, which are then stored back in eDRAMs in preparation for the next computational layer.

A critical aspect of this architecture is the role of the OBU during inference, mirroring its function during training and inference by executing essential shuffle and transpose operations. Subsequently, following the PRM configuration, the weights are fixed and reused. Along with PRM, these two technologies constitute the primary innovation of our RB architecture. By leveraging one MRR array to represent multiple weight matrices, the architecture dramatically reduces the frequency of MRR writing operations, along with power consumption and latency, all while sustaining high performance.”

Literature Background



Paper Title:

Leveraging Contrastive Learning and Self-Training for Multimodal Emotion Recognition with Limited Labeled Samples

Figure Caption:

Illustration of our MR-CCL framework.

Question:

How does the interaction between [module highlighted by red bounding box] and [module highlighted by blue bounding box] support contrastive learning methodology?

Ground-truth Answer:

The interaction between invariant encoder and modality-specific encoders supports contrastive learning by enabling the extraction of both modality-specific embeddings and modality-invariant embeddings. Modality-specific encoders, built with Transformer layers, encode characteristics unique to each modality, while the invariant encoder, structured with linear layers, transforms these embeddings into a unified vector space, capturing relationships between modalities. This facilitates effective feature fusion and interaction for contrastive learning.

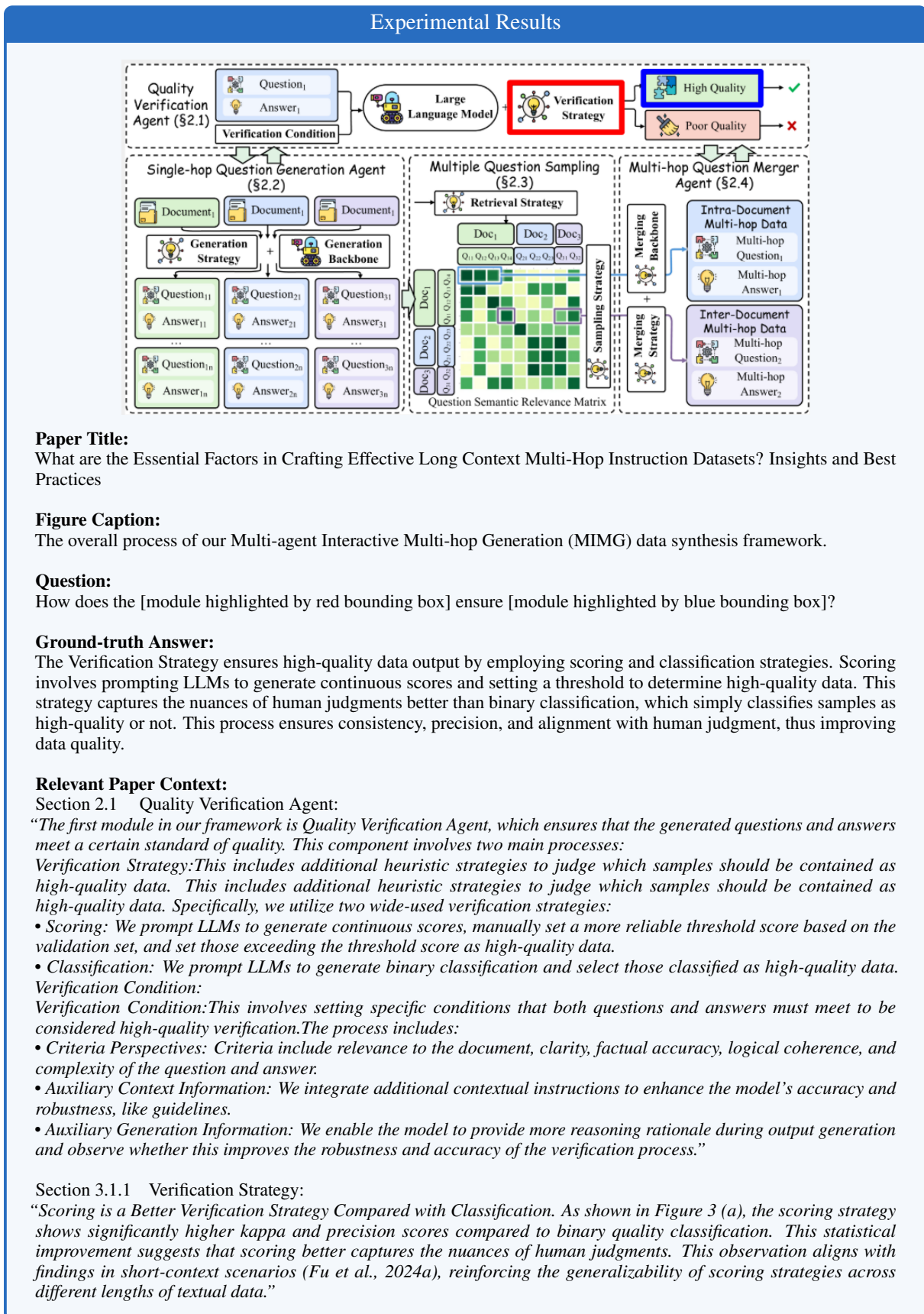
Relevant Paper Context:

Section 2.4.1 Modality Representation Combinatorial Contrastive Learning:

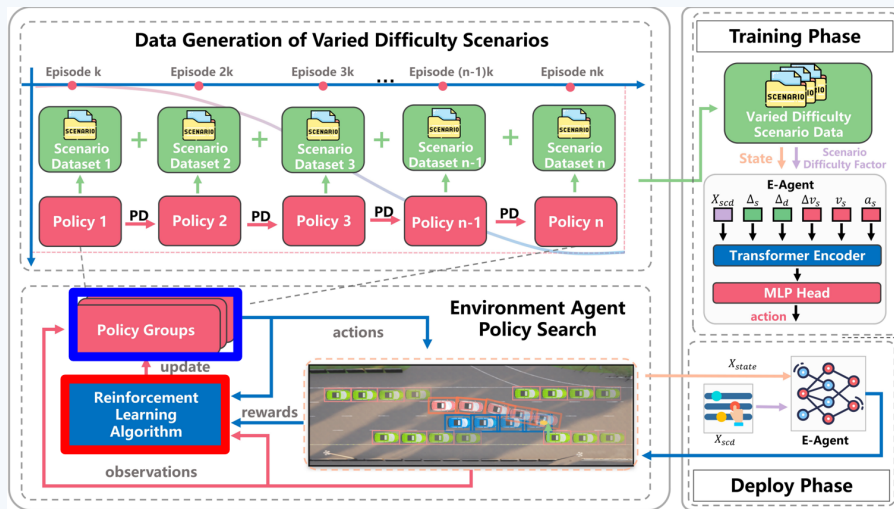
“We propose *Modality Representation Combinatorial Contrastive Learning (MR-CCL)* framework to leverage the given unlabeled data more effectively. The overall architecture is illustrated in Figure 2.

In the realm of multimodal emotion recognition tasks, a proven strategy involves extracting features specific to each modality as well as invariant features that capture relationships between different modalities, which facilitates the fusion and interaction of diverse modal inputs (Zuo et al. 2023; Liu et al. 2024b). To implement our framework, we begin by pre-training three specificity encoders and one invariant encoder using all available unlabeled data. This process is designed to enable the model to discern and encode the intrinsic characteristics and structural nuances of multimodal data. Each specificity encoder is composed of multiple Transformer layers, while the invariant encoder is structured with linear layers.”

B.4 Experimental Results Diagram example



Experimental Results



Paper Title:

Quantitative Representation of Scenario Difficulty for Autonomous Driving Based on Adversarial Policy Search

Figure Caption:

Overall architecture of data driven quantitative representation method of scenario difficulty for autonomous driving based on environment agent policy search.

Question:

How does the [module highlighted by red bounding box] contribute to the updates of [module highlighted by blue bounding box]?

Ground-truth Answer:

The reinforcement learning algorithm contributes to policy group updates by providing a systematic approach to search for optimal policies through the performance improvement phase, where model parameters are updated to pursue better performance, and the convergence stabilization phase, where the optimal policy is obtained. The performance at different stages is used to update and save model parameters to the constructed policy group.

Relevant Paper Context:

Section 4 Data Generation of Scenarios with Varying Difficulty:

“In Section 3, we introduce the concept of environment agent to realize the adversarial policy search by combining logic rules with reinforcement learning. However, due to the black-box nature of data-driven methods, while adversarial actions can be generated, the difficulty of generating adversarial actions is difficult to quantify accurately, which limits the rationality of adversarial scenario generation.

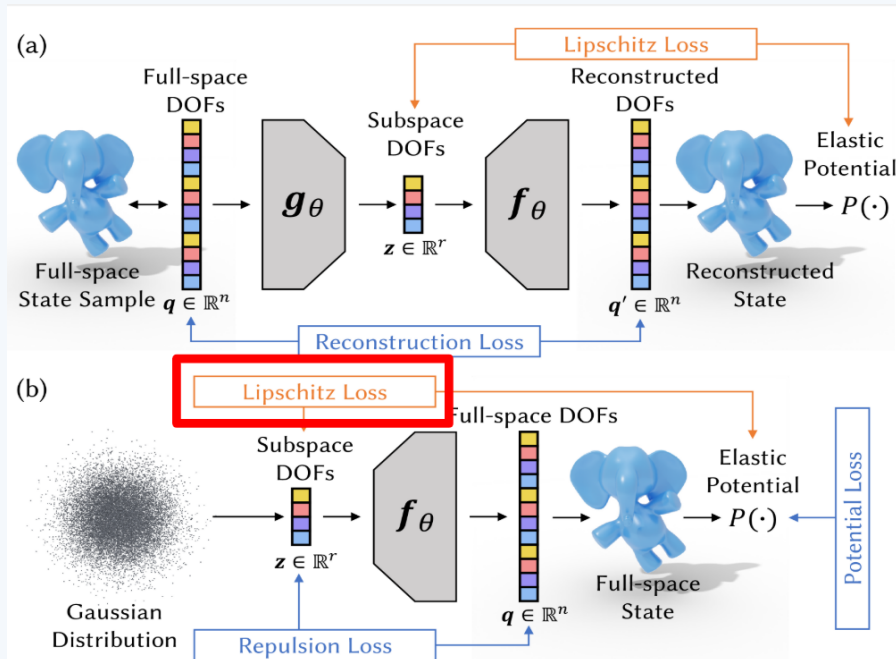
In this section, a data generation method based on scenarios with varying difficulty is presented. The method uses the performance of different stages in the policy search convergence process as a reference to quantify the adversarial intensity, thereby achieving a quantitative representation of scenario difficulty. The model parameters of the environment agent trained on different stages are updated and saved, and then output to the constructed policy group. The policy group is used to generate data that forms the basis for training the scenario difficulty quantitative representation model..”

Section 4.1 Verification Strategy:

“A reinforcement learning training process with stable convergence can be divided into two phases, i.e., the performance improvement phase and the convergence stabilization phase. In the performance improvement phase, the average return is still continuously increasing, which indicates that the policy search is still ongoing and the model parameters are still being updated to pursue better performance. In the convergence stabilization phase, however, the average return remains basically unchanged, indicating that the policy search is basically over, and the obtained policy is already the optimal policy that the current algorithm can achieve.”

B.5 Other Diagram example

Other Diagram Example



Paper Title:

Accelerate Neural Subspace-Based Reduced-Order Solver of Deformable Simulation by Lipschitz Optimization

Figure Caption:

Network training settings for effective neural subspace construction. (a) The supervised setting. (b) The unsupervised setting. Conventional methods only consider the loss shown in blue but do not optimize the Lipschitz loss (shown in orange) to control the landscape of simulation objective in the subspace.

Question:

What are potential limitations of using [module highlighted by red bounding box] in neural subspace training?

Ground-truth Answer:

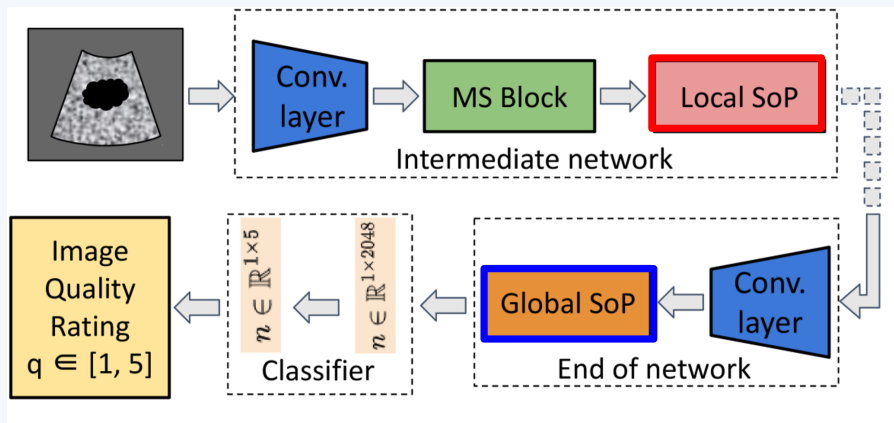
Potential limitations of using Lipschitz optimization in neural subspace training include the intractability of directly optimizing the Lipschitz constant due to the need to traverse all possible point pairs, sparse gradients that could damage Lipschitz characteristics in certain areas, increased memory usage, and potential memory shortages when training high-resolution meshes.

Relevant Paper Context:

Section 5.4 Limitation:

"In this work, Lipschitz optimization is only applied to the elastic potential term of eq. 2. Since the nonlinear mapping is also involved in the inertia term, this may lower the convergence speed of the simulation involving dynamics. Considering that the inertia term is in quadratic form, the Hessian Lipschitz of the inertia term can be optimized by minimizing or bounding the Lipschitz constant of the network's input-output Jacobian. This is a promising direction for future work to further accelerate the simulation with dynamics. Another limitation of our method is the extended training time introduced by incorporating Lipschitz optimization into the pipeline. As shown in Table 1, even with cubature acceleration, the training time is still increased by approximately five times compared to the conventional method. This issue can be addressed by employing fast approximate methods to estimate Lipschitz energy."

Other Diagram Example



Paper Title:

Coaching a Robotic Sonographer: Learning Robotic Ultrasound with Sparse Expert's Feedback

Figure Caption:

State space representation using a deep convolution neural network

Question:

What are the potential challenges of combining [module highlighted by red bounding box] and [module highlighted by blue bounding box] in extracting meaningful image features?

Ground-truth Answer:

Combining local and global second-order pooling (SoP) poses challenges such as increased computational complexity, potential feature redundancy, and the need for careful hyperparameter tuning. It demands substantial data to effectively handle multi-scale features while ensuring the model's robustness. Additionally, balancing local and global information without conflicts can complicate optimization, particularly in real-time medical applications.

Relevant Paper Context:

Section 2.1 State space:

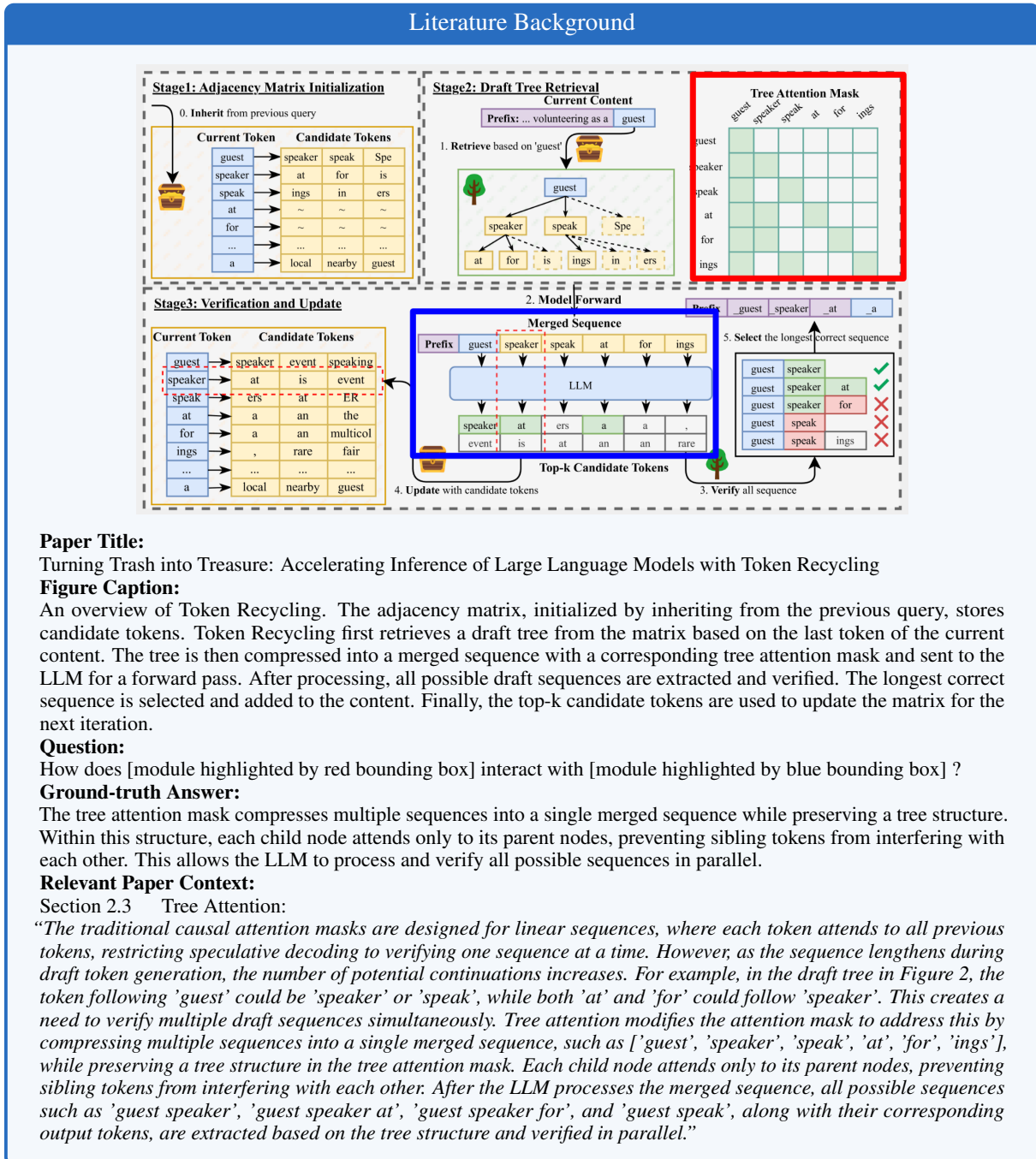
“The state s is defined based on the ultrasound image. We have adopted an image quality classification network from our previous work, which used ResNet50 as a base network with multi-scale and higher-order processing of the image for conducting the holistic assessment of the image quality. The block diagram of this network is shown in Fig. 2. This classifier first extracts features at multiple scales to encode the inter-patient anatomical variations. Then, it uses second-order pooling (SoP) in the intermediate layers (local) and at the end of the network (global) to exploit the second-order statistical dependency of features. The local-to-global SoP will capture the higher-order relationships between different spatial locations and provide the seed for correlating local patches. This network encodes the image into a feature vector of size 2048, which represents the state of the policy.”

Organization	Model	Release	Version	Context Window
<i>Proprietary Models</i>				
OpenAI	o4-mini	2025-4	o4-mini-2025-04-16	–
	GPT-4.1	2025-4	gpt-4.1-2025-04-14	–
	GPT-4.1-mini	2025-4	gpt-4.1-mini-2025-04-14	–
	GPT-4o	2024-8	gpt-4o-2024-08-06	–
Google	Gemini-2.5-Flash	2024-5	gemini-2.5-flash-preview-05-20	–
<i>Open-source Multimodal Foundation Models</i>				
Mistral AI	Pixtral-12B	2024-9	Pixtral-12B-2409	128k
	Mistral-Small-3.1	2025-3	Mistral-Small-3.1-24B	128k
Microsoft	Phi-3.5-Vision	2024-7	Phi-3.5-vision-instruct	32k
	Phi-4-Multimodal	2025-3	Phi-4-Multimodal	128k
Shanghai AI Lab	InternVL3-38B	2025-04	InternVL-3-38B	32k
	InternVL3-8B	2025-04	InternVL3-8B	32k
	InternVL2.5-38B	2024-11	InternVL2.5-38B	32k
	InternVL2.5-8B	2024-11	InternVL2.5-8B	32k
	InternVL2-8B	2024-06	InternVL2-8B	32k
Alibaba	Qwen2.5-VL-72B	2025-1	Qwen2.5-VL-72B-Instruct	128k
	Qwen2-VL-72B	2024-9	Qwen2-VL-72B-Instruct	32k
	Qwen2.5-VL-7B	2025-1	Qwen2.5-VL-7B-Instruct	128k
	Qwen2-VL-7B	2024-9	Qwen2-VL-7B-Instruct	32k

Table 6: Details of the multimodal foundation models evaluated in MISS-QA. The “Source” column includes URLs for proprietary models and Hugging Face (HF) model names for open-source models.

C Error Analysis and Case Study

C.1 Failure to interpret and contextualize schematic diagrams



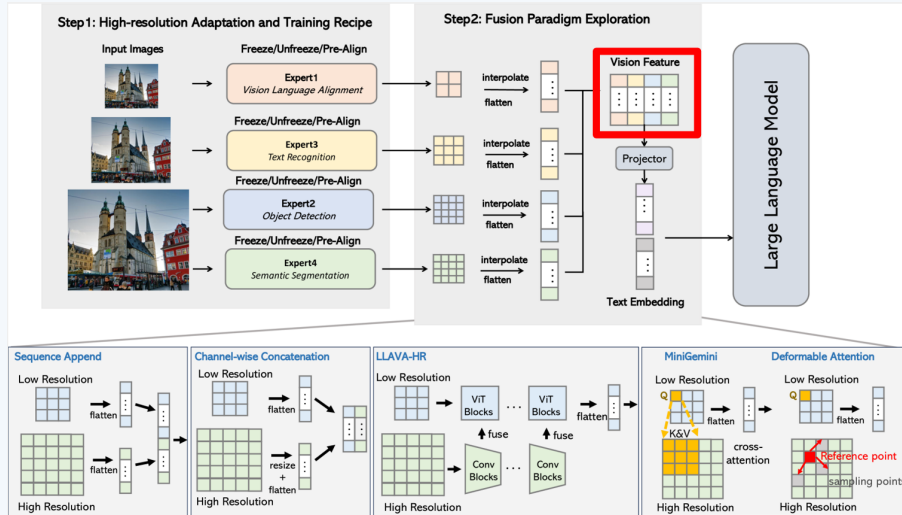
Qwen2-VL-72B:

The module highlighted by the red bounding box, labeled "Tree Attention Mask," interacts with the module highlighted by the blue bounding box, labeled "Merged Sequence," by providing attention weights to the tokens in the merged sequence. The tree attention mask determines which tokens in the merged sequence should be attended to during the model's forward pass. This allows the model to focus on relevant tokens and ignore irrelevant ones, improving the accuracy of the generated sequence.

Error Analysis:

Qwen2-vl-72B's response fails primarily because it does not accurately capture the hierarchical relationship between the modules. It simplifies the interaction, describing the "Tree Attention Mask" (red box) as merely providing attention weights to the "Merged Sequence" (blue box), without explaining how the tree structure constrains and guides the sequence merging process. The response lacks clarity on how the red module enforces parent-child dependencies and prevents sibling token interference, which is crucial for maintaining the tree structure. Additionally, it does not highlight the step-by-step interaction or the layered collaboration between the two modules, leaving the explanation overly vague and incomplete.

Design Rationale



Paper Title:

Eagle: Exploring The Design Space for Multimodal LLMs with Mixture of Encoders

Figure Caption:

Overview of the Eagle exploration pipeline.

Question:

What are the benefits of using channel-wise concatenation in the processing of [module highlighted by red bounding box]?

Ground-truth Answer:

The benefits of using channel-wise concatenation in vision feature processing include achieving the best average performance, maintaining better throughput compared to sequence append, and offering performance, expandability, and efficiency.

Relevant Paper Context:

Section 2.4 Fusion strategy:

“We notice that existing popular fusion strategies, despite their variations in designs, can be broadly represented by the following several categories: (1) Sequence Append: directly appending the visual tokens from different backbones as a longer sequence; (2) Channel Concatenation: concatenating the visual tokens along the channel dimension without increasing the sequence length; (3) LLaVA-HR: injecting high-resolution features into low-resolution vision encoders using mixture-of-resolution adapter; (4) Mini-Gemini: using the CLIP tokens as the low resolution queries to cross-attend another high-resolution vision encoder in the co-located local windows.

Although sequence append shows comparable performance to channel concatenation, it faces the challenge to handle more vision encoders due to the increasing sequence length. Hence, we choose direct channel concatenation as our fusion strategy considering its performance, expandability, and efficiency.”

Qwen2-VL-72B:

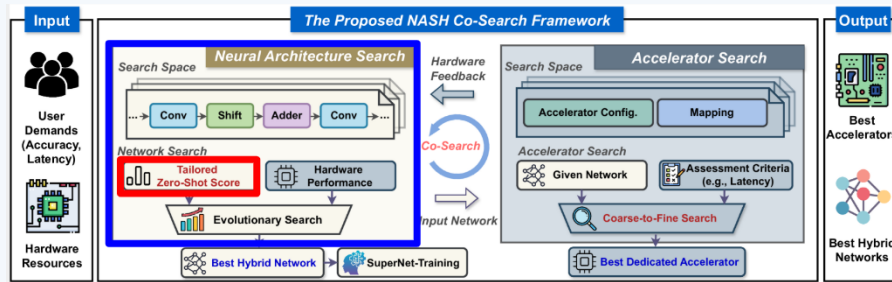
Channel-wise concatenation allows for the combination of features from different resolutions, which can improve the performance of the model.

Error Analysis:

Qwen's response lacks depth as it fails to interpret the schematic diagram and contextualize channel-wise concatenation within the broader design framework. It does not compare its benefits with other fusion strategies like sequence append, missing key insights on performance, expandability, and efficiency. A better response would explicitly reference the diagram and relate the highlighted module to the findings in the paper.

C.2 Inability to retrieve relevant context

Experimental Results



Paper Title:

What are the Essential Factors in Crafting Effective Long Context Multi-Hop Instruction Datasets? Insights and Best Practices

Figure Caption:

The overview of our NASH framework, where we integrate both the neural architecture search (NAS) and coarse-to-fine accelerator search to directly obtain optimal pairing of models and accelerators. Specifically, the NAS consists of a tailored zero-shot metric to pre-identify promising multiplication-reduce hybrid models before supernet training. Besides, the accelerator search involves a novel coarse-to-fine search strategy to expedite the accelerator search process.

Question:

How does the [module highlighted by red bounding box] contribute to the efficiency of [module highlighted by blue bounding box]?

Ground-truth Answer:

The tailored zero-shot score contributes to neural architecture search efficiency by enabling faster assessment due to its swift computational speed. The computation of the tailored zero-shot metric is significantly faster than assessing the accuracy of individual hybrid models derived from the supernet, leading to enhanced search efficiency.

Relevant Paper Context:

Section 3.1 The Tailored Zero-shot Metric:

“To enable a more accurate assessment of our hybrid networks, we integrate two selected zero-shot metrics. Given the significant difference in score magnitudes between these metrics, as shown in Figures 3(b) and 3(c), we focus on relative rankings rather than score magnitudes. Specifically, for a group of networks, the score of our tailored zero-shot metric for a specific network is determined by the relative ranking of its Zen-Score within the group. For instance, if a network exhibits the highest Zen-Score, its term yields a value of 1. The effectiveness of our tailored metric is validated through Table II and Figure 3, which demonstrate the highest Kendall-Tau Correlation. Additionally, this metric contributes to enhanced search efficiency due to the swift computational speed of both NN-Degree and Zen-Score. For example, assessing accuracy for an individual hybrid model from our supernet takes an average of several seconds, whereas computing our tailored zero-shot metric requires less time, making it over X times faster when tested on CIFAR100 and profiled on an NVIDIA GeForce RTX 2080Ti.”

TABLE II The Kendall Tau Coefficient between zero-shot metric scores and real model accuracy. T and E are the abbreviations for trainability and expressivity

Metrics	Mult.-based	Mult.-reduced	Class
SNIP	0.40	-0.01	T
Jacobian Covariant	0.43	0.06	T
Grad Norm	0.36	-0.09	T
Synflow	0.47	0.06	T
Grasp	0.35	0.03	T
Fisher	0.45	-0.05	T
NN-Degree	0.43	0.32	T
Linear Region Number	0.32	0.19	E
Zen-Score	0.40	0.33	E
Ours	-	0.47	TE

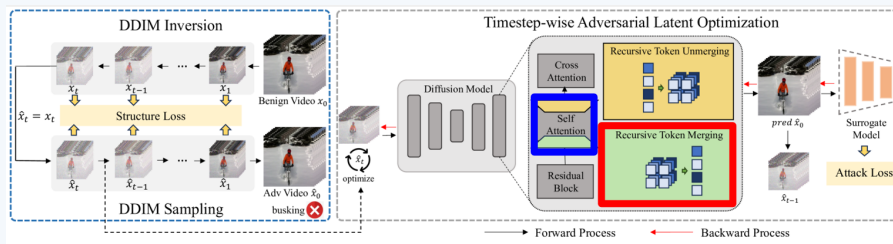
Qwen2-VL-72B:

The Tailored Zero-Shot Score module contributes to the efficiency of the Neural Architecture Search module by providing a fast and accurate way to evaluate the performance of different network architectures without the need for full training. This allows the Evolutionary Search algorithm to efficiently explore the search space and find the best hybrid network.

Error Analysis:

Qwen2’s response fails to explicitly connect the Tailored Zero-Shot Score with the efficiency of Neural Architecture Search (NAS) in the manner suggested by the diagram and the surrounding context. Instead, it merely retrieves a generalized answer based on the keyword, without integrating the broader relationships or contextual dependencies illustrated in the diagram.

Literature Background



Paper Title:

ReToMe-VA: Recursive Token Merging for Video Diffusion-based Unrestricted Adversarial Attack

Figure Caption:

Framework overview of the proposed ReToMe-VA. For a video clip, DDIM inversion is applied to map the benign frames into the latent space. Timestep-wise Adversarial Latent Optimization is employed during the DDIM sampling process to optimize the latents. Throughout the whole pipeline, Recursive Token Merging and Recursive Token Unmerging Modules are integrated into the diffusion model to enhance its effectiveness. Additionally, structure loss is utilized to maintain the structural consistency of video frames. Ultimately, the resulting adversarial video clip is capable of deceiving the target model.

Question:

How does [module highlighted by red bounding box] interact with [module highlighted by blue bounding box] to enhance video consistency?

Ground-truth Answer:

Recursive Token Merging interacts with the Self Attention module by recursively matching and merging similar tokens across frames, enabling the Self Attention module to extract consistent features. This method ensures that the most similar tokens share identical outputs, which maximizes internal uniformity of features across frames and preserves temporal consistency, thereby enhancing video consistency.

Relevant Paper Context:

Section 3.3 Recursive Token Merging:

(...abbreviated...) ”TALO strategy perturbs each benign frame of video separately. This per-frame optimization makes the frames likely optimized along different adversarial directions resulting in motion discontinuity and temporal inconsistency. Furthermore, separately perturbing each benign frame reduces the monotonous gradients because the interactions among the frames are not exploited. To this end, we introduce a recursive token merging (ReToMe) strategy that recursively matches and merges similar tokens across frames together enabling the self-attention module to extract consistent features. In the following, we first provide the basic operation of token merging and token unmerging and then our recursive token merging algorithm.

Token Merging (ToMe) is first applied to speed up diffusion models through several diffusion-specific improvements. Generally, tokens T are partitioned into a source (src) and destination (dst) set. Then, tokens in src are matched to their most similar token in dst , and r most similar edges are selected subsequently. Next, we merge the connected r most similar tokens in src to dst by replacing them as the linked dst tokens. To keep the token number unchanged, we divide merged tokens after self-attention by assigning their values to merged tokens in src .

A self-attention module takes a sequence of input and output tokens across all frames. To partition tokens across frames into src and dst , we define stride as B . We randomly choose one out of the first B frames (e.g., the g -th frame), and select the subsequent frames every B interval into the dst set.

(...abbreviated...) ”

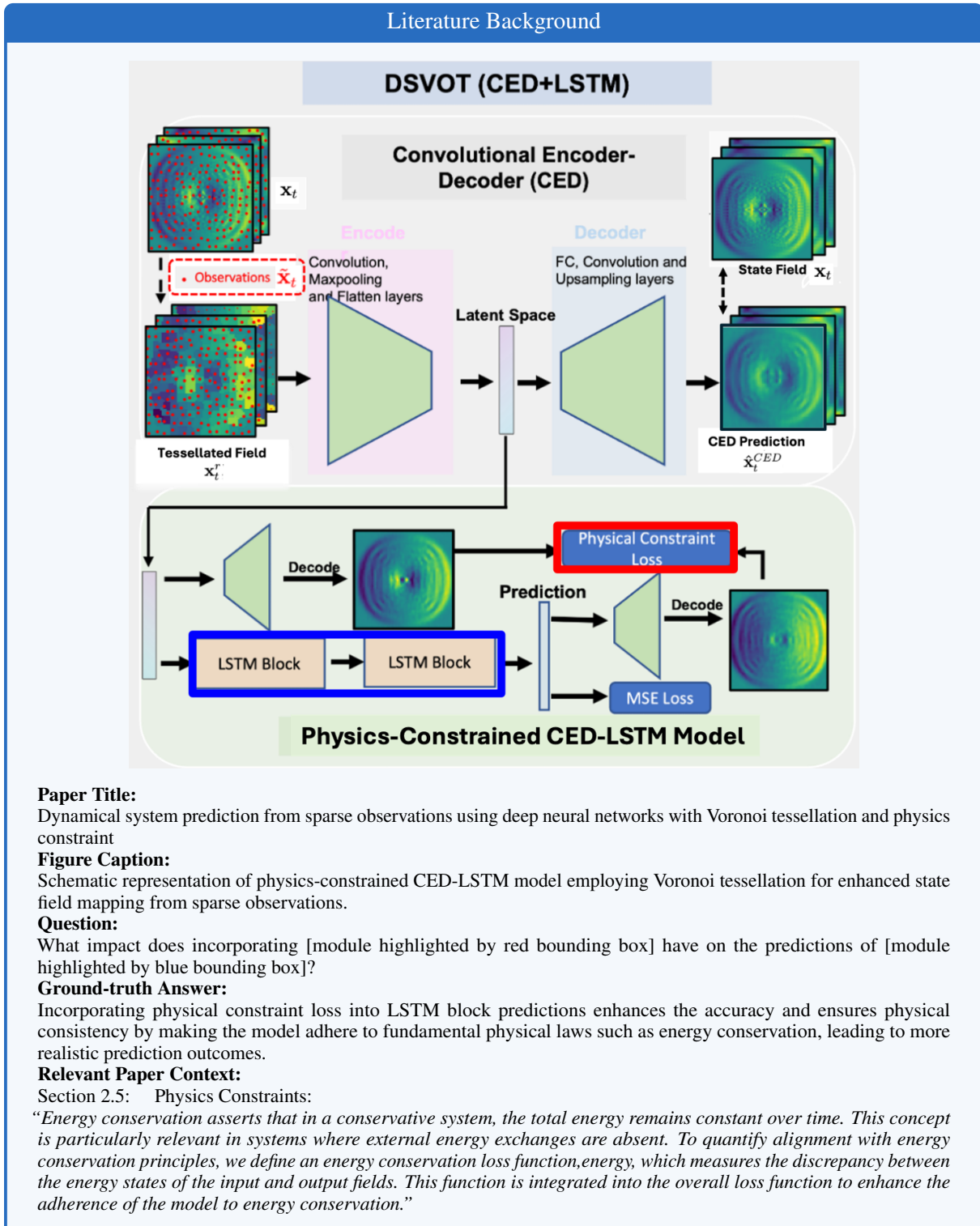
Qwen2-VL-72B:

The module highlighted by the red bounding box, which is the Recursive Token Merging block, interacts with the module highlighted by the blue bounding box, which is the Self Attention block, to enhance video consistency. The Recursive Token Merging block merges tokens from adjacent timesteps, while the Self Attention block attends to the merged tokens to ensure that the information from different timesteps is consistent. This interaction helps to maintain the temporal coherence of the video frames.

Error Analysis:

Qwen2-VL-72B’s response oversimplifies the interaction between Recursive Token Merging (ReToMe) and the Self Attention module. While it correctly identifies their roles, it fails to emphasize how ReToMe recursively merges similar tokens across frames, ensuring temporal consistency and internal feature uniformity. This process mitigates per-frame inconsistencies in adversarial training, preserving structural coherence. The response lacks depth in explaining how ReToMe enhances adversarial effectiveness and video consistency beyond simple token merging.

C.3 Reasoning error



Qwen2-VL-72B:

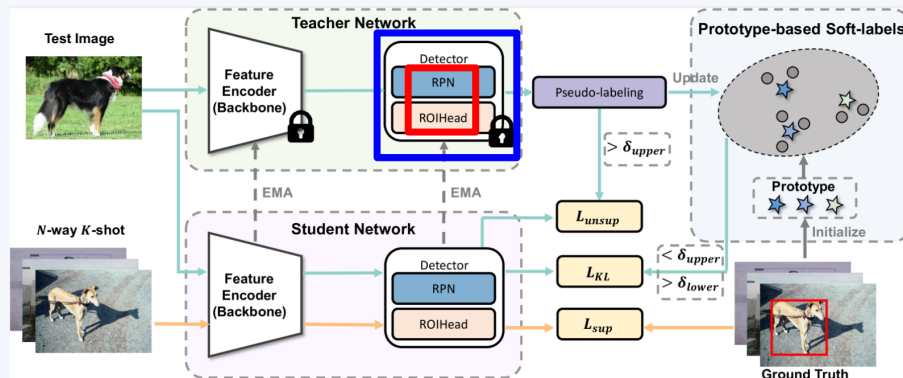
Incorporating the physical constraint loss has a regularization effect on the predictions of the LSTM block. This is because the physical constraint loss ensures that the predictions made by the LSTM block are consistent with the underlying physics of the system being modeled.

Error Analysis:

Qwen2-VL-72B's response lacks depth in its reasoning by overly simplifying the role of physical constraint loss as mere regularization. It fails to acknowledge the iterative parameter update mechanism and how it enhances adaptability in dynamic systems. Additionally, the explanation does not address the fundamental issue of data drift and evolving task complexities, which are critical in ensuring long-term model robustness and accuracy.

C.4 Overconfident response to unanswerable questions

Implementation Details



Paper Title:

PS-TTL: Prototype-based Soft-labels and Test-Time Learning for Few-shot Object Detection

Figure Caption:

The overview of the proposed Prototype-based Soft-labels and Test-Time Learning (PS-TTL) framework for FSOD. Both the student and teacher networks are first initialized by the few-shot detector and then fine-tuned on test data. The teacher network takes test data as input to generate pseudo-labels, while the student model is trained using these pseudo-labels after post-processing with N-way K-shot data as supervision signals and updates the teacher network through EMA. A Prototype-based Soft-labels (PS) strategy is adopted to maintain class prototypes and compute the feature similarity between low-confidence pseudo-labels and class prototypes to replace them with soft-labels.

Question:

What are the specific functions of the [module highlighted by red bounding box] in the [module highlighted by blue bounding box]?

Ground-truth Answer:

The question is unanswerable.

Relevant Paper Context:

Section 2.2 Few-shot Object Detection:

“Similarly, Meta R-CNN combines a two-stage detector and reweights RoI features in the detection head. Attention-RPN exploits matching relationship between the few-shot support set and query set with a contrastive training scheme, which can then be applied to detect novel objects without retraining and fine-tuning.”

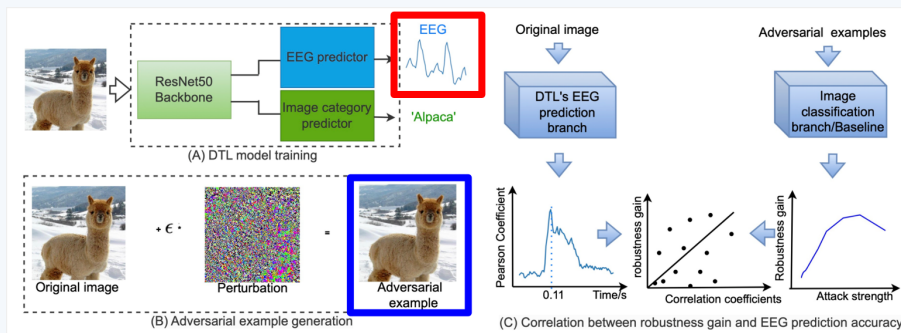
Qwen2-VL-72B:

The module highlighted by the red bounding box includes the RPN and the ROIHead, which are components of the module highlighted by the blue bounding box, the Detector. The ROIHead is responsible for generating region proposals, while the RPN is responsible for classifying and regressing the proposals.

Error Analysis:

Qwen2-vl-72B’s response is problematic because the question is explicitly unanswerable, as confirmed by the official answer. The model incorrectly generates a detailed explanation by hallucinating the roles of modules (e.g., RPN and ROIHead) without any supporting information.

Literature Background



Paper Title:

Limited but consistent gains in adversarial robustness by co-training object recognition models with human EEG

Figure Caption:

Paradigm for improving adversarial robustness via co-training with human EEG: We first trained dual-task learning (DTL) models with original and shuffled EEG data and then evaluated their robustness against various adversarial attacks. We trained four clusters of ResNet50 backbone models, each incorporating a different independent EEG predictor: Dense Layers (CNN), Recurrent Neural Networks (RNN), Transformer, and Attention layers. Finally, we measured the relationship between adversarial robustness gain and EEG prediction accuracy.

Question:

How are [module highlighted by red bounding box] and [module highlighted by blue bounding box] integrated into the model training process?

Ground-truth Answer:

The question is unanswerable.

Relevant Paper Context:

Section 3.4 Adversarial robustness evaluation and Robustness gain:

“Adversarial perturbations are image transformations capable of fooling ANNs while remaining imperceptible for humans. To assess the adversarial robustness of our models, we employed Foolbox to create adversarial versions of the 1654 original validation images under different attack strengths.”

Qwen2-VL-72B:

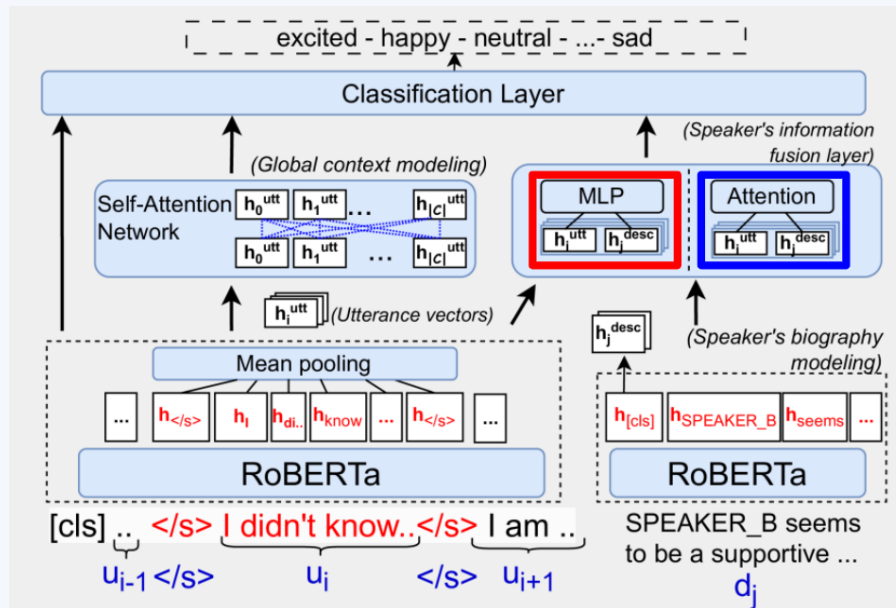
The EEG predictor and the image category predictor are integrated into the model training process by being connected to the ResNet50 backbone. The EEG predictor takes the output of the ResNet50 backbone and predicts the EEG signal, while the image category predictor takes the same output and predicts the image category.

Error Analysis:

Qwen’s answer is inaccurate because the question is explicitly marked as unanswerable, meaning the paper does not provide enough information to address it. Instead of acknowledging this, Qwen generates an unfounded explanation, incorrectly stating how the EEG predictor and image category predictor are integrated into the model training process. This response lacks support from the paper’s content and contradicts the provided ground-truth answer.

C.5 Overreliance on visual elements

Literature Background



Paper Title:

PS-TTL: Prototype-based Soft-labels and Test-Time Learning for Few-shot Object Detection

Figure Caption:

Overview of our BiosERC model architecture.

Question:

How are [module highlighted by red bounding box] and [module highlighted by blue bounding box] utilized to process utterance and description embeddings?

Ground-truth Answer:

In BiosERC, a multi-layer perceptron (MLP) network injects personality information of speakers into their corresponding utterances, creating a unified speaker vector representation. The attention mechanism dynamically incorporates speaker information into each utterance, modeling the relationship between the utterance and all speakers in a conversation to enrich the utterance vector representation.

Relevant Paper Context:

Section 3.4 BERT-based BiosERC architecture:

"This architecture is designed with a straightforward target that injects the personality information of each speaker into their corresponding utterances by a multi-layer perceptron network. Through this mechanism, all the utterances from the same speaker are shared in the unified speaker vector representation, while the weights are updated in the training process. Finally, the utterance vector is fused with the speaker vector which supports emotional classification. We consider a variant of our BiosERC model, which is engineered to dynamically incorporate the speaker's information into each utterance via the attention mechanism. The relationship between the current utterance and all individual speakers is integrated to enrich the utterance vector representation."

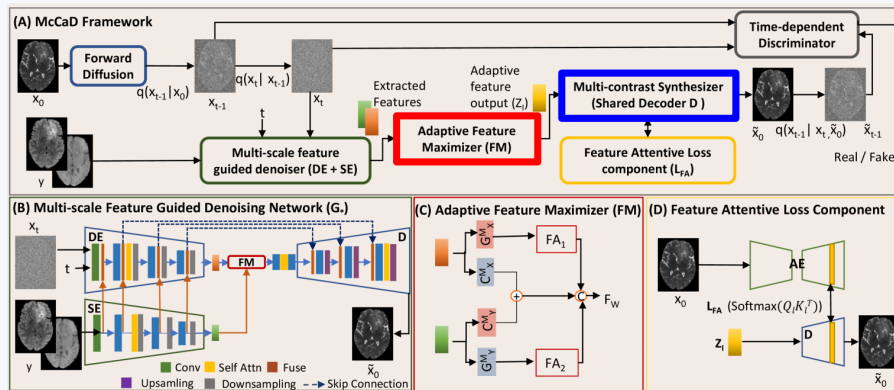
Qwen2-VL-72B:

The module highlighted by the red bounding box (MLP) is used to process utterance embeddings, while the module highlighted by the blue bounding box (Attention) is used to process description embeddings.

Error Analysis:

Qwen2's answer misses the core question by failing to explain how the modules process embeddings. It simply states their functions without addressing the mechanisms or their interplay, showing a lack of deeper question understanding.

Implementation Details



Paper Title:

McCaD: Multi-Contrast MRI Conditioned, Adaptive Adversarial Diffusion Model for High-Fidelity MRI Synthesis

Figure Caption:

Network architecture of McCaD. A: Overall Architecture, B: Multi-scale Feature Guided Denoising Network to incorporate feature characteristics from conditional MRI contrasts at various stages to guide the reverse diffusion process, C: Adaptive Feature Maximizer, to weights more pertinent features within the latent space D: Feature Attentive Loss to improve the perceptual quality of the synthetic results.

Question:

What role does [module highlighted by red bounding box] play in [module highlighted by blue bounding box]?

Ground-truth Answer:

The adaptive feature maximizer unifies feature distributions by utilizing encoded features from the Semantic Encoder and Diffusive Encoder, which undergo separate local and global feature extraction processes. It assigns weights based on feature relevance to facilitate the selection of mutually adaptive and effective shared representations, ultimately leading to more precise denoised target contrast.

Relevant Paper Context:

Section 3.4 BERT-based BiosERC architecture:

“Nevertheless, while multi-stage guidance proves beneficial in extracting valuable information from features at various levels, it is more challenging to maximize the mutual information between the conditional contrasts and the target MR contrast distributions. This is mainly due to intricate dependencies between multi-contrast imaging and finding more common and mutually adaptive feature representation. To overcome this challenge, we propose an adaptive feature maximize (FM) within the denoising network, unifying feature distributions as shown in Fig. 1(C).

The distinction between local and global feature contrasts derived from the denoising and conditional feature distributions aids in adaptively assigning weights to more pertinent features. This adaptive weighting facilitates the selection of mutually dependent and highly effective shared representations within the latent distribution. Consequently, these representations can be leveraged to achieve more precise denoised target contrast.”

Qwen2-VL-72B:

The red box highlights the "Adaptive Feature Maximizer (FM)" module, and the blue box highlights the "Multi-contrast Synthesizer (Shared Decoder D)" module. The Adaptive Feature Maximizer (FM) plays a crucial role in guiding the Multi-contrast Synthesizer.

Error Analysis:

Qwen's response overly relies on visual elements by merely identifying the red and blue boxes without explaining the functional relationship between FM and the synthesizer. It lacks a deeper technical interpretation of FM's role in unifying feature distributions and guiding the synthesizer, failing to integrate the ground-truth context effectively. A stronger response should focus on the adaptive weighting mechanism and its impact on contrast precision rather than just referencing colors.