

# Pay Attention to the Ending: Strong Neural Baselines for the ROC Story Cloze Task

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## Abstract

We consider the ROC story cloze task (Mostafazadeh et al., 2016) and present several findings. We develop a model that uses hierarchical recurrent networks with attention to encode the sentences in the story and score candidate endings. By discarding the large training set and only training on the validation set, we achieve an accuracy of 74.7%. Even when we discard the story plots (sentences before the ending) and only train to choose the better of two endings, we can still reach 72.5%. We then analyze this “ending-only” task setting. We estimate human accuracy to be 78% and find several types of clues that lead to this high accuracy, including those related to sentiment, negation, and general ending likelihood regardless of the story context.

## 1 Introduction

The ROC story cloze task (Mostafazadeh et al., 2016) tests a system’s ability to choose the more plausible of two endings to a story. The incorrect ending is written to still fit the world of the story, e.g., the protagonist typically appears in both endings. The task is designed to test for “common-sense” knowledge, where the difference between the two endings lies in the plausibility of the characters’ actions. The best system of Mostafazadeh et al. (2016) achieves 58.5% accuracy.

The ROC training and evaluation data differ in a key way. The training set contains 5-sentence stories. But the evaluation datasets (the validation and test sets) contain both a correct ending and an incorrect ending. This means that the task is one of outlier detection: systems must estimate the density of correct endings in the training data and

then detect which of the two endings is an outlier. This becomes difficult when the evaluation contains distractors that are still somewhat plausible. For example, a model may place mass on stories that consistently mention the same characters, but this will not be useful for the task because even the incorrect ending uses the correct character names.

In this paper, we discard the 50k training stories and train only on the 1871-story validation set. We develop several neural models based on recurrent networks, comparing flat and hierarchical models for encoding the sentences in the story. We also use an attention mechanism based on the ending to identify useful parts of the plot. Our final model achieves 74.7% on the test set, outperforming all systems of Mostafazadeh et al. (2016) and approaching the state of the art results of concurrent work (Schwartz et al., 2017b).

We then discard the first four sentences of each story and use our model to score endings alone. We achieve 72.5% on the test set, outperforming most prior work without even looking at the story plots. We do a small-scale manual study of this ending-only task, finding that humans can identify the better ending in approximately 78% of cases. We report several reasons for the high accuracy of this ending-only setting, including some that are readily captured by automatic methods, such as sentiment analysis and the presence of negation words, as well as others that are more difficult, like those derived from world knowledge. Our results and analysis, combined with the similar concurrent observations of Schwartz et al. (2017a), suggest that any meaningful system for the ROC task must outperform the best ending-only baselines.

## 2 Task and Datasets

We refer to a 5-sentence sequence as a **story**, the incomplete 4-sentence sequence as a **plot**, and the

fifth sentence as an **ending**. The ROC story corpus (Mostafazadeh et al., 2016) contains training, validation, and test sets. The training set contains 5-sentence stories. The validation and test sets contain 4-sentence plots followed by two candidate endings, with only one correct.

Mostafazadeh et al. (2016) evaluated several methods for solving the task. Since the training set does not contain incorrect endings, their methods are based on computing similarity between the plot and ending. Their best results were obtained with the Deep Structured Semantic Model (DSSM) (Huang et al., 2013) which represents texts using character trigram counts followed by neural network layers and a similarity function.

Concurrently with our work, the LSDSem 2017 shared task was held (Mostafazadeh et al., 2017), focusing on the ROC story cloze task. Several of the participants made similar observations to what we describe here, namely that supervised learning on the validation set is more effective than learning directly from the training set, as well as noting certain biases in the endings (Schwartz et al., 2017a,b; Bugert et al., 2017; Flor and Somasundaran, 2017; Schenk and Chiarcos, 2017; Roemmele et al., 2017; Goel and Singh, 2017; Mihaylov and Frank, 2017).

### 3 Models and Training

We now describe our model variations. The first (ENC PLOT END) encodes the plot and ending separately, then scores them with a scoring function. The second (ENC STORY) concatenates the plot and ending to form a story, then encodes that story and scores its representation with a scoring function. When encoding a sequence of multiple sentences, whether with ENC PLOT END or ENC STORY, we consider two choices: a hierarchical encoder (HIER) that first encodes each sentence and then encodes the sentence representations, and a non-hierarchical encoder (FLAT) that simply encodes the concatenation of all sentences. We also consider the possibility of including an ending-oriented attention mechanism (ATT). For training, we use a simple supervised hinge loss objective.

#### 3.1 Encoders

Our encoders encode text sequences into representations. When using our HIER model, we use a hierarchical recurrent neural network (RNN) (Li et al., 2015) with two levels. The first RNN en-

codes the sequence of words in a sentence; the same RNN is used for sentences in the plot and for each candidate ending. The second RNN encodes the sequence of sentence representations in a plot or story. When using our FLAT model, we only use the first RNN described above; the only change is that the input becomes the concatenation of multiple sentences (separated by sentence boundary tokens).

Below we use  $i$  as a subscript to index sentences in the story or plot, and  $j$  as a superscript to index individual words in sentences. E.g., we use  $w_i$  to indicate the  $i$ th sentence of the story/plot and we use  $w_i^{(j)}$  to denote the word embedding vector of the  $j$ th word in the  $i$ th sentence.

##### 3.1.1 Encoding Word Sequences

We use a bidirectional long short-term memory (BiLSTM) RNN (Hochreiter and Schmidhuber, 1997) to encode a sentence. For sentence  $w_i$ :

$$\begin{aligned} f_i &= \text{forward-LSTM}_1(w_i) \\ b_i &= \text{backward-LSTM}_1(w_i) \end{aligned}$$

where  $f_i$  and  $b_i$  are hidden vector sequences. We add the forward and backward vectors at each step to obtain vectors  $h_i$ , then average to obtain sentence representation  $S_i$ :

$$h_i = f_i + b_i \quad S_i = \frac{1}{|w_i|} \sum_{j=1}^{|w_i|} h_i^{(j)} \quad (1)$$

We define this function from word sequence  $w_i$  to sentence representation  $S_i$  by ENC WORDS( $w_i$ ).

##### 3.1.2 Adding Attention

Attention mechanisms (Bahdanau et al., 2015; Mnih et al., 2014) have yielded considerable performance gains for machine comprehension (Hermann et al., 2015; Sukhbaatar et al., 2015; Chen et al., 2016), parsing (Vinyals et al., 2015), and machine translation (Luong et al., 2015).

After generating the representation  $e = S_5 = \text{ENC WORDS}(w_5)$  for candidate ending  $w_5$ , we use it to compute the attention over the individual hidden vectors of each sentence to compute modified sentence representations  $S_i^\dagger$ . That is:

$$\begin{aligned} \alpha_i^{(j)} &= e^\top M h_i^{(j)} & \beta_i^{(j)} &\propto \exp\{\alpha_i^{(j)}\} \\ S_i^\dagger &= \sum_{j=1}^{|w_i|} \beta_i^{(j)} h_i^{(j)} \end{aligned} \quad (2)$$

where  $h_i^{(j)}$  is the  $j$ th entry of  $h_i$  and  $M$  is a bilinear attention matrix.<sup>1</sup> Figure 1 shows this architecture. We define this attention-augmented encoder as  $\text{ATTENCWORDS}(w_i, e)$ .

### 3.1.3 Encoding Sentence Sequences

We use another BiLSTM to encode the sequence  $S$  of sentence representations  $S_i$ :

$$\begin{aligned} F &= \text{forward-LSTM}_2(S) \\ B &= \text{backward-LSTM}_2(S) \\ \text{ENCSENTS}(S) &= F_{-1} + B_{-1} \end{aligned}$$

where  $F_{-1}$  is the final hidden vector in  $F$ . We also use this encoder to encode the ending  $e$  by treating it as a sequence containing only one element.

## 3.2 Model Variations

Given our encoders, we now define the final representations  $D$  for our modeling variations, combining each of HIER and FLAT with each of ENC-STORY and ENCPLOTEND:

$$\begin{aligned} w_1^k &= \langle w_1, \dots, w_{k-1}, w_k \rangle & S_1^k &= \langle S_1, \dots, S_k \rangle \\ D_{\text{FLATS}} &= \text{ENCWORDS}(w_1^5) \\ S_i &= \text{ENCWORDS}(w_i) \\ D_{\text{FLATPE}} &= \langle \text{ENCWORDS}(w_1^4), S_5 \rangle \\ D_{\text{HIER}} &= \text{ENCSENTS}(S_1^5) \\ D_{\text{HIERPE}} &= \langle \text{ENCSENTS}(S_1^4), \text{ENCSENTS}(S_5) \rangle \end{aligned}$$

When using attention, we replace  $\text{ENCWORDS}$  above with  $\text{ATTENCWORDS}$ .

After encoding the story as  $D$ , we use a feed-forward network to act as a score function that takes  $D$  as input and generates a one-dimensional (scalar) output. We use  $\tanh$  as the activation function on each layer of the feed-forward network and tune the numbers of hidden layers and the layer widths.

## 3.3 Training

Since we are training on the validation set which contains both correct and incorrect endings, we minimize the following hinge loss:

$$L = \max(0, -\text{score}(D^+) + \text{score}(D^-) + \delta)$$

where  $D^+$  is the representation of the correct story,  $D^-$  is the representation of the incorrect story, and  $\delta = 1$  is the margin.

<sup>1</sup>In preliminary experiments we found bilinear attention to work better than attention based on cosine similarity.

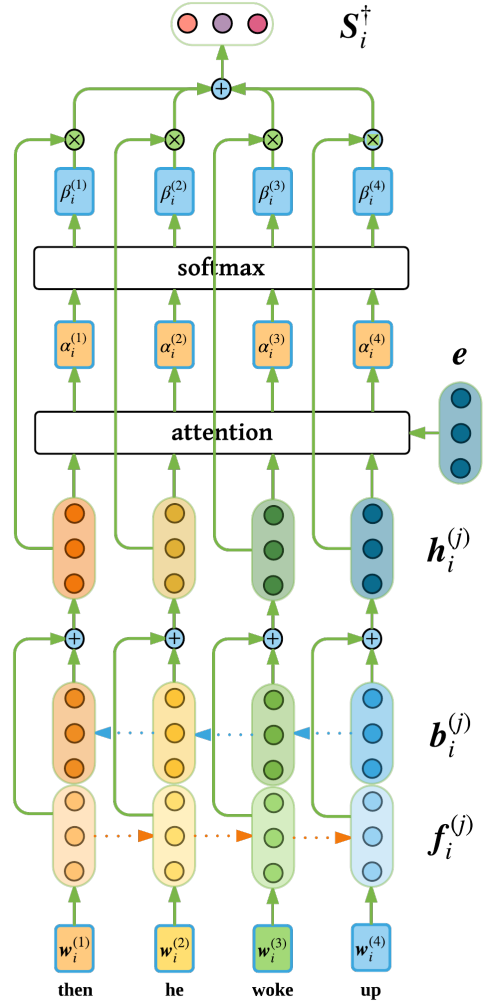


Figure 1: Attention-augmented BiLSTM for encoding a 4-word sentence  $w_i$  into a 3-dimensional representation  $S_i^\dagger$ . The attention function uses the ending representation  $e$ .

## 4 Experimental Setup

We shuffle and split the validation set into 5 folds and do 5-fold cross validation. For modeling decisions, we tune based on the average accuracy of the held-out folds. For final experiments, we choose the fold with the best held-out accuracy and report its test set accuracy. We use Adam (Kingma and Ba, 2015) for optimization with learning rate 0.001 and mini-batch size 50. We use pretrained 300-dimensional GloVe embeddings trained on Wikipedia and Gigaword (Pennington et al., 2014) and keep them fixed during training. We use  $L_2$  regularization for the score feed-forward network, which has a single hidden layer of size 512. We use 300 for the LSTM hidden vector dimensionality for both encoders.

	FLAT	HIER
ENCSTORY	79.08	80.22
ENC PLOTEND	71.75	79.84

Table 1: Accuracies (%) averaged over held-out folds of 5-fold cross validation. Comparing hierarchical (HIER) and non-hierarchical (FLAT) encoders, and encoding story (ENCSTORY) vs. separately encoding plot and ending (ENC PLOTEND). No attention is used.

	-ATT	+ATT
ENCSTORY	80.22	79.95
ENC PLOTEND	79.84	81.24

Table 2: For the ENCSTORY and ENC PLOTEND models, showing the contribution of adding attention (+ATT). All models use the HIER encoder.

## 5 Results

**Modeling Decisions.** We first evaluate our modeling decisions, using the averaged held-out fold accuracy as our model selection criterion. Table 1 shows results when comparing FLAT/HIER and ENCSTORY/ENC PLOTEND. Hierarchical modeling helps especially with ENC PLOTEND.

Table 2 shows the contribution of attention when using HIER. Attention helps when separately encoding the plot and ending, but not when encoding the entire story. We suspect this is because when we use ENCSTORY, the higher BiLSTM processes the sequence  $\langle \mathcal{S}_1^\dagger, \mathcal{S}_2^\dagger, \mathcal{S}_3^\dagger, \mathcal{S}_4^\dagger, \mathcal{S}_5 \rangle$ . That is, the first four sentence representations are in a different space from the ending due to the use of attention.

**Final Results.** Table 3 shows final results. We report the best result from Mostafazadeh et al. (2016), the best result from the concurrently-held LSDSem shared task (Schwartz et al., 2017b), and our final system configuration (with decisions tuned via cross validation as shown in Tables 1-2, then using the model with the best held-out fold accuracy). Our model achieves 74.7%, which is close to the state of the art result of 75.2%.<sup>2</sup>

We also report the results of stripping away the plots and running our system on just the endings (“ending only”). We use the FLAT BiLSTM model on the ending followed by the feed-forward scoring function, using the same loss as above for training. We again use 5-fold cross validation

<sup>2</sup>We also tried to train the DSSM on the validation set, but were unable to approach the performance of our model. The DSSM appears to benefit greatly from the training set.

	val	test
DSSM <sup>‡</sup>	60.4	58.5
UW (Schwartz et al., 2017b)	-	75.2
UW (ending only)	-	72.4
trigram LM (estimated from stories)	52.4	53.6
trigram LM (estimated from endings)	53.8	54.6
Our model (HIER, ENC PLOTEND, ATT)	-	74.7
Our model (ending only)	-	72.5
Human <sup>‡</sup> (story + ending)	100	100
Human (ending only)	78*	-

Table 3: Final results. \* = estimate from 100; see Section 6.1. † = from Mostafazadeh et al. (2016).

on the validation set and choose the model with the highest held-out fold accuracy. We achieve 72.5%, matching the similar ending-only result of Schwartz et al. (2017b). We estimate human performance in the ending-only setting to be 78%. We provide more details in Section 6.1. These results suggest that the dataset contains systematic biases in the composition of its endings and that any meaningful system for the task must outperform the best ending-only baseline.

We also report the results of two  $n$ -gram language model baselines. We estimated trigram models using KenLM (Heafield, 2011) from two different datasets: (1) the entire training stories, and (2) only the endings from the training stories. Using only the endings works better, even though it uses one fifth of the data; this further shows the importance of focusing on endings for this task.

## 6 Analysis

We analyze the attention weights in our final model. Figure 2 shows the distribution of attention weights over position bins, aggregated over the plot sentences in the test set. We find that the attentions generated by the correct ending show higher weight for words early in the sentences, while the attentions for incorrect endings are higher at the ends of the sentences.

We also study the ending-only task to uncover the different kinds of bias that lead to high accuracies in this setting. We consider automatic features that can be computed on the endings and evaluate the accuracy of relying solely upon each feature as a classification rule. We then compute correlations between our ending-only model and each feature. In addition to the trigram model described above, we consider the following rules:

- **sentiment:** choose ending with higher predicted sentiment score from the Stanford sentiment an-

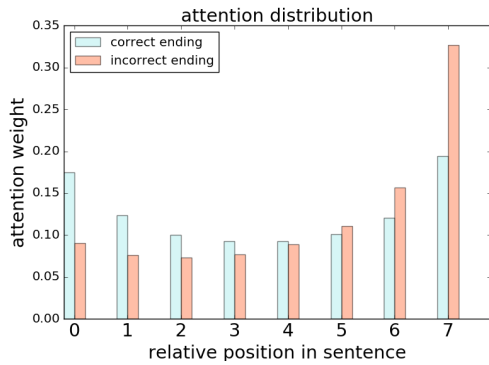


Figure 2: Attention weight distribution in test set plot sentences. Sentences were divided into eighths, then attention weights were averaged for each and normalized. For correct endings, there is more attention on early words in plot sentences.

rule	rule applicability	test accuracy	Spearman correlation
sentiment	65.9%	58.7%	0.214
negation words	20.7%	55.4%	-
length	100%	53.2%	0.047
language model	100%	54.6%	0.135

Table 4: Ending selection rules exhibiting biases in endings. Final column shows correlation between each feature and the score of our model.

alyzer (Socher et al., 2013).

- **negation:** choose ending with fewer words from  $\{not, neither, nor, never, n't, no, rarely\}$ .
- **length:** choose the longer ending.

Table 4 shows the results. Each rule yields accuracy at least 53%, with the sentiment rule nearing 59%. Even though the negation rule is only applicable in 20% of cases, its bias is strong enough to yield 5% improvement over the random baseline. These results show several reasons why an ending-only model can perform well, and suggests that our model may be identifying positive sentiment, due to its correlation of 0.214 with that feature.

We counted words in the correct and incorrect endings and in Table 5 we show some that differ between the top-50 lists for each category. E.g., “never” appears among the top 50 words in incorrect endings but not correct endings. The word count differences are accordant with the results from the sentiment and negation word rules, with non-overlapping words showing significant sentiment difference and that correct endings are more neutral or positive than incorrect ones.

correct endings:	out, !, great, new, found
incorrect endings:	n’t, did, not, never, hated

Table 5: Non-overlapping words in the top 50 most frequent word list of each category.

## 6.1 Human Ending-Only Performance

In order to assess human performance, we randomly chose 100 ending pairs from the validation set and gave them to a human annotator, a native speaker of English who is familiar with the ROC task. The annotator was asked to select the more likely ending based only on the two endings provided. He was correct on 78, observing several kinds of cues in the endings alone in addition to those mentioned above.

In some cases, one ending sentence is simply much more likely than the other based on world knowledge. For example, the ending “the glasses fixed his headaches immediately” is much more likely than “the optometrist gave him comfortable sneakers”. It is possible that the plot could change the preferred ending to the second, but this appears to be rare in the ROC dataset. In another example, “I practice all the time now” is more likely than “I hope I drop the batons” because it seems unlikely that anyone would ever hope to drop batons in the surmised world of the story. While these instances still test for a kind of “commonsense” or “world” knowledge, they do not require the plot to answer.

## 7 Conclusions and Future Work

Our models use none of the ROC training data but achieve strong performance, even when discarding the story plots. We uncovered several sources of bias in the endings that make the ending-only task solvable with greater than 70% accuracy. Our results suggest that any meaningful system for the ROC story cloze task should perform better than the best ending-only system. In future work, we will experiment with additional modeling choices, including adding attention to the higher BiLSTM and adding a decoder and a multi-task objective during training to improve stability.

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