

MUSCLE: A Model Update Strategy for Compatible LLM Evolution

Jessica Echterhoff* Fartash Faghri Raviteja Vemulapalli
UC San Diego Apple Apple

Ting-Yao Hu Chun-Liang Li Oncel Tuzel Hadi Pouransari*
Apple Apple Apple Apple

Abstract

Large Language Models (LLMs) are regularly updated to enhance performance, typically through changes in data or architecture. Within the update process, developers often prioritize improving overall performance metrics, paying less attention to maintaining compatibility with earlier model versions. Instance-level degradation (*instance regression*) of performance from one model version to the next can interfere with a user’s mental model (Bansal et al., 2019) of the capabilities of a particular language model. Users having to adapt their mental model with every update can lead to dissatisfaction, especially when the new model has degraded compared to a prior version for a known use case (*model update regression*). We find that when pretrained LLM base models are updated, fine-tuned user-facing downstream task adapters experience negative flips – previously correct instances are now predicted incorrectly. We observe model update regression between different model versions on a diverse set of tasks and models, even when the downstream task training procedures remain identical. We argue for the importance of maintaining *model update compatibility* during updates, and present evaluation metrics designed specifically for generative tasks, while also being applicable to discriminative tasks. We propose a training strategy to minimize the extent of instance regression in model updates, involving training of a compatibility adapter that can enhance task fine-tuned language models. We show negative flips reduce by up to 40% e.g. when updating Llama 1 to Llama 2 with our proposed method.

1 Introduction

Large Language Models (LLMs) are often pre-trained on large-scale corpora to obtain a base model with general world knowledge. These base

* Research conducted during an internship at Apple. Corresponding authors: jechterh@ucsd.edu, mpouransari@apple.com

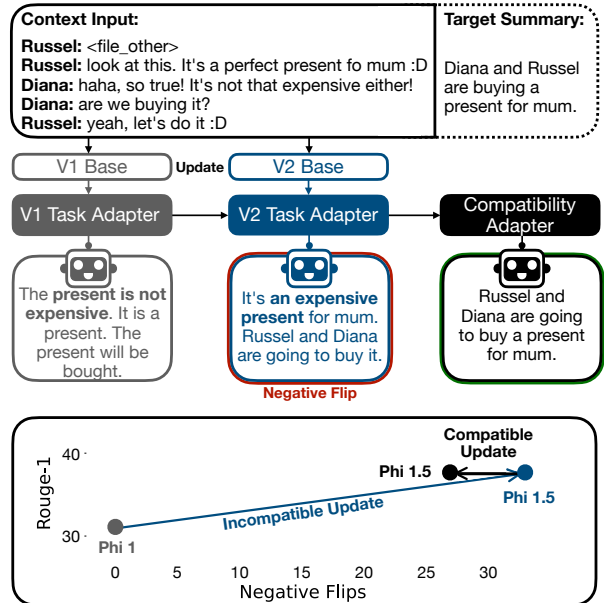


Figure 1: A real example of a model update that introduces instance regression (negative flip, where a previously correct prediction becomes incorrect) (top). With our model update strategy using a compatibility adapter approach, we enhance model update compatibility to the previous model while maintaining the overall performance gain (e.g. measured by the ROUGE-1 score for the summarization task) of the model update (bottom).

models are typically evaluated using a suite of benchmarks that mostly focus on zero/few-shot performance and in-context learning capabilities. Training these models is expensive, and only a few organizations have access to the resources needed. Hence, to enable various user-facing applications such as summarization, chatbots, code assistants, and question-answering, practitioners often adapt pre-trained base models by training task-specific parameter-efficient adapters using downstream task datasets.

Several scenarios drive updates to the base model, e.g. improved training strategy, advances in LLM architectures or increasing model context

length (Touvron et al., 2023a), the availability of additional or higher quality datasets (Gunasekar et al., 2023), the expansion of model vocabulary (e.g., to support multilingual or multimodal models), or simply training for a longer period (Biderman et al., 2023).

When a base model is updated, all associated task adapters need to be retrained/updated to have meaningful downstream models. Hence, in the rest of the paper, we use the term *model update* to refer to an update to a downstream task model, which includes updating the base model and retraining the task adapter. When a model is updated, we evaluate *model update compatibility* with different metrics by four quadrants shown in Fig. 2. The new model could produce a worse prediction (negative flip (quadrant 4)) for many samples (Yan et al., 2021) even when it has a better overall performance when compared to the previous model. A real example of instance regression measured as a negative flip is shown in Fig. 1 for a dialogue summarization task. This kind of regression can confuse the user and impair their satisfaction (Sakai, 2022). We denote the aggregated overall regression for all individual instances as *model update regression* (Table 1). Regression testing has become increasingly important for the evolving use of LLMs accessed via APIs (Ma et al., 2023). When updating models, practitioners typically focus on increasing positive flips (quadrant 2) while avoiding negative flips (quadrant 4) (Cai et al., 2022; Sakai, 2022; Yan et al., 2021; Li et al., 2023b; Schumann et al., 2023). However, they neglect prediction inconsistencies in the scenarios where both model versions are incorrect (quadrant 3) or already correct, but slightly different (quadrant 1). For example, Träuble et al. (2021) assumes the cost of flips from one incorrect class to another incorrect class to be zero. We argue that there is value in evaluating consistency when both models are wrong. A user may have developed coping strategies on how to interact with a model when it is incorrect; therefore, inconsistencies in mistakes can lead to user dissatisfaction.

Previous works have mainly addressed the model update regression challenge for classification tasks (Cai et al., 2022; Sakai, 2022; Yan et al., 2021; Li et al., 2023b; Schumann et al., 2023). In this work, we systematically study the problem of model update compatibility using discriminative and generative downstream tasks and different base models.

	Version 2 ✓	Version 2 ✗
Version 1 ✓	Aligned with GT Similar Answers?	Negative Flips/ Regression
Version 1 ✗	Positive Flips/ Gain	Not Aligned with GT Similar Answers?

Figure 2: Four possibilities arise for each sample when a model is updated. Quadrants 2 and 4 show positive and negative flips, respectively. Quadrant 3 corresponds to instances where both models are incorrect. Encouraging similarity between the old and new models in this case (i.e., making the same mistakes) results in a more seamless model update from the user’s perspective.

Following is a summary of our contributions:

- We formulate the compatibility problem when updating LLMs. We focus on common setups where base LLMs undergo updates and evaluate model compatibility and performance via parameter-efficient, task-specific fine-tuning, as these models are deployed for user interaction.
- We extend the notion of model compatibility from discriminative to generative tasks, and propose compatibility metrics that consider similarities in model behavior after an update, going beyond the negative flip rate metric.
- We investigate model compatibility for different update scenarios using open-weight models and find significant model update regression across various tasks.
- We propose learning a compatibility adapter to align model versions and minimize model update regression. We demonstrate up to 40% reduction in negative flip rate (e.g. for Llama 1 to Llama 2 update in language understanding) and reduced model inconsistency for downstream tasks such as summarization, math reasoning, and commonsense question-answering.

2 Related Work

2.1 Measuring Model Update Regression

Classification Yan et al. (2021) introduce negative flip rate (NFR) to evaluate model compatibility for classification tasks. NFR calculates the fraction of instances that were previously correct but

Instance Regression	An instance i is predicted correctly by an old model \mathcal{M}_{v1} , but incorrectly by a new model \mathcal{M}_{v2} .
Model Update Regression	Aggregation of all instances correctly predicted by an old model \mathcal{M}_{v1} , but incorrectly by an updated model version \mathcal{M}_{v2} .
Model Update Compatibility	Measures the degree to which predictions made by an updated model \mathcal{M}_{v2} remain consistent with the predictions of the previous model version \mathcal{M}_{v1} , specifically on instances where \mathcal{M}_{v1} was correct. Quantifies the alignment or compatibility between model versions across updates.

Table 1: Definitions of Instance Regression, Model Update Regression, and Model Update Compatibility.

are now incorrect with the new model. A similar statistic (Sakai, 2022), backward trust compatibility (BTC) (Srivastava et al., 2020), measures the ratio of instances that the new model predicts correctly among all instances the old model predicts correctly. Matsuno and Sakuma (2023) propose backward compatibility with a conditional distribution, which computes the ratio at which the accuracy of the conditional distribution of the new model is equal to or higher than that of the old model. Cai et al. (2022) introduce the negative flip impact for graph NLP tasks, taking into account the negative flips and the overall error rate of the model. These aforementioned metrics are limited to the evaluation of discriminative classification tasks.

2.2 Reducing Model Update Regression

Model Ensembles Prior work found that model ensembles reduce model update regression. This can be attributed to the reduction of variance by ensembling, as every single model may capture the training data from a distinct aspect (Yan et al., 2021; Xie et al., 2021). Extensions on this line of work include choosing the most centric model from an ensemble (Xie et al., 2021), aligning two models’ uncertainties (Li et al., 2023b), or using gating mechanisms (Lai et al., 2023). Previous work has also used model parts from an old model to infuse into the new one (Ran et al., 2023), with the limitation of both models being required at inference time. For limited use cases, Qin et al. (2023) have shown to re-use previously learned adapters when purely a data update was performed. All these methods either introduce a larger memory footprint by re-using old model parts or are limited to (same-domain) data-updates and same models.

Knowledge Distillation Originally proposed for model compression (Buciluă et al., 2006), a (smaller) student model is trained to mimic a (larger) teacher model. By treating the old model as the teacher and the new model as the student, knowledge distillation has been shown to reduce

model update regression in vision and language discriminative tasks (Yan et al., 2021; Xie et al., 2021; Schumann et al., 2023; Jaekle et al., 2023; Zhang et al., 2021; Shen et al., 2020; Ramanujan et al., 2022). Shen et al. (2020) propose a distillation-based influence loss to align new model representations with those of the old model. Similarly, Ramanujan et al. (2022); Jaekle et al. (2023) apply distillation after a learned transformation module. Schumann et al. (2023) propose weight interpolation between the old and the new model, Zhao et al. (2022) suggest matching old and new model distributions, Yan et al. (2021) distill from an ensemble, and Caciolai et al. (2023) recommend using focal distillation. However, none of these approaches evaluate their approaches on generative tasks or they require both the old and new models to be in memory at inference time.

3 Problem Formulation

While existing methods provide valuable approaches to mitigating model update regression, they predominantly focus on discriminative classification tasks and often require additional memory at inference time. We propose a flexible approach to updating models without sacrificing performance or compatibility across downstream tasks.

Setup We follow the common setup of finetuning a pre-trained base LLM to multiple downstream tasks with task-specific LoRA adapters (Hu et al., 2021). Let $\mathcal{M}_i^{\text{base}}$ denote the i^{th} version of a base LLM with parameters θ_i . We adapt $\mathcal{M}_i^{\text{base}}$ to a downstream task \mathcal{T} using an adapter $\mathcal{A}_i^{\mathcal{T}}$ to obtain a downstream model $\mathcal{M}_i^{\mathcal{T}}$ with weights $\theta_i^{\mathcal{T}} = \theta_i + \Delta_i^{\mathcal{T}}$, where $\Delta_i^{\mathcal{T}}$ denotes the weights of the task-specific adapter $\mathcal{A}_i^{\mathcal{T}}$ learned using the training data corresponding to task \mathcal{T} . When the base model is updated from $\mathcal{M}_{v1}^{\text{base}}$ to $\mathcal{M}_{v2}^{\text{base}}$, the task-specific adapters are re-trained for each downstream task. Hereafter, for simplicity of notation, we use \mathcal{M}_{v1} and \mathcal{M}_{v2} to refer to the task-adapted models $\mathcal{M}_{v1}^{\mathcal{T}}$ and $\mathcal{M}_{v2}^{\mathcal{T}}$, respectively, and explicitly mention the task \mathcal{T} when needed.

3.1 Backward Compatibility Metrics

A backward compatibility metric outputs a compatibility score based on two models, \mathcal{M}_{v1} to \mathcal{M}_{v2} . Yan et al. (2021) propose negative flip rate (NFR) to measure regression in classification models over a dataset $\{x_i, y_i\}_{i=1}^N$, where y_i is the ground truth class for input x_i for a particular task \mathcal{T} :

$$\text{NF}(x_i) \triangleq [\mathcal{M}_{v1}(x_i) = y_i] \wedge [\mathcal{M}_{v2}(x_i) \neq y_i]$$

$$\text{NFR} \triangleq \frac{1}{N} \sum_i^N \mathbf{1}[\text{NF}(x_i)]$$

Here $\mathbf{1}$ denotes the indicator function. This notion of regression is partly applicable to autoregressively trained tasks. LLM benchmarks (Gao et al., 2023) calculate the likelihood of every possible choice in a multiple-choice question and choose the response with the highest likelihood to calculate a *likelihood based accuracy*. This evaluation can indicate model update regression similar to classification for tasks when multiple choices are available (Zellers et al., 2019; Wang et al., 2019; Welbl et al., 2017).

Unobserved Inconsistencies Other inconsistencies arise when the old model predicts class A, the new model class B, and the ground truth is class C. Similarly, if there are multiple ground truth options, a flip could occur within the ground truth options, as in quadrant 1 in Fig. 2. These inconsistencies are not captured by positive or negative flips. We argue that if we cannot produce a better prediction, we should at least stay consistent with the user’s expectations and propose extended negative flips metrics for this use case.

Continuous Metrics In generative tasks for language models, we do not necessarily have multiple choices for which we can predict if an instance regressed or not. Hence a metric incorporating multiple choices and then calculating negative flips is not applicable for continuous evaluation metrics. Typical continuous metrics in generative language tasks are ROUGE (Lin, 2004) or BERT (Zhang et al., 2019) scores. As regular negative flips are incapable of capturing these nuances, we require a new metric to evaluate compatibility for generative tasks like summarization.

3.2 Extended Evaluation Metrics

We propose a suite of metrics that evaluate model update compatibility on a fine-grained basis specifically for generative tasks (e.g summarization).

Accounting for Flips when Both Models are Incorrect

To capture inconsistencies for instances where both old and new models are incorrect, we adapt the negative flip rate as follows when multiple choice options are available:

$$\text{NF}_{mc}(x_i) \triangleq [\mathcal{M}_{v2}(x_i) \neq y_i] \wedge [\mathcal{M}_{v1}(x_i) \neq \mathcal{M}_{v2}(x_i)]$$

$$\text{NFR}_{mc} \triangleq \frac{1}{N} \sum_i^N \mathbf{1}[\text{NF}_{mc}(x_i)]$$

This includes the possibility that neither of the models gives the correct answer, but a change in behavior occurs that can confuse a user. Similarly, for multi-label tasks, this notion can account for ground-truths that may have flipped during a model update when multiple ground truth options exist.

Smooth Compatibility Metrics To add continuous metrics for generative tasks, we evaluate the *expected* model update regression. Our general framework aims to be independent of the actual similarity metric, such that it can be chosen in accordance with any respective task of interest. For example, translation tasks might require BLEU (Papineni et al., 2002), but summarization ROUGE (Lin, 2004) evaluation. Additionally, we want to measure a notion of *performance gain*, when both models are correct, but one might still be better than the other.

Given a similarity metric S , and model outputs $\mathcal{M}_{v1}(x_i)$ and $\mathcal{M}_{v2}(x_i)$ for an input x_i , the difference for a model update for a particular test instance i is

$$D(x_i) \triangleq S(\mathcal{M}_{v2}(x_i), y_i) - S(\mathcal{M}_{v1}(x_i), y_i)$$

acting as an indication of the distance between the two model outputs with respect to the grand truth. This per instance indication of distance enables us to classify which model update compatibility quadrant an instance falls into. In practice, similarity metrics could be BERT Score (Zhang et al., 2019), ROUGE Score (Lin, 2004), BLEU Score (Papineni et al., 2002), or model-as-a-judge metrics (Huang et al., 2024) depending on the use case and task.

To get a metric for generative tasks that is similar to the positive and negative flip rate in classification tasks, we observe the distribution of instances with positive gain or negative regression:

$$\widetilde{\text{PFR}} \triangleq \frac{1}{N} \sum_i^N \mathbf{1}[D(x_i) > 0]$$

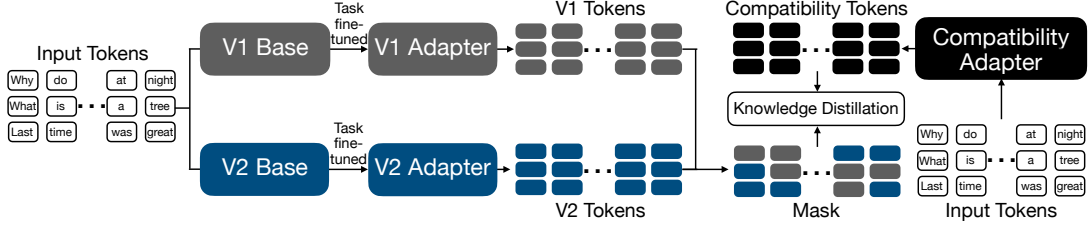


Figure 3: When updating a model, regression on individual tokens and instances can arise. We use a masked approach to select tokens to be aligned with knowledge distillation either with the old version to remain consistent or with the new task model to increase performance.

$$\widetilde{\text{NFR}} \triangleq \frac{1}{N} \sum_i^N \mathbf{1}[D(x_i) < 0]$$

To observe the magnitude of model update regression and gain, we can observe the expectation:

$$m_g \triangleq \frac{1}{N \cdot \widetilde{\text{PFR}}} \sum_i^N D(x_i) \mathbf{1}[D(x_i) > 0]$$

$$m_r \triangleq \frac{1}{N \cdot \widetilde{\text{NFR}}} \sum_i^N |D(x_i)| \mathbf{1}[D(x_i) < 0]$$

These give an indication of the average magnitude of change in a similarity metric when gain or regression occurs.

4 Knowledge Transfer

Now that we have metrics to indicate model update regression, we propose a knowledge distillation approach to minimize this regression for the task-specific models \mathcal{M}_{v_1} and \mathcal{M}_{v_2} . Typically, knowledge distillation minimizes the KL divergence between the soft targets $\sigma(z_t)$ and $\sigma(z_s)$, where z_s and z_t are logits predicted by student and teacher models, respectively.

$$\mathcal{L}_{KL} = \frac{1}{n} \sum_{i=1}^n KL(\sigma(z_{t,i}/T) \parallel \sigma(z_{s,i}/T))$$

, i denotes the i 'th token, n is the total number of tokens available for training, T is temperature parameter, and σ denotes softmax. Most knowledge distillation works consider the distillation from a trained teacher to an untrained student (Tian et al., 2022; Rajasegaran et al., 2020). Recent work (Roth et al., 2024) tackles the goal of knowledge transfer between pre-trained student and teacher models while retaining student knowledge gained a priori, and shows that standard knowledge distillation between pre-trained models struggles to transfer

knowledge without performance drops. Complementary to this work focusing on performance and maintaining prior knowledge, we tackle compatibility with prior models through knowledge transfer.

4.1 Model Update Strategy for Compatible LLM Evolution (MUSCLE)

When the base model is updated, we train a task-specific fine-tuned model, $\mathcal{M}_{v_2}^C$, that has the accuracy benefits of \mathcal{M}_{v_2} , but with most compatibility with \mathcal{M}_{v_1} . We obtain $\mathcal{M}_{v_2}^C$ by training a *compatibility adapter* applied to the base model $\mathcal{M}_{v_2}^{\text{base}}$. We use knowledge from task-specific fine-tuned models \mathcal{M}_{v_1} and \mathcal{M}_{v_2} when training $\mathcal{M}_{v_2}^C$. \mathcal{M}_{v_2} typically has increased prediction capabilities over \mathcal{M}_{v_1} (due to improvements in the base model), but \mathcal{M}_{v_1} has information on already correctly predicted tokens or instances that we want to minimize degradation towards.

We initialize the compatibility adapter with the task-specific adapter of \mathcal{M}_{v_2} , and further fine-tune it (using the task training dataset) by aligning the next token prediction to either \mathcal{M}_{v_1} or \mathcal{M}_{v_2} . We define masking (for individual tokens of a training sequence) following a simple heuristic depending on whether $\mathcal{M}_{v_2}^C$ (the adapter being trained) predicts the correct tokens or not. If it does, we align to \mathcal{M}_{v_2} logits, otherwise, we align to \mathcal{M}_{v_1} . The fine-tuning process of $\mathcal{M}_{v_2}^C$ is depicted in Fig. 3. The fine-tuning loss to train the compatibility adapter, \mathcal{L}_{comp}^m , is defined below:

$$\begin{aligned} m_i &= \mathbf{1}[\text{argmax } \sigma(z_{\mathcal{M}_{v_2}^C,i}) \neq y_i] \\ a_{\mathcal{M}_{v_1}} &= KL(\sigma(z_{\mathcal{M}_{v_1},i}/T) \parallel \sigma(z_{\mathcal{M}_{v_2}^C,i}/T)) \\ a_{\mathcal{M}_{v_2}} &= KL(\sigma(z_{\mathcal{M}_{v_2},i}/T) \parallel \sigma(z_{\mathcal{M}_{v_2}^C,i}/T)) \\ \mathcal{L}_{comp}^m &= \frac{1}{n} \sum_{i=1}^n m_i \cdot a_{\mathcal{M}_{v_1}} + (1 - m_i) \cdot a_{\mathcal{M}_{v_2}} \end{aligned} \quad (1)$$

$\mathcal{M}_{v1}^{\text{base}}$	$\mathcal{M}_{v2}^{\text{base}}$	Update
Phi 1	Phi 1.5	Synthetic data, data selection (Gunasekar et al., 2023; Li et al., 2023a)
Phi 1.5	Phi 2	Synthetic data, data selection, \uparrow parameters (Javaheripi et al., 2023)
Llama 1	Llama 2	More data, \uparrow context size (Touvron et al., 2023a,b)
Vicuna 1.3	Vicuna 1.5	Llama 1 \rightarrow Llama 2, Instruction fine-tuning (Zheng et al., 2024)

Table 2: We select a suite of models with varying update scenarios and parameter sizes and evaluate them on different LLM benchmark tasks. We select Llama and Vicuna models with 7B parameters.

Dataset	Task	Metric
HellaSwag	Language Understanding (Multiple-Choice)	Log-Likelihood Accuracy
	Commonsense Reasoning (Binary-Choice)	Log-Likelihood Accuracy
GSM8k	Grade School Math (Exact Match)	Exact Match Accuracy
SAMsum	Dialogue Summarization	ROUGE-1

Table 3: We tackle compatible model updates for different downstream tasks and datasets, including multiple-choice and generative tasks (Zellers et al., 2019; Bisk et al., 2019; Cobbe et al., 2021; Gliwa et al., 2019).

When evaluating, we denote NFR as negative flip rate between \mathcal{M}_{v1} \mathcal{M}_{v2} , NFR_c as the observed negative flip rate between \mathcal{M}_{v1} and our compatibility model \mathcal{M}_{v2}^C , and $\Delta\text{NFR}_c = \text{NFR}_c - \text{NFR}$.

5 Experimental Setup

5.1 Model Update Assumptions

To analyze the impact of model updates we consider parameter-efficient fine-tuned models using Low-Rank Adapters (LoRA) (Hu et al., 2021). Compared to previous work on continuous learning and model updates (Qin et al., 2022, 2023), we do not limit model updates to be produced by only data updates, but consider different kinds of updates shown in Table 2. We include updates due to data, increased parameters, or different training strategies. We include a wide range of downstream tasks to evaluate model compatibility, including *generative tasks* as summarized in Table 2. For all tasks, we learn the LoRA adapter autoregressively (next-token prediction).

5.2 Task Adapter Training

For each task and each old model \mathcal{M}_{v1} and new model \mathcal{M}_{v2} , we train a LoRA adapter on all linear layers with $r = 128$ and $\alpha = 256$. We use a 0.8/0.2 training/validation split for 10 epochs. We choose the model by cross-entropy validation loss. More information on hyperparameters is shown in Table 8.

5.3 Compatibility Adapter Training

We keep all hyper-parameters the same for task adapter training, and train compatibility adapter with the \mathcal{L}_{comp}^m loss defined in Eq. (1). We analyze the statistical significance of the results on a subset of compatibility adapter training for Phi 1 to Phi 1.5 updates on PIQA using 3 random seeds. We observe a standard deviation of accuracy of 0.0012.

We compare \mathcal{L}_{comp}^m with different masking strategies m in the ablation studies in Section 6.5, but find that the version introduced in Section 4.1 works best for most model updates. For model updates with large performance gaps between \mathcal{M}_{v1} and \mathcal{M}_{v2} we find that an auxiliary cross-entropy loss enhances the stability of training for PIQA and SAMSum from Phi 1 to Phi 1.5, and all Phi updates in GSM8k and Hellaswag (more in Appendix A.4).

5.4 Similarity Metrics

We evaluate multiple-choice tasks with classification-like approaches by choosing the maximum log-likelihood of the possible answers (Gao et al., 2023). For math tasks, we use exact-match accuracy of the final calculated result. For summarization, we cannot evaluate in a classification-like manner. We use ROUGE-1 (Lin, 2004), given that we do not observe relative ranking differences for different ROUGE-n.

6 Results

6.1 Negative Flips Occur in Model Updates

Fig. 4 shows that significant negative flips (up to more than 60%) exist for a variety of base model update scenarios and downstream tasks. We observe negative flips in updates within one model family (e.g. Llama/Vicuna, and Phi models). We find more negative flips for model updates with a smaller delta in performance gain. For generative tasks like SAMsum dialogue summarization, we observe a large number of negative flips as continuous metrics are more sensitive to small changes when updated.

	$\mathcal{M}_{v1}^{\text{base}}$	$\mathcal{M}_{v2}^{\text{base}}$	$\text{acc}_{\mathcal{M}_{v1}}$	$\text{acc}_{\mathcal{M}_{v2}}$	acc_c	$\Delta\text{acc}_c \uparrow$	NFR	$\Delta\text{NFR}_c \downarrow$	$\Delta\% \text{NFR}_c \downarrow$
HellaSwag	Llama 1	Llama 2	72.74	72.91	79.53	6.62	10.27	-4.17	-40.60
	Phi 1.5	Phi 2	69.76	78.02	77.86	-0.16	3.09	0.24	7.77
	Phi 1	Phi 1.5	32.38	69.76	69.86	0.10	2.47	-0.13	-5.26
	Vicuna 1.3	Vicuna 1.5	72.19	71.54	78.10	6.56	10.48	-4.06	-38.74
PIQA	Llama 1	Llama 2	74.86	74.76	79.27	4.51	11.59	-3.97	-34.25
	Phi 1.5	Phi 2	74.65	78.78	78.94	0.16	6.20	-0.11	-1.77
	Phi 1	Phi 1.5	59.03	74.65	74.70	0.05	7.78	-0.05	-0.64
	Vicuna 1.3	Vicuna 1.5	74.70	75.52	78.89	3.37	9.90	-2.88	-29.09

Table 4: Compatible task adapter trained with MUSCLE (corresponding to metrics with suffix c) reduces negative flip rate on the test sets of multiple-choice language tasks. We see most improvements for model updates that have small performance differences.

$\mathcal{M}_{v1}^{\text{base}}$	$\mathcal{M}_{v2}^{\text{base}}$	$\text{EM}_{\mathcal{M}_{v1}}$	$\text{EM}_{\mathcal{M}_{v2}}$	EM_c	$\Delta\text{EM}_c \uparrow$	NFR	$\Delta\text{NFR}_c \downarrow$	$\Delta\% \text{NFR}_c \downarrow$
Llama 1	Llama 2	24.45	33.09	36.66	3.57	8.49	-0.91	-10.72
Phi 1.5	Phi 2	30.02	48.18	50.68	2.50	5.88	-1.71	-29.08
Phi 1	Phi 1.5	3.41	30.02	26.99	-3.03	2.01	-0.04	-1.99
Vicuna 1.3	Vicuna 1.5	26.72	29.91	31.84	1.93	11.60	-0.99	-8.53

Table 5: GSM8K math evaluation with exact match (EM) over the test dataset. For compatibility adapter (corresponding to metrics with suffix c), we observe a decreased negative flip rate while mostly maintaining performance gains.

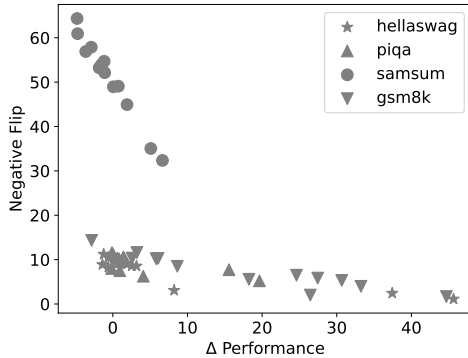


Figure 4: When updating LLM models (e.g. Llama 1 \rightarrow Llama 2), we observe negative flips in different tasks. The smaller the performance gap from an old model to a new model, the more negative flips we observe. We indicate the performance gap by the difference in exact match for GSM8K, Rouge-1 for SAMSUM, and log-likelihood-based accuracy for PIQA and HellaSwag. When evaluating continuous metrics with absolute ROUGE-1 value for summarization on SAMSUM, we observe a large fraction of negative flips. We show the exact models analyzed in Table 9.

6.2 Reduced Negative Flips in Classification

In Table 4, we observe that MUSCLE decreases negative flips when compared to regular model updates without compatibility-specific training (\mathcal{M}_{v2}). Specifically, we see a reduction of NFR by 40% for the update of Llama 1 to Llama 2 and 39% for Vicuna 1.3 to Vicuna 1.5. For updates with

a large performance gap (for example Phi 1 to Phi 1.5), we observe a less strong enhancement with a negative flip rate reduction by 1-5%. In addition to the reduction of negative flips, we also observe an increased accuracy of up to 7% for Llama and Vicuna updates.

In exact match (EM) evaluation, we match the final result of the math question from the prediction to ground truth. Results are shown in Table 5. In this case, we observe that we can reduce the number of negative flips by 29% for Phi 1.5 to Phi 2. When the version 1 model is significantly less accurate (e.g., 3.4% exact-match accuracy for Phi 1), we observe a reduction in accuracy with the compatibility adapter while only being able to decrease negative flips by 2%. For all other updates, MUSCLE increases expected-match accuracy while reducing negative flips.

6.3 Increased Consistent Behavior

When we cannot achieve a positive flip (switching from an incorrect to a correct answer), we might prefer to at least maintain consistent behavior to the old model to avoid unexpected behavior for the user. We evaluate negative flips rate (NFR) and inconsistency flips rate (NFR_{mc}). For model updates that have a large performance gap and a small number of negative flips to begin with (Phi models), we see a limited reduction in inconsistency

$\mathcal{M}_{v1}^{\text{base}}$	$\mathcal{M}_{v2}^{\text{base}}$	$R1_{\mathcal{M}_{v1}}$	$R1_{\mathcal{M}_{v2}}$	$R1_c$	$\Delta R1_c \uparrow$	$\widetilde{\text{NFR}}$	$\Delta \widetilde{\text{NFR}}_c \downarrow$	$\Delta \% \widetilde{\text{NFR}}_c \downarrow$	$\Delta m_g \uparrow$	$\Delta m_r \downarrow$
Llama 1	Llama 2	32.06	32.28	34.79	2.51	48.96	-7.81	-15.95	0.64	-1.13
Phi 1.5	Phi 2	37.53	36.15	40.69	4.54	54.70	-15.02	-27.46	0.24	-3.39
Phi 1	Phi 1.5	30.92	37.53	38.76	1.23	32.60	-5.74	-17.61	-0.38	-0.59
Vicuna 1.3	Vicuna 1.5	30.32	30.88	34.08	3.20	49.69	-10.98	-22.10	-0.02	-1.85

Table 6: For summarization (SAMsum) generative task we reduce model update regression of ROUGE-1 score (R1) by up to 27%.

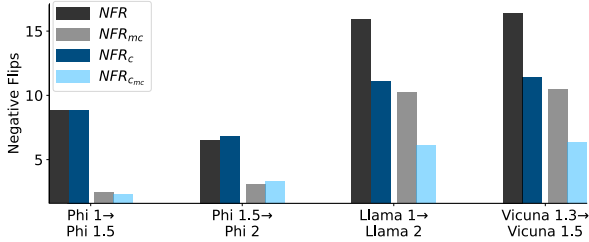


Figure 5: Comparison of NFR vs NFR_{mc} metrics to evaluate inconsistency when updating LLMs for HellaSwag task. We see that using our compatibility adapter (denoted by c), we can reduce inconsistency for Llama and Vicuna models.

flips. However, we observe that we can reduce the inconsistency flips with our method for model updates with small accuracy gaps such as the updates for Llama and Vicuna (Fig. 5) on the HellaSwag dataset.

6.4 Reduced Model Update Regression in Generative Tasks

When evaluating generative tasks, we can reduce model update regression of ROUGE-1 score performance (Table 6). We can reduce negative flips by 18% for updates with weaker version 1 models (Phi 1 \rightarrow Phi 1.5) and 22% for smaller model updates (Vicuna 1.3 \rightarrow Vicuna 1.5) and 27% for Phi 1.5 \rightarrow Phi 2. We see that we decrease ROUGE-1 model update regression by 1-3%, while maintaining gain.

6.5 The Effect of Different Masking Strategies

We analyze different training and masking strategies to evaluate our design choices. On the PIQA dataset and model update Llama 1 \rightarrow Llama 2, we compare MUSCLE with different masking strategies. Intuitively, instance or token-wise likelihood-based masking strategies can be useful for tasks that are evaluated with log-likelihoods (e.g. PIQA, HellaSwag) where multiple choices are available. We compare likelihood-based masking for example on individual tokens,

$$m_i = LL_L = \mathbf{1}[\sigma(z_{\mathcal{M}_{v2}^C, i}) < \sigma(z_{\mathcal{M}_{v1}, i})] \quad (2)$$

	ΔNFR_c	$\Delta \% \text{NFR}_c$	ΔPFR_c	Δacc_c
$\mathcal{L}_{comp}^{\mathcal{M}_{v2}^C \neq y}$	-3.97	-34.25	0.54	4.51
$\mathcal{L}_{comp}^{\mathcal{M}_{v1} = y}$	-2.29	-19.76	-0.60	1.68
$a_{\mathcal{M}_{v1}}$	-2.99	-25.80	-0.82	2.17
$\text{CE} + \mathcal{L}_{comp}^{\mathcal{M}_{v2}^C \neq y}$	-3.10	-26.75	0.38	3.48
$\text{CE} + \mathcal{L}_{comp}^{LL}$	-2.12	-18.29	-0.49	1.63
$\text{CE} + \mathcal{L}_{comp}^{LL_S}$	-1.96	-16.91	0.05	2.01

Table 7: A model update from Llama 1 \rightarrow Llama 2 on PIQA. Different ablations and masking strategies and their impact on negative flips, positive flips, and accuracy improvement.

to check if the likelihood of the ground-truth next token in the current model is smaller than the old model. Only in this case, we align to \mathcal{M}_{v1} , and align to \mathcal{M}_{v2} for every other token. Alternatively, we can also compare the likelihood of the entire sequence

$$m_i = LL_S = \mathbf{1}\left[\sum_i [\sigma(z_{\mathcal{M}_{v2}^C, i}) < \sigma(z_{\mathcal{M}_{v1}, i})]\right] \quad (3)$$

such that we mask all tokens per sequence to get instance-wise masking. For both of these strategies, we see a reduction in negative flips. We note that likelihood-based masking requires auxiliary cross-entropy loss for stability (A.4). Aligning to the old model only if it is already correct with a mask $\mathcal{L}_{comp}^{\mathcal{M}_{v1} = y}$ with $m_i = \mathbf{1}[\sigma(z_{\mathcal{M}_{v1}, i}) = y_i]$ or without masking with KL ($a_{\mathcal{M}_{v1}}$) leads to a small reduction in negative flips. Our approach that aligns to the old model if the current prediction is incorrect ($\mathcal{L}_{comp}^{\mathcal{M}_{v2}^C \neq y}$), leads to the best reduction in negative flips while providing the biggest accuracy gain and increased positive flips (Table 7). This strategy has the additional advantage that it takes into account extended inconsistent flips explained in Fig. 5, as it aligns to \mathcal{M}_{v1} whenever \mathcal{M}_{v2} is incorrect. For this best-performing strategy, we see that including cross-entropy loss ($\text{CE} + \mathcal{L}_{comp}^{\mathcal{M}_{v2}^C \neq y}$) does not lead to additional performance gains.

6.6 Behavior for Different Model Pairs

A general point in the analysis of negative flips is its connection with accuracy: if accuracy is 100%, the NFR must be 0%. This means that compatible model updates become harder when updating $\mathcal{M}_{v1} \rightarrow \mathcal{M}_{v2}$ with lower \mathcal{M}_{v2} accuracy. We report observed compatibility when using vanilla adapter learning, and show a reduction in NFR when using the proposed method (MUSCLE). When $\text{acc}(\mathcal{M}_{v2}) > \text{acc}(\mathcal{M}_{v1})$ for a task, the observed NFR is small (Fig. 4). This has been the case irrespective of the model update scenario and task. We find that MUSCLE reduces the observed NFR the most when $\text{acc}(\mathcal{M}_{v2}) \approx \text{acc}(\mathcal{M}_{v1})$. In such cases, the incompatibility between vanilla model updates is not dominated by the fact that one model version is more accurate than the other, making it an easier use case to be improved by our proposed distillation loss. With multiple frequent incremental model updates in academia and industry, this is a very relevant use case to focus on.

7 Conclusion

In this work, we study the task-specific compatibility problem when updating LLMs. We show that LLM updates with different scenarios, e.g., changes in model architecture, optimization, or training dataset, exhibit significant negative flips – instances previously classified or generated correctly, and incorrectly after the model update. We extend the negative flip metric for discriminative and, for the first time, generative tasks, and report results for various models and tasks.

We propose a novel method (MUSCLE) to train task-specific compatibility adapters when updating an old LLM to a new LLM to reduce negative flips while maintaining performance gain. Our proposed method does not require a modification to the base model training and is only based on adapter training. Further, as opposed to previous works, the proposed solution does not require both versions of the model in memory to enable compatibility, which is often infeasible due to the large size of LLMs.

We observe a mitigation of negative flips of 40% for multiple-choice type evaluations, and 27% for continuous summarization evaluation. We also show insights into model properties that facilitate transfer, finding that our alignment masking strategy provides best results with the additional benefit of mitigating inconsistent update behavior.

8 Limitations, Risks and Future Work

We do not consider a model update that includes changes in tokenization and/or vocabulary size (e.g. Llama 2 (Touvron et al., 2023b) to Llama 3 (AI@Meta, 2024)). Future work can explore compatible vocabulary mapping strategies before learning from prior model versions.

Tackling Large Performance Gaps When there is a large performance gap between M_{v1} and M_{v2} , loss hyperparameter weighting could be an interesting avenue to explore. We unsuccessfully experimented with simple weighting based on average accuracy. We hypothesize that instance-based loss weighting could be a more promising approach to tackle this model update case. As this would require intensive experimentation, we leave this as an avenue for future work. In general, the utility of aligning to prior model versions is limited by the performance of the prior model version. For example, see the update from Phi 1 to Phi 1.5 in Table 5, where Phi 1 only has an accuracy of 3%. In this case, it is arguable if an alignment to \mathcal{M}_{v1} is desired and if the strive for compatibility outweighs a possible performance drop.

MUSCLE Performance Improvements In our work, we observe an interesting overall performance improvement following knowledge transfer, which is an intriguing finding regarding the possibilities of this line of work. Previous works on model compatibility using distillation-like losses have also observed such a phenomenon (e.g., (Jaekle et al., 2023)). Given that we initialize the compatibility adapter with M_{v2} (an independently trained task adapter) and continue fine-tuning it with knowledge transfer loss from M_{v1} , one can argue that the observed performance improvement demonstrates an ensemble knowledge effect (i.e., knowledge from both M_{v2} and M_{v1} is aggregated into our compatibility adapter).

Ethical Considerations and Risks One potential risk of the proposed approach for compatible task-specific LLM updates is the transfer of potential biases from the old model, \mathcal{M}_{v1} , to the new model trained through knowledge transfer. We did not explore this aspect in the current study.

9 Acknowledgements

We would like to thank Rick Chang, Cheng-Yu Hsieh and Yen-Ju Lu for their help with the paper.

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A Appendix

A.1 Training Hyperparameters and Evaluation

We show an overview of the design choices of our LoRA adapter for task and compatibility training in Table 8. We learn about the entire context and answer tokens during fine-tuning. We find that successfully training the compatibility adapter generally requires a larger LoRA rank. Task adapters can be trained with lower rank, but also experience performance boost with higher rank. We use the training splits of the respective datasets where we use 80% of the training set as training data, and 20% as validation data for selecting the best model based on validation loss. We evaluate for selection after each epoch. All compatibility adapter models are initialized with the previously trained task adapter models for version 2 model. KL divergence temperature is set to 2. We use deepspeed for optimization (Rasley et al., 2020). For benchmark eval-

Hyperparameter	Value
Epochs	10
Learning Rate	1e-4
Grad. acc. steps	8
LoRA α	256
LoRA rank	128
Dropout	0.0
Adapter Layers	All linear
Warmup Steps	500
Weight decay	0.0

Table 8: Hyperparameters for the training setup of the task and compatibility adapters.

uation, we use LM evaluation harness (Gao et al., 2023), where most of the benchmarks (GSM8k, HellaSwag, PIQA) are already defined, and we use them as-is. We add an evaluation for SAMsum summarization evaluating ROUGE-1 score with a no-repeat N-gram size of 2, and generation stop words of “Dialogue:”, “Summary:” (which are the keywords for the context and answer behavior), “</s>” and double new lines. All of our tasks are based on the English language.

A.2 Training Cost

All Experiments were run on NVIDIA A100 and H100 GPUs with an overall compute budget of 720x8 GPUh. Assuming hourly rates of 2.5\$, this would amount to 14,400\$. Compared to regular parameter-efficient fine-tuning, our compatibility method requires both model versions in GPU memory during training, hence fewer data batches can be processed per time step. However, as the compatibility adapters are initialized with the task adapters, we can view it as a continued training. There are no differences for inference time and costs compared to regular parameter-efficiently fine-tuned LoRa adapters.

A.3 Model Update Evaluation

In the evaluation of model update regression for different model updates (Fig. 4), we consider the model pairs shown in Table 9.

A.4 Auxiliary Cross-Entropy Loss

For model updates with large performance gaps between \mathcal{M}_{v1} and \mathcal{M}_{v2} , we find that an auxiliary cross-entropy loss enhances the stability of training. When the performance of \mathcal{M}_{v1} is greatly inferior to \mathcal{M}_{v2} , we assume that the inferior \mathcal{M}_{v1} introduces errors that steer the model away too much from the ground truth. We can account for this by adding the cross-entropy loss to align with the ground truth.

$\mathcal{M}_{v1}^{\text{base}}$	$\mathcal{M}_{v2}^{\text{base}}$
Phi 1	Phi 1.5
Phi 1	Phi 2
Phi 1.5	Phi 2
Vicuna 1.3	Vicuna 1.5
Llama 1	Llama 2
Llama 1	Vicuna 1.5
Llama 1	Vicuna 1.3
Vicuna 1.3	Llama 2
Llama 2	Vicuna 1.5
Llama 2	Llama 3
Llama 1	Llama 3
Vicuna 1.3	Llama 3
Vicuna 1.5	Llama 3

Table 9: Model pairs used to analyse model update regression.

Dataset	Train	Test
HellaSwag (Zellers et al., 2019)	40k	10k
PIQA (Bisk et al., 2019)	16k	3k
GSM8k (Cobbe et al., 2021)	7.5k	1.3k
SAMsum (Gliwa et al., 2019)	14.7k	819

Table 10: Dataset size for our experiments.

Using Eq. (1), we add a \mathcal{L}_{CE} for training (scaled with hyperparameter λ).

$$\mathcal{L}_{CE} = -\frac{1}{N} \sum_{i=1}^N \sum_{k=1}^K y_{i,k} \log(\sigma(z_{\mathcal{M}_{v2}^C, i, k})) \quad (4)$$

$$\mathcal{L} = \lambda \mathcal{L}_{comp}^m + (1 - \lambda) \mathcal{L}_{CE} \quad (5)$$

We find that likelihood-based masking (Section 6.5) also requires auxiliary cross-entropy loss for stability. Even though one model version might provide a higher likelihood than the other, this likelihood does not necessarily mean a suitable probability distribution over the vocabulary, hence adding alignment to the ground truth helps to provide better results.

A.5 Downstream Tasks

We describe the datasets used in our experiments. Each dataset poses unique challenges and targets different aspects of language understanding and reasoning. Dataset sizes are shown in Table 10.

GSM8K The Grade School Math 8K (GSM8K) dataset is designed to evaluate mathematical reasoning capabilities. It consists of grade school-level math word problems. These problems require the application of mathematical concepts and the ability to reason about quantities and operations in a textual format. The dataset is structured to test the performance of models on arithmetic, algebra, geometry, and statistics problems, reflecting

a wide range of mathematical knowledge in education. We use this dataset as a representative case to test problem-solving cases. We evaluate model update regression in this task with exact match, which is a strict evaluation on a fraction of produced tokens, but does not account for the reasoning process.

SAMSum The SAMSum dataset consists of dialogue summaries designed to facilitate the evaluation of automatic conversational summarization models. It contains dialogue instances, paired with human-written summaries. These conversations mimic real-life scenarios to enable learning to generate coherent and concise summaries. We use this dataset as a representative case to test language generation behavior. We evaluate model update regression in this task with ROUGE-1.

HellaSwag HellaSWAG is a dataset for assessing common sense reasoning and predictive text modeling. It builds on the SWAG (Zellers et al., 2018) dataset by providing more challenging distractors. HellaSWAG consists of multiple-choice scenarios where a model must predict the most plausible continuation among four options, focusing on everyday activities, scenarios, and interactions. We use this dataset as a representative case to test abilities that require not just linguistic understanding but also real-world knowledge and common sense reasoning. We evaluate model update regression in this task with log-likelihoods for the correct answer, as multiple choices are given.

PIQA The Physical Interaction Question Answering (PIQA) dataset tests the understanding of physical and causal interactions in the real world through textual descriptions. It contains scenarios that require reasoning about physical properties, actions, and outcomes. Each scenario is presented as a question with two possible solutions, where the model must choose the most physically plausible one. We use this dataset as a representative case for evaluating models on tasks that require an understanding of the physical world and its governing principles. We evaluate model update regression in this task with log-likelihoods for the correct answer, as different choices are given.