



Improving a Neural Semantic Parser by Counterfactual Learning from Human Bandit Feedback

Carolyn Lawrence, Stefan Riezler

Heidelberg University
Institute for Computational Linguistics

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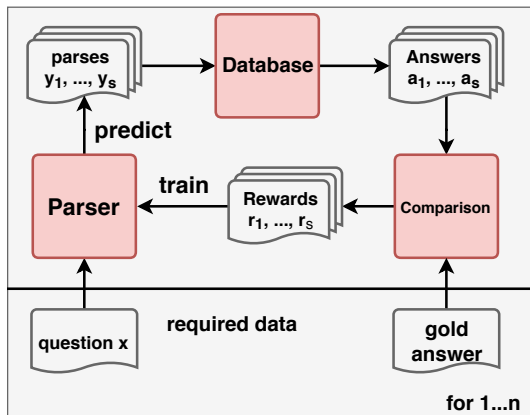
Situation Overview

- ▶ Situation: deployed system (e.g. QA, MT ...)
- ▶ Goal: improve system using **human feedback**
- ▶ Plan: create a log \mathcal{D}_{log} of user-system interactions & improve system offline (safety)

Here: Improve a Neural Semantic Parser

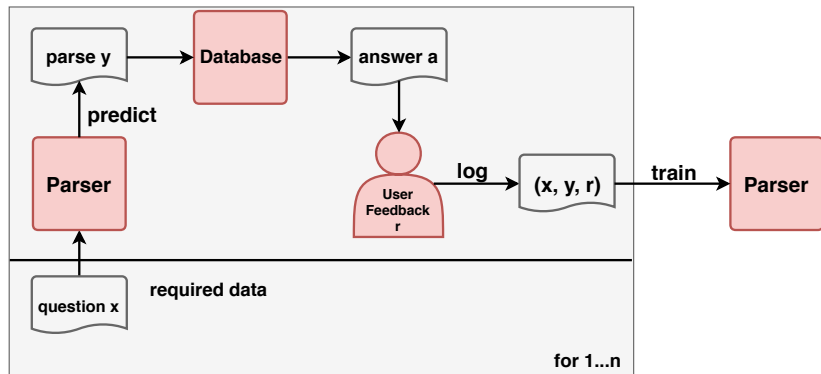


Contrast to Previous Approaches



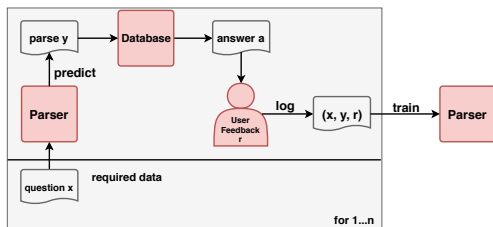
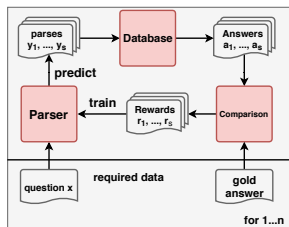


Our Approach





Our Approach



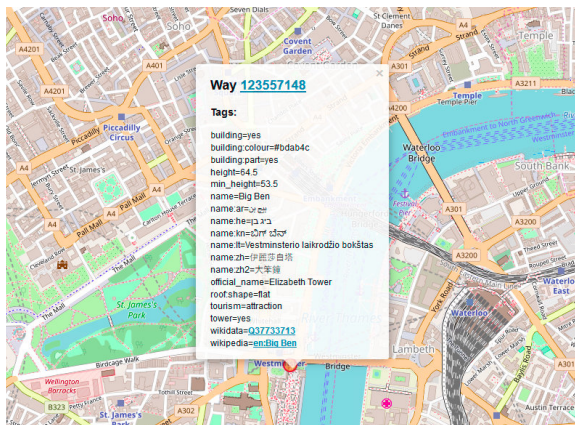
- ▶ No supervision: given an input, the gold output is unknown
- ▶ Bandit: feedback is given for only one system output
- ▶ Bias: $\log \mathcal{D}$ is biased to the decisions of the deployed system

Solution: Counterfactual / Off-policy Reinforcement Learning

Task

A natural language interface to OpenStreetMap

- ▶ OpenStreetMap (OSM): geographical database
- ▶ NLMAPS v2: extension of the previous corpus, now totalling 28,609 question-parse pairs





A natural language interface to OpenStreetMap

- ▶ example question: *"How many hotels are there in Paris?"*
Answer: 951
- ▶ correctness of answers are difficult to judge
→ judge parses by making them human-understandable
- ▶ feedback collection setup:
 1. automatically convert a parse to a set of statements
 2. humans judge the statements



Example: Feedback Formula

Question #216: **What are the names of cinemas that are within walking distance from the Place de la République in Paris?**

		Information found in Question?
Town	Paris	<input checked="" type="checkbox"/> Yes <input type="checkbox"/> No
Reference Point	name : Place de la République	<input checked="" type="checkbox"/> Yes <input type="checkbox"/> No
POI(s)	amenity : parking	<input type="checkbox"/> Yes <input checked="" type="checkbox"/> No
Question Type	What's the name	<input checked="" type="checkbox"/> Yes <input type="checkbox"/> No
Proximity	Around/Near	<input checked="" type="checkbox"/> Yes <input type="checkbox"/> No
Distance	Walking distance	<input checked="" type="checkbox"/> Yes <input type="checkbox"/> No

```
query(around(center(area(keyval('name','Paris')), nwr(keyval('name','Place de la République'))),
search(nwr(keyval('amenity','parking')), maxdist(WALKING_DIST)),qtype(fndkey('name')))
```

Objectives



Counterfactual Learning

RESOURCES

collected log $\mathcal{D}_{log} = \{(x_t, y_t, \delta_t)\}_{t=1}^n$ with

- ▶ x_t : input
- ▶ y_t : most likely output of deployed system π_0
- ▶ $\delta_t \in [-1, 0]$: loss (i.e. negative reward) received from user

DETERMINISTIC PROPENSITY MATCHING (DPM)

- ▶ minimize the expected risk for a target policy π_w

$$\hat{R}_{\text{DPM}}(\pi_w) = \frac{1}{n} \sum_{t=1}^n \delta_t \pi_w(y_t | x_t)$$

- ▶ improve π_w using (stochastic) gradient descent
- ▶ high variance \rightarrow use multiplicative control variate



Multiplicative Control Variate

- ▶ for random variables X and Y , with \bar{Y} the expectation of Y :

$$\mathbb{E}[X] = \mathbb{E}\left[\frac{X}{Y}\right] \cdot \bar{Y}$$

→ RHS has lower variance if Y positively correlates with X

DPM WITH REWEIGHTING (DPM+R)

$$\hat{R}_{\text{DPM+R}}(\pi_w) = \frac{\frac{1}{n} \sum_{t=1}^n \delta_t \pi_w(y_t | x_t)}{\frac{1}{n} \sum_{t=1}^n \pi_w(y_t | x_t)} \cdot 1 \quad \text{Reweight Sum } R$$

- ▶ reduces variance but introduces a bias of order $O(\frac{1}{n})$ that decreases as n increases
 - n should be as large as possible
- ▶ Problem: in stochastic minibatch learning, n is too small



One-Step Late (OSL) Reweighting

Perform gradient descent updates & reweighting asynchronously

- ▶ evaluate reweight sum R on the entire log of size n using parameters w'
- ▶ update using minibatches of size m , $m \ll n$
- ▶ periodically update R

→ retains all desirable properties

DPM+OSL

$$\hat{R}_{\text{DPM+OSL}}(\pi_w) = \frac{\frac{1}{m} \sum_{t=1}^m \delta_t \pi_w(y_t | x_t)}{\frac{1}{n} \sum_{t=1}^n \pi_{w'}(y_t | x_t)}$$



Token-Level Feedback

DPM+T

$$\hat{R}_{\text{DPM+T}}(\pi_w) = \frac{1}{n} \sum_{t=1}^n \left(\prod_{j=1}^{|y_t|} \delta_j \pi_w(y_j | x_t) \right)$$

DPM+T+OSL

$$\hat{R}_{\text{DPM+T+OSL}}(\pi_w) = \frac{\frac{1}{m} \sum_{t=1}^m \left(\prod_{j=1}^{|y_t|} \delta_j \pi_w(y_j | x_t) \right)}{\frac{1}{n} \sum_{t=1}^n \pi_{w'}(y_t | x_t)}$$

Experiments

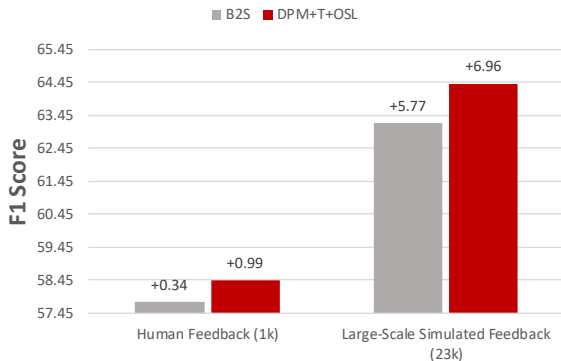


Experimental Setup

- ▶ sequence-to-sequence neural network NEMATUS
- ▶ deployed system: pre-trained on 2k question-parse pairs
- ▶ feedback collection:
 1. humans judged 1k system outputs
 - ▶ average time to judge a parse: 16.4s
 - ▶ most parses (>70%) judged in <10s
 2. simulated feedback for 23k system outputs
 - ▶ token-wise comparison to gold parse
- ▶ bandit-to-supervised conversion (B2S): all instances in log with reward 1 are used as supervised training



Experimental Results





Take Away

COUNTERFACTUAL LEARNING

- ▶ safely improve a system by collecting interaction logs
- ▶ applicable to any task if the underlying model is differentiable
- ▶ DPM+OSL: new objective for stochastic minibatch learning

IMPROVING A SEMANTIC PARSER

- ▶ collect feedback by making parses human-understandable
- ▶ judging a parse is often easier & faster than formulating a parse or answer

NLMAPS v2

- ▶ large question-parse corpus for QA in the geographical domain

FUTURE WORK

- ▶ integrate feedback form in the online NL interface to OSM