

Curr-ReFT: Overcoming Training Bottlenecks in Small-scale Vision-Language Models via Curriculum Reinforcement Finetuning

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Abstract

State-of-the-art vision-language models (VLMs) require massive scaling that limits practical deployment. Small-scale VLMs offer a practical alternative but face out-of-domain (OOD) collapse when trained with traditional supervised fine-tuning (SFT). Through GeneralPoints experiments, we identify that OOD collapse is due to SFT’s tendency to induce visual hallucinations under distribution shifts. Although RL-based post-training effectively mitigates OOD degradation, it faces a critical dilemma with sparse rewards in complex visual reasoning tasks. To this end, we propose Curriculum Reinforcement Finetuning (Curr-ReFT), comprising two sequential stages: (1) Structured Curriculum Reinforcement Learning, which progressively evolves task formats and reward functions to match models’ growing capabilities; and (2) Rejected Sampling-based Self-improvement, which maintains the fundamental capabilities of VLMs through selective learning from high-quality examples. Extensive experiments demonstrate that Curr-ReFT achieves state-of-the-art performance across various visual tasks in both in- and out-of-domain settings and benchmarks. Code and data are available at https://github.com/ding523/Curr_REFT.

1 Introduction

Recent advances in multimodal understanding have led to remarkable vision-language models (VLMs), exemplified by OpenAI (Arrieta et al., 2025; Jaech et al., 2024; Wainwright and Lowe, 2023), InterVL (Chen et al., 2024b; Wang et al., 2022), and QWen (Wang et al., 2024; Yang et al., 2024) series. However, these achievements predominantly rely on massive model scaling (>32B parameters), creating substantial deployment barriers in resource-constrained environments. This limitation moti-

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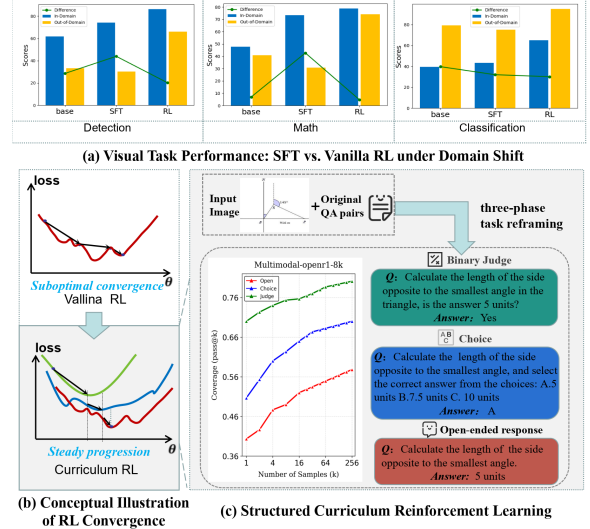


Figure 1: (a) Visual Task Performance: SFT vs. Vanilla RL under in- and out-of-domain settings. (b) Illustration of Vallina RL vs Curriculum RL. The “Training Bottleneck” in small-scale VLMs: suboptimal convergence when facing complex visual reasoning tasks. Our Curriculum RL ensures steady progression of model training through Phased Task Reframing and Hierarchical Reward Design. (c) Structured Curriculum Reinforcement Learning. Curr-RL systematically reformulates input questions into three progressively complex formats. Using multimodal math (OpenR1-8k) as the test case, the pass@k(Cheng et al., 2024) curves reveal a fundamental trade-off between solution space constraints and reasoning complexity.

vates the exploration of efficient training paradigms for small-scale VLMs (<10B parameters).

While supervised fine-tuning (SFT) with high-quality annotated data (Bai et al., 2022; Ziegler et al., 2019) is the dominant training approach for VLMs, it poses a critical challenge for small-scale VLMs: **generalization collapse** (Abbas et al., 2025; Srivastava et al., 2025; Yu et al., 2025b). As evidenced in Fig. 1(a), SFT-trained models consistently outperform base models on in-domain data across detection, classification, and multimodal math tasks. However, these gains are accompa-

nied by significant performance degradation on out-of-domain (OOD) distributions, underscoring the challenge of “OOD degradation”. This phenomenon aligns with recent theoretical findings (Fu et al., 2023; Srivastava et al., 2025) attributing OOD degradation to SFT’s inherent bias toward pattern memorization rather than systematic reasoning (Yu et al., 2025b).

DeepSeek R1-Zero’s (Guo et al., 2025) success with Group Relative Policy Optimization (GRPO) suggests a promising direction for enhancing reasoning through comparative response evaluation. Motivated by these advances, we investigate *whether RL-based post-training can similarly enhance OOD generalization in small-scale vision-language models*. Comprehensive experiments reveal a consistent pattern: while SFT suffers significant OOD degradation, RL-based methods maintain robust generalization across diverse visual tasks (Fig. 1 (a)). Empirical analysis further demonstrates that rule-based RL reduces SFT’s susceptibility to visual hallucinations under distribution shifts (more details in Sec. 4.2.1).

Although RL effectively mitigates OOD challenges, it encounters ‘**Training Bottleneck**’ in visual reasoning tasks, characterized by minimal policy updates, premature convergence to suboptimal strategies, and repetitive generation of low-quality responses (Fig. 1 (b)). This bottleneck arises from **sparse reward** (Xi et al., 2024; Tec et al., 2025; Wei et al., 2023)—*tasks with complex solution spaces provide rarely positive feedback, leading to insufficient learning and suboptimal convergence*.

To address this bottleneck, we propose a Structured Curriculum Reinforcement Learning (Curr-RL) paradigm that progressively evolves task formats to match models’ growing capabilities, inspired by curriculum learning (Kong et al., 2021; Pentina et al., 2015; Lin et al., 2023; Ryu et al., 2024). *Our key insight is that the sparse reward dilemma mainly arises from the vast solution space, hindering the exploration of correct paths, particularly in early-stage training.* (Lin et al., 2023). As illustrated in Fig. 1 (c), Curr-RL employs a three-phase task reframing and hierarchical reward design, enabling smooth transitions from structured to open-ended formats. This progression begins with binary decisions that reconstruct complex visual reasoning into true/false questions, reducing the solution space dimension for more dense rewards. It then progresses to choice selection formats that introduce partially open elements,

and culminates in open-ended generation, developing robust vision-language associations before confronting sparse reward scenarios.

While Curriculum RL effectively boosts domain-specific visual reasoning, it often compromises general-purpose language capabilities (e.g., commonsense and scientific reasoning), a known trade-off in RL fine-tuning (Pan et al., 2024; Hafez and Erekmén, 2024). To address this issue, we introduce a rejection sampling-based self-improvement mechanism that preserves general knowledge. Built upon the Crescent framework (Team et al., 2025), our method employs an LLM-as-judge (e.g., GPT-4o (Wainwright and Lowe, 2023)) to compare the RL-trained model’s responses with reference answers and retain the higher-quality responses.

To this end, we propose Curriculum Reinforcement Finetuning (**Curr-ReFT**). Curr-ReFT comprises two sequential stages: Structured Curriculum Reinforcement Learning and Rejected Sample-based Self-improvement. Extensive experiments demonstrate Curr-ReFT’s state-of-the-art performance on both in- and out-of-domain visual tasks and abundant public benchmarks, with our enhanced small-scale VLMs matching the capabilities of much larger counterparts.

Contributions Summary. (1) **Empirical Insight:** Our experiments reveal that rule-based RL counteracts SFT-induced visual hallucinations, significantly improving OOD generalization in visual tasks via iterative perception refinement. (2) **Curr-ReFT Framework:** An adaptable two-stage post-training paradigm that strengthens visual reasoning while preserving fundamental language capabilities; (3) **Curriculum Dataset:** A newly constructed 12k-example dataset spanning detection, classification, and multimodal math; (4) **Empirical Results:** Extensive experiments demonstrate Curr-ReFT’s superior performance across multiple benchmarks.

2 Related Work

2.1 Reasoning Vision-language models

Recent advancements in multimodal models have evolved from LLaVA’s (Liu et al., 2023) projection-based approach to Qwen-VL (Bai et al., 2023; Wang et al., 2024; Yang et al., 2024) and InternVL (Chen et al., 2024a; Luo et al., 2024) series further advancing visual instruction tuning and architectural efficiency. Concurrently, reasoning-focused methods have progressed from Monte

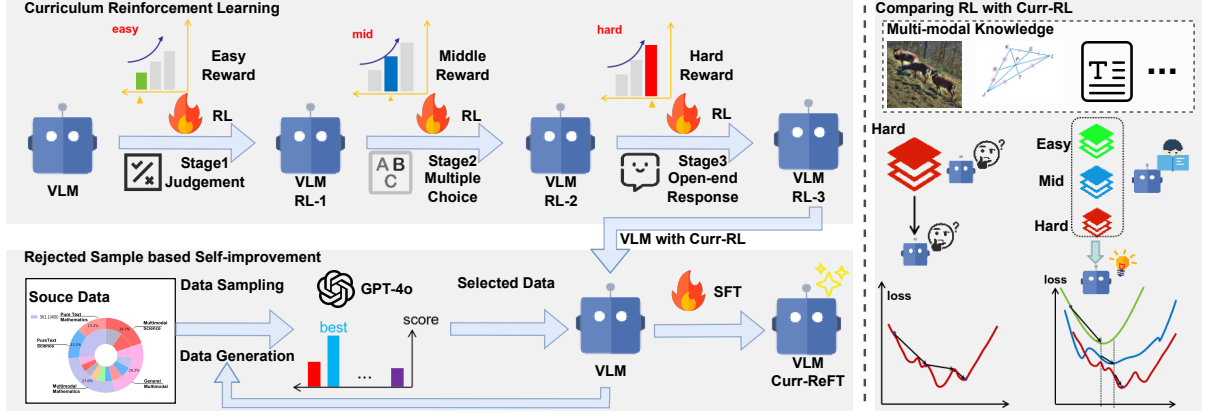


Figure 2: **Overall framework of the proposed Curr-ReFT post-training paradigm.** Curr-ReFT comprises two sequential stages: (1) Curriculum Reinforcement Learning that progressively increases task complexity with aligned reward mechanisms, and (2) Rejected Sample based Self-improvement that maintains fundamental capabilities (Best viewed in color).

Carlo Tree Search techniques (Browne et al., 2012; Yao et al., 2023) to process-supervised learning (Lu et al., 2024; Deng et al., 2025). OpenAI-O1 (Wainwright and Lowe, 2023) established the RL+SFT paradigm, while DeepSeek-R1-Zero’s GRPO (Guo et al., 2025) demonstrated superior reasoning through group-wise response comparisons without auxiliary networks (Schulman et al., 2017). Despite these advances, current research primarily targets math and coding tasks (Liu et al., 2024a), leaving the intersection of visual perception and reasoning largely unexplored. Our Curr-ReFT framework addresses this through multi-stage RL training.

3 Method

In this section, we elaborate **Curr-ReFT**, comprising two sequential training stages: Curriculum Reinforcement Learning (Sec. 3.2), which achieves task progression training through three stages of reward mechanisms, and Rejected Sample based Self-improvement (Sec. 3.3), which preserves fundamental capabilities via quality-guided learning. The overall framework is illustrated in Fig. 2.

3.1 Preliminary

Reinforcement Learning with GRPO

DeepSeek R1-Zero (Guo et al., 2025) introduces the GRPO framework, eliminating dependence on additional critic networks (PPO-based methods (Schulman et al., 2017)). Specifically, GRPO considers the relative performance of responses rather than absolute reward values. For a given input query q . The framework generates N distinct responses $\{o_1, o_2, \dots, o_N\}$ from the current policy

π_θ and evaluates through group-wise comparison:

$$A_i = \frac{r_i - \text{mean}(\{r_1, \dots, r_N\})}{\text{std}(\{r_1, \dots, r_N\})} \quad (1)$$

where A_i represents the normalized relative quality of the i -th response within its group.

3.2 Structured Curriculum Reinforcement Learning

The Structured Curriculum Reinforcement Learning employs a three-phase dynamic adjustment on task formats and reward functions to address RL’s sparse reward issue. We will elaborate Binary Decision Learning, Multiple Choice Learning, and Open-ended Response on the task formats and reward designs in Sec. 3.2.1, Sec. 3.2.2, and Sec. 3.2.3, respectively.

3.2.1 Stage 1: Binary Decision Learning

In the initial stage of reinforcement learning, we adopt binary decision questions as the simplest form of task format, as shown in Fig. 4 (a), which significantly reduces the output freedom to binary choices, making it easier to learn basic visual understanding and reasoning patterns. Models are explicitly prompted to answer with ‘yes’ or ‘no.’ The reward function for this stage is as follows:

$$\mathbf{R}_{\text{Binary}}(\mathbf{o}_{std}, \mathbf{o}_{gt}) = \begin{cases} 1, & \text{if } \mathbf{o}_{std} = \mathbf{o}_{gt} \\ 0, & \text{otherwise} \end{cases} \quad (2)$$

where $\mathbf{o}_{std}$ represents the model’s binary response and $\mathbf{o}_{gt}$ is the ground truth answer.

3.2.2 Stage 2: Multiple Choice Learning

The second stage introduces choice questions, which require more sophisticated decision-making while maintaining structured response formats (as displayed in Fig. 4 (a)). We design different reward mechanisms for single-choice and multiple-choice scenarios to provide appropriate learning signals. For single-choice questions, we maintain a binary reward structure:

$$\mathbf{R}_s(\mathbf{o}_{std}, \mathbf{o}_{gt}) = \begin{cases} 1, & \mathbf{o}_{std} = \mathbf{o}_{gt} \\ 0, & \text{otherwise} \end{cases} \quad (3)$$

For multiple-choice questions, we introduce a more nuanced reward function that considers partial correctness:

$$\mathbf{R}_m(\mathbf{o}_{std}, \mathbf{o}_{gt}) = \begin{cases} 1, & \mathbf{o}_{std} = \mathbf{o}_{gt} \\ 0.2, & \mathbf{o}_{std} \subset \mathbf{o}_{gt}, |\mathbf{o}_{std}| > 0 \\ 0, & \text{otherwise} \end{cases} \quad (4)$$

where $\mathbf{o}_{std}$ represents the model’s selected options and $\mathbf{o}_{gt}$ is the set of correct options. This graduated reward structure encourages the model to identify correct options while maintaining the incentive for complete answers.

3.2.3 Stage 3: Open-ended Response Learning

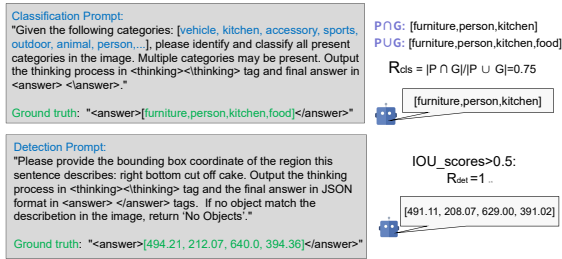


Figure 3: Verifiable Reward for visual tasks in the Open-ended Response stage. We have listed the detection and classification prompt with Verifiable Reward calculation examples.

Inspired by DeepSeek-R1’s success in reasoning tasks, we extend its RL approach to visual domains (Deng et al., 2024). Unlike math or code tasks with clear ground truth, visual tasks require tailored reward functions. We design verifiable, task-specific rewards for open-ended multimodal RL.

Category Overlap Reward for Visual Classification For classification, we propose a Category Overlap Reward, computed as the intersection-over-union (IoU) between predicted and ground-truth

categories. This continuous reward offers proportional credit for partial correctness, providing richer feedback than binary matching. Let the predicted categories be $P = c_1, c_2, \dots, c_m$ and ground-truth categories $G = g_1, g_2, \dots, g_n$, where c_i and g_j denote individual category labels. The reward is calculated based on their set intersection and union:

$$\mathbf{R}_{acc_cls} = \frac{|P \cap G|}{|P \cup G|} = \frac{|\{c_i | c_i \in P \text{ and } c_i \in G\}|}{|\{c_1, \dots, c_m\} \cup \{g_1, \dots, g_n\}|}, \quad (5)$$

where $|P \cap G|$ represents the number of correctly predicted categories, and $|P \cup G|$ represents the total number of unique categories in both sets combined. This reward mechanism provides a continuous value in $[0, 1]$, better reflecting partial correctness in multi-label scenarios compared to binary rewards. The classification reward R_{cls} combines accuracy and format compliance.

IOU rewards for Visual Detection For object detection tasks, we design a comprehensive reward function that evaluates both localization accuracy. The reward mechanism considers three key aspects: spatial accuracy, prediction reliability, and response format compliance.

Given a set of predicted bounding boxes $B_{student} = \{b_1, b_2, \dots, b_n\}$ with corresponding confidence scores $f = \{f_1, f_2, \dots, f_n\}$, and ground truth boxes $B_{gt} = \{b_1^{gt}, b_2^{gt}, \dots, b_m^{gt}\}$, we first establish box-level correspondences through IoU matching. By applying a threshold τ , we filter out low-quality matches where $iou_i < \tau$. The localization accuracy reward R_{loc} is then computed as the mean IoU of the remaining valid matches:

$$\mathbf{R}_{Iou} = \frac{1}{|\mathcal{V}|} \sum_{i \in \mathcal{V}} iou_i, \quad \mathcal{V} = \{i | iou_i \geq \tau\} \quad (6)$$

where $\mathcal{V}$ denotes the set of valid matches and $|\mathcal{V}|$ represents the number of valid matches. To encourage accurate object localization, we further discretize the IoU-based reward using a threshold of 0.5:

$$\mathbf{R}_{acc_det} = \begin{cases} 1, & \text{if } \mathbf{R}_{Iou} > 0.5 \\ 0, & \text{otherwise} \end{cases} \quad (7)$$

The final detection reward $\mathbf{R}_{det}$ combines both localization accuracy and format compliance:

$$\mathbf{R}_{det} = \mathbf{R}_{acc_det} + \mathbf{R}_{format} \quad (8)$$

where R_{acc_det} evaluates spatial localization accuracy and R_{format} verifies response format compliance.

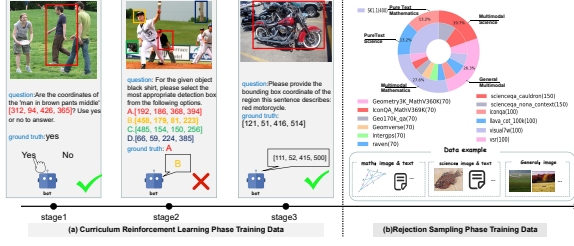


Figure 4: **Illustration of training data organization.** (a) Examples of 3-stage progressive response formats in Curriculum Reinforcement Learning. (b) Data source in Reject-sampling SFT phase (detailed Reject-sampling pipeline in Sec. 3.3).

3.3 Rejected Sample based Self-improvement

To prevent degradation in general domain, we propose a Rejected Sample-based Self-improvement mechanism. This framework comprises three stages: (1) general-domain data construction; (2) automatic refinement by GPT-4-O-guided selection between model and reference responses, enhancing data quality via self-improvement; and (3) supervised fine-tuning on the curated dataset to reinforce general vision-language competence. Specifically, step (1) is detailed in Sec. 3.3.1, while steps (2) and (3) are elaborated in Sec. 3.3.2.

3.3.1 General-domain data construction

The data preparation process involves systematic sampling from a comprehensive dataset. Utilizing GPT-4-O as the reward model, we evaluate generated responses against multiple criteria: accuracy, logical consistency, format compliance, and linguistic fluency. Responses are quantitatively assessed on a 0-100 scale, with those surpassing a threshold of 85 being integrated into the enhanced dataset alongside their corresponding queries. The resultant curated dataset encompasses 1,520 high-quality samples (12.7% selection rate) across science, general knowledge and math (Fig. 4).

3.3.2 Self-Improvement Training

Following dataset construction, we refine the data by selecting high-quality answers from either the original references or model-generated responses, as determined by LLM-as-Judge (GPT-4O(Wainwright and Lowe, 2023)). As illustrated in Algorithm 1, for each query in the dataset, the model generates multiple candidate responses,

which are scored by LLM-as-Judge. The highest-scoring response—regardless of whether it is model-generated or a reference—is retained if it surpasses a quality threshold. The resulting refined dataset is then used to conduct further fine-tuning. This self-improvement stage reinforces general-domain competencies by enabling the model to learn from its own superior outputs while maintaining robust cross-domain capabilities.

Algorithm 1 Rejected Sample based Self-improvement Algorithm

Input: Dataset D , Generative Model G , Reward Model R , Number of samples per input N , Threshold score $\tau = 85$

Output: Enhanced dataset D_{new}

- 1 Initialize an empty enhanced dataset $D_{new} \leftarrow \emptyset$
- 2 **foreach** each question $q \in D$ **do**
- 3 Generate N responses using the generative model G : $\{r_1, r_2, \dots, r_N\} = G(q)$
- 4 Score each response using the reward model R : $\{s_1, s_2, \dots, s_N\} = R(\{r_1, r_2, \dots, r_N\})$
- 5 Find the index of the highest-scored response: $i^* = \arg \max_i s_i$ **if** $s_{i^*} > \tau$ **then**
- 6 Add the highest-scored response to: $D_{new} \leftarrow D_{new} \cup \{(q, r_{i^*})\}$
- 7 **return** the enhanced dataset D_{new}

4 Experiments

Aiming to answer the following questions, we conduct extensive experiments and test on abundant benchmarks:

- **RQ1:** How does RL perform compared to traditional SFT in standard CV tasks?
- **RQ2:** How do models trained with Curr-ReFT perform relative to mainstream VLMs?
- **RQ3:** How do curriculum strategies like order rearrangement impact Curriculum RL performance? How do curriculum learning and rejection sampling contribute to performance in general and visual tasks, respectively?
- **RQ4:** Does Curr-ReFT generalize effectively across different backbone models, model sizes, and application domains?

4.1 Experiment Settings

Visual Datasets. We built an Visual Dataset across **visual detection**, **classification**, and **multimodal**

mathematical reasoning—each with 5,000 training, 1,000 in-domain test and 1,000 out-domain samples. Detection and classification data comes from RefCOCO (Yu et al., 2016) and RefCOCOg (Mao et al., 2016), while math data use Math360K (Shi et al., 2024) and Geo170K (Gao et al., 2023). All training samples are reformatted into binary decision, choice for three-stage Curriculum RL. Out-domain evaluation includes RefGTA (Tanaka et al., 2019) for detection, Pascal-VOC (Everingham et al., 2010) for classification, and CLEVR-70k-Counting for math.

Metrics. We use accuracy as the unified metric. For detection, a prediction is correct if IoU between predicted and ground truth boxes exceeds 0.5.

Benchmarks. Following OpenCompass leaderboards, we updated the LLM-as-Judge to GPT-4-Turbo (2024-04-09) (Wainwright and Lowe, 2023). We evaluate trained models on the following benchmarks: MathVista (Lu et al., 2023), MATH, AI2D (Hiippala et al., 2021), MMVet (Yu et al., 2023), MMBench (Liu et al., 2024b), OCRBench (Liu et al., 2024c), and LLaVABench (Liu et al., 2023).

Baselines. To comprehensively evaluate our approach, we conduct extensive experiments against state-of-the-art VLMs across various scales (3B to 32B). Baseline models include the Qwen2.5-VL (Yang et al., 2024), InternVL (Chen et al., 2024b), and LLaVA (Liu et al., 2023) series. We also compare with prominent methods including Vision-R1 (Huang et al., 2025), Perception-R1 (Yu et al., 2025a), VLM-R1 (Shen et al., 2025), and LISA (Lai et al., 2024).

Training Details All experiments use NVIDIA A800 GPUs. We primarily train Qwen2.5-VL-3B on 8 GPUs (batch size=8), with training Qwen2.5-VL-7B across 16 GPUs. The hyperparameters are set as follows: (1) Learning rates: 2e-5 for RL (GRPO) training, 2e-7 for rejection sampling phase, and 1e-6 for SFT experiments. (2) Maximum pixel size: 401,408. (3) GRPO training steps: 2,500.

The training methods are described as follows: (1) **+SFT** denotes supervised fine-tuning using 12k multimodal data on open-ended response formats. (2) **+ReFT** denotes rejection-sampling-based SFT; the data and sampling strategy are detailed in Sec. 3.3. (3) **+RL** refers to direct GRPO training using the same 12k samples, with reward functions aligned with Stage 3 of Curr-RL in Sec. 3.2.3. (4) **+Curr-RL** involves the three-stage curriculum RL training as detailed in Sec. 3.2. (5) **+RL-ReFT** and **+Curr-ReFT** indicate applying rejection-

sampling-based fine-tuning after RL (GRPO) or curriculum RL, respectively.

4.2 Main Results

4.2.1 Generalization Verification of RL (RQ1)

Methods	In-domain			Out-domain		
	Det	Math	Cls	Det	Math	Cls
Base	61.8	71.3	39.6	55.3	40.8	79.3
+SFT	75.2	73.5	50.2	52.3	30.8	77.2
+RL	88.3	78.8	62.9	64.2	74.1	94.7
+Curr-RL	90.6	82.8	66.8	67.1	78.4	96.6

Table 1: Performance Comparison: In/Out-domain Performance (%). Base model is chosen as the Qwen2.5-VL-3B. Notably, ‘Det’ and ‘Cls’ denote detection and classification.

Changes	Training Data	Test Data
Rule	‘J’/‘Q’/‘K’=10	‘J’, ‘Q’, ‘K’=11, 12, 13
Pattern	Black Cards (♠, ♣)	Red Cards (♥, ♦)

(a) Generalization rules (Numerical Rule and Visual Pattern).

Domain	Task	Changes	SFT	RL
In	Target	/	41.5%	53.6%
	Num_Rec	/	70.5%	73.6%
Out	Target	Rule	24.1%	38.1%
	Target	Color	12.7%	46.4%
	Target	Rule+Color	9.2%	33.1%
	Num_Rec	Color	41.3%	71.3%
	Num_Rec	Rule	63.3%	69.2%
	Num_Rec	Rule+Color	40.2%	68.1%

(b) GeneralPoints results with Qwen2.5-VL-7B. GeneralPoints focus on two tasks: Target Calculation task (‘Target’) and Number Recognition task (‘Num_Rec’). Color changes means training on Black cards (♠, ♣) and testing on Red Cards (♥, ♦). ‘/’ denotes the default setting, training and testing on Black cards (♠, ♣). ‘Rule + Color’ indicates both Rule and Color changes.

Table 2: GeneralPoints task. (a) Generalization rules and (b) Experimental results.

Tab. 1 summarizes the in- and out-of-domain performance of Qwen2.5-VL-3B under different paradigms. Fig. 6 provides qualitative comparisons between SFT and our Curr-RL. Key observations are as follows: (1) While SFT improves in-domain accuracy, it consistently fails on out-of-domain tasks. (2) Curr-RL generates more accurate localizations and comprehensive explanations across diverse OOD settings. Fig. 5 further presents the training dynamics. Curr-RL demonstrates more stable training, faster convergence than RL.

Table 3: **Performance comparison on visual tasks.** ‘In’ denotes in-domain while ‘out’ represents out-of-domain testing. SFT[†] results are shown. Boldface and underlines indicate the best and second-best results.

Methods	Math		Detection		Classification	
	In	Out	In	Out	In	Out
Qwen2.5-VL-3B	71.3	40.8	61.8	55.3	39.6	79.3
InternVL2.5-4B	69.4	36.3	60.2	54.5	41.5	78.9
Qwen2.5-VL-7B	77.9	54.6	76.7	63.6	62.5	81.3
InternVL2.5-8B	76.3	52.1	67.1	59.7	61.1	82.9
InternVL2-26B	83.7	77.4	78.9	<u>68.3</u>	68.1	91.5
LLaVA-32B	83.4	<u>78.7</u>	81.2	65.4	69.6	93.4
Vision-R1-7B	83.8	78.9	89.1	67.9	73.4	96.1
VLM-R1	80.2	68.8	87.9	63.1	65.6	89.7
Perception-R1	77.9	70.1	86.3	62.9	70.1	81.9
LISA-7B	70.2	60.5	85.1	60.9	64.0	82.5
Curr-ReFT-3B	82.3	73.7	89.8	65.6	71.5	95.2
Curr-ReFT-7B	85.3	81.5	92.2	69.5	73.1	98.7

To further explore how RL affects the OOD visual performance of VLMs, we conducted additional experiments on Qwen2.5-VL-7B. GeneralPoints requires the model to use numbers from 4 cards (via image input) and combine them to reach a target number. The generalization rules are detailed in Tab. 2 (a). As shown in Tab. 2 (b), RL demonstrates superior performance in both Rule and Visual Generalization tasks. Notably, SFT shows severe degradation in Visual changes (41.5% $\rightarrow$ 12.7%, -28.8%) compared to Rule changes (-17.4%). RL also excels in OOD Number Recognition (65.3% vs 41.3%, +21.0%). Therefore, we hypothesize that RL’s bidirectional feedback with multi-round error correction can progressively refine the visual perception. In contrast, SFT tends to memorize training data and struggles with OOD visual perception.

4.2.2 Performance Comparison (RQ2)

We report results on visual tasks (Tab. 3) and public benchmarks (Tab. 4), using Curr-ReFT-3B/7B initialized from Qwen2.5-VL-3B/7B. Our results reveal Curr-ReFT’s strong improvements in Visual Tasks and Public Benchmarks. In addition, we observe two noteworthy findings: (1) OOD classification outperforms in-domain by +25.6%, likely due to clearer semantics in OOD test data versus more ambiguous in-domain labels. (2) SFT remains strong on structured tasks like detection, but underperforms in reasoning math tasks.

Public Benchmarks Curr-ReFT-7B performs competitively with much larger models (26B/32B) on

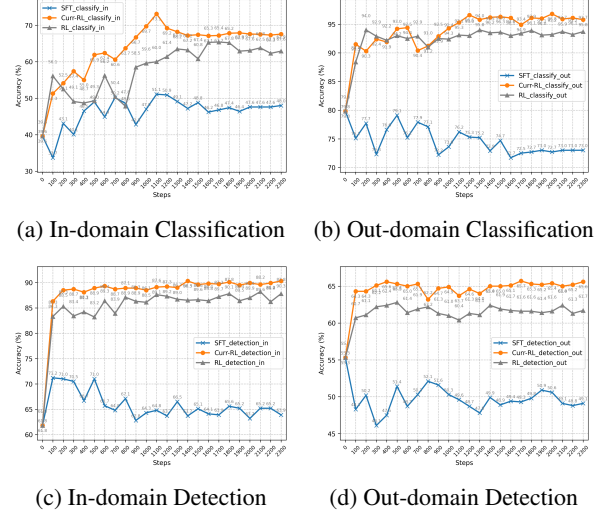


Figure 5: Performance Dynamics: SFT vs. RL vs. Curriculum RL on In-domain and Out-of-domain Tasks.

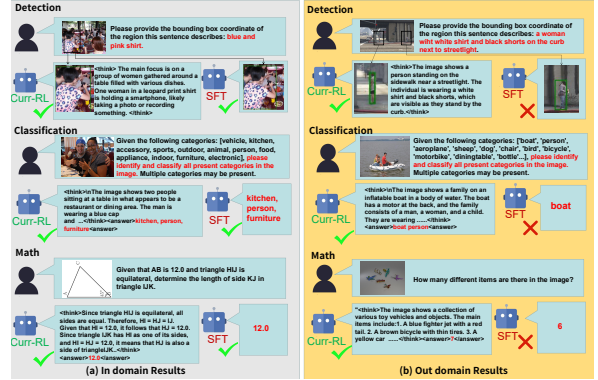


Figure 6: Qualitative comparison between our method and SFT baseline. Thinking process significantly improves reasoning ability.

most benchmarks. On LLaVABench, it reaches 83.6% (Relative), 69.7% (VLM), and 84.5% (GPT-4o), surpassing LLaVA-32B (82.2%) and approaching GPT-4o’s level. This demonstrates the effectiveness of our rejection-based self-improvement in enhancing general vision-language capacity.

In addition, we observe two noteworthy findings: (1) OOD classification outperforms in-domain by +25.6%, likely due to clearer semantics in OOD test data versus more ambiguous in-domain labels. (2) SFT remains strong on structured tasks like detection, but underperforms in reasoning math tasks.

4.2.3 Ablation Study (RQ3)

Tab. 4(a) and Tab. 4(b) report ablation results on visual tasks and benchmarks, respectively. We compare Curr-ReFT-3B with the following variants: (1) +Curr-RL, without reject-sampling SFT; (2) +RL, without curriculum learning. To examine

Model	AI2D	MMVet	MMBench	LLaVABench			MathVista	MATH	OCRBench
				Relative	VLM	GPT4			
Qwen2.5-VL-3B	81.4	61.8	76.8	74.3	63.3	81.1	61.2	55.1	797
InternVL2_5-4B	81.4	61.5	77.2	73.5	64.1	78.2	60.8	50.7	781
Qwen2-VL-7B	83.0	63.8	78.0	73.2	61.2	76.5	61.6	56.6	801
Qwen2.5-VL-7B	84.3	67.3	81.2	81.2	67.1	81.4	67.1	59.2	831
InternVL2_5-8B	84.9	62.8	80.5	81.1	63.7	80.1	64.5	58.1	810
InterVL2-26B	84.5	60.0	81.2	78.1	69.4	81.0	59.6	61.9	815
LLaVA-32b	75.5	69.0	76.8	79.2	68.3	82.2	68.1	59.3	784
LISA-7B	54.3	49.5	48.2	52.9	47.1	68.1	32.4	30.1	569
Perception-R1	71.8	48.9	71.8	58.2	48.2	67.8	67.1	42.1	707
VLM-R1	76.4	51.8	70.1	74.8	67.1	82.1	68.1	46.8	678
Vision-R1-7B	78.2	60.1	63.5	82.9	69.4	82.8	63.5	52.3	718
Curr-ReFT-3B	79.7	69.1	77.4	75.4	68.1	84.5	65.8	55.8	801
Curr-ReFT-7B	83.2	71.3	80.1	83.6	69.7	85.6	68.8	58.6	834

Table 4: **Performance comparison against mainstream VLMs on public benchmarks.** Background colors denote benchmark categories: **yellow** for science (AI2D), **cyan** for general vision-language understanding (MMVet, MMBench, LLaVABench), **green** for math-related tasks (MathVista, MATH), and **red** for OCR (OCRBench). Boldface and underlines indicate the best and second-best results, respectively.

Method	Math		Detection		Classification	
	In	Out	In	Out	In	Out
Base	71.3	17.8	31.8	22.3	39.6	79.8
+SFT	73.5	30.8	75.2	52.3	50.2	77.2
+RL_{Judge}	76.2	71.9	89.4	65.1	63.0	94.1
+RL_{Choice}	77.1	73.2	88.1	63.5	64.9	94.5
+RL	78.8	74.1	88.3	64.2	62.9	93.8
+Curr-RL^{Reverse}	72.4	72.4	80.2	66.1	60.9	94.3
+Curr-RL^{Mix}	77.8	75.4	85.6	67.1	61.8	94.6
+Curr-RL	82.8	78.4	90.6	67.1	66.8	96.6
+ReFT	69.5	52.5	25.7	49.7	39.2	72.4
+RL-ReFT	77.1	70.3	84.3	62.1	54.9	94.5
+Curr-ReFT	80.3	73.7	89.8	65.6	65.4	92.2

(a) **Ablation study results on visual tasks** Notably, color highlighting indicates different training strategies: Vision-specific SFT results (**green**), RL training scheme (**blue**), General-domain Reject-sampling SFT (**yellow**), and proposed Curr-ReFT (gray). Details of ‘+RL_{Judge}’, ‘+RL_{Choice}’, ‘+Curr-RL^{Reverse}’, and ‘+Curr-RL^{Mix}’ are provided in Sec. 4.2.3.

Method	AI2D	MMVet	MathVista	OCR	MMBench	LLaVA	
						VLM	GPT4
Base	81.40	61.80	61.20	797	76.80	63.30	81.10
+SFT	78.45	62.02	61.90	802	73.65	64.30	84.10
+RL	79.43	63.06	62.30	810	74.34	64.70	83.00
+Curr-RL	79.76	64.74	66.30	812	74.90	64.10	85.20
+ReFT	82.51	68.95	57.70	818	79.02	66.10	84.20
+Curr-ReFT	79.66	69.10	65.80	801	77.40	69.70	85.60

(b) **Ablation study on standard benchmarks.** Color coding follows the same scheme as in Tab. 4a. ‘OCR’ denotes OCRBench.

Table 4: **Ablation Study on major components.**

task sensitivity of curriculum learning, we compare +RL_{Judge} and +RL_{Choice} (purely judgment or choice formats), +Curr-RL^{Reverse} (reverse curriculum, starting with open-ended response with finally judg-

Method	Math		Detection		Classification	
	In	Out	In	Out	In	Out
InternVL2_5-4B	69.4	36.3	60.2	54.5	41.5	78.9
+Curr-ReFT	76.8 ↑7.4	46.7 ↑10.4	68.4 ↑8.2	61.2 ↑6.7	50.2 ↑8.7	87.3 ↑8.4
InternVL2_5-8B	76.3	52.1	67.1	59.7	61.1	82.9
+Curr-ReFT	83.1 ↑6.8	60.2 ↑8.1	76.8 ↑9.7	70.4 ↑10.7	67.2 ↑6.1	90.1 ↑7.2
Qwen2-VL-7B	77.9	54.6	76.7	63.6	62.5	81.3
+Curr-ReFT	85.3 ↑7.4	62.6 ↑8.0	84.8 ↑8.1	69.5 ↑5.9	69.6 ↑7.1	87.5 ↑6.2

Table 5: **Scaling Up Experiment on visual dataset:** We evaluate the scalability of the proposed *Curr-ReFT* framework on various vision-language base models. Red ↑ indicates the relative gain.

ment format +Curr-RL^{Mix} (a mixed strategy that uses an equal proportion of the three formats). Our ablation study reveals four key insights:

- Curr-RL consistently outperforms standard RL. Progressive order yields better results than randomized (Mix) or reversed (Reverse) curricula.
- Reject-sampling improves language-centric benchmarks but compromises visual grounding, suggesting that general-domain data weakens alignment with fine-grained visual cues.
- SFT alone is insufficient for generalization under distribution shift. Despite strong in-domain performance, it performs poorly OOD, especially on visual reasoning. The absence of feedback limits its ability to generalize beyond training data.
- Combining Curr-RL with ReFT yields complementary benefits. Curr-ReFT unifies curriculum-driven progression and rejection-based generalization, yielding balanced gains in perception and reasoning.

Table 6: Medical Imaging VQA Results. “VQA-R” denotes VQA-RAD, “PathV” denotes PathVQA, “OmniV” represents OmniMedVQA, respectively.

Model	In-Domain		Out-Domain	
	VQA-R	PathV	OmniV	MMMU
LLAVA-v1.6-7B	52.6	47.9	49.5	41.4
+Curr-RL	57.7	54.1	57.9	49.8
Qwen2.5-VL-3B	58.7	58.1	58.1	54.5
+Curr-RL	67.1	68.9	63.2	66.1
Qwen2.5-VL-7B	60.1	58.9	57.8	56.6
+Curr-RL	71.3	69.3	62.5	57.2

Table 7: Code Generation Results on HumanEval.

Models	Params	HumanEval (Pass@1)
DeepSeek-Coder-1.3B	1.3B	16.8%
+Curr-RL	1.3B	17.3%
Phi-2	2.7B	17.1%
+Curr-RL	2.7B	17.7%
Qwen-Code-7B	7B	26.8%
+Curr-RL	7B	28.0%

4.2.4 Scaling Analysis (RQ4)

To examine the scaling effectiveness of our Curr-ReFT, we conduct extensive experiments on base models of varying sizes and types. The results in Tab. 4 and Tab. 5 indicate that the effectiveness of Curr-ReFT scales effectively with model size. Furthermore, we generalize Curr-ReFT to diverse domains such as medical imaging and code generation. The design principles for curriculum consistency and detailed experimental results are discussed in the Appendix.

5 Conclusion

In this paper, we introduce Curr-ReFT, a novel two-stage post-training paradigm that balances domain-specific visual reasoning and general vision-language capabilities. We provide theoretical insights that reinforcement learning improves both reasoning and out-of-domain visual task generalization. We also release a 12k-example curriculum benchmark spanning visual detection, classification, and multimodal math. Curr-ReFT achieves SOTA on abundant benchmarks, with +5.2% avg. gain in OOD visual tasks.

Limitations and Future Works

While Curr-ReFT effectively improves reasoning and generalization in small-scale VLMs, several potential limitations merit consideration. First, the constrained task formats used in early curriculum stages (e.g., binary or multiple-choice) may bias the model toward generating shorter or less diverse responses in open-ended tasks. Second, although the progressive task transition facilitates stable learning, it may also risk catastrophic forgetting of early-stage skills if not complemented by explicit retention mechanisms. Third, our three-stage curriculum is manually designed, which may limit scalability across domains or modalities.

We partially address the second concern through a rejection-sampling-based self-improvement that reinforces general capabilities. Nonetheless, further exploration of automated curriculum scheduling and lifelong learning strategies remains a promising direction.

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