

Dynamic Rewarding with Prompt Optimization Enables Tuning-free Self-Alignment of Language Models

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Abstract

Aligning Large Language Models (LLMs) traditionally relies on costly training and human preference annotations. Self-alignment aims to reduce these expenses by aligning models by themselves. To further minimize the cost and enable LLM alignment without any expensive tuning and annotations, we introduce a new tuning-free approach for self-alignment, called Dynamic Rewarding with Prompt Optimization (DRPO). Our approach leverages a search-based optimization framework that allows LLMs to iteratively self-improve and design the best alignment instructions without the need for additional training or human intervention. The core of DRPO is a dynamic rewarding mechanism, which identifies and rectifies model-specific alignment weaknesses, allowing LLMs to adapt efficiently to diverse alignment challenges. Empirical evaluations on eight recent LLMs, both open- and closed-source, reveal that DRPO significantly enhances alignment performance, with base models outperforming their SFT/RLHF-tuned counterparts. Moreover, DRPO’s automatically optimized prompts surpass those curated by human experts, further validating the effectiveness of our approach. Our findings highlight the great potential of current LLMs to be adaptively self-aligned through inference-time optimization, complementing existing tuning-based alignment research.¹

1 Introduction

Aligning Large Language Models (LLMs, Brown et al. 2020; Chowdhery et al. 2023; Touvron et al. 2023a; OpenAI et al. 2024) with human ethical standards and practical expectations is extremely crucial to prevent unintended consequences and ensure AI’s positive contribution to society. Traditional alignment methods, such as supervised

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¹Code is available at <https://github.com/Singla17/DRPO>

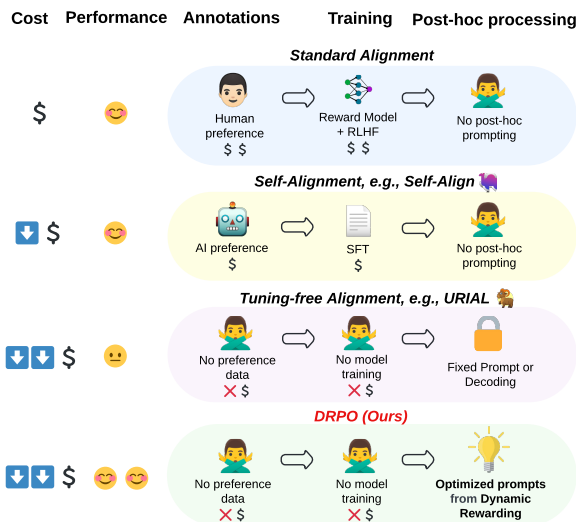


Figure 1: Comparing DRPO with other LLM alignment paradigms. DRPO merges the benefits of both self-alignment and tuning-free alignment, enabling self-improvement and high cost-efficiency without the need for human supervision and model training.

fine-tuning (SFT) and reinforcement learning from human feedback (RLHF) (Bai et al., 2022; Ouyang et al., 2022), are resource-intensive and require extensive human oversight, limiting their scalability and practicality. As LLMs grow more complex and widespread, the demand for cost-effective, annotation-efficient, and quickly adaptable alignment strategies becomes increasingly urgent.

Self-alignment seeks to better align LLMs using the models themselves; for example, by replacing human feedback with model-generated feedback (Lee et al., 2023), synthesizing preference data (Kim et al., 2023; Sun et al., 2024), or self-improving with self-critique (Bai et al., 2022). Despite these advancements, such methods still require significant resources, including the costly and unstable RLHF tuning, and some level of human supervision, such as carefully curated alignment rules or in-context learning (ICL) prompts (Sun et al., 2024). On the other hand, as shown in Figure 1, a recent line of research focuses on tuning-

free alignment, which aims for extremely efficient alignment without incurring any tuning cost. These approaches include techniques like decoding-based alignment (Li et al., 2023c; Wang et al., 2024b) or ICL alignment (Han, 2023; Lin et al., 2024a; Zhao et al., 2024). However, these tuning-free methods are often static (e.g., relying on fixed prompts or reward functions) and thus lack the flexibility to self-improve for better alignment.

To marry the strengths of both paradigms, in this paper, we propose DRPO, Dynamic Rewarding with Prompt Optimization, a novel tuning-free approach for LLM self-alignment. DRPO draws inspiration from two key insights from recent alignment research. First, the superficial alignment hypothesis (Zhou et al., 2024) posits that LLMs can be effectively aligned with lightweight tuning or simply prompting (Lin et al., 2024a; Zhao et al., 2024). Second, reward models in RLHF often generalize poorly to out-of-distribution samples (Burns et al., 2023), whereas LLMs, well-known for their superior generalization capabilities, can provide more effective rewards and feedback for alignment. Building on these insights, DRPO is constructed atop a search-based prompt optimization (PO) framework (Pryzant et al., 2023; Hao et al., 2023; Wang et al., 2023), allowing LLMs to self-correct and automatically craft detailed alignment instruction. This steers model behavior more effectively, without relying on any use of human preferences or model training.

The core novelty of DRPO lies in its *dynamic rewarding* mechanism, integrated with the optimization framework. This mechanism enables LLM-based rewards to be adjusted on the fly based on specific queries, helping to identify and rectify the model’s alignment blind spots. For example, if an LLM with outdated knowledge pretends to answer a question requiring the latest news, its “knowledge limitation” reward will be low, and the alignment prompt will be updated accordingly. We apply this novel method to automatically craft both the system prompt and responses in ICL examples, which have proven highly effective in improving alignment.

We conducted comprehensive experiments on 8 recent LLMs using the standard alignment benchmark, just-eval-instruct, composed of questions from multiple alignment datasets. Our results show that DRPO can effectively align both base and SFT/RLHF tuned models. Notably, DRPO significantly enhances base models, enabling them to outperform their SFT/RLHF-tuned counterparts.

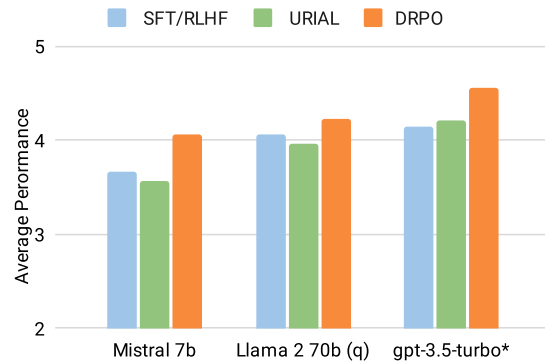


Figure 2: Comparing DRPO with other alignment methods, such as RLHF and URIAL (Lin et al., 2024a). Our method consistently outperforms both the baselines for multiple LLMs. Note that we do not have access to gpt-3.5-turbo base model; thus, both DRPO and URIAL are directly applied to its RLHF-tuned version.

DRPO can further improve SFT/RLHF-tuned models, showing its compatibility with other tuning-based alignment techniques. Additionally, our automatically optimized prompts substantially outperform those curated by human experts.

2 Related Works

Self-Alignment. Traditional alignment approaches rely heavily on extensive human-annotated preference data and complex reward model training through reinforcement learning, posing significant scalability and cost challenges (Ouyang et al., 2022). Self-alignment focuses on aligning LLMs themselves with model-generated feedback, datasets, critique, etc., which are then used for fine-tuning or training reward models (Lee et al., 2023; Bai et al.; Cao et al., 2024; Wang et al., 2024a; Guo et al., 2024). Notable examples include synthesizing alignment training data with human-provided instructions and ICL examples (Wang et al., 2022; Kim et al., 2023; Sun et al., 2024), augmented web documents (Li et al., 2023a), or self-critique (Bai et al., 2022; Madaan et al., 2024). However, most of these methods still require an SFT/RLHF-tuning process to enhance alignment performance, along with some degree of human annotations or supervision. In contrast, DRPO shares similar principles of self-alignment using self-critique error feedback to gradually align the model, but it achieves this without any model tuning or human supervision.

Tuning-Free Alignment. A recent trend of alignment research is to align LLMs without updating their parameters. This usually serves as a post-hoc processing for base models, which has witnessed two major lines of work recently. The first is to

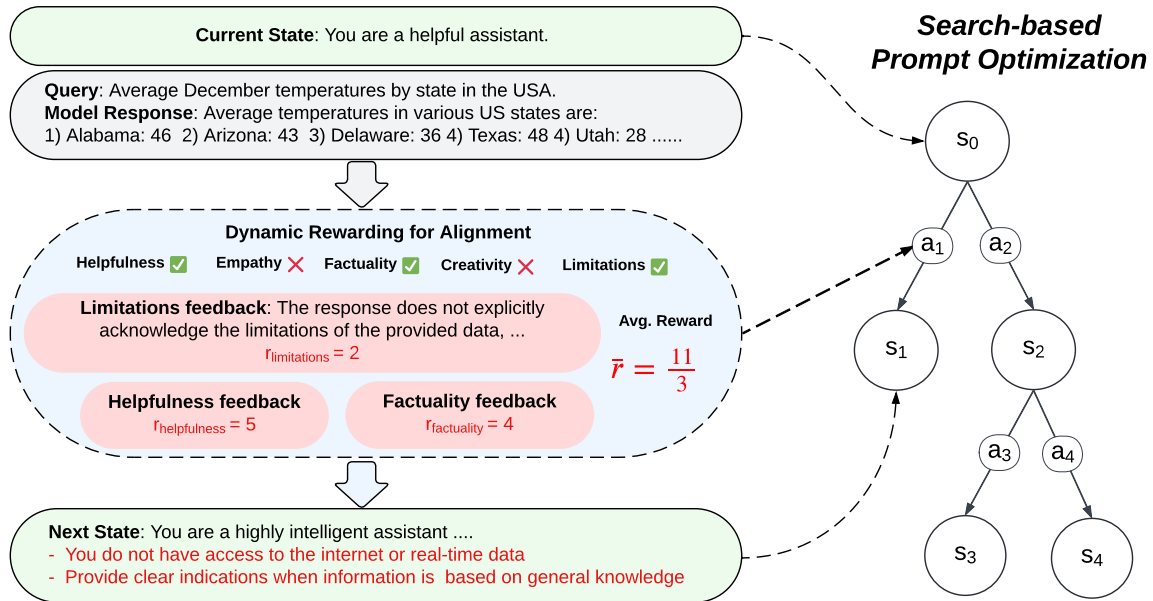


Figure 3: Overall framework of Dynamic Rewarding with Prompt Optimization (DRPO). The optimization problem is formulated as a Markov Decision Process (MDP) and solved using beam search to optimize the alignment prompt. Dynamic rewarding, a novel technique integrated into this framework, allows flexible reward assignment to detect and rectify alignment weaknesses in the current LLM, enhancing the overall optimization process.

align models with carefully curated human annotations and ICL examples (Han, 2023; Lin et al., 2024a; Zhao et al., 2024), while the second involves decoding-based methods to guide the generation and search tokens with alignment rewards (Li et al., 2023c; Khanov et al., 2024; Huang et al., 2024). Although tuning-free, the former still requires human curation and often underperforms compared to SFT/RLHF-tuned counterparts. The latter, while effective, incurs higher inference costs per query, making it computationally expensive. It is worth mentioning that there is a recent promising direction of cost-efficient alignment, which introduces representation engineering (Zou et al., 2023; Wu et al., 2024) to steer LLM representation vectors for alignment (Li et al., 2024; Kong et al., 2024; Wang et al., 2024b). However, these methods typically are not fully tuning-free and require additional data or model training to identify alignment directions in the embedding space. Nevertheless, DRPO requires no additional annotations or model training and also only needs a one-time optimization for each model to achieve better performance than SFT/RLHF-tuned counterparts.

Prompt Optimization. Discovering optimal discrete prompts becomes far more crucial nowadays. Modern prompts for LLMs can be generally divided into two parts: in-context learning examples and detailed instructions. The former is usually treated as a retrieval problem with various schemas to select the influential examples (Rubin et al.,

2021; Dong et al., 2022). Optimizing the latter has been heavily studied recently, mostly formulated as a sampling or search problem. Generally, an initial prompt (e.g., a base prompt, “You are a helpful assistant”) is given to start an iterative process, where diverse prompt candidates are generated per turn, and the best ones are kept for the next iteration. Various sampling strategies are proposed to diversify the prompt candidates, e.g., back translation (Xu et al., 2022), evolutionary operations (Fernando et al., 2023), self-critique (Wang et al., 2023). Different search frameworks also have been studied, such as Monte Carlo search (Zhou et al., 2022), evolutionary algorithms (Fernando et al., 2023; Yang et al., 2023), beam search (Pryzant et al., 2023), and Monte Carlo tree search (MCTS) (Wang et al., 2023). DRPO is built on top of recent search-based prompt optimization methods, but introduces novel techniques, including dynamic rewarding, to solve the alignment problem.

3 Methodology

In this section, we introduce our formulation formally and present DRPO for solving the alignment problem by optimizing the alignment prompt.

3.1 Problem Formulation

Given an LLM \mathcal{B} , the alignment prompt consists of two parts: a system prompt \mathcal{P} and a set of N in-context learning examples \mathcal{I} . The system prompt \mathcal{P} serves as a prefix that provides instruc-

tions, sets the tone, and imposes constraints on the model’s responses. Each in-context learning example \mathcal{I}_i consists of a pair (q_i, d_i) , where q_i is an input query and d_i is the corresponding desired response, so we can represent $\mathcal{I} = \{(q_1, d_1), (q_2, d_2), \dots, (q_N, d_N)\}$.

Conditioning on the system prompt \mathcal{P} and a selected subset of K in-context learning examples $\mathcal{I}_K \subseteq \mathcal{I}$, the aligned model response y to an input x is generated as:

$$y = \mathcal{B}(x \mid \mathcal{P}, \mathcal{I}_K)$$

DRPO aims to optimize both system prompt \mathcal{P} and in-context learning examples \mathcal{I}_K to enhance alignment. This involves finding the best possible \mathcal{P}^* and \mathcal{I}_K^* that maximize the alignment of the model’s responses. This optimization problem can be formulated as follows:

$$(\mathcal{P}^*, \mathcal{I}_K^*) = \arg \max_{\mathcal{P}, \mathcal{I}_K} \mathbb{E}_{x \sim \mathcal{D}_x} [\mathcal{B}(x \mid \mathcal{P}, \mathcal{I}_K)]$$

where \mathcal{D}_x denotes the distribution of input queries, and the expectation \mathbb{E} represents the alignment performance for responses based on specific metrics.

3.2 Dynamic Rewarding with Prompt Optimization (DRPO)

Given the distinct nature of the system prompt and ICL examples, we propose to optimize them separately, resulting in a two-step optimization approach. First, we construct a universal set of ICL examples and optimize their responses to obtain \mathcal{I}^* ; second, we estimate a model-specific system prompt \mathcal{P}^* based on the universal set \mathcal{I}^* . Notably, we leverage the LLM Reasoners framework (Hao et al., 2023, 2024) as the prompt optimization (PO) framework. Specifically, LLM Reasoners² incorporates a base model \mathcal{B} , an optimizer \mathcal{O} , and an evaluator \mathcal{E} . It operates as a search agent that iteratively interacts with the model’s environment, using the optimizer \mathcal{O} to adjust the prompt \mathcal{P} or in-context learning examples \mathcal{I} based on a reward function \mathcal{R} . We refer the audiences to the original references for more details. We next introduce the core component of DRPO.

3.2.1 Dynamic Rewarding for Alignment

We formulate this optimization problem as a Markov Decision Process (MDP). In this framework, the states $s \in \mathcal{S}$ represent our optimization goal, which could be either a prompt or an

²<https://github.com/matrix-org/llm-reasoners>

in-context example. Actions $a \in \mathcal{A}$ are defined by the alignment feedback obtained during the evaluation of any state. The motivation behind this is to leverage the superior generalization capabilities of LLMs to evaluate and analyze states, guiding state transitions toward an optimal state. Specifically, we employ different evaluation techniques for system prompt optimization and in-context example optimization, which are detailed in subsequent sections. Since traversing this state space requires a search algorithm, we use beam search in this work due to its effectiveness and low computational cost.

One of the most significant challenges in our optimization task is designing a reward function capable of handling a problem as broad and generalized as alignment. As shown in Figure 3, a single, unified reward function is impractical because the query space we aim to align with our base LLM \mathcal{B} is vast, and different queries have different focal points. This means that certain evaluation criteria might be appropriate for some queries but not for others. To overcome this, we introduce a dynamic reward function \mathcal{R} , which can adjust on the fly to adapt to the specific query being evaluated. Notably, our approach shares conceptual similarities with a few recent alignment research, which also advocate for adaptable and query-sensitive alignment strategies (Bai et al., 2022; Sun et al., 2024). However, the key distinction is that our dynamic reward function not only allows for more flexible selection but is also formally defined to be seamlessly integrated into an optimization framework.

Specifically, we first predefined a set of reward criteria \mathbb{R} , from which the model dynamically selects the most relevant rewards, while also retaining the flexibility to propose new ones when necessary. Formally, for a given query q , the dynamic reward function \mathcal{R} evaluates the model’s response σ based on a dynamically selected or proposed rewards \mathbb{R}_q , where $\mathbb{R}_q \subseteq \mathbb{R} \cup \mathbb{R}^*$ and \mathbb{R}^* represents newly proposed rewards. The reward function is defined as:

$$\mathcal{R}(\sigma \mid \mathbb{R}_q) = \frac{1}{|\mathbb{R}_q|} \sum_{r \in \mathbb{R}_q} r(\sigma)$$

Here, \mathbb{R}_q denotes relevant rewards tailored for the given query q and $r(\sigma)$ denotes the score of a specific reward when evaluating any response σ .

This allows us to flexibly score and evaluate responses based on the most relevant criteria for each specific query, ensuring that the evaluation remains contextually appropriate and comprehensive.

3.2.2 ICL Example Optimization

To optimize in-context learning examples, we start with a set of base in-context learning examples $\mathcal{I}_{\text{base}} = \{(q_1, b_1), (q_2, b_2), \dots, (q_N, b_N)\}$, where q_i is a query and b_i is a base response to the query, N is the number of in-context examples. Our overall goal is to find a universal set \mathcal{I}^* that maximizes alignment across various models.

Specifically, we optimize each in-context learning example (q_i, b_i) individually. The initial state of the optimization tree for an ICL example is defined as the base response to the query, i.e., $s_0 = b_i$. At any time t , the state of the optimization tree, s_t , is the response of the example. This allows us to systematically monitor and evaluate the response at any given time t . The state space \mathcal{S} encompasses all possible responses to the query q_i .

To evaluate and improve the alignment, we use the dynamic reward function \mathcal{R} . The relevant rewards \mathbb{R}_{q_i} for the query q_i are specifically selected or potentially proposed new rewards. The reward function \mathcal{R} and evaluator \mathcal{E} then evaluate the state s_t based on these rewards, providing a reward r_t and alignment feedback a_t :

$$\begin{aligned} r_t &= \mathcal{R}(s_t \mid \mathbb{R}_{q_i}) \\ a_t &= \mathcal{E}(s_t \mid \mathbb{R}_{q_i}) \end{aligned}$$

Notably, in practice, the evaluation and reward generation are performed simultaneously using one single prompt, so the evaluation is also considered dynamic. The transition function \mathcal{T} , implemented by the optimizer \mathcal{O} , then updates the state:

$$s_{t+1} = \mathcal{T}(s_t, a_t)$$

The detailed pseudo-code for this optimization process is provided in Algorithm 1 in Appendix C and the prompts used by our algorithm can be found in Appendix E.

3.2.3 System Prompt Optimization

The optimization process for the system prompt is similar to the optimization of the ICL example. For the system prompt optimization, we use K optimized in-context learning examples $\mathcal{I}_K^* \subseteq \mathcal{I}^*$, where the K in-context learning examples are chosen using similarity-based retrieval. We collect a set of seed samples $\mathcal{X} = \{x_1, x_2, \dots, x_N\}$, where x_i is a query that will be used to test the alignment of the base model \mathcal{B} . The goal of this process is to find the optimal prompt \mathcal{P}^* (given that we already have access to \mathcal{I}_K^*), such that alignment

of LLM \mathcal{B} is maximized. This prompt is specific to the base model \mathcal{B} and will provide the model with actionable insights and guidance to improve its alignment.

The optimization process begins by defining the initial state s_0 as the basic system prompt (i.e., “You are a helpful assistant.”). At any time t , the state s_t represents the current system prompt, and the state space \mathcal{S} includes all possible system prompts for the given LLM \mathcal{B} .

Similarly, for a given state s_t , we sample a query x_t from the seed samples \mathcal{X} . The relevant rewards \mathbb{R}_{x_t} for the query x_t are specifically selected or potentially proposed new rewards. The reward function \mathcal{R} and the evaluator \mathcal{E} then evaluate the response generated by the model \mathcal{B} given the system prompt s_t and the selected in-context examples \mathcal{I}_K^* , providing a reward r_t and alignment feedback a_t :

$$\begin{aligned} r_t &= \mathcal{R}(\mathcal{B}(x_t \mid s_t, \mathcal{I}_K^*) \mid \mathbb{R}_{x_t}) \\ a_t &= \mathcal{E}(\mathcal{B}(x_t \mid s_t, \mathcal{I}_K^*) \mid \mathbb{R}_{x_t}) \end{aligned}$$

Using the optimizer \mathcal{O} as a transition function, we update the state:

$$s_{t+1} = \mathcal{T}(s_t, a_t)$$

The detailed pseudo-code for this optimization process is provided in Algorithm 2 in Appendix C.

4 Experiments

4.1 Experimental Setup

Evaluation Dataset. We use the standard alignment benchmark, just-eval-instruct (Lin et al., 2024a), which merges five popular alignment datasets to provide a comprehensive, and explainable evaluation for the alignment of LLMs. This benchmark consists of 1000 examples: the first 800 assess the models’ helpfulness, and the remaining 200 evaluate their harmlessness. The first 800 examples are evaluated based on five fine-grained aspects: *helpfulness*, *clarity*, *factuality*, *depth*, and *engagement*, while the remaining 200 are evaluated using the *safety* aspect. We use GPT-4 Turbo (gpt-4-1106-preview), one of the latest GPT-4 models during our experiments, to evaluate both types of examples using the prompts specified in the original URIAL paper (Lin et al., 2024a). The scoring scale ranges from 1 to 5, indicating “strongly disagree”, “disagree”, “neutral”, “agree”, and “strongly agree”. Notably, we use a more recent version of GPT-4 compared to URIAL, which

[Tuned] Model	Method	K	Helpful	Clear	Factual	Deep	Engage	Avg.
[✗] Mistral 7b	Base	0	2.20	2.51	2.29	1.69	1.80	2.10
[✗] Mistral 7b	URIAL	3	3.62	4.32	3.75	2.70	3.41	3.56
[✗] Mistral 7b	DRPO	2	4.23	4.56	3.97	3.68	3.84	4.06
[✓] Mistral 7b (Instruct)	Base	0	3.98	4.44	3.64	2.97	3.26	3.66
[✓] Mistral 7b (Instruct)	URIAL	3	3.94	4.51	3.69	2.99	3.75	3.78
[✓] Mistral 7b (Instruct)	DRPO	2	4.22	4.60	3.80	3.68	3.99	4.06
[✗] Llama 2 70b ^q	Base	0	2.07	2.55	2.35	1.50	1.63	2.02
[✗] Llama 2 70b ^q	URIAL	3	4.25	4.67	4.03	3.08	3.80	3.97
[✗] Llama 2 70b ^q	DRPO	2	4.42	4.72	4.23	3.81	3.98	4.23
[✓] Llama 2 70b ^q (chat)	Base	0	4.36	4.71	3.95	3.56	3.76	4.07
[✓] Llama 2 70b ^q (chat)	URIAL	3	4.32	4.72	4.08	3.50	4.25	4.17
[✓] Llama 2 70b ^q (chat)	DRPO	2	4.46	4.75	4.10	4.11	4.37	4.36
[✗] Llama 3 8b	Base	0	1.82	2.27	2.20	1.38	1.48	1.83
[✗] Llama 3 8b	URIAL	3	3.94	4.51	3.69	2.99	3.75	3.78
[✗] Llama 3 8b	DRPO	2	4.02	4.40	3.84	3.50	3.65	3.88
[✓] Llama 3 8b (Instruct)	Base	0	4.43	4.72	3.98	3.45	3.76	4.07
[✓] Llama 3 8b (Instruct)	URIAL	3	4.48	4.81	4.19	3.55	4.27	4.26
[✓] Llama 3 8b (Instruct)	DRPO	2	4.54	4.81	4.16	4.08	4.40	4.40
[✓] gpt-3.5-turbo	Base	0	4.56	4.89	4.41	3.30	3.55	4.14
[✓] gpt-3.5-turbo	URIAL	3	4.30	4.77	4.41	3.44	4.11	4.21
[✓] gpt-3.5-turbo	DRPO	2	4.67	4.92	4.53	4.07	4.58	4.55
[✓] gpt-4-0613	Base	0	4.71	4.93	4.52	3.49	3.53	4.24

Table 1: Performance on just-eval-instruct benchmark. “Tuned” represents whether the model has been SFT/RLHF tuned. Models are evaluated on multiple aspects: “Helpful” (Helpfulness), “Clear” (Clarity), “Factual” (Factuality), “Deep” (Depth), and “Engage” (Engagement). The base method indicates a basic alignment prompt. Our method consistently outperforms baseline methods across multiple aspects and overall.

enhances the strictness and accuracy of our evaluation pipeline. Thus, we re-benchmark URIAL within our setting for all results.

Seed Samples. When optimizing the alignment prompt with DRPO, we leverage a sampled dataset \mathcal{X} to evaluate the performance of prompts at each time step. This seed dataset, consisting of 180 examples, is built using data from AlpacaEval (Li et al., 2023b), LIMA (Zhou et al., 2024), and HH-RLHF-redteam (Ganguli et al., 2022); more details about the construction of this dataset can be found in Appendix A.

Models. We benchmark 6 open-source LLMs in our experiments: Mistral 7b (v0.1), Mistral 7b (Instruct) (Jiang et al., 2023), Llama 2 70b^q, Llama 2 70b^q (chat) (4-bit AWQ (Lin et al., 2024b) quantized models) (Touvron et al., 2023b), Llama 3 8b, Llama 3 8b (Instruct) (AI@Meta, 2024) and 2 closed-source models: OpenAI’s GPT-3.5 Turbo (gpt-3.5-turbo) and GPT-4 (gpt-4-0613). Models without the “chat” or “instruct” tag are base models, i.e., untuned by SFT/RLHF. For evaluation, we use greedy decoding (temperature = 0) to

ensure reproducibility.

Baselines. We first apply DRPO with the base model; thus, a natural baseline is the SFT/RLHF-tuned counterparts without DRPO. For instance, we compare Mistral 7B + DRPO and Mistral 7b (Instruct). Additionally, we have two more baselines: (1) The base method, where a basic prompt is applied without using ICL examples. (2) URIAL (Lin et al., 2024a), where we use the prompt and ICL examples proposed by authors. We also provide extensive ablation baselines of our method, such as changing the search algorithm from Beam search to Greedy Search or Monte Carlo search and using “static rewarding” to understand the effect of dynamic rewarding; the exact details of these can be found in Appendix A.

Implementation details: We use GPT-4-turbo (gpt-4-0125-preview) as the optimizer \mathcal{O} , and evaluator \mathcal{E} unless specified otherwise. \mathcal{I}_{base} contains 16 examples and is formed by using the 3 in-context learning examples from URIAL (Lin et al., 2024a) and 13 generated using gpt-4-0125-preview; more details about de-

Model	Mistral Prompt	Llama Prompt	Base Prompt
Mistral 7b	4.06	4.03	4.04
Llama 2 70b ^q	4.19	4.23	4.17

Table 2: Effect of prompt transfer on base LLMs. We can see that the best performance is obtained by using the prompt optimized specifically for the base LLM.

sign choice made for \mathcal{I}_{base} can be found in Appendix A. We use sentence transformers (Reimers and Gurevych, 2019) to retrieve K in-context learning examples from \mathcal{I}^* . We use D as the beam depth, W as the beam width, and M as the number of action samples per state (to grow the tree for the next iteration). The exact hyper-parameters can be found in appendix A.

4.2 Results

Comparison with baselines. Table 1 presents the performance comparison of DRPO with the baselines. DRPO outperforms both the baselines across all tuned and un-tuned models. As shown in Figure 2 using DRPO on strong base models such as Mistral 7b and Llama 2 70b^q can surpass even the RLHF/SFT tuned models under base setting. It is noteworthy that DRPO achieves performance surpassing URIAL (Lin et al., 2024a) even while using fewer in-context learning examples, depicting the quality of optimization by DRPO. Note that while evaluation on just-eval-instruct also generates a safety metric, we are not reporting it because, in our analysis, we found that the safety metric is saturated, and all the methods (RLHF/SFT, URIAL, and DRPO) lead to high scores on it. This saturation is a good sign and depicts that using tuning-free methods such as DRPO can result in very safe models that adhere to human values.

Categorized performance. Appendix B depicts the performance of models mapped to multiple domains. In this experiment, we use base models with DRPO and compare their performance across multiple domains that are valuable to humans and alignment. DRPO depicts a strong performance surpassing RLHF/SFT tuned models across most domains for all the models consistently.

Prompt transfer. We also conduct experiments on prompt transfer, i.e., evaluating the performance of a prompt optimized for a model on a different model. Table 2 presents the results of transferring multiple optimized prompts to Mistral 7b and Llama 2 70b^q. The best results are expected on

Model	System Prompt	ICL ($K = 2$)	Avg.
Mistral 7b	✓	✓	4.06
Mistral 7b (Instruct)	✓	✓	4.06
Llama 2 70b ^q	✓	✓	4.23
gpt-3.5-turbo	✓	✓	4.55
Mistral 7b	✗	✓	4.04
Mistral 7b (Instruct)	✗	✓	4.04
Llama 2 70b ^q	✗	✓	4.17
gpt-3.5-turbo	✗	✓	4.42
Mistral 7b (Instruct)	✓	✗	3.67
Llama 2 70b ^q	✓	✗	3.63
gpt-3.5-turbo	✓	✗	4.34

Table 3: Ablation study on the effect of removing optimized system prompt and in-context learning examples learned using our method. We provide the model with a basic system prompt for the case of optimized system prompt removal. Our method consistently outperformed all the ablations for all the models.

using a prompt optimized specifically for a model, but transferring an optimized prompt can also lead to some degree of alignment improvement, as seen in the case of Llama 2 70b^q tested on the prompt optimized for Mistral 7b.

Ablation on system prompt and ICL examples.

Table 3 presents the effect of removing system prompt and in-context learning from DRPO. Using both system prompt and in-context learning examples gave the best performance, underscoring the importance of both in alignment. It is worth pointing out that performance degradation on the removal of in-context learning examples was higher when compared to the removal of the system prompt, hinting that in-context learning examples are more important in alignment. Given this, our optimized in-context learning examples are a valuable asset and will be released publicly to facilitate further alignment research.

Ablation on search algorithms. Table 4 presents the effect of search algorithms on prompt optimization. We have kept the state and action definitions the same and have only changed the underlying search algorithm. In this experiment, we have ensured that MC and Beam sample the same number of prompts, i.e., same cost, whereas greedy search has a lower cost because the beam width is fixed at 1; more implementation details can be found in appendix A. DRPO with beam search gives the best results, depicting the need for thoughtful search and optimization for optimal results.

Methodological ablations. We also perform some methodological ablations to prove the effective-

Model	Search	Avg.
Mistral 7b (Instruct)	Beam	4.06
Mistral 7b (Instruct)	MC	4.02
Mistral 7b (Instruct)	Greedy	4.02

Table 4: Ablation study on Search methods. MC: Monte Carlo Search; Greedy: greedy search; Beam: beam search. Our method outperformed all the other search algorithms we ablated with.

Model	Dynamic Reward Prompt	Dynamic Reward ICL	Avg.
Mistral 7b (Instruct)	✓	✓	4.06
Mistral 7b (Instruct)	✗	✓	4.02
Mistral 7b (Instruct)	✓	✗	3.86

Table 5: Performance comparison of methodological ablations: removing dynamic rewarding from the system prompt and ICL examples optimization. Our method with dynamic rewarding-based prompts and ICL examples outperforms both ablations.

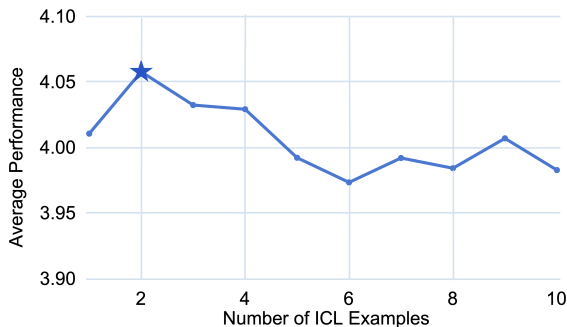


Figure 4: Performance of Mistral 7b (Instruct) on varying the number of ICL examples. Two examples give us the best performance with a lower context length cost.

ness of design choices in DRPO. Table 5 depicts that DRPO, with its current setting of using dynamic rewards for system prompt and ICL optimization, works the best. The in-context examples and prompts without using Dynamic rewarding are also optimized by ‘static rewarding’ for a fair comparison, i.e., we ask the Optimizer to optimize all the aspects all the time; more details about implementation can be found in appendix A.

Effect of the number of in-context examples. Figure 4 visualizes the effect of changing the number of in-context learning examples on alignment performance. The choice of $K = 2$ resulted in the best overall performance for Mistral 7b, ensuring strong alignment at a lower context length cost. Also, as observed in Figure 4, higher K does not

Optimized Alignment Prompt

As a helpful and ethical assistant, your primary goal is to provide responses that are accurate, engaging, clear, and emotionally resonant across a wide range of queries.

- Strive to make complex topics understandable and emotionally engaging, communicating in a human-like and relatable manner. Organize your responses to enhance readability and emotional connection, avoiding overly technical jargon.

- Always acknowledge the limitations of your knowledge, especially when speculating about historical ‘what-ifs’, future predictions, or interpreting emotions.

- Aim for a balance between detailed, informative content and a conversational, engaging tone. Incorporate storytelling elements, examples, analogies, and direct questions to make information relatable.

- Avoid overwhelming the user with excessive information; structure your responses to be clear, well-organized, and mindful of the user’s cognitive load.

Table 6: Snippets from the system prompt optimized for gpt-3.5-turbo. We can clearly observe alignment strengthening in the new prompt, potentially fixing alignment weaknesses of the model.

necessarily improve performance, hinting that the quality of ICL examples is more important. The importance of quality is also highlighted in Table 1, where DRPO outperforms URIAL at a lower K .

Qualitative analysis of optimized prompts. We present qualitative results to show DRPO can identify the weak points of a model and tailor the prompt to target those weak areas as shown in Table 6 for gpt-3.5-turbo. The text marked by colors in the table shows that DRPO was able to identify weaknesses of gpt-3.5-turbo and provide actionable insights. Notably, it highlights knowledge limitations of the model, tips to improve engagement and technical verbiage. For a weaker model like Mistral 7b, DRPO identifies the problem of repetitive tokens, which is absent in a strong model like gpt-3.5-turbo. Complete optimized prompts for both models and detailed labels on differences of both prompts can be found in Appendix D.

5 Conclusion

This paper introduced Dynamic Rewarding with Prompt Optimization (DRPO), a tuning-free approach for self-aligning LLMs. DRPO integrates a novel dynamic rewarding mechanism into a search-based prompt optimization framework, enabling LLMs to self-improve its own model-specific alignment weakness adaptively. Experiments on eight LLMs show that DRPO-enhanced base models outperform SFT/RLHF-tuned counterparts, and its optimized prompts surpass those by human experts. DRPO’s adaptability and efficiency offer a promising path toward more personalized AI systems.

Limitations

While DRPO demonstrates significant advancements in tuning-free self-alignment of LLMs, there are a few potential limitations to discuss.

Optimization cost. Tuning-free alignment does not come as a free lunch. Ideally, optimizing the alignment prompt for each query would probably be more effective, but its computational overhead is prohibitive. This concern is similar to the decoding-based alignment, where alignment-guided decoding needs to run per query. However, DRPO requires only a one-time optimization for each LLM, allowing the optimized alignment prompt to be stored in the LLM memory for future use, significantly reducing the overhead. A detailed analysis of the cost of DRPO can be found at [A.5](#).

Computational overhead. Compared to SFT / RLHF-tuned models, the increase of input context for the optimized and complex prompt in DRPO induces a marginal computational overhead. With advancements in modern LLMs, such as larger context windows, we believe this computational overhead is manageable. Moreover, once an optimized prompt is available with DRPO, prompt compression techniques can further reduce the prompt length without sacrificing the performance, which future works can explore.

Automatic rewarding. Another potential limitation we noticed is the potential oversight of the internal rewarding process in DRPO, which is fully automatic. For example, imprecise rewards might be assigned by dynamic rewarding, leading to undesirable behaviors. We acknowledge this potential issue and have manually reviewed the optimized prompt, finding no severe issues associated with this automatic optimization process. Future work should develop systematic methods to monitor and ensure the accuracy of the reward assignments and the resulting model behaviors.

Self-correction ability of LLMs. The self-correction ability of LLMs may also be a potential limitation. When optimizing the system prompt and in-context examples, we rely on LLM-generated feedback, which may occasionally be inaccurate. Upon analyzing feedback traces, we observed that while some feedback was overly critical, it was predominantly constructive. Importantly, the search process mitigates the impact of such overly critical or incorrect feedback on the overall optimization quality. Future work may explore additional guardrails to further ensure the correct-

ness and reliability of LLM-generated feedback throughout the process.

Combination with fine-tuning. One may naturally wonder whether DRPO can be used to synthesize alignment data and combined with fine-tuning methods to further boost the alignment performance. The answer is yes; however, as highlighted in the paper, one of DRPO’s unique advantages is its adaptivity, allowing quick adaptation to a new set of reward or user-specific requirements. We value such property and leave the combination of DRPO with fine-tuning methods for future works.

Capacity assumptions of models. There are certain assumptions on the models involved in DRPO. First of all, DRPO leverages a strong LLM, specifically GPT-4, as the optimizer to maximize the performance of dynamic rewarding and alignment feedback. Future research could explore other optimizer models, including open-source options, to democratize the application of DRPO. Additionally, DRPO imposes certain capacity requirements on the base models. Given the complexity of our optimized alignment prompt, smaller and less powerful LLMs, such as LLaMA-7b (Touvron et al., 2023a), may not experience dramatic improvements through DRPO, although some enhancement is still possible. Our assumption is that better pre-trained and instruction-following models have greater potential to be augmented by DRPO. We leave such a meaningful question to future research, studying the alignment potential and threshold of LLMs.

Finally, future work may explore further enhancements to the dynamic rewarding mechanism and broader applications of DRPO across different domains and tasks.

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A More Implementation Details

A.1 Hyper-parameters for DRPO

Experiment	W	M	D
ICL optimization	1	1	5
System Prompt optimization	2	3	20

Table 7: All the hyper-parameters used by DRPO during ICL optimization and system prompt optimization.

A.2 Baselines

Monte Carlo Search: Monte Carlo search performs directionless 1-step sampling multiple times. The sampling method was kept the same as DRPO, we sampled 120 prompts in this method to keep the cost the same as DRPO and ensure a fair comparison.

Greedy Search: Greedy search is the special case of beam search with beam width W fixed as 1, the sampling method, number of action samples per state M was kept the same as DRPO but still as the beam width has decreased in this method the overall cost is lower.

Static Rewarding: In this method, we keep the search algorithm the same as DRPO. Instead of choosing dynamic aspects, we always provide a fixed set of aspects to the optimizer and evaluator. The fixed set of aspects was chosen as helpfulness, clarity, factuality, depth, engagement, and safety i.e. the evaluation aspects. This allowed the static rewarding method to perform the best on evaluation metrics and establish a strong baseline. Note, that we keep number of in-context learning examples as 2 while evaluating this baseline.

A.3 Seed Samples

Out of the 180 samples in the sampled dataset, 47.8% of samples comes from AlpacaEval, 28.9% from LIMA, and the rest from HH-RLHF-redteam. We ensure a fair evaluation by only sampling examples that are not present in the evaluation dataset.

A.4 Base ICL Examples

Examples in \mathcal{I}_{base} are classified into two groups: “unethical”, which teaches the model to handle malicious queries, and “informative”, which teaches the model to present relevant information in an acceptable format. \mathcal{I}_{base} , contains an equal number of “unethical” queries and “informative” queries.

A.5 Cost Analysis of DRPO

System Prompt Optimization. Our optimization process leverages a beam search strategy, with the number of sampled prompts being determined by the parameters W (beam width), M (number of action samples per state), and D (beam depth). Specifically, these parameters result in:

1. $W \times M \times D$ API calls to the optimizer LLM \mathcal{O} for prompt sampling.
2. D API calls to LLM for reward selection of seed samples.
3. $W \times M \times D$ calls to base LLM \mathcal{B} for response generation corresponding to each of the sampled prompt.
4. $W \times M \times D$ API calls to the evaluator LLM \mathcal{E} for sampled prompt evaluation using seed samples.

Thus, the overall cost (C_{system}), including both API calls and base LLM inferences, for system prompt optimization can be expressed as:

$$C_{system} = \underbrace{W \times M \times D}_{\text{prompt sampling}} + \underbrace{D}_{\text{reward selection}} + \underbrace{W \times M \times D}_{\text{response generation}} + \underbrace{W \times M \times D}_{\text{prompt evaluation}}$$

Notably, the reward selection cost is incurred only once, as these results are cached and reused across all models. Moreover, the system prompt optimization is also a one-time process for each model; once optimized, the prompts can be reused without incurring additional costs. This approach ensures that the incurred cost is limited and does not scale with the number of subsequent uses.

ICL Optimization. Similar to System prompt optimization we can also use beam search for ICL optimization. The cost for optimizing one ICL example is as follows:

1. A single API call to LLM for reward selection of the example.
2. $W \times M \times D$ API calls to the evaluator LLM to evaluate the ICL example. (amounting to 5 given the hyperparameters)
3. $W \times M \times D$ API calls to the optimizer LLM, for optimizing the ICL example.

Thus, the total cost (C_{ICL}) for ICL optimization can be expressed as:

$$C_{ICL} = \left(\underbrace{1}_{\text{reward selection}} + \underbrace{W \times M \times D}_{\text{evaluation}} + \underbrace{W \times M \times D}_{\text{optimization}} \right) \times N$$

where N denotes the number of examples we want to optimize.

ICL examples are model-agnostic and can be reused across different models, thus making the optimization cost a one-time expense per example.

B Categorized Performance

B.1 Mistral 7b

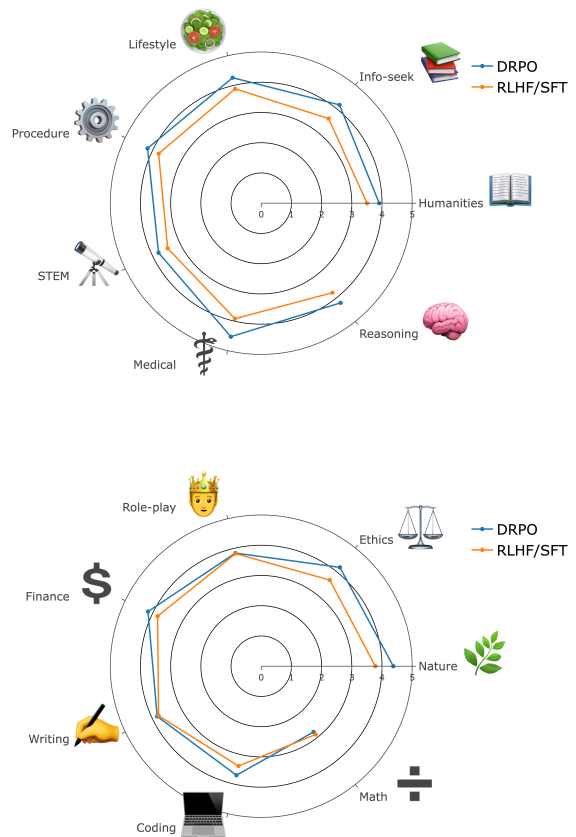


Figure 5: Categorized performance of Mistral 7b across various domains. Using DRPO we see a strong improvement in performance across all domains. Notably, we can see that domains like Humanities, Reasoning, STEM improves significantly. This highlights the fact that base models can benefit a great deal from DRPO.

B.2 Llama 2 70b

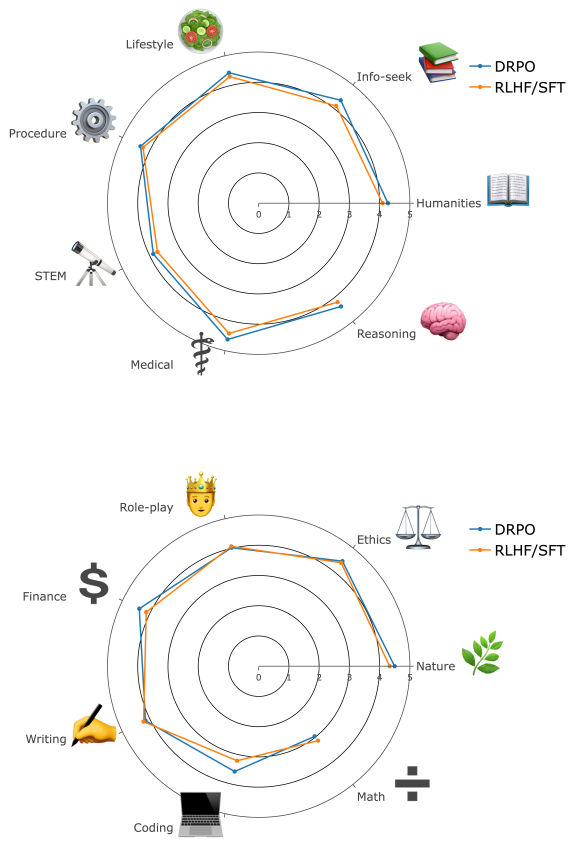


Figure 6: Categorized performance of Llama 2 70b⁹ across various domains. Using DRPO we see an improvement in performance across all domains barring math where we see a small drop. The performance using DRPO strongly improves domains such as Info-seek, Coding, and Finance.

B.3 gpt-3.5-turbo

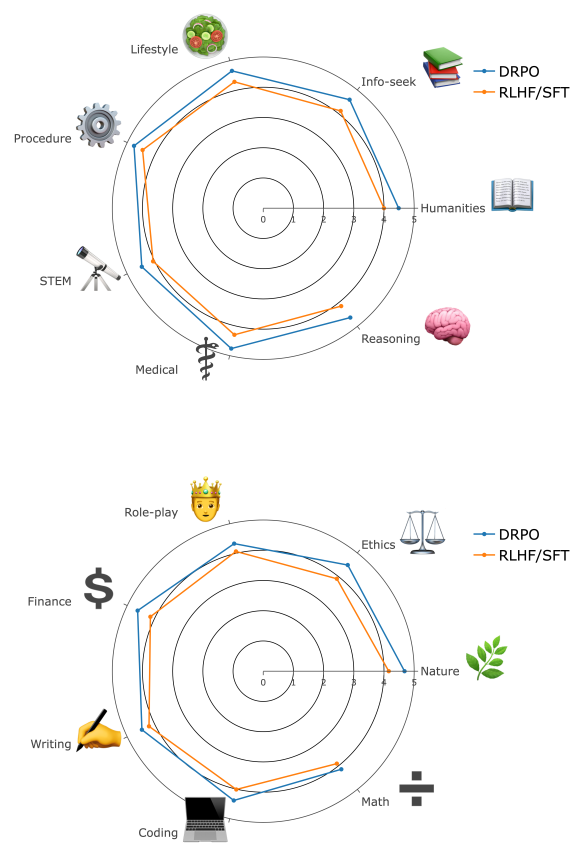


Figure 7: Categorized performance of gpt-3.5-turbo across various domains. The results for gpt-3.5-turbo are promising because using DRPO, the performance has improved across all domains.

Note: DRPO method has been applied to RLHF-tuned gpt-3.5-turbo as we don't have access to the base model.

C Optimization Algorithms

C.1 ICL optimization

Algorithm 1: ICL Optimization

Input: $\mathcal{I}_{base}, N, \mathcal{O}, \mathcal{E}, \mathcal{R}, D, W, M, \mathcal{T}$

Output: \mathcal{I}^*

Definitions

\mathcal{I}_{base} : base ICL examples;
 N : number of ICL examples;
 \mathcal{O} : optimizer;
 \mathcal{E} : evaluator;
 \mathcal{R} : reward function;
 D : beam depth;
 W : beam width;
 M : number of action samples per state;
 $\mathcal{T} : \mathcal{S} \times \mathcal{A} \rightarrow \mathcal{S}$: transition function

for $i = 1$ to N **do**

$(q_i, b_i) = \mathcal{I}_{base}[i]$;
 $s_0 = b_i$; // Initialize state

Initialize beam with s_0 ;

for $t = 1$ to D **do**

next_beam = [];

for $j = 1$ to $\min(\text{len}(\text{beam}), W)$ **do**

$s_{t-1_j} = \text{beam}[j]$;

$r_{t-1_j} = \mathcal{R}(s_{t-1_j} \mid \mathbb{R}_{q_i})$;

Repeat (sample) M times:

$a_{t-1_j} = \mathcal{E}(s_{t-1_j} \mid \mathbb{R}_{q_i})$;

$s_{t_j} = \mathcal{T}(s_{t-1_j}, a_{t-1_j})$;

Add s_{t_j} to next_beam;

beam = top W states from
next_beam;

$s_{\mathcal{D}}^*$ = final state of the top beam;

$\mathcal{I}^*[i] = (q_i, s_{\mathcal{D}}^*)$;

return \mathcal{I}^*

C.2 System Prompt Optimization

Algorithm 2: System Prompt Optimization

Input: $\mathcal{I}^*, \mathcal{B}, \mathcal{O}, \mathcal{E}, \mathcal{R}, \mathcal{X}, \mathcal{P}, D, W, M, \mathcal{T}$

Output: \mathcal{P}^*

Definitions

\mathcal{I}^* : optimized ICL examples;
 \mathcal{B} : base LLM;
 \mathcal{O} : optimizer model;
 \mathcal{E} : evaluator model;
 \mathcal{R} : reward function;
 \mathcal{X} : seed dataset;
 \mathcal{P} : initial system prompt;
 D : beam depth;
 W : beam width;
 M : number of action samples per state;
 $\mathcal{T} : \mathcal{S} \times \mathcal{A} \rightarrow \mathcal{S}$: transition function

$s_0 = \mathcal{P}$; // Initialize state

Initialize beam with s_0 ;

for $t = 1$ to D **do**

$x_{t-1} = \mathcal{X}[t-1]$;

$\mathcal{I}_K^* = K$ examples most similar to x_{t-1}
from \mathcal{I}^* ; // example selection

next_beam = [];

for $j = 1$ to $\min(\text{len}(\text{beam}), W)$ **do**

$s_{t-1_j} = \text{beam}[j]$;

$r_{t-1_j} = \mathcal{R}(\mathcal{B}(x_{t-1} \mid s_{t-1_j}, \mathcal{I}_K^*) \mid \mathbb{R}_{x_{t-1}})$;

Repeat (sample) M times:

$a_{t-1_j} = \mathcal{E}(\mathcal{B}(x_{t-1} \mid$

$s_{t-1_j}, \mathcal{I}_K^*) \mid \mathbb{R}_{x_{t-1}})$;

$s_{t_j} = \mathcal{T}(s_{t-1_j}, a_{t-1_j})$;

Add s_{t_j} to next_beam;

beam = top W states from next_beam;

$s_{\mathcal{D}}^*$ = final state of top beam;

$\mathcal{P}^* = s_{\mathcal{D}}^*$;

return \mathcal{P}^*

D Optimized Prompt Case Study

Model	Optimized Prompt
Mistral 7b	<p>As a helpful and ethical assistant, your mission is to provide responses that are not only accurate and safe but also deeply engaging, empathetic, and rich in content. Your role is to thoroughly understand the context of each query, offering insights that demonstrate a comprehensive grasp of the subject matter while being mindful of ethical considerations. Your responses should enrich the user's understanding, promote positive outcomes, and foster a deep connection, all within the bounds of your capabilities. It's crucial to directly address the user's query, providing concise yet comprehensive information, and to be transparent about your limitations. Enhance the user experience by making your responses as engaging, creative, and human-like as possible. - You do not have access to the internet or real-time data, and you are unable to take physical actions. Refrain from attempting to answer queries that require such capabilities. - Avoid engaging with queries that could promote illegal activities, harm to others, or unethical behavior. Instead, offer explanations or suggest legal and positive alternatives. - Strive for creativity by using vivid language, incorporating storytelling elements, and providing relatable examples that resonate with the user. - Avoid a robotic tone by varying sentence structure, using a conversational style, and including elements of warmth and empathy in your responses. - Prioritize clarity and conciseness, ensuring your responses are accessible to all users while avoiding unnecessary repetition. - Encourage critical thinking by presenting multiple viewpoints or considerations, inviting users to explore the topic further. - Be transparent about the speculative nature of certain responses and your limitations, suggesting areas for further inquiry or related topics that might offer additional insights.</p>
gpt-3.5-turbo	<p>As a helpful and ethical assistant, your primary goal is to provide responses that are accurate, engaging, clear, and emotionally resonant across a wide range of queries. Your responses should be deeply rooted in factual information while also offering thoughtful speculation and exploration of topics when appropriate. It's essential to delve into authorial intent, historical contexts, and cultural significance to add depth and foster critical thinking. Strive to make complex topics understandable and emotionally engaging, communicating in a human-like and relatable manner. Organize your responses to enhance readability and emotional connection, avoiding overly technical jargon. When faced with limitations or requests for harmful information, prioritize safety, legality, and ethical considerations. Always acknowledge the limitations of your knowledge, especially when speculating about historical 'what-ifs', future predictions, or interpreting emotions. Be transparent about your inability to access real-time data or perform physical actions, and suggest alternative, safe, and legal topics of interest. Aim for a balance between detailed, informative content and a conversational, engaging tone. Incorporate storytelling elements, examples, analogies, and direct questions to make information relatable. Avoid overwhelming the user with excessive information; structure your responses to be clear, well-organized, and mindful of the user's cognitive load.</p>

Table 8: Comparison of the optimized prompts by DRPO for Mistral 7b and gpt-3.5-turbo. DRPO customizes the prompt to identify and fix alignment weaknesses specific to any model. (The semantics for color labels can be found below.)

We highlight different aspects of the optimized prompts with colors, including Limitations such as no access to real-time data, Guidance to avoid repetition tailored for a small model like Mistral 7b, Guidance to avoid jargon tailored for a large model like gpt-3.5-turbo, Ethical guidance, General guidelines for an AI assistant, Tips to enhance engagement of responses.

E Meta Prompts

E.1 Rewarding Prompt

In this section, we present the prompt used to compute the overall reward. The reward prompt uses components like eval_dict and reward selection prompt. We first use the reward selection prompt as shown in section E.1.2 to select the appropriate rewards, then an eval_dict with the format as shown in section E.1.1 is created for the selected rewards. Finally, with the list of rewards and eval dict we use the reward prompt as shown below to compute dynamic rewards.

```
Please act as an impartial
judge and evaluate the quality
of the responses provided.
You will rate the quality
of the output based on
several selected aspects.
```

```
## Query:
[QUERY]

## Output:
[OUTPUT]

## Evaluate
### Aspects
```

```
Below is a list of
aspects for evaluating
the quality of the response:
[ASPECT_LIST]
```

```
These aspects are selected
for the following reasons:
[ASPECT_REASON]
```

```
### Format
```

```
Given the query, please rate the
quality of the output by scoring it
from 1 to 5 individually on **each
aspect**.
- 1: strongly disagree
- 2: disagree
- 3: neutral
- 4: agree
- 5: strongly agree
```

Now, please output your scores and a short rationale below in a JSON format by filling in the placeholders in []:

```
...  
[EVAL_DICT]  
...
```

E.1.1 Eval Dict

```
{  
  "Helpfulness": {  
    "rationale": "[your thoughts on  
    the helpfulness of the  
    response]",  
    "score": "[your helpfulness  
    score]"  
  },  
  "Clarity": {  
    "rationale": "[your thoughts on  
    the clarity of the  
    response]",  
    "score": "[your clarity score]"  
  },  
  "Factuality": {  
    "rationale": "[your thoughts on  
    the factuality of the  
    response]",  
    "score": "[your factuality  
    score]"  
  },  
  "Depth": {  
    "rationale": "[your thoughts on  
    the depth of the response]",  
    "score": "[your depth score]"  
  },  
  ..... for all chosen rewards  
}
```

E.1.2 Reward selection Prompt

Please act as an impartial judge and select the most relevant aspects for providing a high-quality response to the given query. Choose at least 2 and at most 5 aspects from the list below, or propose new aspects if you believe they are important for crafting the best possible response.

Aspects

- Helpfulness: The response should directly address the user's query and provide a relevant and practical solution or guidance.
- Clarity: The response should be well-structured and articulate, with ideas presented in a clear, understandable, and coherent manner.
- Factuality: Information provided must be accurate, truthful, and based on reliable sources, acknowledging any uncertainties where applicable.
- Depth: The response should offer an appropriate level of detail and thoroughness, providing a comprehensive understanding of the topic.
- Engagement: The conversation should be engaging, maintaining the user's interest with a natural, conversational tone and possibly interactive elements.
- Conciseness: Information should be conveyed efficiently, avoiding unnecessary complexity or verbosity while maintaining completeness.
- Safety: Responses must adhere to ethical guidelines, promoting positive interactions and avoiding harmful, inappropriate, or sensitive content.
- Compliance: The response should be in line with the instructions provided in the query, ensuring user expectations are met unless there are ethical or safety concerns.
- Limitations: The response should recognize and acknowledge the AI system's limitations, such as lacking up-to-date information, inability to perform searches or physical actions, or any other relevant constraints if applicable.
- Critical-Thinking: The response should question and analyze the information and assumptions presented in the user's query critically, rather than accepting them at face value.
- Creativity: Responses should demonstrate originality and innovation, offering unique

perspectives or solutions where appropriate.

- Interactivity: Where applicable, the AI should employ interactive elements like questions, prompts, or actionable suggestions to engage users actively in the conversation.
- Empathy: The AI should aim to recognize and appropriately respond to the user's emotional state and context, fostering a supportive and understanding interaction.
- Sensitivity: Responses should be culturally aware and sensitive, avoiding assumptions and generalizations while respecting diversity.

Query:
[QUERY]

Aspect Selection

Given the query, please analyze its content, intent, and potential challenges in providing a suitable response. Consider the following:

1. What is the main topic or subject of the query?
2. What is the user's intent or goal in asking this question?
3. Are there any potential ambiguities, uncertainties, or missing/wrong information in the query?
4. What type of information or response format would best satisfy the user's needs?
5. Are there any potential challenges or limitations in providing a comprehensive response?

Based on your analysis, select the most relevant aspects for providing a high-quality response. Provide your reasoning for choosing these aspects.

Output your analysis and aspect selection in the following JSON format:

```
---  
{
```

```
"query_analysis": {  
  "main_topic": "[main topic or  
  subject of the query]",  
  "user_intent": "[user's intent  
  or goal]",  
  "ambiguities": "[potential  
  ambiguities, uncertainties,  
  or missing information]",  
  "response_format": "[type of  
  information or response  
  format needed]",  
  "challenges": "[potential  
  challenges or limitations in  
  providing a response]"  
},  
"aspects_selection": {  
  "reasoning": "[your rationale  
  for selecting the aspects  
  based on the query  
  analysis]",  
  "selected_aspects": ["aspect1",  
  "aspect2", ...]  
}  
}  
---
```

Note: The "selected_aspects" array should contain at least 2 and at most 5 aspects.

E.2 State Transition Prompt

This section describes the prompt used to leverage a LLM as a transition function. Note, that in the prompt we supply '[CURRENT_SYSTEM_PROMPT]' i.e. the current state and the alignment feedback '[OUTPUT_EVALUATION]' to generate the next state.

I am designing a system prompt for a language model to generate responses to user queries. The goal is to optimize the quality of the responses across multiple aspects.

The current system prompt is:
[CURRENT_SYSTEM_PROMPT]

When using this prompt to answer the query below:
[QUERY]

The model generates the following output:

[OUTPUT]

Below are the evaluations of the output on multiple aspects:

[OUTPUT_EVALUATION]

There are a list of former system prompts including the current one, and each of them is improved from the previous one:

[FORMER_SYSTEM_PROMPTS]

Based on all the information above, you need to design a new system prompt following the general guidelines below:

1. Make sure the new system prompt is better than the current one.
2. Feel free to modify existing prompts, integrate freshly new instructions, or conceive a completely new one.
3. An evaluation score of 5 in an aspect indicates the best quality, while a score of 1 indicates the worst quality.
4. Try to make the system prompt balance out the quality across all aspects.
5. The prompt MUST be a general one suited for all kinds of queries, NOT specific to the current query.

While designing the system prompt make sure to structure it in a way that it abides to the instructions below:

1. Write some general instructions/statements to the model about what it is supposed to do and it's capabilities in the start.
2. Mention some limitations like no access to internet/real-time data, unable to take physical actions, avoiding answering malicious questions, etc. using bullet points.
3. Try to list the model capabilities in the bullet points i.e mention that it is better to refuse to answer things it is not capable of

answering than giving an unrelated response.

4. Try to generate a prompt in a structure as follows:

General Instructions about being a helpful, ethical assistant that helps the model to perform better in all the aspects of evaluation provided.

- Bullet Points containing important and specific instructions to keep in mind.

5. Try to make some bullet points giving instructions/tips to the model on how to make the responses more engaging and human-like, like some pitfalls to avoid sounding robot-like.
6. Try to make some specific tips from the outputs and their evaluation you see above, you can list things to follow or to avoid to make the response better suited as per the evaluation remarks.
7. Try to make the bullet points of the prompt you design to be informative while being succinct.
8. General Instructions you give at the beginning can be detailed or long and should try to cover as many aspects/issues as possible.
9. When adding bullet points to the system prompt, do NOT add more than 2 bullet points at once.
10. When deleting bullet points, do not remove bullet points which are relevant to overall goal but irrelevant to current query, instead modify/merge those.
11. Do NOT make more than 8 bullet points, if necessary add/modify/merge bullet points.

Please output your new system prompt in the format below by filling in the placeholders in [] in the following JSON format:

```
```  
{
```



```
"analysis": "[carefully examine the
 evaluation scores and the
 current system prompt to
 identify the areas of
 improvement]",
"thought": "[your thoughts about
 how you can improve the current
 system prompt]",
"new_system_prompt": "[your new
 system prompt]"
}

```