

Zero-shot Cross-lingual Conversational Semantic Role Labeling

Han Wu^{1,2}, Haochen Tan^{1,2}, Kun Xu^{3†}, Shuqi Liu^{1,2}, Lianwei Wu⁴, Linqi Song^{1,2*}

¹City University of Hong Kong Shenzhen Research Institute

²Department of Computer Science, City University of Hong Kong, ³Huawei

⁴Laboratory for Integrated Aero-Space-Ground-Ocean Big Data Application Technology,

School of Computer Science, Northwestern Polytechnical University

{hanwu32-c, haochetan-2, shuqiliu-4}@my.cityu.edu.hk

syxu828@gmail.com, wlw@nwpu.edu.cn

linqi.song@cityu.edu.hk

Abstract

While conversational semantic role labeling (CSRL) has shown its usefulness on Chinese conversational tasks, it is still under-explored in non-Chinese languages due to the lack of multilingual CSRL annotations for the parser training. To avoid expensive data collection and error-propagation of translation-based methods, we present a simple but effective approach to perform zero-shot cross-lingual CSRL. Our model implicitly learns language-agnostic, conversational structure-aware and semantically rich representations with the hierarchical encoders and elaborately designed pre-training objectives. Experimental results show that our model outperforms all baselines by large margins on two newly collected English CSRL test sets. More importantly, we confirm the usefulness of CSRL to non-Chinese conversational tasks such as the question-in-context rewriting task in English and the multi-turn dialogue response generation tasks in English, German and Japanese by incorporating the CSRL information into the downstream conversation-based models. We believe this finding is significant and will facilitate the research of non-Chinese dialogue tasks which suffer the problems of ellipsis and anaphora.

1 Introduction

Conversational Semantic Role Labeling (CSRL) (Xu et al., 2021) is a recently proposed dialogue understanding task, which aims to extract predicate-argument pairs from the entire conversation. Figure 1 illustrates a CSRL example where a CSRL parser is required to identify “《泰坦尼克号》(Titanic)” as the ARG1 argument of the predicate “看过 (watched)” and the ARG0 argument of the predicate “是 (is)”. We can see that in the original conversation, “《泰坦尼克号》(Titanic)” is omitted in the second turn and referred as “这 (this)” in the

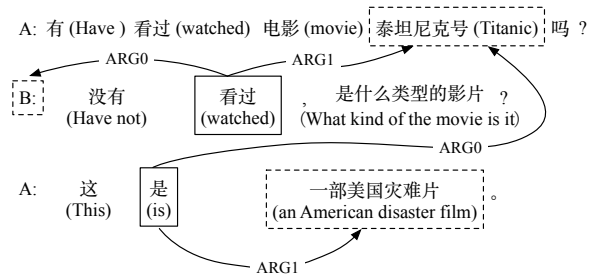


Figure 1: An example of CSRL parsing.

last turn. By recovering the dropped and referred components in conversation, CSRL has shown its usefulness to a set of Chinese dialogue tasks, including multi-turn dialogue rewriting (Su et al., 2019) and response generation (Wu et al., 2019). However, there remains a paucity of evidence on its effectiveness towards non-Chinese languages owing to the lack of multilingual CSRL models. To adapt a model into new languages, previous solutions can be divided into three categories: 1) manually annotating a new dataset in the target language (Daza and Frank, 2020) 2) borrowing machine translation and word alignment techniques to transfer the dataset from the source language into the target language (Daza and Frank, 2019; Fei et al., 2020a) 3) zero-shot transfer learning with multilingual pre-trained language model (Rijhwani et al., 2019; Sherborne and Lapata, 2021). Due to the fact that manually collecting annotations is costly and translation-based methods might introduce translation or word alignment errors, zero-shot cross-lingual transfer learning is more practical to the NLP community.

Recent works have witnessed prominent performances of multilingual pre-trained language models (PrLMs) (Devlin et al., 2019; Conneau et al., 2020) on cross-lingual tasks, including machine translation (Lin et al., 2020; Chen et al., 2021), semantic role labeling (SRL) (Conia and Navigli, 2020; Conia et al., 2021) and semantic parsing (Fei et al., 2020b; Sherborne and Lapata, 2021). How-

[†] Work done when Kun Xu was in Tencent AI Lab.

* Corresponding author.

ever, cross-lingual CSRL, as a combination of three challenging tasks (i.e., cross-lingual task, dialogue task and SRL task), suffers three outstanding difficulties: 1) **latent space alignment** - how to map word representations of different languages into an overlapping space; 2) **conversation structure encoding** - how to capture high-level dialogue features such as speaker dependency and temporal dependency; and 3) **semantic arguments identification** - how to highlight the relations between the predicate and its arguments, wherein PrLMs can only partially encode multilingual inputs to an overlapping vector space. Although there are some success that can separately achieve structural conversation encoding (Mehri et al., 2019; Zhang and Zhao, 2021) and semantic arguments identification (Wu et al., 2021a), a unified method for jointly solving these problems is still under-explored, especially in a cross-lingual scenario.

In this work, we summarize our contributions as follows: **(1)** We propose a simple but effective model which consists of three modules, namely cross-lingual language model (CLM), structure-aware conversation encoder (SA-Encoder) and predicate-argument encoder (PA-Encoder), and five well-designed pre-training objectives. Our model implicitly learns language-agnostic, conversational structure-aware and semantically rich representations to perform zero-shot cross-lingual CSRL. **(2)** Experiments show that our method achieves impressive cross-lingual performance on the language pair (Zh→En), and outperforms all baselines on the two newly collected English CSRL test sets. **(3)** We confirm the usefulness of CSRL to the question-in-context rewriting task in English and multi-turn response generation tasks in English, German and Japanese. We believe this finding is important and will facilitate the research of non-Chinese dialogue tasks that suffer from ellipsis and anaphora. **(4)** We release our code, the new annotated English CSRL test sets and checkpoints of our best models to facilitate the further research at <https://github.com/hahahawu/Zero-Shot-XCSRL>.

2 Related Work

Zero-shot cross-lingual transfer learning. Recently, thanks to the rapid development of multilingual pre-trained language models such as multilingual BERT (Devlin et al., 2019) and XLM-R (Conneau et al., 2020), a number of approaches have been proposed for zero-shot cross-lingual transfer

learning on various downstream tasks, including semantic parsing (Sherborne and Lapata, 2021), natural language generation (Shen et al., 2018) and understanding (Liu et al., 2019; Lauscher et al., 2020). In this work, we claim our method is zero-shot because no non-Chinese CSRL annotations are seen during the CSRL training stage. For decoding, we directly use the cross-lingual CSRL model trained on Chinese CSRL data to analyze conversations in other languages. To our best knowledge, our work is the first step to cross-lingual CSRL.

Conversational semantic role labeling. While ellipsis and anaphora frequently occur in dialogues, Xu et al. (2021) observed that most of the dropped or referred components can be found in dialogue histories. Following this observation, they proposed conversational semantic role labeling (CSRL) which required the model to find predicate-argument structures over the entire conversation instead of a single sentence. In this way, when analyzing a predicate in the latest utterance, a CSRL model needs to consider both the current turn and previous turns to search potential arguments, and thus might recover the omitted components. Furthermore, Xu et al. (2020, 2021) also confirmed the usefulness of CSRL to Chinese dialogue tasks by applying CSRL information into downstream dialogue tasks. However, there are still two main problems to be solved for CSRL task: (1) the performance of current state-of-the-art CSRL model (Xu et al., 2021) is still far from satisfactory due to the lack of high-level conversational and semantic features modeling; (2) the usefulness of CSRL to conversational tasks in non-Chinese languages has not been confirmed yet due to the lack of cross-lingual CSRL models. In this work, we primarily focus on the latter problem and propose a simple but effective model to perform cross-lingual CSRL. We would like to distinguish our work from the work (Wu et al., 2021b) which purely focuses on improving the monolingual CSRL performance where they try to model predicate-aware representations. This solution could benefit to monolingual CSRL task, but hurt the cross-lingual performance, because the relative positions of the predicates may differ from language to language.

3 Methodology

Following Xu et al. (2021), we solve the CSRL task as a sequence labeling problem. Formally, given a dialogue $C = \{u_1, u_2, \dots, u_N\}$ of N utter-

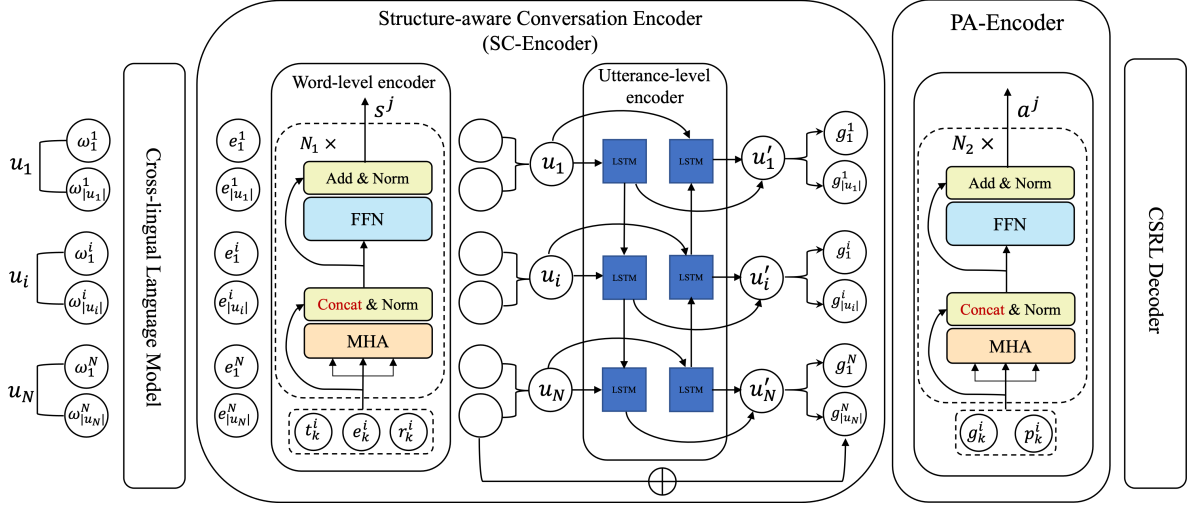


Figure 2: Overall model architecture.

ances, where $u_i = \{w_1^i, w_2^i, \dots, w_{|u_i|}^i\}$ consisting of a sequence of words, and a predicate indicator $p = (p_1^1, \dots, p_k^i, \dots, p_{|u_N|}^N)$ used to identify whether a word is the predicate or not, our goal is to assign each word with a semantic role label $l \in L$ where L is the label set. We also incorporate speaker role indicator r to distinguish speakers, and dialogue turn indicator t to distinguish dialogue turns.

3.1 Architecture

Cross-lingual Language Model (CLM) We concatenate all utterances into a sequence and then use a pre-trained cross-lingual language model such as XLM-R (Conneau et al., 2020) or mBERT (Devlin et al., 2019) to capture the syntactic and semantic characteristics. Following Conia et al. (2021), we obtain word representations $\mathbf{e} \in \mathbb{R}^{|S| \times d}$ by concatenating the hidden states of the four top-most layers of the language model, where $|S|$ is the sequence length and d is the dimension of the hidden state.

Structure-aware Conversation Encoder (SC-Encoder) Different from standard SRL (Carreras and Màrquez, 2005), CSRL requires the models to find arguments from not only the current turn, but also previous turns, thus bringing more challenges of dialogue modeling. To address this problem, we propose a universal structure-aware conversation encoder which comprises of two parts, i.e., word-level encoder and utterance-level encoder. Formally, with the speaker role embedding $\mathbf{r} \in \mathbb{R}^{|S| \times d}$ and dialogue turn embedding $\mathbf{t} \in \mathbb{R}^{|S| \times d}$, the word-level encoder computes a sequence of timestep en-

codings $\mathbf{s} \in \mathbb{R}^{|S| \times d}$ as follows:

$$\mathbf{s}_{(i,k)}^j = \begin{cases} \mathbf{e}_k^i \oplus \mathbf{t}_k^i \oplus \mathbf{r}_k^i & \text{if } j = 0 \\ \mathbf{s}_{(i,k)}^{j-1} \oplus \text{MTRANS}^j(\mathbf{s}_{(i,k)}^{j-1}) & \text{otherwise} \end{cases} \quad (1)$$

where $\mathbf{s}_{(i,k)}^j$ is the timestep encoding of k -th token in i -th utterance from j -th word-level encoder layer while $j \in (0, \dots, N_1)$, \oplus represents vector concatenation, and MTRANS is the **Modified Transformer** encoder layer. Concretely, we replace the [Add] operation in the first residual connection layer with [Concat] because we argue that concatenation is a superior approach to preserve the information from previous layers¹.

We obtain utterance representations $\mathbf{u} \in \mathbb{R}^{N \times d}$ by max-pooling over words in the same utterance. Then we pass the resulting utterance representations \mathbf{u} through a stack of Bi-LSTM (Hochreiter and Schmidhuber, 1997) layers to obtain the sequentially encoded utterance representations $\mathbf{u}' \in \mathbb{R}^{N \times d}$. Finally, we combine the utterance-level feature \mathbf{u}' with the word-level feature \mathbf{s} to obtain structure-aware dialogue context representations $\mathbf{g} \in \mathbb{R}^{|S| \times d}$ as follows:

$$\mathbf{g}_k^i = \text{Swish}(\mathbf{W}^g[\mathbf{s}_{(i,k)}^{N_1} \oplus \mathbf{u}'_i] + \mathbf{b}^g) \quad (2)$$

where $\text{Swish}(x) = x \cdot \text{sigmoid}(x)$ is a non-linear activation function, $\mathbf{s}_{(i,k)}^{N_1}$ is the encoding of k -th token in i -th utterance from the last layer of the word-level encoder. \mathbf{W}^g and \mathbf{b}^g are trainable parameters.

Predicate-Argument Encoder (PA-Encoder) We introduce the third module (i.e., predicate-argument encoder) whose goal is to capture the

¹More details about MTRANS in Appendix B.

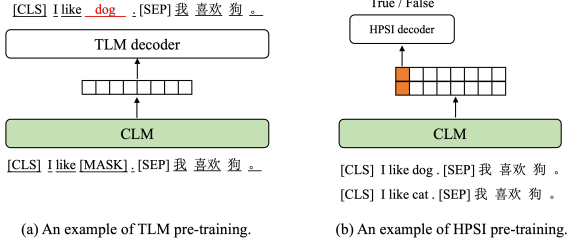


Figure 3: Illustration of pre-training objectives for latent space alignment.

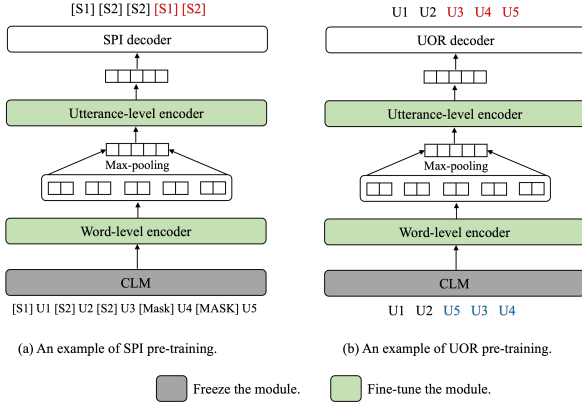


Figure 4: Illustration of pre-training objectives for conversation structure encoding.

relations between each predicate-argument couple that appears in the conversation. Similar with the word-level encoder, we use a stack of MTRANS layers to implement this encoder. Formally, with the predicate embedding $\mathbf{p} \in \mathbb{R}^{|S| \times d}$, the model calculates the predicate-specific argument encodings $\mathbf{a} \in \mathbb{R}^{|S| \times d}$ as follows:

$$\mathbf{a}_{(i,k)}^j = \begin{cases} \mathbf{g}_k^i \oplus \mathbf{p}_k^i & \text{if } j = 0 \\ \mathbf{a}_{(i,k)}^{j-1} \oplus \text{MTRANS}^j(\mathbf{a}_{(i,k)}^{j-1}) & \text{otherwise} \end{cases} \quad (3)$$

where $\mathbf{a}_{(i,k)}^j$ is the argument encoding of k -th token in i -th utterance from j -th encoder layer while $j \in (0, \dots, N_2)$. Finally, we obtain the semantic role encoding \mathbf{l} using the resulting argument encodings from the last layer of the predicate-argument encoder:

$$\mathbf{l}_k^i = \text{Swish}(\mathbf{W}^l \mathbf{a}_{(i,k)}^{N_2} + \mathbf{b}^l) \quad (4)$$

In particular, our proposed model is mostly language-agnostic since we do not explicitly introduce any language-specific knowledge such as word order, part-of-speech tags or dependent relations, and only introduce the predicate indicator that might contain some language-specific information in the semantic module, which would not affect latent space alignment and dialogue modeling.

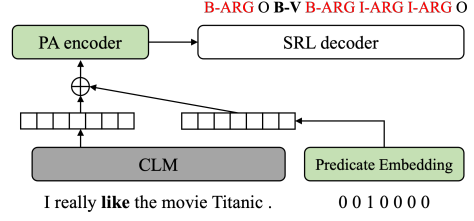


Figure 5: Illustration of pre-training objectives for semantic argument identification.

3.2 Pre-training Objectives

Besides the universal model, we also elaborately design five pre-training objectives to model task-specific but language-agnostic features for better cross-lingual performance. In this section, we divide our pre-training objectives into three groups according to the challenges to be solved.

Latent space alignment In cross-lingual language module, we use mBERT or XLM-R to align the latent space of different languages. Although mBERT and XLM-R have exhibited good alignment ability, even both of them are trained with unpaired data, we may further improve it when we have access to parallel data.

We first use translation language model (TLM) (Conneau and Lample, 2019) to learn word-level alignment ability. Concretely, we concatenate parallel sentences as a single consecutive token sequence with special tokens separating them and then perform masked language modeling (MLM) (Devlin et al., 2019) on the concatenated sequence. Besides, we also attempt to improve sentence-level alignment ability using hard parallel sentence identification (HPSI). Specifically, we select a pair of parallel or non-parallel sentences from the training set with equal probability. Then the model is required to predict whether the sampled sentence pair is parallel or not. Different from the standard PSI (Dou and Neubig, 2021), we sample the non-parallel sentence upon the n-gram similarity or construct it by text perturbation (details in Appendix A) instead of in a random manner. Figure 3 illustrates the workflows of TLM and HPSI. We pre-train the CLM using the combination of TLM and HPSI, finally achieving latent space alignment.

Conversation structure encoding Although there are a number of pre-training objectives proposed to learn dialogue context representations (Mehri et al., 2019) and structural representations (Zhang and Zhao, 2021), we tend to explicitly model speaker dependency and temporal depen-

Dataset	language	#dialogue	#utterance	#predicate	#tokens per utterance	cross ratio
DuConv	ZH	3,000	27,198	33,673	10.56	21.89%
Persona-Chat	EN	50	2,669	477	17.96	17.74%
CMU-DoG	EN	50	3,217	450	12.57	7.41%

Table 1: Statistics of the annotations on DuConv, NewsDialog and PersonalDialog.

dency in the conversation, both of which have been proven to be critical to CSRL task (Xu et al., 2021).

We first propose speaker role identification (SPI) to learn speaker dependency in the conversation. Specifically, we randomly sample $K_1\%$ utterances and replace their speaker indicators with special mask tags. To make the task harder and effective, we split the utterances into clauses if only two interlocutors utter in turn in a conversation. The goal of SPI is to predict the masked speaker roles according to the corrupted speaker indicators and context. Secondly, we borrow utterance order permutation (UOR) to encourage the model to be aware of temporal connections among utterances in the context. Concretely, given a set of utterances, we randomly shuffle the last $K_2\%$ utterances and require the model to organize them into a coherent context. Figure 4 illustrates the workflows of SPI and UOR. We pre-train the SC-Encoder using the combination of SPI and UOR.

Semantic arguments identification The core of all SRL-related tasks is to recognize the predicate-argument pairs from the input. Therefore, we propose semantic arguments identification (SAI) objective to strengthen the correlations between the predicate and its arguments with the help of external standard SRL corpus, i.e., CoNLL-2012. Specifically, for each SRL sample, we only focus on those arguments, including ARG0-4, ARG-LOC, ARG-TMP and ARG-PRP, all of which are defined in both SRL and CSRL tasks. The model is encouraged to find the textual spans of these arguments with the given predicate. We believe this objective would benefit to boundary detection, especially for location and temporal arguments. Figure 5 illustrates the workflow of SAI. We drop the SC-Encoder to fit in standard SRL samples which do not have any conversational characteristics.

3.3 Training

Hierarchical Pre-training The pre-training is hierarchically conducted according to different modules, and the pre-training of the upper module is based on the pre-trained lower modules. Specifi-

cally, we first train CLM module with TLM and HPSI; then we train SC-Encoder with SPI and UOR while keeping the weights of pre-trained CLM module unchanged; finally we train PA-Encoder with SAI while freezing the weights of pre-trained CLM and SC-Encoder modules. Hopefully, we expect that each module could acquire different knowledge with specific pre-training objectives.

CSRL training We initialize the specific modules, including CLM, SC-Encoder and PA-Encoder, from the pre-trained checkpoints. The CSRL model is trained only using Chinese CSRL annotations and no additional data is introduced during the CSRL training stage. We train our model to minimize the cross-entropy error for a training sample with label y based on the semantic role encoding l ,

$$p = \text{softmax}(l_t) \quad \mathcal{L}_{CSRL} = - \sum_{l=1}^L y \log p \quad (5)$$

4 Experiments

4.1 Datasets

CSRL data We use the same split as Xu et al. (2021) where DuConv annotations are splitted into 80%/10%/10% as train/dev/in-domain test set. Furthermore, we manually collect two CSRL test sets for cross-lingual evaluation based on Persona-Chat(Zhang et al., 2018) and CMU-DoG(Zhou et al., 2018), both of which are English conversation datasets. The CSRL data annotation is difficult because it needs great expertise in SRL and dialogue. So we only explore cross-lingual CSRL on Chinese→English (Zh→En) here, and we leave other languages for future work.

Following the instructions in Xu et al. (2021), we manually collect two out-of-domain CSRL test sets based on English dialogue datasets Persona-Chat and CMU-DoG. Specifically, we also annotate the arguments ARG0-4, ARG-TMP, ARG-LOC and ARG-PRP and require that the labeled arguments can only appear in the current turn or the previous turns. We employ three annotators who have studied Chinese CSRL annotations for a period time before this annotation. The first two annotators are

Method	Trainable parameters	DuConv			Persona-Chat			CMU-DoG		
		F1 _{all}	F1 _{cross}	F1 _{intra}	F1 _{all}	F1 _{cross}	F1 _{intra}	F1 _{all}	F1 _{cross}	F1 _{intra}
SimpleBERT	117 M	86.54	81.62	87.02	-	-	-	-	-	-
CSRL-BERT	147 M	88.46	81.94	89.46	-	-	-	-	-	-
CSAGN	163 M	89.47	84.57	90.15	-	-	-	-	-	-
SimpleXLMR	292 M	84.75	63.44	85.12	62.96	14.29	63.03	50.54	14.29	58.50
CSRL-XLMR	320 M	88.03	78.12	89.33	63.18	18.71	65.05	53.84	34.20	59.78
CSAGN-XLMR	338 M	88.52	82.45	89.98	63.02	17.82	64.97	52.73	30.11	58.91
Translation-test	-	-	-	-	63.49	13.90	66.67	47.91	27.44	50.92
Translation-train	-	-	-	-	60.12	9.67	62.50	44.27	25.40	47.87
<i>Fine-tune all parameters</i>										
Ours _{mBERT}	272 M	87.20	81.14	88.11	58.38	9.39	61.77	48.13	20.92	52.91
Ours _{XLM-R}	372 M	88.35	83.39	89.21	67.29	24.29	70.61	61.74	60.32	62.67
Ours _{XLM-R + pre-train}	372 M	88.60	84.10	89.24	67.23	25.43	69.89	59.24	58.94	60.89
<i>Freeze parameters of the language model</i>										
Ours _{mBERT}	180 M	87.08	81.46	87.98	59.04	11.23	62.13	48.87	21.78	53.54
Ours _{XLM-R}	180 M	88.30	83.38	89.17	65.57	24.11	68.51	59.60	56.16	60.78
Ours _{XLM-R + pre-train}	180 M	88.60	83.72	89.27	66.75	24.13	69.44	58.45	58.92	58.82

Table 2: Evaluation results on the DuConv, Persona-Chat and CMU-DoG datasets.

required to label all cases and any disagreements between them are solved by the third annotator. The statistics of the datasets are listed in Table 1.

Pre-training data For TLM and HPSI objectives which requires parallel data to enhance alignment ability, we choose IWSLT’14 English↔Chinese (En↔Zh) translations². For SPI and UOR objectives whose goal is to model high-level conversational features, we select samples from Chinese conversation dataset (i.e., DuConv) and English conversation datasets (i.e., Persona-Chat and CMU-DoG) with equal probability. For SAI, we borrow the Chinese and English SRL annotations from CoNLL-2012(Pradhan et al., 2012).

We stress that by **keeping the sampling balance** of Chinese and English data for every pre-training objective and **sharing all parameters across the languages**, our model would capture task-specific but language-agnostic features.

4.2 Experimental Setup

Following previous work(Xu et al., 2021), we evaluate our system on micro-average F1_{all}, F1_{cross} and F1_{intra} over the (predicate, argument, label) tuples, wherein we calculate F1_{cross} and F1_{intra} over the arguments in the different, or same turn as the predicate. We refer these two types of arguments as *cross*-arguments and *intra*-arguments. For language in-domain evaluation, we compare to *SimpleBERT* (Shi and Lin, 2019), *CSRL-BERT* (Xu et al., 2021) and *CSAGN* (Wu et al., 2021b), all

²<https://wit3.fbk.eu/>

of which employ the Chinese pre-trained language model as the backbone. For cross-lingual evaluation, we compare to *SimpleXLMR*, *CSRL-XLMR* and *CSAGN-XLMR* by simply replacing the BERT backbones of those models with XLM-R. Additionally, we also compare to the back-translation baselines, i.e., Translate-test and Translate-train. Specifically, Translate-test means that the English test data is translated and projected to Chinese annotations using Google Translate (Wu et al., 2016) and the state-of-the-art word alignment toolkit Awesome-align(Dou and Neubig, 2021). Similarly, Translate-train means the Chinese training data is translated and projected to English annotations for training. We feed the translated samples into CSAGN/CSAGN-XLMR to obtain the back-translation results.

4.3 Main Results

Table 2 summarized the results of all compared methods on DuConv, Persona-Chat and CMU-DoG datasets. Firstly, we can see that our method achieves competitive performance over all datasets, especially in cross-lingual scenario where our method outperforms the baselines by large margins no matter fine-tuning or freezing the language model during the CSRL training stage. Although CSAGN exceeds our method on DuConv test set, it fails to work well in cross-lingual scenario. We think this is because it heavily relies on the rich features from the Chinese pre-trained language model and it is overfitting on the predicate-aware information. Superior to CSAGN, our model with the

Method	DuConv			Persona-Chat			CMU-DoG		
	F1 _{all}	F1 _{cross}	F1 _{intra}	F1 _{all}	F1 _{cross}	F1 _{intra}	F1 _{all}	F1 _{cross}	F1 _{intra}
All objectives	88.60	83.72	89.27	66.75	24.13	69.44	58.45	58.92	58.82
w/o TLM & HPSI	88.07	81.90	89.06	65.07	23.91	68.34	58.23	53.15	59.24
w/o SPI & UOR	87.75	81.56	88.81	68.35	22.86	71.29	58.08	47.93	60.22
w/o SAI	88.00	83.16	89.06	64.74	23.33	67.99	59.94	54.68	61.87
only w/ TLM & HPSI	87.82	83.21	88.95	65.56	24.12	68.60	57.32	52.74	59.11
only w/ SPI & UOR	88.45	83.70	89.10	64.09	24.09	67.50	59.71	57.23	60.80
only w/ SAI	88.49	82.97	89.24	65.82	23.30	69.18	57.20	50.54	57.63
w/ end2end pre-training	87.28	81.02	88.73	64.37	21.17	67.77	57.86	50.40	58.20
Ours _{XLM-R}	88.30	83.38	89.17	65.57	24.11	68.51	59.60	56.16	60.78
w/o SC-Encoder	88.02	79.11	89.05	63.12	17.55	66.70	57.72	50.42	58.03
w/o PA-Encoder	88.10	81.32	88.78	64.05	22.38	64.82	58.24	54.00	59.23
w/o SC-Encoder and PA-Encoder	86.14	73.63	87.12	62.87	12.38	63.02	52.44	41.02	56.23
w/o MTRANS	88.25	83.01	89.08	65.27	23.10	68.38	58.58	55.41	59.98

Table 3: Ablation studies on pre-training objectives and different modules.

multilingual backbone achieves outstanding performance on both language in-domain and cross-lingual datasets. This observation is expected because (1) our model is language-agnostic which makes the cross-lingual transfer easier; (2) our model captures high-level conversational features in SC-Encoder, thus enhancing the capacities of the model to recognize cross-arguments; (3) rich semantic features are modeled by PA-Encoder, which would improve the capacities of the model to recognize intra-arguments.

Secondly, although our model has achieved good performance over all datasets, further improvements can be observed after incorporating the proposed pre-training objectives, especially when freezing the parameters of the language model. Exceptionally, we find that the performance on the CMU-DoG dataset heavily drops after introducing the pre-training objectives, especially in terms of F1_{intra}. We think this is because the semantic argument spans in CoNLL-2012 are relatively different from those in CMU-DoG, thus leading to the vague boundary detection and performance drop. To verify this assumption, we conduct an ablation study by removing SAI from the pre-training stage. Interestingly, we observe substantial improvements over F1_{all} and F1_{intra}, suggesting that pre-training on CoNLL-2012 does hurt the performance on CMU-DoG. Furthermore, we also find that fine-tuning all parameters leads to slightly better performance than freezing the language model during the CSRL training stage. This finding is consistent with the previous work (Conia et al., 2021).

Table 3 presents the results of ablation studies on pre-training objectives and different modules.

U1	how many games did the colts win?
U2	the Colts _{ARG0} finished with a 12-2 record.
Question	who did they play _{predicate} in the playoffs?
Question'	who did the Colts play in the playoffs?

Table 4: An example of question-in-context rewriting.

For the pre-training objectives, we found that (1) removing TLM & HPSI objective hurts the performance consistently but slightly; (2) SPI & UOR objectives help the model to better identify the cross-arguments; (3) SAI objective helps to find intra-arguments on DuConv and Persona-Chat, but might hurt the F1_{intra} score on CMU-DoG; (4) hierarchical pre-training is superior to end-to-end pre-training which simultaneously optimizes all auxiliary objectives. We think this is because the end2end pre-training is extremely unstable and confuses the optimization process of the model.

For model components, we found that only removing one of the SC-Encoder, PA-Encoder or MTRANS slightly affect the performance. However, the performance heavily decreases when SC-Encoder and PA-Encoder are both removed. We think the reason is that at least one module is needed to capture the high-level features on the top of the language model. We preserve these two modules in our model since they essentially learn different abilities, i.e., the ability of dialogue modeling and semantics modeling, which also makes our model more explainable.

4.4 Applications

Xu et al. (2021) has confirmed the usefulness of CSRL by applying CSRL parsing results to two Chinese dialogue tasks, including dialogue context rewriting and dialogue response generation. In the

Method	Persona-Chat (en)			BConTrast (de)		BSD (ja)	
	B1/2	D1/2	Human [1-5]	B1/2	D1/2	B1/2	D1/2
Seq2Seq	0.138/0.069	0.051/0.094	2.72	0.089/0.042	0.041/0.089	0.125/0.051	0.123/0.248
mUniLM _{wo} /CSRL	0.188/0.113	0.114/0.217	3.02	0.107/0.061	0.079/0.187	0.162/0.080	0.175/0.320
mUniLM _w /CSRL	0.195/0.122	0.116/0.223	3.16	0.112/0.065	0.082/0.191	0.178/0.088	0.177/0.326
mBART _{wo} /CSRL	0.198/0.125	0.120/0.228	3.20	0.115/0.072	0.086/0.206	0.193/0.097	0.182/0.340
mBART _w /CSRL	0.217/0.136	0.124/0.233	3.25	0.118/0.077	0.090/0.212	0.205/0.110	0.185/0.346

Table 5: Evaluations on response generation tasks in English, German and Japanese.

Method	B1	B2	B4
Seq2Seq	-	-	49.67
SARG(Huang et al., 2020)	-	-	54.80
RUN(Liu et al., 2020a)	70.50	61.20	49.10
Human evaluation	-	-	59.92
Ours _{wo} /CSRL	69.24	62.93	52.78
Ours _w /CSRL	70.26	64.19	54.23

Table 6: Evaluation results on the dataset of CANARD.

same vein, we also explore whether CSRL could benefit to the same non-Chinese dialogue tasks.

Question-in-context Rewriting *Question-in-context rewriting* (Elgohary et al., 2019) is a challenging task which requires the model to resolve the conversational dependencies between the question and the context, and then rewrite the original question into independent one. This is an example in Table 4. The question “who did they play in the playoffs?” cannot be independently understood without knowing “they” refer to, but it can be resolved with the given context.

Since the CSRL models can identify the predicate-argument structures from the entire conversation, we believe that it can help this rewriting task by searching the dropped or referred components from the context. For example, in Table 4, our CSRL parser can find that the ARG0 of the predicate “play” is “the Colts”. Motivated by this observation, we attempt to borrow CSRL to help the question rewriting with the context. We first employ the pre-trained cross-lingual CSRL parser (Ours_{XLM-R + pre-train}) to extract predicate-argument pairs from conversations. We adopt the model proposed in (Xu et al., 2020) to achieve the rewriting. More details about the model are in Appendix E.

Since the rewriting datasets are only available in Chinese and English, we hereby only evaluate on CANARD (Elgohary et al., 2019) which is a widely used English question rewriting dataset, and report the BLEU scores. Table 6 lists the evaluation results on CANARD. We can see that our implementation with CSRL achieves competitive performance against the state-of-the-art rewriting models,

i.e., SARG (Huang et al., 2020) and RUN (Liu et al., 2020a), and significantly outperforms the baseline method (Bahdanau et al., 2014). Note that, in this part, we are more focused on the improvements after introducing CSRL information. We find that the scores across all metrics are improved with the aid of CSRL. To figure out the reasons of these improvements, we investigate which type of questions could benefit from CSRL information most. By comparing the rewritten questions of different methods, we find that the questions that require information completion, especially those containing referred components (around 15% cases), benefit from CSRL most. This observation is in line with our expectation that our CSRL parser could consistently offer essential guidance by recovering the dropped or referred text components.

Multi-turn Dialogue Response Generation Besides the rewriting task that is heavily affected by omitted components, we also explore the usefulness of CSRL to *multi-turn dialogue response generation*, one of the main challenges in dialogue community. In contrast to single-turn dialogue response generation, multi-turn dialogues suffer more frequently occurred ellipsis and anaphora, which leads to vague context representations. To this end, we attempt to employ CSRL to build better context representations. In specific, we highlight the words picked up by the CSRL parser, and then teach the model to pay more attention on those words which would hold more semantic features.

We evaluate on three dialogue datasets in different languages, including **Persona-Chat** (Zhang et al., 2018) in English, **BConTrast** (Farajian et al., 2020) in German and **BSD** (Rikters et al., 2019) in Japanese. We report BLEU-1/2 and Distinct-1/2 scores for the comparison. We employ the pre-trained cross-lingual CSRL parser (Ours_{XLM-R}) to analyze the latest utterance, and obtain the predicate-argument pairs. Then the concatenated sequence of the extracted pairs and the context is fed into our model for response generation. We

adopt the UniLM (Dong et al., 2019) or mBART (Liu et al., 2020b) as our generation model. More implementation details are in Appendix E.

Table 5 summarizes the results on three datasets. We can see that the models with different backbones can consistently benefit from the additional introduced CSRL information. While substantial gains from CSRL information are obtained on English and Japanese dialogues, smaller improvements are observed on the German dialogue task. We think this is because English is well-represented in pre-trained multilingual models and Japanese is more similar to Chinese while German accounts for none of both. Apart from automatic evaluation criteria, we also conduct human evaluation on the English dataset. Specifically, we randomly select 200 generated responses for each method, and then recruit three annotators to evaluate the coherence and informativeness of the response against the conversation context by giving a score ranging from 1(worst) to 5(best). We find that the method with CSRL wins in 35% cases, and ties with the vanilla model in around 55% cases. With more careful analysis, we find that the responses that contains entities mentioned in histories benefit from CSRL information most. We think this is because non-phrases are more likely to be recognized as semantic arguments by CSRL parser, and then receive more attentions during encoding.

5 Conclusion

In this work, we propose a simple but effective model with five pre-training objectives to perform zero-shot cross-lingual CSRL, and also confirm the usefulness of CSRL to non-Chinese dialogue tasks.

Acknowledgements

This work was supported in part by the Hong Kong RGC grant ECS 21212419, the Technological Breakthrough Project of Science, Technology and Innovation Commission of Shenzhen Municipality under Grants JSGG20201102162000001, InnoHK initiative, the Government of the HKSAR, Laboratory for AI-Powered Financial Technologies, the Hong Kong UGC Special Virtual Teaching and Learning (VTL) Grant 6430300, Shenzhen Science and Technology Program and Guangdong Basic and Applied Basic Research Foundation 2021A1515110717, and the Tencent AI Lab Rhino-Bird Gift Fund.

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A Hard Parallel Sentence Identification Sampling

Following previous work (Robinson et al., 2020; Wei et al., 2020) which suggests that contrastive learning of representations benefits from hard negative samples, we also try to select hard negative samples for PSI task based on n-gram similarity and text perturbation. Specifically, for each sentence, we calculate its n-gram similarity scores to other sentences, where $n = 1, 2, 3, 4$, and then we select the sentence with the highest score at each gram as the candidate sentence; additionally, we construct the corrupted sentence as the candidate by token deletion, token replacement and token order permutation. Finally, we sample from the candidate set created by n-gram similarity at 40% time and from the candidate set created by text perturbation at 60% time.

B Modified Transformer Encoder Layer

To overcome the information forgetting of hierarchical models, we attempt to modify the standard Transformer to better reserve the information from the previous layers. In specific, we try following variants:

- **MTRANS**. Replacing the [Add] operation in the **first** residual connection layer with [Concat].
- **LATER-MTRANS**. Replacing the [Add] operation in the **second** residual connection layer with [Concat].
- **BOTH-MTRANS**. Replacing the [Add] operations in **both** the first and second residual connection layers with [Concat].

Our intuition of substituting the summation with concatenation is that the residual layer with concatenation would introduce additional parameters, and we expect these additional parameters to retain more history information. As shown in Table 2, we obtain some gains while using MTRANS. Additionally, we also report the $F1_{all}$ scores on DuConv/Persona-Chat/CMU-DoG datasets while using LATER-MTRANS and BOTH-MTRANS here. LATER-MTRANS achieves 88.18/65.32/58.44 points, and BOTH-MTRANS achieves 88.40/66.12/59.72 points against the standard Transformer achieving 88.25/65.27/58.58 points. Although BOTH-MTRANS achieves the

best performance, we finally choose MTRANS since BOTH-MTRANS brings a large volume of additional parameters which leads to a huge model size while the increasing of model parameters caused by MTRANS is acceptable.

C Experimental settings

We implement the model in PyTorch (Paszke et al., 2019), and use the pre-trained language model of multilingual BERT (mBERT) or XLM-RoBERTa (XLM-R) made available by the Transformer library (Wolf et al., 2020) as the backbone. We train the model using AdamW (Loshchilov and Hutter, 2018) with a linear learning rate schedule. For each model, we run five different random seeds and report the average score. More details and hyper-parameters are listed in Table 7.

D Baselines

We compare to following baseline models,

1. **SimpleBERT/SimpleXLMR** (Shi and Lin, 2019). It uses the Chinese BERT or XLM-R as the backbone and simply concatenates the entire dialogue context with the predicate.
2. **CSRL- BERT/XLMR** (Xu et al., 2021). It uses the Chinese BERT or XLM-R as the backbone but attempts to encode the conversation structural information by integrating the dialogue turn and speaker embeddings in the input embedding layer.
3. **CSAGN/CSAGN-XLMR** (Wu et al., 2021b). It uses the Chinese BERT or XLM-R as the backbone and employ the relational graph neural network to model predicate- and speaker-aware dependencies. We implement this baseline based on the code <https://github.com/hahahawu/CSAGN>.

E Application Models

Rewriting Model. We adopt the model proposed in (Xu et al., 2020) which directly concatenates the predicate-argument structures, the conversation context and the question as a sequence, and then feeds them into the model with special attention masks. During decoding, the model takes CSRL pairs and the context to generate the rewritten question word by word. The input representation, attention strategies and loss function of our model are same as (Xu et al., 2020)’s. We initialize the model

using the base BERT model and use AdamW with a linear learning rate schedule to update parameters.

Note that we only attempt to introduce the CSRL information as a condition into our generation-based model. We did not include the CSRL information into the state-of-the-art rewriting models, i.e., SARG and RUN because these models rewrite the sentence by learning a text editing matrix instead of directly learning the distributions of the target words. Unfortunately, there are no straightforward ways to include our CSRL information into these models to help the matrix learning.

Response Generation Model. Our model for response generation is directly borrowed from UniLM (Dong et al., 2019) or mBART (Liu et al., 2020b). For UniLM, the generation process is same with the rewriting task, wherein the extracted semantic pairs, the context and the response are concatenated into a sequence and encoded with the special mask. For mBART, we just concatenate the extracted predicate-argument pairs with the context into a sequence, and then feed the sequence into the encoder for training; during decoding, our model takes semantic information and the context as input to generate the response word by word. The input representation, attention strategies for CSRL structures and loss function are same as the rewriter model’s. We initialize the model using the base multilingual BERT or mBART and use AdamW with a linear learning rate schedule to update parameters.

F Hyper-parameters

We list the hyper-parameters of CSRL experiments (Table 7), rewriting experiments (Table 8) and response experiments (Table 9) below.

Name	Value
Language model	xlm-roberta-base
Hidden state size	512
Word-level encoder layers	2
Pred.-arg encoder layers	1
Batch size per GPU	24
Max learning rate	5e-5
Min learning rate	1e-5
Max <i>lr</i> for LM fine-tuning	1e-5
Min <i>lr</i> for Lm fine-tuning	1e-6
Max sequence length	512
Max training epochs	50
Max training steps	15000
Early-stop patience	10

Table 7: Hyper-parameters in CSRL experiments.

Name	Value
Language model	bert-base-cased
Hidden state size	768
Batch size per GPU	16
Max learning rate	3e-5
Min learning rate	1e-5
Max sequence length	512
Max decode length	32
Max training epochs	20
Early-stop patience	5

Table 8: Hyper-parameters in rewriting experiments.

Name	Value
Language model	mBERT and mBART
Hidden state size	768
Batch size per GPU	16
Max learning rate	5e-5
Min learning rate	3e-5
Max sequence length	512
Max decode length	64
Max training epochs	20
Early-stop patience	5

Table 9: Hyper-parameters in response generation experiments.