

Practical Correlated Topic Modeling and Analysis via the Rectified Anchor Word Algorithm (Supplementary Material)

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A Implementation

For reproducibility, we provide pseudocode for algorithms integrated in different parts of JSMF.

A.1 Rectification

Algorithm 1 Alternating Projection

def RECTIFY-C_AP(\mathbf{C}, K)

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1:  $\mathbf{C}_{\mathcal{NN}} \leftarrow \mathbf{C}$ 
2: repeat
3:    $(\mathbf{U}, \Lambda_K) = \text{TRUNCATED-EIG}(\mathbf{C}_{\mathcal{NN}}, K)$ 
4:    $\Lambda_K^+ \leftarrow \text{diag}(\max\{\text{diag}(\Lambda_K), 0\})$ 
5:    $\mathbf{C}_{\mathcal{PSD}} \leftarrow \mathbf{U} \Lambda_K^+ \mathbf{U}^T$ 
6:    $\mathbf{C}_{\mathcal{NOR}} \leftarrow \mathbf{C}_{\mathcal{PSD}} + \frac{1 - \sum_{i,j} \mathbf{C}_{\mathcal{PSD}}(i,j)}{N^2} \mathbf{1}\mathbf{1}^T$ 
7:    $\mathbf{C}_{\mathcal{NN}} \leftarrow \max\{\mathbf{C}_{\mathcal{NOR}}, 0\}$ 
8: until the convergence of  $\mathbf{C}_{\mathcal{NN}}$ 
9: return  $\mathbf{C} \leftarrow \mathbf{C}_{\mathcal{NN}} / (\sum_{i,j} \mathbf{C}_{\mathcal{NN}}(i,j))$ 

```

$\text{diag}(\cdot)$ is the Matlab-style operation that maps the input vector into the diagonal matrix or extracts the diagonal vector from the input matrix.

Algorithm 2 Cyclic Douglas-Rachford Iteration

def RECTIFY-C_DR(\mathbf{C}, K)

```

1:  $\mathbf{C}_3 \leftarrow \mathbf{C}$ 
2: repeat
3:    $\mathbf{C}_1 \leftarrow \frac{\mathbf{I} + \mathbf{R}_{\mathcal{NOR}} \mathbf{R}_{\mathcal{PSD}}}{2} \mathbf{C}_3$ 
4:    $\mathbf{C}_2 \leftarrow \frac{\mathbf{I} + \mathbf{R}_{\mathcal{NN}} \mathbf{R}_{\mathcal{NOR}}}{2} \mathbf{C}_1$ 
5:    $\mathbf{C}_3 \leftarrow \frac{\mathbf{I} + \mathbf{R}_{\mathcal{PSD}} \mathbf{R}_{\mathcal{NN}}}{2} \mathbf{C}_2$ 
6: until the convergence of  $\mathbf{C}_3$ 
7: return  $\mathbf{C} \leftarrow \mathbf{C}_3 / (\sum_{i,j} \mathbf{C}_3(i,j))$ 

```

\mathbf{I} is the identity mapping, $\mathbf{R}_{\mathcal{NOR}} \mathbf{R}_{\mathcal{PSD}}$ denotes the composition of two reflection operators: the matrix is first reflected onto the \mathcal{PSD} space, then onto the \mathcal{NOR} space. $\mathbf{R}_{\mathcal{PSD}} \mathbf{C} = 2\mathbf{C}_{\mathcal{PSD}} - \mathbf{C}$, and similarly for \mathcal{NOR} and \mathcal{NN} .

A.2 Topic Inference

Algorithm 3 Sparse Implicit Column-pivoted QR

def FIND-S($\bar{\mathbf{C}}, K$)

```

1:  $(\mathbf{P}, \mathbf{Q}, \mathbf{S}, \mathbf{r}) \leftarrow (\bar{\mathbf{C}}^T, \mathbf{0}^{N \times K}, \emptyset, \mathbf{0}^K)$ 
2:  $\mathbf{u} \leftarrow (\|\mathbf{p}_1\|_2^2, \dots, \|\mathbf{p}_N\|_2^2) \in \mathbb{R}^{1 \times N}$ 
3: for  $k = 1$  to  $K$  do
4:    $n \leftarrow \text{argmax}_{1 \leq i \leq N} u_i$ 
5:    $(\mathbf{S}, \mathbf{q}_k, r_k) \leftarrow (\mathbf{S} \cup \{n\}, \mathbf{p}_n, \sqrt{u_n})$ 
6:    $\mathbf{q}_k \leftarrow (\mathbf{q}_k - \sum_{l=1}^{k-1} \langle \mathbf{q}_l, \mathbf{p}_n \rangle \mathbf{q}_l) / r_k$ 
7:    $\mathbf{u} \leftarrow \mathbf{u} - (\mathbf{q}_k^T \mathbf{P}) \circ (\mathbf{q}_k^T \mathbf{P})$ 
8: end for
9: return  $(\mathbf{S}, \mathbf{r})$ 

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$\circ : \mathbb{R}^N \times \mathbb{R}^N \rightarrow \mathbb{R}^N$ denotes entry-wise multiplication of two vectors.

Algorithm 4 ADMM

def RECOVER-B($\bar{\mathbf{C}}, \mathbf{c}, \mathbf{S}, \lambda, \gamma$)

```

1:  $(\mathbf{U}, \check{\mathbf{B}}, \mathbf{B}) \leftarrow ((\bar{\mathbf{C}}_{S*})^T, \mathbf{0}^{K \times N}, \mathbf{0}^{N \times K})$ 
2:  $\check{\mathbf{B}}_{*S} \leftarrow \mathbf{I}_K$  ( $\mathbf{I}_K = K \times K$  identity matrix)
3:  $\mathbf{F} \leftarrow (\gamma \mathbf{U}^T \mathbf{U} + \mathbf{I}_K)^{-1}$ 
4: for each  $i \in \{1, \dots, N\} \setminus S$  (in parallel) do
5:    $(\mathbf{v}, \mathbf{f}) \leftarrow ((\bar{\mathbf{C}}_{i*})^T, \gamma \mathbf{U}^T \mathbf{v})$ 
6:    $\mathbf{y}^{(0)} \leftarrow \Pi_{\Delta^{K-1}}((\mathbf{U}^T \mathbf{U})^{-1}(\mathbf{f}/\gamma))$ 
7:    $\mathbf{q}^{(0)} \leftarrow \mathbf{y}^{(0)}$ 
8:   repeat
9:      $\mathbf{p}^{(t)} \leftarrow \mathbf{F}(2\mathbf{y}^{(t-1)} - \mathbf{q}^{(t-1)} + \mathbf{f})$ 
10:     $\mathbf{q}^{(t)} \leftarrow \mathbf{q}^{(t-1)} + \lambda(\mathbf{p}^{(t)} - \mathbf{y}^{(t-1)})$ 
11:     $\mathbf{y}^{(t)} \leftarrow \Pi_{\Delta^{K-1}}(\mathbf{q}^{(t)})$ 
12:   until the convergence of  $\mathbf{y}^{(t)}$ 
13:    $\check{\mathbf{B}}_{*i} \leftarrow \mathbf{y}^{(t)}$ 
14: end for
15: for  $(i, k) \in \{1, \dots, N\} \times \{1, \dots, K\}$  do
16:    $B_{ik} \leftarrow (\check{\mathbf{B}}_{ki} \mathbf{c}_i) / (\sum_{i'=1}^N \check{\mathbf{B}}_{ki} \mathbf{c}_{i'})$ 
17: end for
18: return  $\mathbf{B}$ 

```

$\Pi_{\Delta^{K-1}}(\cdot)$ is the orthogonal projection to the $K-1$ simplex.

Algorithm 5 Diagonal Recovery

def RECOVER-A(C, B, S)1: $(C_{SS}, D) \leftarrow (C(S, S), B(S, *))$ 2: $A \leftarrow D^{-1}C_{SS}D^{-1}$ 3: **return** A

Set indexing extracts a principle submatrix whose rows and columns correspond to the arguments. Since $B(S, *)$ is diagonal, we use the element-wise reciprocal of D as D^{-1} .
