AMR Dependency Parsing with a Typed Semantic Algebra

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Abstract

We present a semantic parser for Abstract Meaning Representations which learns to parse strings into tree representations of the compositional structure of an AMR graph. This allows us to use standard neural techniques for supertagging and dependency tree parsing, constrained by a linguistically principled type system. We present two approximative decoding algorithms, which achieve state-of-the-art accuracy and outperform strong baselines.

1 Introduction

Over the past few years, Abstract Meaning Representations (AMRs, Banarescu et al. (2013)) have become a popular target representation for semantic parsing. AMRs are graphs which describe the predicate-argument structure of a sentence. Because they are graphs and not trees, they can capture reentrant semantic relations, such as those induced by control verbs and coordination. However, it is technically much more challenging to parse a string into a graph than into a tree. For instance, grammar-based approaches (Peng et al., 2015; Artzi et al., 2015) require the induction of a grammar from the training corpus, which is hard because graphs can be decomposed into smaller pieces in far more ways than trees. Neural sequence-to-sequence models, which do very well on string-to-tree parsing (Vinyals et al., 2014), can be applied to AMRs but face the challenge that graphs cannot easily be represented as sequences (van Noord and Bos, 2017a,b).

In this paper, we tackle this challenge by making the compositional structure of the AMR explicit. As in our previous work, Groschwitz et al. (2017), we view an AMR as consisting of atomic graphs representing the meanings of the individual words, which were combined compositionally using linguistically motivated operations for combining a head with its arguments and modifiers. We represent this structure as terms over the *AM algebra* as defined in Groschwitz et al. (2017). This previous work had no parser; here we show that the terms of the AM algebra can be viewed as dependency trees over the string, and we train a dependency parser to map strings into such trees, which we then evaluate into AMRs in a postprocessing step. The dependency parser relies on type information, which encodes the semantic valencies of the atomic graphs, to guide its decisions.

More specifically, we combine a neural supertagger for identifying the elementary graphs for the individual words with a neural dependency model along the lines of Kiperwasser and Goldberg (2016) for identifying the operations of the algebra. One key challenge is that the resulting term of the AM algebra must be semantically well-typed. This makes the decoding problem NP-complete. We present two approximation algorithms: one which takes the unlabeled dependency tree as given, and one which assumes that all dependencies are projective. We evaluate on two data sets, achieving state-of-the-art results on one and near state-of-theart results on the other (Smatch f-scores of 71.0 and 70.2 respectively). Our approach clearly outperforms strong but non-compositional baselines.

Plan of the paper. After reviewing related work in Section 2, we explain the AM algebra in Section 3 and extend it to a dependency view in Section 4. We explain model training in Section 5 and decoding in Section 6. Section 7 evaluates a number of variants of our system.

2 Related Work

Recently, AMR parsing has generated considerable research activity, due to the availability of large-

scale annotated data (Banarescu et al., 2013) and two successful SemEval Challenges (May, 2016; May and Priyadarshi, 2017).

Methods from dependency parsing have been shown to be very successful for AMR parsing. For instance, the JAMR parser (Flanigan et al., 2014, 2016) distinguishes concept identification (assigning graph fragments to words) from relation identification (adding graph edges which connect these fragments), and solves the former with a supertagging-style method and the latter with a graph-based dependency parser. Foland and Martin (2017) use a variant of this method based on an intricate neural model, yielding state-of-the-art results. We go beyond these approaches by explicitly modeling the compositional structure of the AMR, which allows the dependency parser to combine AMRs for the words using a small set of universal operations, guided by the types of these AMRs.

Other recent methods directly implement a dependency parser for AMRs, e.g. the transitionbased model of Damonte et al. (2017), or postprocess the output of a dependency parser by adding missing edges (Du et al., 2014; Wang et al., 2015). In contrast to these, our model makes no strong assumptions on the dependency parsing algorithm that is used; here we choose that of Kiperwasser and Goldberg (2016).

The commitment of our parser to derive AMRs compositionally mirrors that of grammar-based AMR parsers (Artzi et al., 2015; Peng et al., 2015). In particular, there are parallels between the types we use in the AM algebra and CCG categories (see Section 3 for details). As a neural system, our parser struggles less with coverage issues than these, and avoids the complex grammar induction process these models require.

More generally, our use of semantic types to restrict our parser is reminiscent of Kwiatkowski et al. (2010), Krishnamurthy et al. (2017) and Zhang et al. (2017), and the idea of deriving semantic representations from dependency trees is also present in Reddy et al. (2017).

3 The AM algebra

A core idea of this paper is to parse a string into a graph by instead parsing a string into a dependencystyle tree representation of the graph's compositional structure, represented as terms of the *Apply-Modify* (*AM*) algebra (Groschwitz et al., 2017).

The values of the AM algebra are annotated s-



Figure 1: Elementary as-graphs G_{want} , G_{writer} , G_{sleep} , and G_{sound} for the words "want", "writer", "sleep", and "soundly" respectively.

graphs, or as-graphs: directed graphs with node and edge labels in which certain nodes have been designated as sources (Courcelle and Engelfriet, 2012) and annotated with type information. Some examples of as-graphs are shown in Fig. 1. Each as-graph has exactly one root, indicated by the bold outline. The sources are indicated by red labels; for instance, G_{want} has an S-source and an O-source. The annotations, written in square brackets behind the red source names, will be explained below. We use these sources to mark open argument slots; for example, G_{sleep} in Fig. 1 represents an intransitive verb, missing its subject, which will be added at the S-source.

The AM algebra can combine as-graphs with each other using two linguistically motivated operations: apply and modify. Apply (APP) adds an argument to a predicate. For example, we can add a subject – the graph G_{writer} in Fig. 1 – to the graph $G_{\rm VP}$ in Fig. 2d using APP_s, yielding the complete AMR in Fig. 2b. Linguistically, this is like filling the subject (s) slot of the predicate wants to sleep soundly with the argument the writer. In general, for a source a, $APP_a(G_P, G_A)$, combines the asgraph G_P representing a predicate, or head, with the as-graph G_A , which represents an argument. It does this by plugging the root node of G_A into the *a*-source u of G_P – that is, the node u of G_P marked with source a. The root of the resulting as-graph G is the root of G_P , and we remove the a marking on u, since that slot is now filled.

The modify operation (MOD) adds a modifier to a graph. For example, we can combine two elementary graphs from Fig. 1 with MOD_m (G_{sleep} , G_{sound}), yielding the graph in Fig. 2c. The Msource of the modifier $G_{soundly}$ attaches to the root of G_{sleep} . The root of the result is the same as the root of G_{sleep} in the same sense that a verb phrase with an adverb modifier is still a verb phrase. In general, $MOD_a(G_H, G_M)$, combines a head G_H with a modifier G_M . It plugs the root of G_H into the *a*-source *u* of G_M . Although this may add incoming edges to the root of G_H , that node is still the root of the resulting graph G. We remove the a marking from G_M .

In both APP and MOD, if there is any other source b which is present in both graphs, the nodes marked with b are unified with each other. For example, when G_{want} is 0-applied to t_1 in Fig. 2d, the s-sources of the graphs for "want" and "sleep soundly" are unified into a single node, creating a reentrancy. This falls out of the definition of *merge* for s-graphs which formally underlies both operations (see (Courcelle and Engelfriet, 2012)).

Finally, the AM algebra uses types to restrict its operations. Here we define the *type* of an as-graph as the set of its sources with their annotations¹; thus for example, in Fig. 1, the graph for "writer" has the empty type [], G_{sleep} has type [s], and G_{want} has type [S, O[S]]. Each source in an as-graph specifies with its annotation the type of the as-graph which is plugged into it via APP. In other words, for a source a, we may only a-apply G_P with G_A if the annotation of the *a*-source in G_P matches the type of G_A . For example, the O-source of G_{wants} (Fig. 1) requires that we plug in an as-graph of type [s]; observe that this means that the reentrancy in Fig. 2b is lexically specified by the control verb "want". All other source nodes in Fig. 1 have no annotation, indicating a type requirement of [].

Linguistically, modification is optional; we therefore want the modified graph to be derivationally just like the unmodified graph, in that exactly the same operations can apply to it. In a typed algebra, this means MOD should not change the type of the head. MOD_a therefore requires that the modifier G_M have no sources not already present in the head G_H , except a, which will be deleted anyway.

As in any algebra, we can build *terms* from constants (denoting elementary as-graphs) by recursively combining them with the operations of the AM algebra. By evaluating the operations bottomup, we obtain an as-graph as the value of such a term; see Fig. 2 for an example. However, as discussed above, an operation in the term may be undefined due to a type mismatch. We call an AMterm *well-typed* if all its operations are defined. Every well-typed AM-term evaluates to an as-graph. Since the applicability of an AM operation depends only on the types, we also write $\tau = f(\tau_1, \tau_2)$ if as-graphs of type τ_1 and τ_2 can be combined with the operation f and the result has type τ . **Relationship to CCG.** There is close relationship between the types of the AM algebra and the categories of CCG. A type [S, O] specifies that the as-graph needs to be applied to two arguments to be semantically complete, similar a CCG category such as $S\NP/NP$, where a string needs to be applied to two NP arguments to be syntactically complete. However, AM types govern the combination of *graphs*, while CCG categories control the combination of strings. This relieves AM types of the need to talk about word order; there are no "forward" or "backward" slashes in AM types, and a smaller set of operations. Also, the AM algebra spells out raising and control phenomena more explicitly in the types.

4 Indexed AM terms

In this paper, we connect AM terms to the input string w for which we want to produce a graph. We do this in an *indexed AM term*, exemplified in Fig. 3a. We assume that every elementary as-graph G at a leaf represents the meaning of an individual word token w_i in w, and write G[i] to annotate the leaf G with the index i of this token. This induces a connection between the nodes of the AMR and the tokens of the string, in that the label of each node was contributed by the elementary as-graph of exactly one token.

We define the *head index* of a subtree t to be the index of the token which contributed the root of the as-graph to which t evaluates. For a leaf with annotation i, the head index is i; for an APP or MOD node, the head index is the head index of the left child, i.e. of the head argument. We annotate each APP and MOD operation with the head index of the left and right subtree.

4.1 AM dependency trees

We can represent indexed AM terms more compactly as AM dependency trees, as shown in Fig. 3b. The nodes of such a dependency tree are the tokens of w. We draw an edge with label f from i to k if there is a node with label f[i, k] in the indexed AM term. For example, the tree in 3b has an edge labeled MOD_m from 5 (G_{sleep}) to 6 ($G_{soundly}$) because there is a node in the term in 3a labeled MOD_m[5, 6]. The same AM dependency tree may represent multiple indexed AM terms, because the order of apply and modify operations is not specified in the dependency tree. However, it can be shown that all well-typed AM terms that map to

¹See (Groschwitz et al., 2017) for a more formally complete definition.



Figure 2: (a) An AM-term with its value (b), along with the values for its subexpressions (c) $t_1 = MOD_m(G_{sleep}, G_{sound})$ and (d) $t_2 = APP_o(G_{want}, t_1)$.



Figure 3: (a) An indexed AM term and (b) an AM dependency tree, linking the term in Fig. 2;a to the sentence "The writer wants to sleep soundly".

the same AM dependency tree evaluate to the same as-graph. We define a *well-typed* AM dependency tree as one that represents a well-typed AM term.

Because not all words in the sentence contribute to the AMR, we include a mechanism for ignoring words in the input. As a special case, we allow the constant \perp , which represents a dummy as-graph (of type \perp) which we use as the semantic value of words without a semantic value in the AMR. We furthermore allow the edge label IGNORE in an AM dependency tree, where IGNORE $(\tau_1, \tau_2) = \tau_1$ if $\tau_2 = \bot$ and is undefined otherwise; in particular, an AM dependency tree with IGNORE edges is only well-typed if all IGNORE edges point into \perp nodes. We keep all other operations $f(\tau_1, \tau_2)$ as is, i.e. they are undefined if either τ_1 or τ_2 is \perp , and never yield \perp as a result. When reconstructing an AM term from the AM dependency tree, we skip IGNORE edges, such that the subtree below them will not contribute to the overall AMR.

4.2 Converting AMRs to AM terms

In order to train a model that parses sentences into AM dependency trees, we need to convert an AMR corpus – in which sentences are annotated with AMRs – into a treebank of AM dependency trees. We do this in three steps: first, we break each AMR up into elementary graphs and identify their roots; second, we assign sources and annotations to make elementary as-graphs out of them; and third, combine them into indexed AM terms.

For the first step, an aligner uses hand-written heuristics to identify the string token to which each

node in the AMR corresponds (see Section C in the Supplementary Materials for details). We proceed in a similar fashion as the JAMR aligner (Flanigan et al., 2014), i.e. by starting from high-confidence token-node pairs and then extending them until the whole AMR is covered. Unlike the JAMR aligner, our heuristics ensure that exactly one node in each elementary graph is marked as the root, i.e. as the node where other graphs can attach their edges through APP and MOD. When an edge connects nodes of two different elementary graphs, we use the "blob decomposition" algorithm of Groschwitz et al. (2017) to decide to which elementary graph it belongs. For the example AMR in Fig. 2b, we would obtain the graphs in Fig. 1 (without source annotations). Note that ARG edges belong with the nodes at which they start, whereas the "manner" edge in G_{soundly} goes with its target.

In the second step we assign source names and annotations to the unlabeled nodes of each elementary graph. Note that the annotations are crucial to our system's ability to generate graphs with reentrancies. We mostly follow the algorithm of Groschwitz et al. (2017), which determines necessary annotations based on the structure of the given graph. The algorithm chooses each source name depending on the incoming edge label. For instance, the two leaves of G_{want} can have the source labels s and o because they have incoming edges labeled ARG0 and ARG1. However, the Groschwitz algorithm is not deterministic: It allows object promotion (the sources for an ARG3 edge may be 03, 02, or O), unaccusative subjects (promoting the minimal object to s if the elementary graph contains an ARGi-edge (i > 0) but no ARG0-edge (Perlmutter, 1978)), and passive alternation (swapping O and S). To make our as-graphs more consistent, we prefer constants that promote objects as far as possible, use unaccusative subjects, and no passive alternation, but still allow constants that do not satisfy these conditions if necessary. This increased our Smatch score significantly.

Finally, we choose an arbitrary AM dependency

tree that combines the chosen elementary as-graphs into the annotated AMR; in practice, the differences between the trees seem to be negligible.²

5 Training

We can now model the AMR parsing task as the problem of computing the best well-typed AM dependency tree t for a given sentence w. Because t is well-typed, it can be decoded into an (indexed) AM term and thence evaluated to an as-graph.

We describe t in terms of the elementary asgraphs G[i] it uses for each token i and of its edges f[i, k]. We assume a node-factored, edge-factored model for the *score* $\omega(t)$ of t:

$$\omega(t) = \sum_{1 \le i \le n} \omega(G[i]) + \sum_{f[i,k] \in E} \omega(f[i,k]), \quad (1)$$

where the edge weight further decomposes into the sum $\omega(f[i,k]) = \omega(i \to k) + \omega(f \mid i \to k)$ of a score $\omega(i \to k)$ for the presence of an edge from i to k and a score $\omega(f \mid i \to k)$ for this edge having label f. Our aim is to compute the well-typed t with the highest score.

We present three models for ω : one for the graph scores and two for the edge scores. All of these are based on a two-layer bidirectional LSTM, which reads inputs $\mathbf{x} = (x_1, \dots, x_n)$ token by token, concatenating the hidden states of the forward and the backward LSTMs in each layer. On the second layer, we thus obtain vector representations $v_i = \text{BiLSTM}(\mathbf{x}, i)$ for the individual input tokens (see Fig. 4). Our models differ in the inputs \mathbf{x} and the way they predict scores from the v_i .

5.1 Supertagging for elementary as-graphs

We construe the prediction of the as-graphs G[i] for each input position *i* as a supertagging task (Lewis et al., 2016). The supertagger reads inputs $x_i = (w_i, p_i, c_i)$, where w_i is the word token, p_i its POS tag, and c_i is a character-based LSTM encoding of w_i . We use pretrained GloVe embeddings (Pennington et al., 2014) concatenated with learned embeddings for w_i , and learned embeddings for p_i .

To predict the score for each elementary as-graph out of a set of K options, we add a K-dimensional output layer as follows:

$$\omega(G[i]) = \log \operatorname{softmax}(W \cdot v_i + b)$$



Figure 4: Architecture of the neural taggers.

and train the neural network using a cross-entropy loss function. This maximizes the likelihood of the elementary as-graphs in the training data.

5.2 Kiperwasser & Goldberg edge model

Predicting the edge scores amounts to a dependency parsing problem. We chose the dependency parser of Kiperwasser and Goldberg (2016), henceforth K&G, to learn them, because of its accuracy and its fit with our overall architecture. The K&G parser scores the potential edge from i to k and its label from the concatenations of v_i and v_k :

$$\begin{aligned} \mathbf{MLP}_{\theta}(v) &= W_2 \cdot \tanh(W_1 \cdot v + b_1) + b_2 \\ \omega(i \to k) &= \mathbf{MLP}_{\mathbf{E}}(v_i \circ v_k) \\ \omega(f \mid i \to k) &= \mathbf{MLP}_{\mathbf{LBL}}(v_i \circ v_k) \end{aligned}$$

We use inputs $x_i = (w_i, p_i, \tau_i)$ including the type τ_i of the supertag G[i] at position *i*, using trained embeddings for all three. At evaluation time, we use the best scoring supertag according to the model of Section 5.1. At training time, we sample from q, where $q(\tau_i) = (1 - \delta) + \delta \cdot p(\tau_i | p_i, p_{i-1})$, $q(\tau) = \delta \cdot p(\tau | p_i, p_{i-1})$ for any $\tau \neq \tau_i$ and δ is a hyperparameter controlling the bias towards the aligned supertag. We train the model using K&G's original DyNet implementation. Their algorithm uses a hinge loss function, which maximizes the score difference between the gold dependency tree and the best predicted dependency tree, and therefore requires parsing each training instance in each iteration. Because the AM dependency trees are highly non-projective, we replaced the projective parser used in the off-the-shelf implementation by the Chu-Liu-Edmonds algorithm implemented in the TurboParser (Martins et al., 2010), improving the LAS on the development set by 30 points.

5.3 Local edge model

We also trained a *local* edge score model, which uses a cross-entropy rather than a hinge loss and therefore avoids the repeated parsing at training

²Indeed, we conjecture that for a fixed set of constants and a fixed AMR, there is only one dependency tree.

time. Instead, we follow the intuition that every node in a dependency tree has at most one incoming edge, and train the model to score the correct incoming edge as high as possible. This model takes inputs $x_i = (w_i, p_i)$.

We define the edge and edge label scores as in Section 5.2, with tanh replaced by ReLU. We further add a learned parameter v_{\perp} for the "LSTM embedding" of a nonexistent node, obtaining scores $\omega(\perp \rightarrow k)$ for k having no incoming edge.

To train $\omega(i \to k)$, we collect all scores for edges ending at the same node k into a vector $\omega(\bullet \to k)$. We then minimize the cross-entropy loss for the gold edge into k under softmax($\omega(\bullet \to k)$), maximizing the likelihood of the gold edges. To train the labels $\omega(f \mid i \to k)$, we simply minimize the cross-entropy loss of the actual edge labels f of the edges which are present in the gold AM dependency trees.

The PyTorch code for this and the supertagger are available at bitbucket.org/tclup/ amr-dependency.

6 Decoding

Given learned estimates for the graph and edge scores, we now tackle the challenge of computing the best well-typed dependency tree t for the input string w, under the score model (equation (1)). The requirement that t must be well-typed is crucial to ensure that it can be evaluated to an AMR graph, but as we show in the Supplementary Materials (Section A), makes the decoding problem NP-complete. Thus, an exact algorithm is not practical. In this section, we develop two different approximation algorithms for AM dependency parsing: one which assumes the (unlabeled) dependency tree structure as known, and one which assumes that the AM dependency tree is projective.

6.1 Projective decoder

The projective decoder assumes that the AM dependency tree is projective, i.e. has no crossing dependency edges. Because of this assumption, it can recursively combine adjacent substrings using dynamic programming. The algorithm is shown in Fig. 5 as a parsing schema (Shieber et al., 1995), which derives items of the form $([i, k], r, \tau)$ with scores *s*. An item represents a well-typed derivation of the substring from *i* to *k* with head index *r*, and which evaluates to an as-graph of type τ .

The parsing schema consists of three types of

$$\begin{split} \frac{s = \omega(G[i]) \quad G \neq \bot}{([i,i+1],i,\tau(G)):s} \quad \text{Init} \\ \frac{([i,k],r,\tau):s \quad s' = \omega(\bot[k])}{([i,k+1],r,\tau):s+s'} \quad \text{Skip-R} \\ \frac{([i,k],r,\tau):s \quad s' = \omega(\bot[i-1])}{([i-1,k],r,\tau):s+s'} \quad \text{Skip-L} \\ \frac{([i,j],r_1,\tau_1):s_1 \quad ([j,k],r_2,\tau_2):s_2}{\tau = f(\tau_1,\tau_2) \text{ defined } s = \omega(f[r_1,r_2])} \quad \text{Arc-R } [f] \\ \frac{([i,j],r_1,\tau_1):s_1 \quad ([j,k],r_2,\tau_2):s_2}{\tau = f(\tau_2,\tau_1) \text{ defined } s = \omega(f[r_2,r_1])} \quad \text{Arc-L } [f] \end{split}$$

Figure 5: Rules for the projective decoder.

rules. First, the Init rule generates an item for each graph fragment G[i] that the supertagger predicted for the token w_i , along with the score and type of that graph fragment. Second, given items for adjacent substrings [i, j] and [j, k], the Arc rules apply an operation f to combine the indexed AM terms for the two substrings, with Arc-R making the left-hand substring the head and the right-hand substring the argument or modifier, and Arc-L the other way around. We ensure that the result is well-typed by requiring that the types can be combined with f. Finally, the Skip rules allow us to extend a substring such that it covers tokens which do not correspond to a graph fragment (i.e., their AM term is \perp), introducing IGNORE edges. After all possible items have been derived, we extract the best well-typed tree from the item of the form $([1, n], r, \tau)$ with the highest score, where $\tau = []$.

Because we keep track of the head indices, the projective decoder is a bilexical parsing algorithm, and shares a parsing complexity of $O(n^5)$ with other bilexical algorithms such as the Collins parser. It could be improved to a complexity of $O(n^4)$ using the algorithm of Eisner and Satta (1999).

6.2 Fixed-tree decoder

The fixed-tree decoder computes the best unlabeled dependency tree t_r for w, using the edge scores $\omega(i \rightarrow k)$, and then computes the best AM dependency tree for w whose unlabeled version is t_r . The Chu-Liu-Edmonds algorithm produces a forest of dependency trees, which we want to combine into t_r . We choose the tree whose root r has the highest score for being the root of the AM dependency tree and make the roots of all others children of r.

At this point, the shape of t_r is fixed. We choose

$$\begin{aligned} \frac{s = \omega(G[i])}{(i, \emptyset, \tau(G)) : s} & \text{Init} \\ (i, C_1, \tau_1) : s_1 \quad (k, Ch(k), \tau_2) : s_2 \\ k \in Ch(i) \backslash C_1 \\ \underline{\tau = f(\tau_1, \tau_2) \text{ defined } s = \omega(f[i, k])} \\ (i, C_1 \cup \{k\}, \tau) : s_1 + s_2 + s} \text{ Edge}[f] \end{aligned}$$

Figure 6: Rules for the fixed-tree decoder.

supertags for the nodes and edge labels for the edges by traversing t_r bottom-up, computing types for the subtrees as we go along. Formally, we apply the parsing schema in Fig. 6. It uses items of the form $(i, C, \tau) : s$, where $1 \le i \le n$ is a node of t_r , C is the set of children of i for which we have already chosen edge labels, and τ is a type. We write Ch(i) for the set of children of i in t_r .

The Init rule generates an item for each graph that the supertagger can assign to each token i in w, ensuring that every token is also assigned \perp as a possible supertag. The Edge rule labels an edge from a parent node i in t_r to one of its children k, whose children already have edge labels. As above, this rule ensures that a well-typed AM dependency tree is generated by locally checking the types. In particular, if all types τ_2 that can be derived for kare incompatible with τ_1 , we fall back to an item for k with $\tau_2 = \perp$ (which always exists), along with an IGNORE edge from i to k.

The complexity of this algorithm is $O(n \cdot 2^d \cdot d)$, where d is the maximal arity of the nodes in t_r .

7 Evaluation

We evaluate our models on the LDC2015E86 and LDC2017T10³ datasets (henceforth "2015" and "2017"). Technical details and hyperparameters of our implementation can be found in Sections B to D of the Supplementary Materials.

7.1 Training data

The original LDC datasets pair strings with AMRs. We convert each AMR in the training and development set into an AM dependency tree, using the procedure of Section 4.2. About 10% of the training instances cannot be split into elementary as-graphs by our aligner; we removed these from the training data. Of the remaining AM dependency trees, 37% are non-projective.

Furthermore, the AM algebra is designed to handle short-range reentrancies, modeling grammatical phenomena such as control and coordination, as in the derivation in Fig. 2. It cannot easily handle the long-range reentrancies in AMRs which are caused by coreference, a non-compositional phenomenon.⁴ We remove such reentrancies from our training data (about 60% of the roughly 20,000 reentrant edges). Despite this, our model performs well on reentrant edges (see Table 2).

7.2 Pre- and postprocessing

We use simple pre- and postprocessing steps to handle rare words and some AMR-specific patterns. In AMRs, named entities follow a pattern shown in Fig. 7. Here the named entity is of type "person", has a name edge to a "name" node whose children spell out the tokens of "Agatha Christie", and a link to a wiki entry. Before training, we replace each "name" node, its children, and the corresponding span in the sentence with a special NAME token, and we completely remove wiki edges. In this example, this leaves us with only a "person" and a NAME node. Further, we replace numbers and some date patterns with NUMBER and DATE tokens. On the training data this is straightforward, since names and dates are explicitly annotated in the AMR. At evaluation time, we detect dates and numbers with regular expressions, and names with Stanford CoreNLP (Manning et al., 2014). We also use Stanford CoreNLP for our POS tags.

Each elementary as-graph generated by the procedure of Section 4.2 has a unique node whose label corresponds most closely to the aligned word (e.g. the "want" node in G_{want} and the "write" node in G_{writer}). We replace these node labels with LEX in preprocessing, reducing the number of different elementary as-graphs from 28730 to 2370. We factor the supertagger model of Section 5.1 such that the unlexicalized version of G[i] and the label for LEX are predicted separately.

At evaluation, we re-lexicalize all LEX nodes in the predicted AMR. For words that were frequent in the training data (at least 10 times), we take the supertagger's prediction for the label. For rarer words, we use simple heuristics, explained in the Supplementary Materials (Section D). For names, we just look up name nodes with their children and wiki entries observed for the name string in the training data, and for unseen names use the literal tokens as the name, and no wiki entry. Similarly,

³https://catalog.ldc.upenn.edu/ LDC2017T10, identical to LDC2016E25.

⁴As Damonte et al. (2017) comment: "A valid criticism of AMR is that these two reentrancies are of a completely different type, and should not be collapsed together."

we collect the type for each encountered name (e.g. "person" for "Agatha Christie"), and correct it in the output if the tagger made a different prediction. We recover dates and numbers straightforwardly.

7.3 Supertagger accuracy

All of our models rely on the supertagger to predict elementary as-graphs; they differ only in the edge scores. We evaluated the accuracy of the supertagger on the converted development set (in which each token has a supertag) of the 2015 data set, and achieved an accuracy of 73%. The correct supertag is within the supertagger's 4 best predictions for 90% of the tokens, and within the 10 best for 95%.

Interestingly, supertags that introduce grammatical reentrancies are predicted quite reliably, although they are relatively rare in the training data. The elementary as-graph for subject control verbs (see G_{want} in Fig. 1) accounts for only 0.8% of supertags in the training data, yet 58% of its occurrences in the development data are predicted correctly (84% in 4-best). The supertag for VP coordination (with type [OP1[S], OP2[S]]) makes up for 0.4% of the training data, but 74% of its occurrences are recognized correctly (92% in 4-best). Thus the prediction of informative types for individual words is feasible.

7.4 Comparison to Baselines

Type-unaware fixed-tree baseline. The fixed-tree decoder is built to ensure well-typedness of the predicted AM dependency trees. To investigate to what extent this is required, we consider a baseline which just adds the individually highest-scoring supertags and edge labels to the unlabeled dependency tree t_u , ignoring types. This leads to AM dependency trees which are not well-typed for 75% of the sentences (we fall back to the largest well-typed subtree in these cases). Thus, an off-the-shelf dependency parser can reliably predict the tree structure of the AM dependency tree, but correct supertag and edge label assignment requires a decoder which takes the types into account.

JAMR-style baseline. Our elementary asgraphs differ from the elementary graphs used in JAMR-style algorithms in that they contain explicit source nodes, which restrict the way in which they can be combined with other as-graphs. We investigate the impact of this choice by implementing a strong JAMR-style baseline. We adapt the AMR-todependency conversion of Section 4.2 by removing all unlabeled nodes with source names from the

Model	2015	2017
Ours		
local edge + projective decoder	70.2 ± 0.3	71.0 ±0.5
local edge + fixed-tree decoder	$69.4{\pm}0.6$	70.2 ± 0.5
K&G edge + projective decoder	$68.6 {\pm} 0.7$	$69.4{\pm}0.4$
K&G edge + fixed-tree decoder	69.6 ± 0.4	$69.9 {\pm} 0.2$
Baselines		
fixed-tree (type-unaware)	26.0 ± 0.6	27.9 ± 0.6
JAMR-style	66.1	66.2
Previous work		
CAMR (Wang et al., 2015)	66.5	-
JAMR (Flanigan et al., 2016)	67	-
Damonte et al. (2017)	64	-
van Noord and Bos (2017b)	68.5	71.0
Foland and Martin (2017)	70.7	-
Buys and Blunsom (2017)	-	61.9

Table 1: 2015 & 2017 test set Smatch scores

elementary graphs. For instance, the graph G_{want} in Fig. 1 now only consists of a single "want" node. We then aim to directly predict AMR edges between these graphs, using a variant of the local edge scoring model of Section 5.3 which learns scores for each edge in isolation. (The assumption for the original local model, that each node has only one incoming edge, does not apply here.)

When parsing a string, we choose the highestscoring supertag for each word; there are only 628 different supertags in this setting, and 1-best supertagging accuracy is high at 88%. We then follow the JAMR parsing algorithm by predicting all edges whose score is over a threshold (we found -0.02 to be optimal) and then adding edges until the graph is connected. Because we do not predict which node is the root of the AMR, we evaluated this model as if it always predicted the root correctly, overestimating its score slightly.

7.5 Results

Table 1 shows the Smatch scores (Cai and Knight, 2013) of our models, compared to a selection of previously published results. Our results are averages over 4 runs with 95% confidence intervals (JAMR-style baselines are single runs). On the 2015 dataset, our best models (local + projective, K&G + fixed-tree) outperform all previous work, with the exception of the Foland and Martin (2017) model; on the 2017 set we match state of the art results (though note that van Noord and Bos (2017b) use 100k additional sentences of silver data). The fixed-tree decoder seems to work well with either edge model, but performance of the projective decoder drops with the K&G edge scores. It may be that, while the hinge loss used in the K&G edge scoring model is useful to finding the correct un-

	2015				2017			
Metric	W'15	F'16	D'17	PD	FTD	vN'17	PD	FTD
Smatch	67	67	64	70	70	71	71	70
Unlabeled	69	69	69	73	73	74	74	74
No WSD	64	68	65	71	70	72	72	70
Named Ent.	75	79	83	79	78	79	78	77
Wikification	0	75	64	71	72	65	71	71
Negations	18	45	48	52	52	62	57	55
Concepts	80	83	83	83	84	82	84	84
Reentrancies	41	42	41	46	44	52	49	46
SRL	60	60	56	63	61	66	64	62

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Table 2: Details for the LDC2015E86 and LDC2017T10 test sets

Figure 7: A named entity

labeled dependency tree in the fixed-tree decoder, scores for bad edges – which are never used when computing the hinge loss – are not trained accurately. Thus such edges may be erroneously used by the projective decoder.

As expected, the type-unaware baseline has low recall, due to its inability to produce well-typed trees. The fact that our models outperform the JAMR-style baseline so clearly is an indication that they indeed gain some of their accuracy from the type information in the elementary as-graphs, confirming our hypothesis that an explicit model of the compositional structure of the AMR can help the parser learn an accurate model.

Table 2 analyzes the performance of our two best systems (PD = projective, FTD = fixed-tree) in more detail, using the categories of Damonte et al. (2017), and compares them to Wang's, Flanigan's, and Damonte's AMR parsers on the 2015 set and , and van Noord and Bos (2017b) for the 2017 dataset. (Foland and Martin (2017) did not publish such results.) The good scores we achieve on reentrancy identification, despite removing a large amount of reentrant edges from the training data, indicates that our elementary as-graphs successfully encode phenomena such as control and coordination.

The projective decoder is given 4, and the fixedtree decoder 6, supertags for each token. We trained the supertagging and edge scoring models of Section 5 separately; joint training did not help. Not sampling the supertag types τ_i during training of the K&G model, removing them from the input, and removing the character-based LSTM encodings c_i from the input of the supertagger, all reduced our models' accuracy.

7.6 Differences between the parsers

Although the Smatch scores for our two best models are close, they sometimes struggle with different sentences. The fixed-tree parser is at the mercy of the fixed tree; the projective parser cannot produce non-projective AM dependency trees. It is remarkable that the projective parser does so well, given the prevalence of non-projective trees in the training data. Looking at its analyses, we find that it frequently manages to find a projective tree which yields an (almost) correct AMR, by choosing supertags with unusual types, and by using modify rather than apply (or vice versa).

8 Conclusion

We presented an AMR parser which applies methods from supertagging and dependency parsing to map a string into a well-typed AM term, which it then evaluates into an AMR. The AM term represents the compositional semantic structure of the AMR explicitly, allowing us to use standard treebased parsing techniques.

The projective parser currently computes the complete parse chart. In future work, we will speed it up through the use of pruning techniques. We will also look into more principled methods for splitting the AMRs into elementary as-graphs to replace our hand-crafted heuristics. In particular, advanced methods for alignments, as in Lyu and Titov (2018), seem promising. Overcoming the need for heuristics also seems to be a crucial ingredient for applying our method to other semantic representations.

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