

Preservation of Recognizability for Weighted Linear Extended Top-Down Tree Transducers*

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Abstract

An open question in [FÜLÖP, MALETTI, VOGLER: Weighted extended tree transducers. *Fundamenta Informaticae* 111(2), 2011] asks whether weighted linear extended tree transducers preserve recognizability in countably complete commutative semirings. In this contribution, the question is answered positively, which is achieved with a construction that utilizes *inside weights*. Due to the completeness of the semiring, the inside weights always exist, but the construction is only effective if they can be effectively determined. It is demonstrated how to achieve this in a number of important cases.

1 Introduction

Syntax-based statistical machine translation (Knight, 2007) created renewed interest in tree automata and tree transducer theory (Fülöp and Vogler, 2009). In particular, it sparked research on extended top-down tree transducers (Graehl et al., 2009), which are top-down tree transducers (Rounds, 1970; Thatcher, 1970) in which the left-hand sides can contain several (or no) input symbols. A recent contribution by Fülöp et al. (2011) investigates the theoretical properties of weighted extended tree transducers over countably complete and commutative semirings (Hebisch and Weinert, 1998; Golan, 1999). Such semirings permit sums of countably many summands, which still obey the usual associativity, commutativity, and distributivity laws. We will use the same class of semirings.

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Figure 1: Syntax-based machine translation pipeline.

Extended top-down tree transducers are used as translation models (TM) in syntax-based machine translation. In the standard pipeline (see Figure 1; LM is short for language model) the translation model is applied to the parses of the input sentence, which can be represented as a recognizable weighted forest (Fülöp and Vogler, 2009). In practice, only the best or the n -best parses are used, but in principle, we can use the recognizable weighted forest of all parses. In either case, the translation model transforms the input trees into a weighted forest of translated output trees. A class of transducers preserves recognizability if for every transducer of the class and each recognizable weighted forest, this weighted forest of translated output trees is again recognizable. Fülöp et al. (2011) investigates which extended top-down tree transducers preserve recognizability under forward (i.e., the setting previously described) and backward application (i.e., the setting, in which we start with the output trees and apply the inverse of the translation model), but the question remained open for forward application of weighted linear extended top-down tree transducers [see Table 1 for an overview of the existing results for forward application due to Engelfriet (1975) in the unweighted case and Fülöp et al. (2010) and Fülöp et al. (2011) for the weighted case]. In conclusion, Fülöp et al. (2011) ask: “Are there a commutative semiring S that is countably complete wrt. \sum , a linear wxtt \mathcal{M} [weighted extended top-down tree transducer with regular look-ahead; see Section 4], and a recognizable

<i>model</i>		<i>preserves regularity</i>
unweighted	ln-XTOP	✓
	l-XTOP	✓
	l-XTOP ^R	✓
	XTOP	✗
weighted	ln-XTOP	✓
	l-XTOP	✓
	l-XTOP ^R	✓
	XTOP	✗

Table 1: Overview of the known results due to Engelfriet (1975) and Fülöp et al. (2011) and our results in boxes.

weighted tree language φ such that $\mathcal{M}(\varphi)$ [forward application] is not recognizable? Or even harder, are there S and \mathcal{M} with the same properties such that $\mathcal{M}(\tilde{1})$ [$\tilde{1}$ is the weighted forest in which each tree has weight 1] is not recognizable?”

In this contribution, we thus investigate preservation of recognizability (under forward application) for linear extended top-down tree transducers with regular look-ahead (Engelfriet, 1977), which are equivalent to linear weighted extended tree transducers by Fülöp et al. (2011). We show that they always preserve recognizability, thus confirming the implicit hypothesis of Fülöp et al. (2011). The essential tool for our construction is the inside weight (Lari and Young, 1990; Graehl et al., 2008) of the states of the weighted tree grammar (Alexandrakis and Bozapalidis, 1987) representing the parses. The inside weight of a state q is the sum of all weights of trees accepted in this state. In our main construction (see Section 5) we first compose the input weighted tree grammar with the transducer (input restriction). This is particularly simple since we just abuse the look-ahead of the initial rules. In a second step, we normalize the obtained transducer, which yields the standard product construction typically used for input restriction. Finally, we project to the output by basically eliminating the left-hand sides. In this step, the inside weights of states belonging to deleted subtrees are multiplied to the production weight. Due to the completeness of the semiring, the inside weights always exist, but the infinite sums have to be computed effectively for the final step of the construction to

be effective. This problem is addressed in Section 6, where we show several methods to effectively compute or approximate the inside weights for all states of a weighted tree grammar.

2 Notation

Our weights will be taken from a commutative semiring $(A, +, \cdot, 0, 1)$, which is an algebraic structure of two commutative monoids $(A, +, 0)$ and $(A, \cdot, 1)$ such that \cdot distributes over $+$ and $0 \cdot a = 0$ for all $a \in A$. An infinitary sum operation \sum is a family $(\sum_I)_I$ where I is a countable index set and $\sum_I: A^I \rightarrow A$. Given $f: I \rightarrow A$, we write $\sum_{i \in I} f(i)$ instead of $\sum_I f$. The semiring together with the infinitary sum operation \sum is *countably complete* (Eilenberg, 1974; Hebisch and Weinert, 1998; Golan, 1999; Karner, 2004) if for all countable sets I and $a_i \in A$ with $i \in I$

- $\sum_{i \in I} a_i = a_m + a_n$ if $I = \{m, n\}$,
- $\sum_{i \in I} a_i = \sum_{j \in J} (\sum_{i \in I_j} a_i)$ if $I = \bigcup_{j \in J} I_j$ for countable sets J and I_j with $j \in J$ such that $I_j \cap I_{j'} = \emptyset$ for all different $j, j' \in J$, and
- $a \cdot (\sum_{i \in I} a_i) = \sum_{i \in I} (a \cdot a_i)$ for all $a \in A$.

For such a semiring, we let $a^* = \sum_{i \in \mathbb{N}} a^i$ for every $a \in A$. In the following, we assume that $(A, +, \cdot, 0, 1)$ is a commutative semiring that is countably complete with respect to \sum .

Our trees have node labels taken from an alphabet Σ and leaves might also be labeled by elements of a set V . Given a set T , we write $\Sigma(T)$ for the set

$$\{\sigma(t_1, \dots, t_k) \mid k \in \mathbb{N}, \sigma \in \Sigma, t_1, \dots, t_k \in T\} .$$

The set $T_\Sigma(V)$ of Σ -trees with V -leaves is defined as the smallest set T such that $V \cup \Sigma(T) \subseteq T$. We write T_Σ for $T_\Sigma(\emptyset)$. For each tree $t \in T_\Sigma(V)$ we identify nodes by positions. The root of t has position ε and the position iw with $i \in \mathbb{N}$ and $w \in \mathbb{N}^*$ addresses the position w in the i -th direct subtree at the root. The set of all positions in t is $\text{pos}(t)$. We write $t(w)$ for the label (taken from $\Sigma \cup V$) of t at position $w \in \text{pos}(t)$. Similarly, we use $t|_w$ to address the subtree of t that is rooted in position w , and $t[u]_w$ to represent the tree that is obtained from replacing the subtree $t|_w$ at w by $u \in T_\Sigma(V)$. For a given set $L \subseteq \Sigma \cup V$ of labels, we let

$$\text{pos}_L(t) = \{w \in \text{pos}(t) \mid t(w) \in L\}$$

be the set of all positions whose label belongs to L . We also write $\text{pos}_l(t)$ instead of $\text{pos}_{\{l\}}(t)$.

We often use the set $X = \{x_1, x_2, \dots\}$ of variables and its finite subsets $X_k = \{x_1, \dots, x_k\}$ for every $k \in \mathbb{N}$ to label leaves. Let V be a set potentially containing some variables of X . The tree $t \in T_\Sigma(V)$ is *linear* if $|\text{pos}_x(t)| \leq 1$ for every $x \in X$. Moreover, $\text{var}(t) = \{x \in X \mid \text{pos}_x(t) \neq \emptyset\}$ collects all variables that occur in t . Given a finite set Q and $T \subseteq T_\Sigma(V)$, we let

$$Q[T] = \{q(t) \mid q \in Q, t \in T\} .$$

We will treat elements of $Q[T]$ (in which elements of Q are always used as unary symbols) as special trees of $T_{\Sigma \cup Q}(V)$. A substitution θ is a mapping $\theta: X \rightarrow T_\Sigma(V)$. When applied to $t \in T_\Sigma(V)$, it returns the tree $t\theta$, which is obtained from t by replacing all occurrences of $x \in X$ (in parallel) by $\theta(x)$. This can be defined recursively by $x\theta = \theta(x)$ for all $x \in X$, $v\theta = v$ for all $v \in V \setminus X$, and $\sigma(t_1, \dots, t_k)\theta = \sigma(t_1\theta, \dots, t_k\theta)$ for all $\sigma \in \Sigma$ and $t_1, \dots, t_k \in T_\Sigma(V)$.

3 Weighted Tree Grammars

In this section, we will recall weighted tree grammars (Alexandrakis and Bozapalidis, 1987) [see (Fülöp and Vogler, 2009) for a modern treatment and a complete historical account]. In general, weighted tree grammars (WTGs) offer an efficient representation of weighted forests, which are sets of trees such that each individual tree is equipped with a weight. The representation is even more efficient than packed forests (Mi et al., 2008) and moreover can represent an infinite number of weighted trees. To avoid confusion between the nonterminals of a parser, which produces the forests considered here, and our WTGs, we will refer to the nonterminals of our WTG as *states*.

Definition 1. A *weighted tree grammar* (WTG) is a system (Q, Σ, q_0, P) where

- Q is a finite set of states (nonterminals),
- Σ is the alphabet of symbols,
- $q_0 \in Q$ is the starting state, and
- P is a finite set of productions $q \xrightarrow{a} t$, where $q \in Q$, $a \in A$, and $t \in T_\Sigma(Q)$. \square

Example 2. We illustrate our notation on the WTG $G_{\text{ex}} = (Q, \Sigma, q_s, P)$ where

- $Q = \{q_s, q_{np}, q_{prp}, q_n, q_{adj}\}$,

- Σ contains “S”, “NP”, “VP”, “PP”, “DT”, “NN”, “N”, “VBD”, “PRP”, “ADJ”, “man”, “hill”, “telescope”, “laughs”, “the”, “on”, “with”, “old”, and “young”, and
- P contains the productions

$$\begin{aligned} q_s &\xrightarrow{1.0} \text{S}(q_{np}, \text{VP}(\text{VBD}(\text{laughs}))) & (\rho_1) \\ q_{np} &\xrightarrow{0.4} \text{NP}(q_{np}, \text{PP}(q_{prp}, q_{np})) \\ q_{np} &\xrightarrow{0.6} \text{NP}(\text{DT}(\text{the}), q_n) & (\rho_2) \\ q_{prp} &\xrightarrow{0.5} \text{PRP}(\text{on}) \\ q_{prp} &\xrightarrow{0.5} \text{PRP}(\text{with}) \\ q_n &\xrightarrow{0.3} \text{N}(q_{adj}, q_n) \\ q_n &\xrightarrow{0.3} \text{NN}(\text{man}) & (\rho_3) \\ q_n &\xrightarrow{0.2} \text{NN}(\text{hill}) \\ q_n &\xrightarrow{0.2} \text{NN}(\text{telescope}) \\ q_{adj} &\xrightarrow{0.5} \text{ADJ}(\text{old}) \\ q_{adj} &\xrightarrow{0.5} \text{ADJ}(\text{young}) \end{aligned}$$

It produces a weighted forest representing sentences about young and old men with telescopes on hills. \square

In the following, let $G = (Q, \Sigma, q_0, P)$ be a WTG. For every production $\rho = q \xrightarrow{a} t$ in P , we let $\text{wt}_G(\rho) = a$. The semantics of G is defined with the help of derivations. Let $\xi \in T_\Sigma(Q)$ be a sentential form, and let $w \in \text{pos}_Q(\xi)$ be such that w is the lexicographically smallest Q -labeled position in ξ . Then $\xi \Rightarrow_G^\rho \xi[t]_w$ if $\xi(w) = q$. For a sequence $\rho_1, \dots, \rho_n \in P$ of productions, we let $\text{wt}_G(\rho_1 \cdots \rho_n) = \prod_{i=1}^n \text{wt}_G(\rho_i)$. For every $q \in Q$ and $t \in T_\Sigma(Q)$, we let

$$\text{wt}_G(q, t) = \sum_{\substack{\rho_1, \dots, \rho_n \in P \\ q \Rightarrow_G^{\rho_1} \cdots \Rightarrow_G^{\rho_n} t}} \text{wt}_G(\rho_1 \cdots \rho_n) .$$

The WTG G computes the weighted forest $L_G: T_\Sigma \rightarrow A$ such that $L_G(t) = \text{wt}_G(q_0, t)$ for every $t \in T_\Sigma$. Two WTGs are equivalent if they compute the same weighted forest. Since productions of weight 0 are useless, we often omit them.

Example 3. For the WTG G_{ex} of Example 2 we display a derivation with weight 0.18 for the sentence “the man laughs” in Figure 2. \square

The notion of inside weights (Lari and Young, 1990) is well-established, and Maletti and Satta

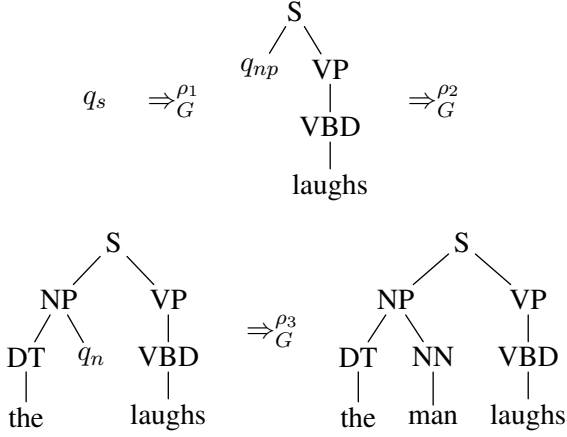


Figure 2: Derivation with weight $1.0 \cdot 0.6 \cdot 0.3$.

(2009) consider them for WTGs. Let us recall the definition.

Definition 4. The *inside weight* of state $q \in Q$ is

$$\text{in}_G(q) = \sum_{t \in T_\Sigma} \text{wt}_G(q, t) . \quad \square$$

In Section 6 we demonstrate how to compute inside weights. Finally, let us introduce WTGs in normal form. The WTG G is in *normal form* if $t \in \Sigma(Q)$ for all its productions $q \xrightarrow{a} t$ in P . The following theorem was proven by Alexandrakis and Bozpalidis (1987) as Proposition 1.2.

Theorem 5. For every WTG there exists an equivalent WTG in normal form. \square

Example 6. The WTG G_{ex} of Example 2 is not normalized. To illustrate the normalization step, we show the normalization of the production ρ_2 , which is replaced by the following three productions:

$$\begin{aligned} q_{np} &\xrightarrow{0.6} \text{NP}(q_{dt}, q_n) & q_{dt} &\xrightarrow{1.0} \text{DT}(q_t) \\ q_t &\xrightarrow{1.0} \text{the} . & & \end{aligned} \quad \square$$

4 Weighted linear extended tree transducers

The model discussed in this contribution is an extension of the classical *top-down tree transducer*, which was introduced by Rounds (1970) and Thatcher (1970). Here we consider a weighted and extended variant that additionally has regular look-ahead. The weighted top-down tree transducer is discussed in (Fülöp and Vogler, 2009), and extended top-down tree transducers were studied in (Arnold and Dauchet, 1982; Knight and

Graehl, 2005; Knight, 2007; Graehl et al., 2008; Graehl et al., 2009). The combination (weighted extended top-down tree transducer) was recently investigated by Fülöp et al. (2011), who also considered (weighted) regular look-ahead, which was first introduced by Engelfriet (1977) in the unweighted setting.

Definition 7. A *linear extended top-down tree transducer with full regular look-ahead* (1-XTOP_f^R) is a system $(S, \Sigma, \Delta, s_0, G, R)$ where

- S is a finite set of *states*,
- Σ and Δ are alphabets of *input* and *output symbols*, respectively,
- $s_0 \in S$ is an *initial state*,
- $G = (Q, \Sigma, q_0, P)$ is a WTG, and
- R is a finite set of *weighted rules* of the form $\ell \xrightarrow{a} \mu r$ where
 - $a \in A$ is the *rule weight*,
 - $\ell \in S[T_\Sigma(X)]$ is the linear *left-hand side*,
 - $\mu: \text{var}(\ell) \rightarrow Q$ is the *look-ahead*, and
 - $r \in T_\Delta(S[\text{var}(\ell)])$ is the linear *right-hand side*. \square

In the following, let $M = (S, \Sigma, \Delta, s_0, G, R)$ be an 1-XTOP_f^R . We assume that the WTG G contains a state \top such that $\text{wt}_G(\top, t) = 1$ for every $t \in T_\Sigma$. In essence, this state represents the trivial look-ahead. If $\mu(x) = \top$ for every rule $\ell \xrightarrow{a} \mu r \in R$ and $x \in \text{var}(r)$ (respectively, $x \in \text{var}(\ell)$), then M is an 1-XTOP^R (respectively, 1-XTOP). 1-XTOP^R and 1-XTOP coincide exactly with the models of Fülöp et al. (2011), and in the latter model we drop the look-ahead component μ and the WTG G completely.

Example 8. The rules of our running example 1-XTOP M_{ex} (over the input and output alphabet Σ , which is also used by the WTG G_{ex} of Example 2) are displayed in Figure 3. \square

Next, we present the semantics. Without loss of generality, we assume that we can distinguish states from input and output symbols (i.e., $S \cap (\Sigma \cup \Delta) = \emptyset$). A *sentential form* of M is a tree of $\text{SF}(M) = T_\Delta(Q[T_\Sigma])$. Let $\rho = \ell \xrightarrow{a} \mu r$ be a rule of R . Moreover, let $\xi, \zeta \in \text{SF}(M)$ be sentential forms and $w \in \mathbb{N}^*$ be the lexicographically smallest position in $\text{pos}_Q(\xi)$. We write $\xi \xrightarrow{b}_{M, \rho} \zeta$ if there exists a substitution $\theta: X \rightarrow T_\Sigma$ such that

- $\xi = \xi[\ell\theta]_w$,
- $\zeta = \xi[r\theta]_w$, and
- $b = a \cdot \prod_{x \in \text{var}(\ell)} \text{wt}_G(\mu(x), \theta(x))$.

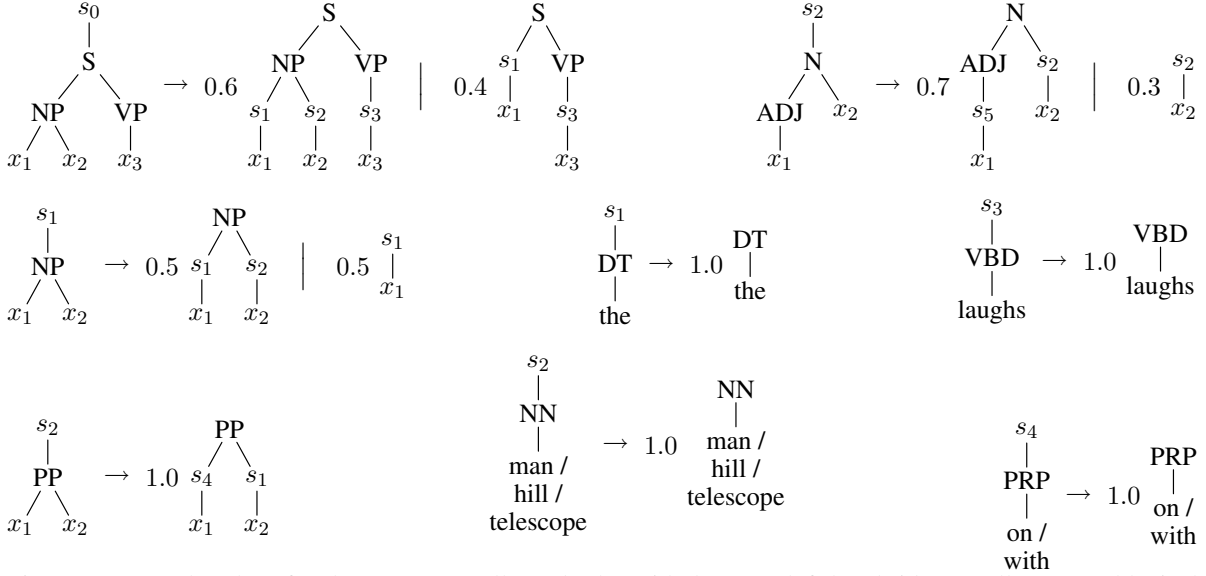


Figure 3: Example rules of an l-XTOP. We collapsed rules with the same left-hand side as well as several lexical items to save space.

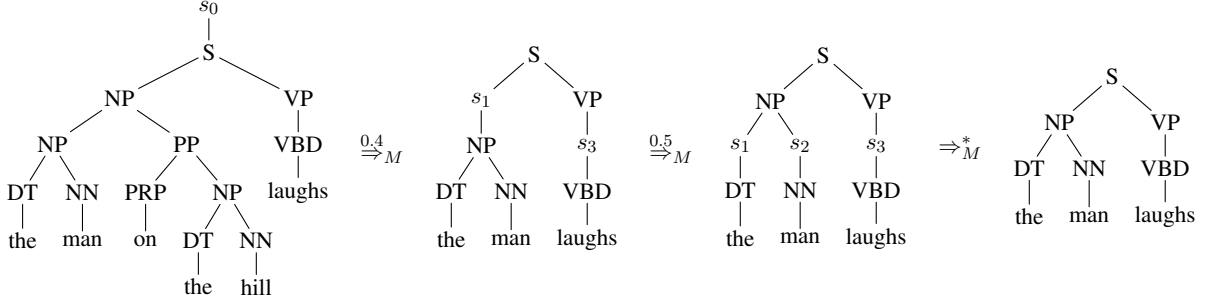


Figure 4: Derivation with weight $0.4 \cdot 0.5 \cdot 1.0$ (rules omitted).

The *tree transformation* τ_M computed by M is defined by

$$\tau_M(t, u) = \sum_{\substack{\rho_1, \dots, \rho_n \in R \\ s_0(t) \xrightarrow{a_1}_{M, \rho_1} \dots \xrightarrow{a_n}_{M, \rho_n} u}} a_1 \cdot \dots \cdot a_n$$

for every $t \in T_\Sigma$ and $u \in T_\Delta$.

Example 9. A sequence of derivation steps of the l-XTOP M_{ex} is illustrated in Figure 4. The transformation it computes is capable of deleting the PP child of every NP-node with probability 0.4 as well as deleting the ADJ child of every N-node with probability 0.3. \square

A detailed exposition to unweighted l-XTOP^R is presented by Arnold and Dauchet (1982) and Graehl et al. (2009).

5 The construction

In this section, we present the main construction of this contribution, in which we will construct a

WTG for the forward application of another WTG via an l-XTOP^R. Let us first introduce the main notions. Let $L: T_\Sigma \rightarrow A$ be a weighted forest and $\tau: T_\Sigma \times T_\Delta \rightarrow A$ be a weighted tree transformation. Then the forward application of L via τ yields the weighted forest $\tau(L): T_\Delta \rightarrow A$ such that $(\tau(L))(u) = \sum_{t \in T_\Sigma} L(t) \cdot \tau(t, u)$ for every $u \in T_\Delta$. In other words, to compute the weight of u in $\tau(L)$, we consider all input trees t and multiply their weight in L with their translation weight to u . The sum of all those products yields the weight for u in $\tau(L)$. In the particular setting considered in this contribution, the weighted forest L is computed by a WTG and the weighted tree transformation τ is computed by an l-XTOP^R. The question is whether the resulting weighted forest $\tau(L)$ can be computed by a WTG.

Our approach to answer this question consists of three steps: (i) composition, (ii) normalization, and (iii) range projection, which we address in separate sections. Our input is

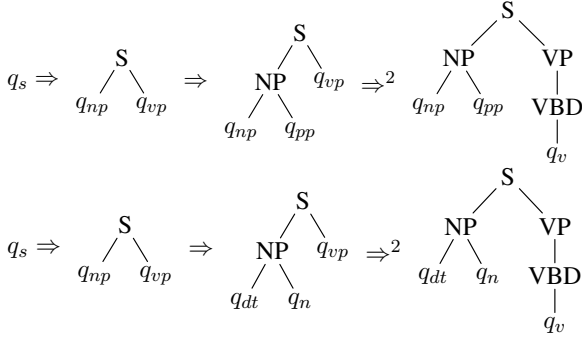


Figure 5: Two derivations (without production and grammar decoration) with weight 0.4 [top] and 0.6 [bottom] of the normalized version of the WTG G_{ex} (see Example 10).

the WTG $G' = (Q', \Sigma, q'_0, P')$, which computes the weighted forest $L = L_{G'}$, and the 1-XTOP^R $M = (S, \Sigma, \Delta, s_0, G, R)$ with $G = (Q, \Sigma, q_0, P)$, which computes the weighted tree transformation $\tau = \tau_M$. Without loss of generality, we suppose that G and G' contain a special state \top such that $\text{wt}_G(\top, t) = \text{wt}_{G'}(\top, t) = 1$ for all $t \in T_\Sigma$. Moreover, we assume that the WTG G' is in normal form. Finally, we assume that s_0 is separated, which means that the initial state of M does not occur in any right-hand side. Our example 1-XTOP M_{ex} has this property. All these restrictions can be assumed without loss of generality. Finally, for every state $s \in S$, we let

$$R_s = \{\ell \xrightarrow{a}_{\mu} r \in R \mid \ell(\varepsilon) = s\} .$$

5.1 Composition

We combine the WTG G' and the 1-XTOP^R M into a single 1-XTOP^R M' that computes

$$\tau_{M'}(t, u) = L_{G'}(t) \cdot \tau_M(t, u) = L(t) \cdot \tau(t, u)$$

for every $t \in T_\Sigma$ and $u \in T_\Delta$. To this end, we construct

$$M' = (S, \Sigma, \Delta, s_0, G \times G', (R \setminus R_{s_0}) \cup R')$$

such that $G \times G'$ is the classical product WTG [see Proposition 5.1 of (Berstel and Reutenauer, 1982)] and for every rule $\ell \xrightarrow{a}_{\mu} r$ in R_{s_0} and $\theta: \text{var}(\ell) \rightarrow Q'$, the rule

$$\ell \xrightarrow{a \cdot \text{wt}_{G'}(q'_0, \ell\theta)}_{\mu'} r$$

is in R' , where $\mu'(x) = \langle \mu(x), \theta(x) \rangle$ for every $x \in \text{var}(\ell)$.

Example 10. Let us illustrate the construction on the WTG G_{ex} of Example 2 and the 1-XTOP M_{ex} of Example 8. According to our assumptions, G_{ex} should first be normalized (see Theorem 5). We have two rules in R_{s_0} and they have the same left-hand side ℓ . It can be determined easily that $\text{wt}_{G_{\text{ex}}}(q_s, \ell\theta) \neq 0$ only if

- $\theta(x_1)\theta(x_2)\theta(x_3) = q_{np}q_{pp}q_v$ or
- $\theta(x_1)\theta(x_2)\theta(x_3) = q_{dt}q_nq_v$.

Figure 5 shows the two corresponding derivations and their weights. Thus, the s_0 -rules are replaced by the 4 rules displayed in Figure 6. \square

Theorem 11. For every $t \in T_\Sigma$ and $u \in T_\Delta$, we have $\tau_{M'}(t, u) = L(t) \cdot \tau(t, u)$.

Proof. We prove an intermediate property for each derivation of M . Let

$$s_0(t) \xrightarrow{b_1}_{M, \rho_1} \cdots \xrightarrow{b_n}_{M, \rho_n} u$$

be a derivation of M . Let $\rho_1 = \ell \xrightarrow{a_1}_{\mu} r$ be the first rule, which trivially must be in R_{s_0} . Then for every $\theta: \text{var}(\ell) \rightarrow Q'$, there exists a derivation

$$s_0(t) \xrightarrow{c_1}_{M', \rho'_1} \xi_2 \xrightarrow{b_2}_{M', \rho_2} \cdots \xrightarrow{b_n}_{M', \rho_n} u$$

in M' such that

$$c_1 = b_1 \cdot \text{wt}_{G'}(q'_0, \ell\theta) \cdot \prod_{x \in \text{var}(\ell)} \text{wt}_{G'}(\theta(x), \theta'(x)) ,$$

where $\theta': \text{var}(\ell) \rightarrow T_\Sigma$ is such that $t = \ell\theta'$. Since we sum over all such derivations and

$$\begin{aligned} & \sum_{\theta: \text{var}(\ell) \rightarrow Q'} \text{wt}_{G'}(q'_0, \ell\theta) \cdot \prod_{x \in \text{var}(\ell)} \text{wt}_{G'}(\theta(x), \theta'(x)) \\ &= \text{wt}_{G'}(q'_0, t) = L_{G'}(t) \end{aligned}$$

by a straightforward extension of Lemma 4.1.8 of (Borchardt, 2005), we obtain that the derivations in M' sum to $L_{G'}(t) \cdot b_1 \cdot \dots \cdot b_n$ as desired. The main property follows trivially from the intermediate result. \square

5.2 Normalization

Currently, the weights of the input WTG are only on the initial rules and in its look-ahead. Next, we use essentially the same method as in the previous section to remove the look-ahead from all variables that are not deleted. Let $M' = (S, \Sigma, \Delta, s_0, G \times G', R)$ be the 1-XTOP^R M' constructed in the previous section and

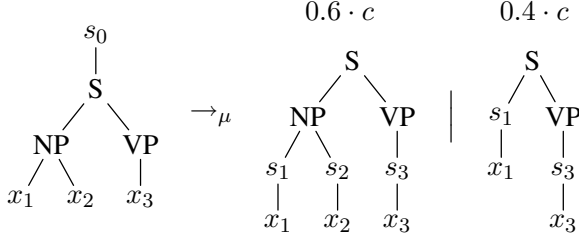


Figure 6: 4 new l-XTOP_f^R rules, where μ and c are either (i) $\mu(x_1)\mu(x_2)\mu(x_3) = q_{np}q_{pp}q_v$ and $c = 0.4$ or (ii) $\mu(x_1)\mu(x_2)\mu(x_3) = q_{dt}q_nq_v$ and $c = 0.6$ (see Example 10).

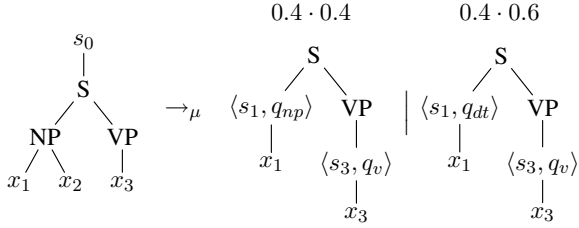


Figure 7: New l-XTOP_f^R rules, where $\mu(x_2) = q_{pp}$ [left] and $\mu(x_2) = q_n$ [right] (see Figure 6).

$\rho = \ell \xrightarrow{\alpha} r \in R$ be a rule with $\mu(x) = \langle \top, q' \rangle$ for some $q' \in Q' \setminus \{\top\}$ and $x \in \text{var}(r)$. Note that $\mu(x) = \langle \top, q' \rangle$ for some $q' \in Q'$ for all $x \in \text{var}(r)$ since M is an l-XTOP^R. Then we construct the l-XTOP_f^R M''

$$(S \cup S \times Q', \Sigma, \Delta, s_0, G \times G', (R \setminus \{\rho\}) \cup R')$$

such that R' contains the rule $\ell \xrightarrow{\alpha} r'$, where

$$\mu'(x') = \begin{cases} \langle \top, \top \rangle & \text{if } x = x' \\ \mu(x') & \text{otherwise} \end{cases}$$

for all $x' \in \text{var}(\ell)$ and r' is obtained from r by replacing the subtree $s(x)$ with $s \in S$ by $\langle s, q' \rangle(x)$. Additionally, for every rule $\ell'' \xrightarrow{\alpha''} r''$ in R_s and $\theta: \text{var}(\ell'') \rightarrow Q'$, the rule

$$\ell'' \xrightarrow{\alpha'' \cdot \text{wt}_{G'}(q', \ell''\theta)} \mu''' r''$$

is in R' , where $\mu'''(x) = \langle \mu''(x), \theta(x) \rangle$ for every $x \in \text{var}(\ell)$. This procedure is iterated until we obtain an l-XTOP^R M'' . Clearly, the iteration must terminate since we do not change the rule shape, which yields that the size of the potential rule set is bounded.

Theorem 12. The l-XTOP^R M'' and the l-XTOP_f^R M' are equivalent.

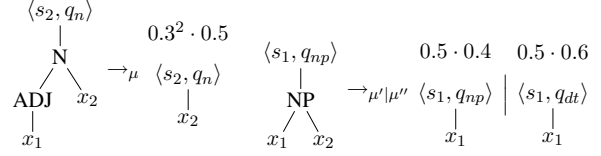


Figure 8: New l-XTOP_f^R rules, where $\mu(x_1)$ is either q_{old} or q_{young} , $\mu'(x_2) = q_{pp}$, and $\mu''(x_2) = q_n$.

Proof. It can be proved that the l-XTOP_f^R constructed after each iteration is equivalent to its input l-XTOP_f^R in the same fashion as in Theorem 11 with the only difference that the rule replacement now occurs anywhere in the derivation (not necessarily at the beginning) and potentially several times. Consequently, the finally obtained l-XTOP^R M'' is equivalent to M' . \square

Example 13. Let us reconsider the l-XTOP_f^R constructed in the previous section and apply the normalization step. The interesting rules (i.e., those rules $l \xrightarrow{\alpha} r$ where $\text{var}(r) \neq \text{var}(l)$) are displayed in Figures 7 and 8. \square

5.3 Range projection

We now have an l-XTOP^R M'' with rules R'' computing $\tau_{M''}(t, u) = L(t) \cdot \tau(t, u)$. In the final step, we simply disregard the input and project to the output. Formally, we want to construct a WTG G'' such that

$$L_{G''}(u) = \sum_{t \in T_\Sigma} \tau_{M''}(t, u) = \sum_{t \in T_\Sigma} L(t) \cdot \tau(t, u)$$

for every $u \in T_\Delta$. Let us suppose that \bar{G} is the WTG inside M'' . Recall that the *inside weight* of state $q \in Q$ is

$$\text{in}_{\bar{G}}(q) = \sum_{t \in T_\Sigma} \text{wt}_{\bar{G}}(q, t).$$

We construct the WTG

$$G'' = (S \cup S \times Q', \Delta, s_0, P'')$$

such that $\ell(\varepsilon) \xrightarrow{c} r'$ is in P'' for every rule $\ell \xrightarrow{\alpha} r \in R''$, where

$$c = a \cdot \prod_{x \in \text{var}(\ell) \setminus \text{var}(r)} \text{in}_{\bar{G}}(\mu(x))$$

and r' is obtained from r by removing the variables of X . If the same production is constructed from several rules, then we add the weights. Note that the WTG G'' can be effectively computed if $\text{in}_{\bar{G}}(q)$ is computable for every state q .

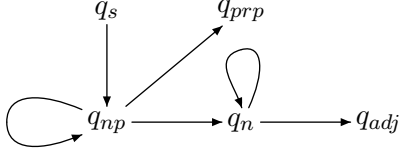


Figure 9: Dependency graph of the WTG G_{ex} .

Theorem 14. For every $u \in T_{\Delta}$, we have

$$L_{G''}(u) = \sum_{t \in T_{\Sigma}} L(t) \cdot \tau(t, u) = (\tau(L))(u) .$$

□

Example 15. The WTG productions for the rules of Figures 7 and 8 are

$$\begin{aligned} s_0 &\xrightarrow{0.4 \cdot 0.4} \mathbf{S}(\langle s_1, q_{np} \rangle, \mathbf{VP}(\langle s_3, q_v \rangle)) \\ s_0 &\xrightarrow{0.4 \cdot 0.6} \mathbf{S}(\langle s_1, q_{dt} \rangle, \mathbf{VP}(\langle s_3, q_v \rangle)) \\ \langle s_2, q_n \rangle &\xrightarrow{0.3 \cdot 0.3} \langle s_2, q_n \rangle \\ \langle s_1, q_{np} \rangle &\xrightarrow{0.5 \cdot 0.4} \langle s_1, q_{np} \rangle \\ \langle s_1, q_{np} \rangle &\xrightarrow{0.5 \cdot 0.6} \langle s_1, q_{dt} \rangle . \end{aligned}$$

Note that all inside weights are 1 in our example. The first production uses the inside weight of q_{pp} , whereas the second production uses the inside weight of q_n . Note that the third production can be constructed twice. □

6 Computation of inside weights

In this section, we address how to effectively compute the inside weight for every state. If the WTG $G = (Q, \Sigma, q_0, P)$ permits only finitely many derivations, then for every $q \in Q$, the inside weight $\text{in}_G(q)$ can be computed according to Definition 4 because $\text{wt}_G(q, t) = 0$ for almost all $t \in T_{\Sigma}$. If P contains (useful) recursive rules, then this approach does not work anymore. Our WTG G_{ex} of Example 2 has the following two recursive rules:

$$q_{np} \xrightarrow{0.4} \mathbf{NP}(q_{np}, \mathbf{PP}(q_{pp}, q_{np})) \quad (\rho_4)$$

$$q_n \xrightarrow{0.3} \mathbf{N}(q_{adj}, q_n) . \quad (\rho_5)$$

The dependency graph of G_{ex} , which is shown in Figure 9, has cycles, which yields that G_{ex} permits infinitely many derivations. Due to the completeness of the semiring, even the infinite sum of Definition 4 is well-defined, but we still have to compute it. We will present two simple methods to achieve this: (a) an analytic method and (b) an approximation in the next sections.

6.1 Analytic computation

In simple cases we can compute the inside weight using the stars a^* , which we defined in Section 2. Let us first list some interesting countably complete semirings for NLP applications and their corresponding stars.

- *Probabilities:* $(\mathbb{R}_{\geq 0}^{\infty}, +, \cdot, 0, 1)$ where $\mathbb{R}_{\geq 0}^{\infty}$ contains all nonnegative real numbers and ∞ , which is bigger than every real number. For every $a \in \mathbb{R}_{\geq 0}^{\infty}$ we have

$$a^* = \begin{cases} \frac{1}{1-a} & \text{if } 0 \leq a < 1 \\ \infty & \text{otherwise} \end{cases}$$

- *VITERBI:* $([0, 1], \max, \cdot, 0, 1)$ where $[0, 1]$ is the (inclusive) interval of real numbers between 0 and 1. For every $0 \leq a \leq 1$ we have $a^* = 1$.
- *Tropical:* $(\mathbb{R}_{\geq 0}^{\infty}, \min, +, \infty, 0)$ where $a^* = 0$ for every $a \in \mathbb{R}_{\geq 0}^{\infty}$.
- *Tree unification:* $(2^{T_{\Sigma}(X_1)}, \cup, \sqcup, \emptyset, \{x_1\})$ where $2^{T_{\Sigma}(X_1)} = \{L \mid L \subseteq T_{\Sigma}(X_1)\}$ and \sqcup is unification (where different occurrences of x_1 can be replaced differently) extended to sets as usual. For every $L \subseteq T_{\Sigma}(X_k)$ we have $L^* = \{x_1\} \cup (L \sqcup L)$.

We can always try to develop a regular expression (Fülöp and Vogler, 2009) for the weighted forest recognized by a certain state, in which we then can drop the actual trees and only compute with the weights. This is particularly easy if our WTG has only left- or right-recursive productions because in this case we obtain classical regular expressions (for strings). Let us consider production ρ_5 . It is right-recursive. On the string level, we obtain the following unweighted regular expression for the string language generated by q_n :

$$L(q_{adj})^*(\text{man} \mid \text{hill} \mid \text{telescope})$$

where $L(q_{adj}) = \{\text{old}, \text{young}\}$ is the set of strings generated by q_{adj} . Correspondingly, we can derive the inside weight by replacing the generated string with the weights used to derive them. For example, the production ρ_5 , which generates the state q_{adj} , has weight 0.3. We obtain the expression

$$\text{in}_G(q_n) = (0.3 \cdot \text{in}_G(q_{adj}))^* \cdot (0.3 + 0.2 + 0.2) .$$

Example 16. If we calculate in the probability semiring and $\text{in}_G(q_{adj}) = 1$, then

$$\text{in}_G(q_n) = \frac{1}{1 - 0.3} \cdot (0.3 + 0.2 + 0.2) = 1 ,$$

as expected (since our productions induce a probability distribution on all trees generated from each state). \square

Example 17. If we calculate in the *tropical semiring*, then we obtain

$$\text{in}_G(q_n) = \min(0.3, 0.2, 0.2) = 0.2 . \quad \square$$

It should be stressed that this method only allows us to compute $\text{in}_G(q)$ in very simple cases (e.g., WTG containing only left- or right-recursive productions). The production ρ_4 has a more complicated recursion, so this simple method cannot be used for our full example WTG.

However, for extremal semirings the inside weight always coincides with a particular derivation. Let us also recall this result. The semiring is *extremal* if $a + a' \in \{a, a'\}$ for all $a, a' \in A$. The VITERBI and the tropical semiring are extremal. Recall that

$$\begin{aligned} \text{in}_G(q) &= \sum_{t \in T_\Sigma} \text{wt}_G(q, t) \\ &= \sum_{t \in T_\Sigma} \sum_{\substack{\rho_1, \dots, \rho_n \in P \\ q \Rightarrow_G^{\rho_1} \dots \Rightarrow_G^{\rho_n} t}} \text{wt}_G(\rho_1 \cdots \rho_n) , \end{aligned}$$

which yields that $\text{in}_G(q)$ coincides with the derivation weight $\text{wt}_G(\rho_1 \cdots \rho_n)$ of some derivation $q \Rightarrow_G^{\rho_1} \cdots \Rightarrow_G^{\rho_n} t$ for some $t \in T_\Sigma$. In the VITERBI semiring this is the highest scoring derivation and in the tropical semiring it is the lowest scoring derivation (mind that in the VITERBI semiring the production weights are multiplied in a derivation, whereas they are added in the tropical semiring). There are efficient algorithms (Viterbi, 1967) that compute those derivations and their weights.

6.2 Numerical Approximation

Next, we show how to obtain a numerical approximation of the inside weights (up to any desired precision) in the probability semiring, which is the most important of all semirings discussed here. A similar approach was used by Stolcke (1995) for context-free grammars. To keep the presentation simple, let us suppose that

$G = (Q, \Sigma, q_0, P)$ is in normal form (see Theorem 5). The method works just as well in the general case.

We first observe an important property of the inside weights. For every state $q \in Q$

$$\text{in}_G(q) = \sum_{q \xrightarrow{\alpha} \sigma(q_1, \dots, q_n) \in P} a \cdot \text{in}_G(q_1) \cdot \dots \cdot \text{in}_G(q_n) ,$$

which can trivially be understood as a system of equations (where each $\text{in}_G(q)$ with $q \in Q$ is a variable). Since there is one such equation for each variable $\text{in}_G(q)$ with $q \in Q$, we have a system of $|Q|$ non-linear polynomial equations in $|Q|$ variables.

Several methods to solve non-linear systems of equations are known in the numerical calculus literature. For example, the NEWTON-RAPHSON method allows us to iteratively compute the roots of any differentiable real-valued function, which can be used to solve our system of equations because we can compute the JACOBI matrix for our system of equations easily. Given a good starting point, the NEWTON-RAPHSON method assures quadratic convergence to a root. A good starting point can be obtained, for example, by bisection (Corliss, 1977). Another popular root-finding approximation is described by Brent (1973).

Example 18. For the WTG of Example 2 we obtain the following system of equations:

$$\begin{aligned} \text{in}_G(q_s) &= 1.0 \cdot \text{in}_G(q_{np}) \\ \text{in}_G(q_{np}) &= 0.4 \cdot \text{in}_G(q_{np}) \cdot \text{in}_G(q_{prp}) \cdot \text{in}_G(q_{np}) \\ &\quad + 0.6 \cdot \text{in}_G(q_n) \\ \text{in}_G(q_n) &= 0.3 \cdot \text{in}_G(q_{adj}) \cdot \text{in}_G(q_n) \\ &\quad + 0.3 + 0.2 + 0.2 \\ \text{in}_G(q_{adj}) &= 0.5 + 0.5 \\ \text{in}_G(q_{prp}) &= 0.5 + 0.5 . \end{aligned}$$

Together with $\text{in}_G(q_n) = 1$, which we already calculated in Example 16, the only interesting value is

$$\text{in}_G(q_s) = \text{in}_G(q_{np}) = 0.4 \cdot \text{in}_G(q_{np})^2 + 0.6 ,$$

which yields the roots $\text{in}_G(q_{np}) = 1$ and $\text{in}_G(q_{np}) = 1.5$. The former is the desired solution. As before, this is the expected solution. \square

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