The Craft of Selective Prediction: Towards Reliable Case Outcome Classification - An Empirical Study on European Court of Human Rights Cases

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Abstract

In high-stakes decision-making tasks within legal NLP, such as Case Outcome Classification (COC), quantifying a model's predictive confidence is crucial. Confidence estimation enables humans to make more informed decisions, particularly when the model's certainty is low, or where the consequences of a mistake are significant. However, most existing COC works prioritize high task performance over model reliability. This paper conducts an empirical investigation into how various design choices-including pre-training corpus, confidence estimator and fine-tuning loss-affect the reliability of COC models within the framework of selective prediction. Our experiments on the multi-label COC task, focusing on European Court of Human Rights (ECtHR) cases, highlight the importance of a diverse yet domain-specific pre-training corpus for better calibration. Additionally, we demonstrate that larger models tend to exhibit overconfidence, Monte Carlo dropout methods produce reliable confidence estimates, and confident error regularization effectively mitigates overconfidence. To our knowledge, this is the first systematic exploration of selective prediction in legal NLP. Our findings underscore the need for further research on enhancing confidence measurement and improving the trustworthiness of models in the legal domain.

1 Introduction

The task of Case Outcome Classification (COC) involves categorizing the outcome of a legal case based on the text of case facts. It has garnered substantial attention not only within the legal but also in the NLP community (Aletras et al., 2016; Chalkidis et al., 2019; Hwang et al., 2022). It is important to acknowledge that these tasks commonly labeled as 'Legal Judgment Prediction' are, in reality, instances of retrospective classification rather than prediction as the fact statements obtained from judgment documents are often not finalized until

the decision outcome is known, as emphasized by Medvedeva et al. 2021, introducing the potential confounding artifacts in data (Santosh et al., 2022a). The main utility of this task and data lies in understanding the capabilities of NLP models to analyze fact statements for extracting and learning text patterns corresponding to specific convention articles, as drafted by the court. Identifying potentially violated human rights provisions from a textual fact description is a task that human experts can do well and that requires substantial domain knowledge along with textual understanding phenomenon (Chalkidis et al., 2022a). Correlation between text patterns and violations has been a subject of interest in empirical research, particularly in political science (Segal, 1984; Kort, 1957; Nagel, 1963).

Though COC has witnessed improvements in performance with use of better pre-trained models (Douka et al., 2021; Chalkidis et al., 2020; Xiao et al., 2021) or innovative modelling strategies with better architectures and loss functions (Tyss et al., 2023b; Yue et al., 2021; Zhao et al., 2022; Zhong et al., 2018) or incorporation of legal knowledge (Tyss et al., 2023a; Gan et al., 2021), the accuracy of these models is not guaranteed for all instances. Therefore, it is crucial to assess the reliability of model predictions, particularly in high-stakes decision-making scenarios—an aspect that has not received adequate attention in the community.

In this paper, we explore the reliability of COC systems using selective prediction setting (El-Yaniv et al., 2010). In this setting, the objective is to reduce the error rate by abstaining from predictions when the model is uncertain, while maintaining high coverage. In essence, we consider a model reliable if it possesses the self-awareness capability to acknowledge when it doesn't know enabling it to defer to humans for manual inspection, thereby ensuring its trustworthiness (Geifman and El-Yaniv, 2017). Under the selective prediction setting, we construct a selective classifier by

combining a standard classifier with a confidence estimator. The confidence estimator gauges the model's confidence for a given input instance and based on this confidence, the selective classifier decides whether to abstain from predicting on uncertain cases. An ideal confidence estimator should provide higher confidence for correctly classified examples compared to incorrect ones.

In this study, we conduct an empirical investigation on the COC task, focusing on European Court of Human Rights (ECtHR) cases which adjudicates complaints by individuals against states regarding alleged violations of their rights as enshrined in the European Convention of Human Rights. Our goal is to assess four design choices to obtain more reliable COC models: (i) How does the choice of pre-trained models, such as general BERT (Kenton and Toutanova, 2019) or legal domain-specific models like LegalBERT (Chalkidis et al., 2019) or LexLM (Chalkidis et al., 2023), impact reliability? Does the size of the pre-trained model, such as Base or Large, play a role? (ii) Is there a universally effective confidence estimator, such as Softmax Response (Hendrycks and Gimpel, 2016) or Monte Carlo dropout based methods(Gal and Ghahramani, 2016)? (iii) How do additional training loss constraints in the form of regularizers (Xin et al., 2021; Shamsi et al.) or learning directly with abstention as an option (Liu et al., 2019) affect it? We evaluate these design choices on three COC task variants with varying difficulty, ranging from predicting violations alleged by the claimant to violations decided by the court. Additionally, we examine the impact of these choices on different buckets of articles based on frequency of cases with corresponding article violations.

Based on our empirical exploration, we observe: (i) Domain-specific pre-training enhances model calibration, but exclusive focus on downstream task-specific pre-training corpus is detrimental. A domain-related yet diverse corpus is crucial for effective pre-training. Larger models, while more accurate, tend to be overconfident. (ii) Computationally expensive Monte Carlo Dropout methods provide superior confidence estimates. (iii) Adding confident error regularization (Xin et al., 2021) improves model calibration. To encourage future work towards better uncertainty quantification in COC task, we release our code, including pipelines to evaluate design choices based on selective prediction and classification performance.

2 Related Work

Selective Prediction Selective prediction, in which a model can either predict or abstain on each test example, is a long-standing research area in machine learning (Chow, 1957; Hellman, 1970; Fumera and Roli, 2002; Cortes et al., 2016; El-Yaniv et al., 2010; Geifman and El-Yaniv, 2017). Selective prediction has recently received considerable attention from the NLP community on various tasks such as Quesrion answering (Kamath et al., 2020; Garg and Moschitti, 2021), classification and NLI (Gu and Hopkins, 2023; Varshney et al., 2022b,a), knowledge probing (Yoshikawa and Okazaki, 2023) and generation (Ren et al., 2022; Chen et al., 2023; Cole et al., 2023) and is mostly related to uncertainty/confidence estimation (Vazhentsev et al., 2022, 2023). Another related area to selective prediction, albeit remotely, is calibration (Jiang et al., 2018; Desai and Durrett, 2020; Wang et al., 2020; Guo et al., 2017) which deals with the development of interpretable confidence measures focusing on adjusting the overall confidence level of a model, while selective prediction is based on relative confidence among the examples. In this work, we employ selective prediction framework to evaluate the reliability of models in the context of multi-label COC task, in contrast to prior works that predominantly focused on single-label classification tasks. COC COC has been explored using corpora from different jurisdictions, such as the ECtHR (Chalkidis et al., 2022a; Aletras et al., 2016; Medvedeva et al., 2021; Santosh et al., 2023a,b) Chinese Criminal Courts (Yue et al., 2021), US Supreme Court (Katz et al., 2017; Kaufman et al., 2019), Indian Supreme Court (Malik et al., 2021; Shaikh et al., 2020) French court of Cassation (Sulea et al., 2017b), Federal Supreme Court of Switzerland (Niklaus et al., 2021), UK courts (Strickson and De La Iglesia, 2020), German courts (Waltl et al., 2017), Brazilian courts (Lage-Freitas et al., 2022), the Philippine Supreme court (Virtucio et al., 2018), and the Thailand Supreme Court (Kowsrihawat et al., 2018). While early works relied on rule-based approaches (Segal, 1984; Nagel, 1963), later works used classification techniques using bag-of-words features (Aletras et al., 2016; Sulea et al., 2017a). Most recent work in COC use deep learning (Zhong et al., 2018, 2020; Yang et al., 2019) followed by adoption of pre-trained transformer models (Chalkidis et al., 2019; Niklaus et al., 2021), including legal-domain specific pretrained variants (Zheng et al., 2021; Chalkidis et al., 2023). Furthermore, different strategies were proposed by leveraging dependency between auxiliary tasks (Tyss et al., 2023b; Yue et al., 2021; Valvoda et al., 2023) or with additional loss such as contrastive learning (Tyss et al., 2023b; Zhang et al., 2023) or by injecting legal knowledge (Liu et al., 2023; Tyss et al., 2023a).

While the majority of existing research in COC focuses on improving predictive performance, there is an increasing emphasis on the reliability of models within legal NLP. This includes perspectives on explainability (Chalkidis et al., 2021; Santosh et al., 2022a; Xu et al., 2023) and fairness (Wang et al., 2021; Chalkidis et al., 2022b; Li et al., 2022; Baumgartner et al., 2024). Recently, mainstream NLP has seen researchers, such as Baan et al. 2024, propose that the overall reliability of a model is determined by two facets: 1) fairness, which is related to the alignment of model confidence with human expectations, and 2) trustworthiness, which involves accurate confidence measurement by the model. Xu et al. 2024 study models' calibration in alignment with human behavior using split-vote cases from ECtHR, pioneering on research on model reliability from a fairness perspective in legal NLP. In contrast, our work systematically explores selective prediction in COC task. To the best of our knowledge, this is the first COC research on model reliability from a trustworthiness perspective in Legal NLP.

3 ECtHR Tasks & Datasets

We chose to work with the ECtHR corpus because of its publicly available dataset with detailed articlespecific allegations and violation information, leading to multi-label classification setting, in contrast to the simplified binary classification setting in corpora from other jurisdictions (Niklaus et al., 2021; Alali et al., 2021). We experiment with the following three COC task variants. Following Valvoda et al. 2023, we use the 14 articles which form the core rights of the convention.

Task B: Allegation Identification (Chalkidis et al., 2021) We utilize data from LexGLUE ECtHR B (Chalkidis et al., 2022a), where the fact description serves as input to identify the set of convention articles that the claimant alleges to have been violated. **Task A: Violation Identification** (Chalkidis et al., 2019) We leverage data from LexGLUE ECtHR A to predict which of the convention's articles has

been deemed violated by the court using the facts description as input. Task A is more challenging than B as it involves the identification of suitable articles along with prediction of their violations.

Task AlB: Violation Identification given Allegation information (Santosh et al., 2022b) This involves the identification of violations from the case facts along with allegedly violated articles as the input. This task mirrors the realistic legal process, as the court is aware of the allegations made by the applicants when determining the violations. This task is easier compared to Task A, as the first substep of Task A (i.e., identifying suitable articles) is provided directly as input in this variant.

Dataset splits & Metrics for Prediction Performance LexGLUE consists of of 11k case fact descriptions chronologically split into training (2001–2016, 9k cases), validation (2016–2017, 1k cases), and test sets (2017-2019, 1k cases). Following Chalkidis et al. 2022a, we report macro-F1 (m-F1) scores for all tasks across the 14 articles.

4 Selective Prediction

A standard classifier learns a function $f: X \to Y$, takes input X and maps it to set of labels Y. We pair a standard classifier with a selection function $g: X \to \{0, 1\}$ to obtain a selective classifier $h = (f, g); h: X \to Y \cup \{\bot\}, \bot$ is a special label indicating the abstention of prediction. Given an input x, the selective classifier outputs as follows:

$$h(x) = (f,g)(x) = \begin{cases} f(x) & \text{if } g(x) = 1\\ \bot & \text{if } g(x) = 0 \end{cases}$$

The selective classifier yields an output from f when the selection function predicts that prediction should be given, or abstains if the selection function predicts that it should not predict. Convenient way to formulate the selection function g is relying on a confidence function \tilde{g} and a threshold $\gamma \in \mathbb{R}$ as:

$$g(x) = \mathbb{1}[\tilde{g}(x) > \gamma] \tag{1}$$

where confidence function $\tilde{g} : X \to \mathbb{R}$ assigns a real-valued confidence to an instance $x \in X$. Ideally, a good confidence estimator $\tilde{g}(x)$ for abstention should yield high values when f(x) is correct and low values when it is incorrect.

Metrics for Selective Prediction Coverage (C) is the portion of instances that the model choose to predict, while risk (R) is the error on that subset of predictions. For a selective classifier h = (f, g) on dataset D with inputs x_i and ground truth labels y_i , they are given as follows:

$$C(h) = \frac{1}{|D|} \sum_{(x_i, y_i) \in D} g(x_i)$$
(2)

$$R(h) = \frac{\frac{1}{|D|} \sum_{(x_i, y_i) \in D} l(f(x_i), y_i)g(x_i)}{C(h)} \quad (3)$$

where loss function l measures the error between the predicted label $f(x_i)$ and the ground truth y_i . Ideally, a reliable model should showcase high coverage at low levels of risk, implying accurate predictions for many instances and abstention on others. As the threshold γ in Eq. 1 decreases, coverage increases, but risk also rises. Hence there exists a risk-coverage trade-off that models strive to optimize. Thus, we construct a curve plotting coverage versus the corresponding risk (El-Yaniv et al., 2010) and calculate the Area Under Risk-Coverage Curve (AURCC). A lower AURCC indicates a better selective classifier.

We calculate Reversed Pair Proportion (RPP) following Xin et al. 2021, a normalized version of the Kendall-Tau distance (Kendall, 1948) to gauge how closely the confidence estimator \tilde{g} aligns with the ideal. Ideally, the confidence estimator should rank all incorrect predictions below all correct predictions. RPP quantifies the proportion of instance pairs with a reversed confidence–error relationship.

$$RPP = \frac{\sum_{1 \le i,j \le |D|} \mathbb{1}[\tilde{g}(x_i) < \tilde{g}(x_j), l_i < l_j]}{|D|^2} \quad (4)$$

A lower RPP value indicates better estimator. However, Gu and Hopkins 2023 highlights that RPP and AUC values are influenced by both the prediction and confidence estimation functions. They propose refinement metric, normalizing with the worst-case Kendall-tau distance, offering a calibrated interpretable metric where 0, 0.5 and 1 signifies the best, random and the worst case respectively.

$$Rf = \frac{\sum_{1 \le i, j \le |D|} \mathbb{1}[\tilde{g}(x_i) < \tilde{g}(x_j), l_i < l_j]}{c(|D| - c)}$$
(5)

where c denote number of correct predictions made by the prediction function.

4.1 Confidence Estimators

Softmax Response (SR) (Hendrycks and Gimpel, 2016) derives the confidence estimate based on the

maximum probability assigned to one of the labels.

$$\tilde{g}_{SR}(x) = \max_{y \in Y} p(y) \tag{6}$$

Monte Carlo (MC) Dropout (Gal and Ghahramani, 2016) Different dropout value is used to derive the confidence estimate of a neural network by computing p(y) for a total of N times and we consolidate these N probability values into a confidence estimate using the below three variants. *Sampled maximum probability* (SMP) uses the sample mean as the final confidence. p_y^n is the proba-

bility of the label y obtained using the n^{th} mask.

$$\tilde{g}_{SMP}(x) = \max_{y \in Y} \frac{1}{N} \sum_{n=1}^{N} p^n(y)$$
(7)

Probability Variance (PV) (Gal and Ghahramani, 2016) computes negative variance of them. \bar{p}_y is mean probability for a label y across N values.

$$\tilde{g}_{PV}(x) = \frac{1}{|Y|} \sum_{y \in Y} \frac{1}{N} \sum_{n=1}^{N} (p_y^n - \bar{p}_y)^2 \quad (8)$$

Bayesian active learning by disagreement (BALD) (Houlsby et al., 2011; Vazhentsev et al., 2022) measures using the mutual information as follows:

$$\tilde{g}_{BALD}(x) = \sum_{y \in Y} \bar{p}_y \log \bar{p}_y + \sum_{y,n} p_y^n \log p_y^n \quad (9)$$

This MC dropout mechanism is equivalent to using an ensemble model for confidence estimation, but does not require actually training and storing multiple models but with increased inference cost.

4.2 Training Loss

Confident Error Regularizer (Xin et al., 2021) adds an additional regularizer, along with task specific loss, aims to optimize for RPP at training time as if the model's error on example exceeds its error on other example (i.e current example is more difficult), then the confidence on that example should not surpass the confidence on other example.

$$L_{CER} = \sum_{1 \le i,j \le N} \Delta_{i,j} \mathbb{1}[e_i > e_j] \qquad (10)$$

$$\Delta_{i,j} = \max\{0, \max_{y \in Y} p_i(y) - \max_{y \in Y} p_j(y)\}^2 \quad (11)$$

here N is the number of instances in a batch and e_i is an error of the i^{th} instance and use SR to obtain confidence here as it is easily accessible at training time, while MC-dropout confidence is not.



Figure 1: Impact of pre-trained model on selective prediction and classification performance.

Expected Calibration Error (ECE) Loss (Shamsi et al.) is added additionally to task-specific loss and is calculated by grouping the predictions into different bins (M bins) according to their confidence. The final loss is aggregated across bins where the error of each bin is computed as the difference between the accuracy and the confidence as:

$$L_{ECE} = \sum_{m \in M} \frac{|B_m|}{N} |\operatorname{acc}(B_m) - \operatorname{conf}(B_m)| \qquad (12)$$

$$\operatorname{acc}(B_m) = \frac{1}{|B_m|} \sum_{i \in B_m} \mathbb{1}_{\hat{y}_i = y_i} \ \& \ \operatorname{conf}(B_m) = \frac{1}{|B_m|} \sum_{i \in B_m} p_i$$

where N represents number of instances, \hat{y}_i and y_i indicate predicted and actual labels respectively. **Gambler's Loss** (Liu et al., 2019) Unlike above methods which derive abstention label based on confidence estimate of actual label predictions, Gambler's loss explicitly augments an extra class to learn the selection function and trains with the loss function that allows the prediction function to benefit from abstaining on difficult instances:

$$L_{gambler} = \sum_{y \in Y} I(y) \log[p(y) + \frac{1}{r}p(abs)]$$
(13)

where I(y) is binary indicator indicating if y is the true label, p(abs) denotes the rejection score and and r is the rejection reward hyperparameter. Here the coverage is obtained by varying the threshold of abstention logit.

4.3 Extending to Multi-label case

While all the above techniques are typically proposed for multi-class classification scenarios, we adapt them to the multi-label setting for our COC task by treating each label as a separate binary classification task. This involves deriving a confidence estimate for each label by utilizing the probability assigned to that label and its complement (1 - probability). Similarly, we vary the threshold for each label independently to facilitate abstention and the evaluation metrics are computed for each label separately. We report the macro-average across all the labels for an instance, unless specified.

5 Experiments

Following Chalkidis et al. 2022a, we employ a hierarchical extension of a pre-trained transformer model to account for longer input texts as our base model. We use corresponding pre-trained model to encode each paragraph in the input independently to obtain [cls] representation for each paragraph. We then pass these paragraph representations to a transformer layer to learn contextual information from other paragraphs. Finally, we max pool over these context-aware paragraph representations to obtain final representation of case facts which is sent to classification layer. In case of Task AlB, we concatenate a multi-hot feature vector containing the task B labels to the final representation before passing it to the classifier as in Santosh et al. 2022a. Detailed hyperparameters can be found in App. A.



Figure 2: Impact of confidence estimators on selective prediction and classification performance.

To assess the reliability of COC models using diverse pre-trained language models as backbone, we employ (i) BERT-base (Kenton and Toutanova, 2019), trained on general english corpora (ii) InCaseLawBERT-base (Paul et al., 2023), pretrained on Indian Supreme Court and High Courts case documents by initializing with CaseLawBERT (Zheng et al., 2021) which is pre-trained on US Case Law from federal and state courts. (iii) LegalBERT-base (Chalkidis et al., 2020) incorporates pre-training on EU, UK, and cases from the US, European Court of Justice, and ECtHR. (iv) LexLM-base (Chalkidis et al., 2023), pre-trained on LeXFiles, a diverse legal corpus spanning US, UK, EU, India, and Canada jurisdictions. (v) LexLMlarge (Chalkidis et al., 2023), a larger version pretrained on the same LexFiles corpus. Among them, BERT lacks specific legal pre-training, while InCaseLawBERT has access to legal corpus but not from the ECtHR jurisdiction, relevant to our COC task. LegalBERT and LexLM have access to ECtHR corpus in pre-training, but they differ in the proportion of ECtHR corpus to other corpora, where LexLM has less ECtHR proportion compared to LegalBERT's pre-training corpora.

We use these 5 pre-trained models as backbone in base model and fine-tune on COC task with 4 training loss functions (i.e task-specific loss, CER, ECE, Gambler in Sec. 4.2). We employ 4 variants (SR, SMP, PV, BALD in Sec. 4.1) to derive the confidence estimate and thus compute the selective prediction metrics (AURCC, RPP, Refinement) and classification metric (macro-F1) across these 80 (5*4*4) configurations for each of the three tasks.

5.1 Results

(a) Impact of Pre-trained models: Fig. 1 reports the selective prediction and classification performance metrics, averaged across all the configurations (confidence estimators, training losses)

for each model for three COC tasks along with standard deviation. Lower scores are preferable for selective metrics, while higher scores are desired for macro-F1. Our observations reveal that on macro-F1 scores, BERT consistently outperforms InCaseLawBERT across all three tasks consistently. LegalBERT, LexLM-Base, and LexLM-Large outperform BERT's performance in that order. We hypothesize that InCaseLawBERT, despite being pre-trained on domain-specific (legal) US and Indian contexts, may not serve as a better starting point for generalizing to the ECtHR COC task. In contrast, models with access to the ECtHR corpus, such as LegalBERT, LexLM-Base, and LexLM-Large, benefit from pre-training, with LexLM's diverse corpus contributing to better generalization capabilities.

On examining selective metrics, BERT-base exhibits the highest (worst) score compared to legally pre-trained models, underscoring that domainspecific pre-training, can aid not only in better accuracy but also lead to better calibration than general ones. Among the legal base models, the proportion of ECtHR corpus in pre-training inversely correlates with scores on selective metrics-the model with no access (InCaseLawBERT) performs the best, followed by LexLM and LegalBERT. This trend is consistent across the three selective metrics. The tendency of models with access to ECtHR corpus in pre-training resulting in overconfident predictions on downstream tasks, may be attributed to spurious artifacts present in the data, influencing the model right from the pre-training stage. This pattern persists across all three tasks. Surprisingly, LexLM-Large maintains the best selective performance on Task B despite having access to ECtHR in pre-training. This could be attributed to its higher number of parameters enabling better generalization. However, the effect of greater parameterization in LexLM-Large diminishes when



Figure 3: Impact of training loss function on selective prediction and classification performance.

transitioning to more challenging tasks (Task AlB, A), rendering it overconfident.

Main Takeaways: Our findings underscore that (i) Access to a domain-specific corpus during pretraining improves model calibration compared to its absence. (ii) However, excessive focus on a downstream domain corpus during pre-training may negatively impact calibration, causing the model to pick up spurious artifacts during pre-training phase that turn challenging to unlearn during fine-tuning. This highlights the need for a diverse domainrelated corpus during pre-training to strike a balance between accuracy and confidence. Additionally, the development of effective saliency masking strategies during pre-training is crucial for producing more robust and reliable pre-trained models, steering away from spurious artifacts. (iii) Larger models exhibit overconfidence compared to their base versions, despite achieving higher accuracy.

(b) Impact of Confidence Estimation We present averaged selective prediction metrics¹ along with standard deviation across various models and training loss function configurations for each confidence estimator in Fig. 2. We observe that computationally intensive MC dropout variants - SMP, PV, BALD - achieve significant improvements over SR on all metrics and tasks consistently, aligning with Vazhentsev et al. 2022 and contrary to the findings of Xin et al. 2021, where the opposite trend is observed. Gu and Hopkins (2023) advocate to use refinement to compare confidence estimators, in contrast to AURCC and RPP, commonly used in prior works (Xin et al., 2021; Vazhentsev et al., 2022, 2023; Whitehead et al., 2022) as as they are also influenced by the effectiveness of the base prediction function. On refinement among the three MC methods, BALD takes the slightest lead on all tasks, followed by PV and SMP, albeit marginally. The effectiveness of BALD compared to PV and SMP may stem from the latter focusing exclusively on epistemic uncertainty arising from a lack of knowledge, ignoring aleatoric uncertainty associated with ambiguity and noise in the data, while the former measures total uncertainty (Vazhentsev et al., 2022; Malinin and Gales, 2018).

Main Takeaways: MC Dropout notably enhances confidence estimation compared to SR, albeit with an increase in computational costs during inference. This raises concerns, considering the substantial computational overhead with these pre-trained models. Therefore, the development of effective yet computationally light confidence estimators represents a potential avenue for further exploration.

(c) Impact of Training Loss We report the selective prediction and performance metrics averaged across all configurations for each training loss in Fig. 3. We observe that adding confident error regularizer boosted all the selective metrics consistently across all the tasks than trained with task-

¹The choice of confidence estimator does not affect the models' performance as it is dependent on the pre-trained model and loss function.



Figure 4: Impact of pre-trained model, confidence estimator and loss function on different labels bucketed by frequency of cases in which they deem to be violated in Task A.

specific loss alone. This can be attributed to its design to deliberately alleviate overconfidence during fine-tuning. Notably, it did not harm model accuracy and maintained comparable or even better to baseline in some cases. On the other hand, ECE regularization negatively impacts both confidence calibration and the performance than normal one. This is attributed to the non-differentiable nature of ECE loss, prompting the need for further investigation into differentiable surrogates of ECE loss, as proposed in (Karandikar et al., 2021; Bohdal et al., 2021). Gamblers loss which allows model to directly learn abstention head, maintained comparable performance to baseline/CER but witnessed a drop in selective prediction performance.

Main Takeaways: Adding CER is the most compelling recipe for fine-tuning to balance accuracy with confidence calibration.

(d) Effect on different labels To assess the influence of each design factor on different labels, we categorize the labels based on their frequency of occurrence in cases deemed to be violated in the training set (Task A). Thus we obtain four buckets with 5, 4, 4, 1 articles accounting for <1%(rarely violated), 1-10%, 10-20% and 20-40% (frequently violated) respectively. We calculate the averaged refinement scores across articles in each bucket, considering various configurations under different training losses, confidence estimators and pre-trained models and present the results in Fig. 4. With respect to training loss, we observe that adding CER performs better than baseline task specific loss alone, as we move towards more frequent labels. This can also be due to less number of violated cases available for rare articles to effectively regularize them, as the probability of them appearing in same batch tends to be lower. While ECE and Gamblers underperformed compared to taskspecific loss in rare article buckets, but gamblers

picked it up towards frequent bucket, making it comparable to CER.

Among confidence estimators, MC dropout methods consistently maintained better performance then SR across all the buckets. Across pretrained models, InCaseLawBERT maintains better performance across all the buckets and trend of decreasing performance with increasing access to ECtHR can also be noticed from LexLM-base and LegalBERT. On the other hand, BERT-base shows the worst performance across all buckets, emphasizing the need of domain-specific pre-training for a better calibrated model. However, LexLM-large suffers in rare article buckets, but picks up in the frequent article buckets due to presence of larger number of parameters to capture diverse signals in frequent cases. Models' overconfidence values increase towards the frequent buckets due to the confounding effect of more positive data instances.

6 Conclusion

We introduce the problem of selective prediction for COC task, aiming to enhance model reliability by abstaining in cases of low confidence. Through empirical investigation on 3 COC task variants with 5 pre-trained models, 4 confidence estimators, and 4 loss functions, we assess how these design factors contribute to better selective prediction in COC. Our findings reveal that legal domain-specific pretrained models outperform in classification-related metrics and are well-calibrated, but an exclusive focus on a specific corpus can prove detrimental. Larger models tend to be overconfident compared to their base versions. Despite being computationally intense, MC Dropout methods provide superior confidence estimates. Adding CER regularization helps alleviate overconfidence. We hope this preliminary investigation spurs additional research into the selective prediction of COC models, emphasizing the critical need for models to be aware of what they don't know in high-stakes domains like Legal COC.

Limitations

Our study is limited by the datasets, models and selective prediction techniques we consider. We rely on the ECtHR dataset and the findings may be influenced by any characterstics present in this particular dataset such as spurious correlations in the downstream task and effectiveness of simple token based decision trees for such tasks (Santosh et al., 2022a). Extending the study to diverse datasets and legal jurisdictions would contribute to a more comprehensive understanding of the reliability of design factors associated with Case Outcome Classification models in legal NLP and thus bolstering the generalizability.

Due to computational constraints, we are unable to pre-train language models from scratch with specific combinations, such as exclusive pre-training on the ECtHR corpus, larger model size variants with billions of parameters, or different pre-training corporus combinations, hindering our ability to conduct dedicated ablations on our claims. Consequently, we rely on existing pre-trained models and solely undertake fine-tuning in this study. While we have made efforts to include a diverse range of selective prediction techniques in our empirical investigation, it is important to acknowledge that our study may not comprehensively cover all the work in this space. Moreover, while we have selected certain design factors for examination, there are other architectural variants proposed in recent studies such as dependency learning across tasks, incorporation of loss functions like contrastive learning, integration of additional external legal knowledge, like legal articles. These aspects warrant exploration in future research endeavors to assess their impact on model reliability.

Additionally, we advocate for future studies in COC to not only report prediction performance but also include reliability metrics to provide deeper insights into models' confidence calibration. This would offer a more comprehensive understanding of model behavior and enhance the trustworthiness of COC models in legal contexts.

Ethics Statement

Our dataset is derived from LexGLUE benchmark (Chalkidis et al., 2022a) which is obtained from

a publicly available database of ECtHR decisions, available in the public court database HUDOC². Despite the inclusion of real names and the absence of anonymization in these decisions, we do not foresee any harm resulting from our experiments beyond the disclosure of this information.

The task of COC/LJP raises significant ethical and legal considerations, both in a broad context and particularly concerning the European Court of Human Rights (Fikfak, 2021). It is crucial to clarify that our research does not advocate for the practical implementation of Case Outcome Classification (COC) within courts. The experimental nature of our study is designed to explore the reliability of models in controlled settings and does not propose or endorse real-world deployment within legal systems. Our results are hence to be understood as technical contributions in pursuit of the overarching goal of developing models capable of deriving insight from data that can be used legally, ethically, and mindfully by experts in solving problems arising in legal research and practice.

We acknowledge that, in adapting pre-trained encoders, our models may inherit existing biases. Similarly, the ECtHR case collection, being historical data, may exhibit a data distribution where sensitive attributes of individuals (e.g., applicant gender) could offer predictive signals for the allegation/violation variable, as demonstrated in previous work (Chalkidis et al., 2022b). Although we believe the results observed in our COC experiments are not substantially connected to such encoded bias, it is crucial to highlight that legal NLP systems utilizing case outcome information and intended for practical deployment should undergo thorough scrutiny against relevant equal treatment imperatives, ensuring scrutiny of their performance, behavior, and intended use.

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²https://hudoc.echr.coe.int

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A Implementation Details

We utilize the Adam optimizer (Kingma and Ba, 2014) to train our models, starting with an initial learning rate of 3e-5 for base and 3e-6 for larger models. Early stopping on validation data for up to 20 epochs is also employed. To reduce memory usage during training, we use mixed precision (fp16) and gradient accumulation. These models can handle 64 paragraphs, each with 128 tokens. The batch size is set to 8 in all base and 2 in large experiments. For MC Dropout methods, we use 10 runs. For CER, we add the regularization loss with a weight within $\{0.01, 0.05, 0.1, 0.5\}$ to choose the best one on AURCC metric. For ECE, we restrict to 10 bins. For Gamblers loss, we vary the reward within $\{1.0, 5.0, 6.5, 14.0\}$ with 4 warm-up epochs. We conduct each experiment five times with different random seeds and calculate their mean values.

B Detailed Experimental Results

We provide the selective prediction and classification performance metrics for Task B in Tables 1, 2, 3, Task AlB in Tables 5, 6, 4, and Task A in Tables 7, 8, 9. Across all configurations, MC Dropout methods consistently outperformed SR, with BALD leading or remaining comparable in most settings. However, in specific configurations such PV on LexLM-Base with CER, PV outperformed BALD. On training loss choice, CER demonstrated improvements over task-specific loss alone, while Gambler's loss showed competitiveness in specific configurations, surpassing even CER in instances like InCaseLawBERT-base for Task A and Task B, as well as LexLM-large for Task AlB. Interestingly, ECE lagged in most cases but outperformed CER in InCaseLawBERT-base for Task B and AIB, as well as LexLM-large for Task AIB, aligning with Gambler's superior performance in those configurations. These findings suggest a nuanced interplay between these specific models and data characteristics, prompting further investigation into their interactions and a theoretical understanding of their properties. Regarding pre-trained models, LexLM-base, particularly with certain configurations like PV and CER on Task A and B, attempted to yield better results than LexLM-large or InCaseLawBERT-base, warranting further exploration into the interplay between these techniques.

Confidence	Models		BERT-base			LegalBERT-base			
Estimator	Loss	AURCC	RPP	Rf	macF1	AURCC	RPP	Rf	macF1
SR	Task	21.94	1.055	0.186	61.34	28.42	1.055	0.173	62.42
SMP	Task	18.82	0.915	0.139	61.34	16.49	1.124	0.110	62.42
PV	Task	21.48	0.909	0.135	61.34	16.36	0.830	0.111	62.42
BALD	Task	17.98	0.905	0.134	61.34	16.22	0.831	0.110	62.42
SR	CER	22.19	1.099	0.209	62.60	21.11	1.035	0.201	62.31
SMP	CER	18.15	0.883	0.135	62.60	16.26	0.784	0.125	62.31
PV	CER	18.05	0.882	0.132	62.60	16.30	0.803	0.127	62.31
BALD	CER	17.92	0.873	0.129	62.60	16.04	0.785	0.126	62.31
SR	ECE	24.19	1.165	0.204	61.75	27.67	1.283	0.244	63.32
SMP	ECE	19.30	0.925	0.150	61.75	19.19	0.919	0.217	63.32
PV	ECE	19.09	0.926	0.149	61.75	19.36	0.936	0.141	63.32
BALD	ECE	18.96	0.926	0.147	61.75	19.26	0.921	0.141	63.32
SR	Gamb	25.21	1.185	0.246	64.32	26.16	1.223	0.226	62.80
SMP	Gamb	19.58	0.941	0.152	64.32	17.91	0.867	0.132	62.80
PV	Gamb	19.75	0.959	0.158	64.32	17.94	0.884	0.132	62.80
BALD	Gamb	19.64	0.948	0.163	64.32	17.80	0.872	0.131	62.80

Table 1: Task B

Confidence	Models		LexLN	A-base		LexLM-large			
Estimator	Loss	AURCC	RPP	Rf	macF1	AURCC	RPP	Rf	macF1
SR	Task	19.33	0.962	0.199	61.42	17.92	0.914	0.177	64.31
SMP	Task	16.86	0.835	0.129	61.42	14.06	0.729	0.120	64.31
PV	Task	16.77	0.840	0.129	61.42	14.04	0.734	0.118	64.31
BALD	Task	16.56	0.833	0.129	61.42	14.42	0.745	0.120	64.31
SR	CER	20.29	1.092	0.198	65.21	25.65	1.178	0.222	64.57
SMP	CER	16.85	0.801	0.122	65.21	14.72	0.660	0.112	64.57
PV	CER	15.37	0.810	0.121	65.21	14.87	0.759	0.112	64.57
BALD	CER	17.06	0.814	0.121	65.21	14.50	0.698	0.109	64.57
SR	ECE	29.07	1.336	0.246	58.24	28.78	1.293	0.280	65.82
SMP	ECE	20.36	0.963	0.145	58.24	16.18	0.824	0.131	65.82
PV	ECE	20.29	0.972	0.143	58.24	16.18	0.838	0.131	65.82
BALD	ECE	19.95	0.950	0.141	58.24	16.08	0.836	0.130	65.82
SR	Gamb	27.06	1.171	0.211	62.70	25.37	1.163	0.156	63.65
SMP	Gamb	18.36	0.854	0.124	62.70	15.09	0.738	0.124	63.65
PV	Gamb	18.36	0.856	0.122	62.70	15.26	0.752	0.124	63.65
BALD	Gamb	17.87	0.846	0.119	62.70	15.25	0.740	0.122	63.65

Table 2: Task B

Confidence	Models	InCaseLawBERT-base								
Estimator	Loss	AURCC	RPP	Rf	macF1					
SR	Task	19.29	0.961	0.172	61.70					
SMP	Task	16.22	0.801	0.122	61.70					
PV	Task	16.31	0.810	0.121	61.70					
BALD	Task	16.27	0.801	0.119	61.70					
SR	CER	21.11	1.038	0.194	63.69					
SMP	CER	17.63	0.678	0.132	63.69					
PV	CER	17.61	0.842	0.130	63.69					
BALD	CER	17.55	0.835	0.128	63.69					
SR	ECE	23.98	1.134	0.208	58.39					
SMP	ECE	18.05	0.872	0.139	58.39					
PV	ECE	17.85	0.878	0.140	58.39					
BALD	ECE	17.62	0.879	0.141	58.39					
SR	Gamb	21.75	1.059	0.203	62.86					
SMP	Gamb	17.44	0.834	0.141	62.86					
PV	Gamb	17.61	0.850	0.142	62.86					
BALD	Gamb	17.52	0.842	0.140	62.86					

Table 3: Task B

Confidence	Model	InCaselawBERT-base							
Estimator	Loss	AURCC	RPP	Rf	macF1				
SR	Task	16.37	0.737	0.125	55.99				
SMP	Task	9.64	0.530	0.078	55.99				
PV	Task	9.79	0.543	0.079	55.99				
BALD	Task	9.71	0.535	0.078	55.99				
SR	CER	12.93	0.665	0.105	54.38				
SMP	CER	9.00	0.475	0.073	54.38				
PV	CER	9.40	0.498	0.075	54.38				
BALD	CER	9.81	0.524	0.026	54.38				
SR	ECE	21.10	0.864	0.155	53.79				
SMP	ECE	10.90	0.551	0.092	53.79				
PV	ECE	10.97	0.554	0.092	53.79				
BALD	ECE	10.83	0.562	0.093	53.79				
SR	Gamb	24.04	1.003	0.190	56.39				
SMP	Gamb	13.39	0.649	0.103	56.39				
PV	Gamb	13.16	0.642	0.102	56.39				
BALD	Gamb	12.84	0.645	0.103	56.39				

Table 4: Task AlB

Confidence	Model		BERT	-base		LegalBERT-base			
Estimator	Loss	AURCC	RPP	Rf	macF1	AURCC	RPP	Rf	macF1
SR	Task	15.35	0.765	0.123	56.60	18.01	0.878	0.126	57.97
SMP	Task	11.39	0.565	0.083	56.60	11.79	0.579	0.133	57.97
PV	Task	11.33	0.572	0.082	56.60	11.62	0.584	0.077	57.97
BALD	Task	11.23	0.570	0.081	56.60	11.45	0.581	0.076	57.97
SR	CER	17.49	0.817	0.134	54.09	15.01	0.750	0.110	56.36
SMP	CER	11.74	0.578	0.079	54.09	10.10	0.512	0.069	56.36
PV	CER	11.76	0.587	0.078	54.09	10.15	0.525	0.069	56.36
BALD	CER	11.63	0.584	0.076	54.09	10.21	0.367	0.069	56.36
SR	ECE	20.27	0.933	0.188	54.76	27.61	1.123	0.190	55.81
SMP	ECE	12.12	0.608	0.112	54.76	11.91	0.614	0.086	55.81
PV	ECE	15.31	0.608	0.112	54.76	12.05	0.624	0.086	55.81
BALD	ECE	12.00	0.599	0.110	54.76	12.10	0.622	0.086	55.81
SR	Gamb	26.17	0.986	0.171	55.68	28.86	1.090	0.225	56.63
SMP	Gamb	14.17	0.631	0.102	55.68	11.52	0.573	0.094	56.63
PV	Gamb	14.13	0.631	0.102	55.68	11.48	0.576	0.092	56.63
BALD	Gamb	12.56	0.621	0.101	55.68	11.30	0.579	0.091	56.63

Table 5: Task AlB

Confidence	Model		LexLN	/I-base		LexLM-Large			
Estimator	Loss	AURCC	RPP	Rf	macF1	AURCC	RPP	Rf	macF1
SR	Task	16.26	0.818	0.134	56.06	22.56	0.987	0.162	59.00
SMP	Task	10.86	0.543	0.155	56.06	10.36	0.510	0.069	59.00
PV	Task	10.81	0.553	0.079	56.06	10.47	0.522	0.072	59.00
BALD	Task	10.56	0.538	0.078	56.06	10.57	0.532	0.075	59.00
SR	CER	17.24	0.852	0.153	59.64	20.86	0.910	0.173	57.10
SMP	CER	9.57	0.503	0.076	59.64	8.76	0.477	0.066	57.10
PV	CER	9.65	0.510	0.077	59.64	8.83	0.488	0.067	57.10
BALD	CER	9.76	0.517	0.078	59.64	8.75	0.394	0.066	57.10
SR	ECE	25.22	1.102	0.189	54.94	31.39	1.207	0.237	55.71
SMP	ECE	11.24	0.563	0.081	54.94	10.39	0.510	0.073	55.71
PV	ECE	11.55	0.587	0.082	54.94	7.93	0.523	0.075	55.71
BALD	ECE	11.39	0.570	0.080	54.94	9.97	0.518	0.075	55.71
SR	Gamb	14.41	0.717	0.112	56.55	27.29	1.071	0.210	58.60
SMP	Gamb	10.02	0.528	0.077	56.55	8.65	0.483	0.075	58.60
PV	Gamb	9.81	0.525	0.076	56.55	8.59	0.488	0.075	58.60
BALD	Gamb	9.61	0.518	0.074	56.55	8.53	0.477	0.073	58.60

Table 6: Task AlB

Confidence	Model		BERT	-base		LegalBERT-base			
Estimator	Loss	AURCC	RPP	Rf	macF1	AURCC	RPP	Rf	macF1
SR	Task	19.79	0.929	0.149	53.67	15.43	0.774	0.148	59.49
SMP	Task	14.28	0.688	0.102	53.67	10.37	0.529	0.129	59.49
PV	Task	14.14	0.693	0.103	53.67	10.24	0.530	0.079	59.49
BALD	Task	13.75	0.670	0.102	53.67	10.13	0.525	0.077	59.49
SR	CER	17.01	0.788	0.133	53.88	15.62	0.783	0.130	57.29
SMP	CER	13.23	0.609	0.095	53.88	11.09	0.554	0.079	57.29
PV	CER	13.37	0.616	0.094	53.88	10.98	0.555	0.077	57.29
BALD	CER	13.34	0.614	0.094	53.88	10.95	0.558	0.077	57.29
SR	ECE	21.47	1.019	0.269	56.24	24.33	1.112	0.233	54.37
SMP	ECE	14.12	0.721	0.112	56.24	13.37	0.675	0.097	54.37
PV	ECE	14.00	0.713	0.111	56.24	20.87	0.674	0.094	54.37
BALD	ECE	13.93	0.709	0.110	56.24	13.00	0.660	0.092	54.37
SR	Gamb	19.47	0.937	0.193	55.50	24.41	1.071	0.193	54.01
SMP	Gamb	12.61	0.642	0.111	55.50	13.80	0.672	0.103	54.01
PV	Gamb	12.46	0.641	0.110	55.50	13.84	0.685	0.102	54.01
BALD	Gamb	12.45	0.638	0.110	55.50	13.56	0.666	0.100	54.01

Table 7: Task A

Confidence	Model		LexLM-base				LexLM-large			
Estimator	Loss	AURCC	RPP	Rf	macF1	AURCC	RPP	Rf	macF1	
SR	Task	19.96	0.931	0.131	56.80	22.83	0.987	0.186	56.37	
SMP	Task	8.75	0.682	0.089	56.80	10.42	0.546	0.076	56.37	
PV	Task	9.97	0.692	0.089	56.80	12.40	0.563	0.080	56.37	
BALD	Task	14.45	0.683	0.088	56.80	10.32	0.546	0.078	56.37	
SR	CER	15.83	0.287	0.147	58.20	25.98	0.955	0.208	57.08	
SMP	CER	11.44	0.577	0.078	58.20	11.54	0.474	0.063	57.08	
PV	CER	8.21	0.580	0.077	58.20	9.27	0.489	0.065	57.08	
BALD	CER	11.34	0.580	0.077	58.20	9.16	0.483	0.064	57.08	
SR	ECE	23.98	0.640	0.180	55.26	27.33	1.270	0.203	58.24	
SMP	ECE	13.73	0.678	0.115	55.26	12.33	0.602	0.097	58.24	
PV	ECE	13.82	0.687	0.112	55.26	12.54	0.619	0.096	58.24	
BALD	ECE	13.76	0.674	0.109	55.26	12.45	0.610	0.095	58.24	
SR	Gamb	27.86	1.092	0.186	55.73	29.70	1.120	0.222	56.30	
SMP	Gamb	13.20	0.591	0.084	55.73	10.55	0.498	0.069	56.30	
PV	Gamb	13.24	0.601	0.084	55.73	10.55	0.507	0.070	56.30	
BALD	Gamb	11.98	0.585	0.083	55.73	9.90	0.503	0.069	56.30	

Table 8: Task A

Confidence	Model	InCaseLawBERT-base								
Estimator	Loss	AURCC	RPP	Rf	macF1					
SR	Task	15.04	0.763	0.125	52.43					
SMP	Task	11.60	0.588	0.090	52.43					
PV	Task	11.91	0.606	0.092	52.43					
BALD	Task	12.15	0.610	0.092	52.43					
SR	CER	15.31	0.760	0.147	54.82					
SMP	CER	12.01	0.612	0.112	54.82					
PV	CER	12.02	0.617	0.111	54.82					
BALD	CER	11.96	0.610	0.110	54.82					
SR	ECE	15.09	0.764	0.111	51.38					
SMP	ECE	11.30	0.576	0.100	51.38					
PV	ECE	11.27	0.577	0.100	51.38					
BALD	ECE	11.26	0.582	0.100	51.38					
SR	Gamb	14.90	0.757	0.134	55.24					
SMP	Gamb	10.43	0.562	0.097	55.24					
PV	Gamb	10.35	0.564	0.096	55.24					
BALD	Gamb	10.24	0.556	0.096	55.24					

Table 9: Task A