## In-Context Learning of Soft Nearest Neighbor Classifiers for Intelligible Tabular Machine Learning

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## Abstract

With in-context learning foundation models like TabPFN excelling on small supervised tabular learning tasks, it has been argued that "boosted trees are not the best default choice when working with data in tables".<sup>1</sup> However, such foundation models are inherently blackbox models that do not provide interpretable predictions. We introduce a novel learning task to train ICL models to act as a nearest neighbor algorithm, which enables intelligible inference and does not decrease performance empirically.

## 1 Introduction

In-context learning (ICL) yields state-of-the-art models for small supervised tabular learning tasks, exemplified by TabPFN (Hollmann et al., 2023, 2025). TabPFN is trained to solve supervised tabular learning tasks via in-context learning directly, meaning that at the inference time, the model is effectively fitted to the task without any weight updates. While such a model shows impressive performance, its inference mechanism is not interpretable, and users have to rely on model-agnostic explainability methods (Rundel et al., 2024). This is in contrast to recent requirements for more transparent, interpretable, and intelligible models (Rudin, 2019). <sup>2</sup>

K-Nearest neighbor (KNN) algorithms, a complementary research direction, recently reappeared in tabular state-of-the-art methods, such as Modern-NCA (Ye et al., 2025) and TabR (Gorishniy et al., 2024). KNN-based methods make predictions based on the similarity between a query and training samples, thus offering transparent, exampledriven inference. However, the performance of KNN is highly dependent on a similarity function

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(a)  $L_2$  based similarity (b) SoftKNN-ICL similarity

Figure 1: Our in-context learning model makes predictions by weighting labels of similar data points (alpha value encodes weight). In contrast to L2-based nearest neighbor methods (left), our method learns the similarity function via in-context learning (right).

and the choice of hyperparameter k, which are both dataset-specific, rendering this approach inappropriate for foundation models (FMs) working across many different datasets. The generalization to the soft-nearest neighbor method (Goldberger et al., 2004) bases its predictions on the weighted sum of the labels of all training samples in the dataset, yielding accurate predictions while still being human-interpretable. The ModernNCA extension (Ye et al., 2025) demonstrates that learning the similarity function via a neural network can further boost the performance.

In our work, we aim to obtain intelligible, stateof-the-art, off-the-shelf models and study "How can we leverage nearest neighbor methods to make ICL more intelligible?"

More precisely, we propose a novel training task for tabular ICL models, inspired by continuous nearest neighbor methods (Ye et al., 2025) and RAG (Gorishniy et al., 2024) (see Figure 1). Our contributions are the following:

 We introduce a novel training task for ICL, yielding an intelligible extension for any tabular ICL model. We dub our method SoftKNN-ICL.

<sup>&</sup>lt;sup>1</sup>https://bsky.app/profile/sammuller.bsky.

<sup>&</sup>lt;sup>2</sup>See Vaughan and Wallach (2021) for a discussion of the term "intelligibility".

2. We qualitatively and quantitatively evaluate our method on standard tasks and demonstrate it achieves competitive performance while being intelligible.

The following section discusses related literature on ICL for tabular data, nearest neighbor methods in deep learning and intelligible deep learning methods. After introducing and evaluating our method in Section 3 and Section 4, we further discuss how our method relates to kernel learning in Section 5 and conclude with future work and limitations in Section 6.

## 2 Related Work

In-context learning for tabular data. One of the successful paradigms for training tabular deep learning (DL) is ICL, where a model is trained on many datasets to make predictions for a test (query) set conditioned on the train (support) set. Interestingly, the ICL regime in the model competes with usual, in-weight learning, and has a transient nature (Singh et al., 2023). Early works on ICL for tabular data were developed for specific tasks (Garnelo et al., 2018a,b). Later work demonstrated that training these models using purely synthetic data can achieve strong performance (Müller et al., 2022; Hollmann et al., 2023; den Breejen et al., 2024), but general pre-training on natural data is also possible (Ma et al., 2024). ICL models perform well and primarily differ in the data used for pre-training, e.g., real or synthetic data, and architectural design, e.g., cell-based attention (den Breejen and Yun, 2025), yielding continuous performance improvements over time (den Breejen et al., 2024; Hollmann et al., 2025; Qu et al., 2025a). We leverage this model class and propose a new training task.

Few works argue that ICL models such as TabPFN learn an efficient kernel (Nagler, 2023; McCarter, 2024), and we will discuss this connection in more detail in Section 5. In concurrent work to make TabPFN invariant to class order, Arbel et al. (2025) also noted this connection. Their resulting model leverages a technique similar to ours but further processes a combination of labels with a non-linear module, because the main emphasis of their work is performance rather than intelligibility.

Finally, a complementary research direction leverages the ICL capability of LLMs for tabular data, instead of training FMs on tabular data (Gardner et al., 2024). While they perform well for small datasets, they are computationally expensive, not robust to table manipulations, and inherently struggle with large tables (Fang et al., 2024).

Development of nearest neighbor algorithms (NNA) in deep learning. NNAs are used extensively in deep learning models and mostly build on Nearest Component Analysis (NCA, Goldberger et al., 2004), also known as soft-NN, to allow for back-propagation. In NCA, the label for an unseen test sample is predicted by taking a weighted average of all available training samples. The followup work Nonlinear NCA (NNCA) (Salakhutdinov and Hinton, 2007) extends NCA to operate on features extracted with a neural network. The work of Vinyals et al. (2016) uses an NNA for few-shot learning and a bi-LSTM to capture global context. Plötz and Roth (2018) generalized this to a differentiable KNN selection rule, outputting a set of neighbors, rather than their average. Wang and Sabuncu (2023) study explainability of soft-NN methods for image classification from the perspective of the kernel methods. Recently, Li et al. (2024) proved that a 1-NN can be learned in-context with a onelayer transformer. Our model continues this line of research and is the first to explicitly combine NNAs with ICL, by training an ICL embedder that captures global context and produces features for a soft-NN.

Applications of NNAs in deep learning. The use of NNAs can be broadly categorized into two groups: those where NNAs serve as the core model and those where they enhance the performance of a downstream model. Retrieval-Augmented Generation (RAG) is a prominent method that improves the performance of an LLM by enriching the context with relevant information from an external knowledge base (Lewis et al., 2020). NNAs are also employed for scaling prompt size in LLMs (Xu et al., 2023; Zhao et al., 2024), and context localization in tabular ICL models, helping to relax the support set size limitations (Koshil et al., 2024; Thomas et al., 2024; Nejjar et al., 2024; Xu et al., 2025). Examples of the models with NNA as a core algorithm include the extended version of NNCA, ModernNCA (Ye et al., 2025), and TabR (Gorishniy et al., 2024), which is inspired by RAG. Our method SoftKNN-ICL also falls within the category of models using NNA at its core.

**Intelligibility in deep learning.** A model's decisions can be made intelligible either by designing the model to be explainable from the outset (intrinsic interpretability) or by applying post hoc

explanation methods after training, which often entail a computational overhead or require a separate dataset. Basic DL models like MLP, ResNet, or Transformer are not intrinsically interpretable and require post-hoc explanation methods (Molnar, 2025) like SHAP (Lundberg and Lee, 2017) or LIME (Ribeiro et al., 2016). However, by combining neural networks with explainable methods like GAM (Chang et al., 2022), it is possible to leverage the complex features of DL models while maintaining intrinsic explainability. A more exotic approach is to train a deep learning meta-model that predicts the optimal parameters of an explainable model (Müller et al., 2023; Mueller et al., 2024), which, however, are constrained in size. Our model also combines an ICL transformer with an NNA model, which is considered intelligible if the features of the sample are/or can be made interpretable, e.g., by dimensionality reduction (Molnar, 2025).

## 3 Methodology

We are interested in supervised tabular classification, which is the task to predict test labels  $\mathbf{y}^q \in \{c \in \mathbb{N} : c \leq C\}^m$  given p features of m test samples  $\mathbf{X}^q \in \mathbb{R}^{m \times p}$  and a training set  $(\mathbf{X}^s, \mathbf{y}^s)$ , where  $\mathbf{X}^s \in \mathbb{R}^{n \times p}$  and  $\mathbf{y}^s \in \{c \in \mathbb{N} : c \leq C\}^n$ .

Here, we focus on ICL approaches, which means a pre-trained model  $f_{\theta}$  is "fitted" on the data set during the inference without weight updates, in contrast to the classical in-weight learning approach. To disambiguate the terminology, when talking about inference, we refer to the test set as *query* and the training set as *support*.

We introduce a novel learning task that implements a nearest neighbor method. KNN is the most popular nearest neighbor method and operates by assigning each query point a label  $y_j$  based on the majority vote of its k closest neighbors in the support set. This can be written down using an indicator function  $\mathbb{1}_{\mathcal{N}}(x) := \{1 \text{ if } x \in \mathcal{N}, \text{ else } 0\}$ , and defining a neighborhood  $\mathcal{N}_j := \mathcal{N}(\mathbf{X}^q[j], \mathbf{X}^s, k)$ as a function returning a set of nearest neighbors according to a similarity function, most commonly based on the Euclidean distance. Then, the predicted label is:

$$\hat{y}_j = \operatorname*{arg\,max}_{c \in C} \sum_{i=1}^n \frac{ohc(\mathbf{y}^s)[i] \mathbb{1}_{\mathcal{N}_j}(\mathbf{X}^s[i])}{k}$$

with  $ohc(\mathbf{y}^s) = \{0, 1\}^{n \times C}$  being the one-hotencoded labels of the support set.



Figure 2: The architecture of SoftKNN-ICL. At the core of our approach is an ICL transformer that produces embeddings used to compute similarities between the query and support samples. The final prediction is obtained by taking a similarity-weighted average of the support labels.

However, we cannot directly leverage this as a learning task to fit a model, since the neighborhood function  $\mathcal{N}(\cdot, \cdot, \cdot)$  is not differentiable. Instead, we propose to train the model using a continuous generalization of the KNN model (Goldberger et al., 2004) by allowing all data points to contribute to the prediction according to their similarity  $a_j(\mathbf{X}^s[i]) = a(\mathbf{X}^q[j], \mathbf{X}^s[i]) :=$  $sim(\mathbf{X}^q[j], \mathbf{X}^s[i])$ :

$$\hat{\mathbf{y}}_j = \operatorname*{arg\,max}_{c \in C} \frac{\sum_{i=1}^n ohc(\mathbf{y}^s)[i]a_j(\mathbf{X}^s[i])}{\sum_{i=1}^n a_j(\mathbf{X}^s[i])}.$$
 (1)

Now, the prediction is the weighted average of all labels in the support set, similar to Nadaraya-Watson kernel regression (Nadaraya, 1964; Watson, 1964), with the main difference that we do not explicitly condition the similarity function on the distance between inputs. We parametrize the similarity function by introducing an embedding function  $f_{\theta}$  mapping the raw data to a latent space using information from the support and query sets:  $a(f_{\theta}(\mathbf{X}^s, \mathbf{y}^s, \mathbf{X}^q)) \rightarrow \mathbf{A}^s, \mathbf{A}^s \in [0, 1]^{m \times n}$ . This allows learning a similarity function based on the given learning task, and we will explain later how to use a standard transformer architecture for this. Assuming similarity scores are normalized wrt. support  $|\mathbf{A}^{s}[i, \cdot]|_{1} = 1$ , prediction (1) can be written in matrix form:

$$\hat{\mathbf{y}}^q = \mathbf{A}^s \cdot \operatorname{ohc}(\mathbf{y}^s), \hat{\mathbf{y}}^q \in \{0, 1\}^{m \times C}, \quad (2)$$

where labels can be obtained as  $\hat{\mathbf{y}}_j = \arg \max_{c \in C} \hat{\mathbf{y}}^q[j, \cdot]$  This setup directly conceptually matches ICL, which operates on support and query sets. However, existing ICL models are not (yet) explicitly trained to make predictions by weighting support set labels.

We propose implementing the similarity function a by taking the transformed embeddings of the query and the support set and a merged  $\mathbf{KV}^T$ matrix of a transformer layer  $\mathbf{W} \in \mathbb{R}^{d \times d}$ :

$$a(\mathbf{E}^{q}[j], \mathbf{E}^{s}) := \operatorname{softmax}((\mathbf{E}^{q}(\mathbf{W} \cdot \mathbf{E}^{sT}))[j, \cdot]),$$
(3)

with  $f_{\theta}(\mathbf{X}^{s}, \mathbf{y}^{s}, \mathbf{X}^{q}) \rightarrow (\mathbf{E}^{s}, \mathbf{E}^{q}), \ \mathbf{E}^{s} \in \mathbb{R}^{n \times d}$ and  $\mathbf{E}^q \in \mathbb{R}^{m \times d}$  being the corresponding embeddings of  $\mathbf{X}^s$  and  $\mathbf{X}^q$  with dimensionality d. Thus,  $\mathbf{a}^q := \mathbf{A}^s[q]$  is a corresponding row of the "attention matrix" representing attention values from query  $\mathbf{x}^q$  to the support samples  $\mathbf{X}^s$ . The merged  $\mathbf{K}\mathbf{V}^T$  matrix follows work on learning KNN via ICL with linear transformers (Li et al., 2024). This means that we train our transformer model, for a given query point, to attend to similar points in the support set and to make predictions by weighting the labels of all points in the support set based on these similarity (attention) values. For training our model, we use the cross-entropy loss  $L(\hat{\mathbf{y}}^q, \mathbf{y}^q) = CE(\hat{\mathbf{y}}^q, \mathbf{y}^q)$ . We refer to this model as SoftKNN-ICL and display its structure in Figure 2.

We also experimented with the alternative, potentially more straightforward, implementation which outputs the 1-d logit per token by setting m = 1and d = 1 and taking a softmax over the sample dimension,  $a(\mathbf{E}^s, \mathbf{E}^q) := \text{softmax}(\mathbf{E}^s[\cdot, 1])$ . However, this version results in inferior convergence and requires advanced pre-training schedules, so we do not consider it further.

**Implementation and Hardware Details.** Our implementation is based on the repository of den Breejen et al. (2024), and we will release our code upon acceptance.<sup>3</sup> Following other works in the field, e.g., Hollmann et al. (2023) and den Breejen et al. (2024), the model is trained using synthetic data only. Concretely, we use the TabForest prior as

introduced by den Breejen et al. (2024), which is a mix of the original TabPFN prior (Hollmann et al., 2023) and the forest prior (den Breejen et al., 2024). In practice, we add information from the label in  $X^s$  as part of the input token, following the standard TabPFN methodology. Optimization is performed using Adam (Kingma and Ba, 2015) with learning rate of 4e–5. We employ cosine annealing (Loshchilov and Hutter, 2017) with linear warmup (10 epochs with 8192 datasets) for learning rate scheduling. SoftKNN-ICL is trained using three V100 GPUs on 24.6M synthetic datasets.

#### **4** Experimental Evaluation

We divide the evaluation of our model into two parts. First, we perform a study using toy problems to analyze the decision boundaries of our model. Second, we compare our model against competitor models on standard benchmark datasets.

#### 4.1 Decision Boundaries on Toy Problems

First, we want to study how our model behaves on simple toy problems. In Figure 3 we compare decision boundaries on 2-dimensional toy datasets of our SoftKNN-ICL to KNN (using k = 3) and the Nadaraya-Watson estimator (using RBF kernel with  $\gamma = 15$ ) as the methodologically closest non-deep-learning methods. Furthermore, we compare against an SVM (using RBF kernel with  $\gamma = 5, C = 3$ ) and TabForestPFN (den Breejen et al., 2024). Overall, SoftKNN-ICL yields competitive performance and reasonable decision boundaries. Compared to the nearest neighbor methods (second and third column), our method provides reasonable uncertainty estimates when moving away from seen datapoints (see "Moons" and "Circles") and is less prone to overfitting on noisy datasets (see "Noisy Moons" and "Noisy Circles"). Additionally, it performs comparably to the Tab-ForestPFN model, which is desirable.

Furthermore, we study the neighborhood used to make predictions. In the last column of Figure 3, we visualize the values of  $a^q$  (see Equation (1)), i.e., the predicted similarity between the query point (black cross) and the data set. Overall, the neighborhood of SoftKNN-ICL can become very small, with the bias of selecting samples from the same class (see "Circles"). The most interesting finding is that the model dynamically adjusts the number of samples it considers for prediction: when the neighborhood is noisy (i.e., the nearest samples do

<sup>&</sup>lt;sup>3</sup>https://github.com/FelixdenBreejen/ TabForestPFN



Figure 3: Decision boundary of SoftKNN-ICL and other methods on toy datasets.

not exhibit a dominant class), it aggregates information from more points, similar to decreasing  $\gamma$ in an RBF kernel. In contrast, when the nearest sample is strongly indicative, the model relies primarily on the labels of a few samples (compare "Moons" and "Circles" with "Noisy Moons" and "Noisy Circles").

#### 4.2 Evaluation on Real-World Datasets

Next, we compare our method against baselines using standard benchmark tasks. Concretely, we use the same datasets as the TabPFN paper (Hollmann et al., 2023): these are 30 datasets from the OpenML benchmarking suites CC-18 (Bischl et al., 2021), restricted to contain at most 2 000 data points. Inspired by the original evaluation protocol, which uses five randomized 50/50 train/test splits, we conducted a two-fold cross-validation five times to reduce the variance of our results by guaranteeing that each datapoint is used for testing in each repetition while using training and test sets of the same size as in the original evaluation protocol. We provide OpenML task IDs in Table 2 in Appendix A to allow reproducing our results. We compare average AUC across all repetitions and datasets.

As baselines, we use the TabPFN model provided by Hollmann et al. (2023) and the Tab-ForestPFN model provided by den Breejen et al. (2024), which is trained with the same TabForest prior (den Breejen et al., 2024) as our model SoftKNN-ICL. Additionally, we disable ensembling by input permutations for all PFN-style models.<sup>4</sup> To test the capabilities of the nearest neighbor algorithm, we also use a traditional KNN with k = 1 and k = 5 from scikit-learn (Pedregosa et al., 2011), where we preprocess the data as it is

<sup>&</sup>lt;sup>4</sup>Enabling ensembling could further boost our performance, but this is not the goal of our study. Furthermore, ensembling would decrease the intelligibility of our proposed method.

Model Name	k	avg. AUC
Random Forest	n.a.	0.8712
TabForestPFN	n.a.	0.8816
TabPFN	n.a.	0.8856
KNN	1	0.7498
	5	0.8272
SoftKNN-ICL (ours)	1	0.7746
	5	0.8460
	10	0.8606
	all	0.87975

Table 1: Average AUC of all methods on 30 datasets using 5-repeated 2-fold cross-validation. We boldface the best method in each category.

in the original evaluation protocol (Hollmann et al., 2023).

We present average AUC values in Table 1. Notably, SoftKNN-ICL outperforms KNN with different values of K and matches the performance of TabPFN and the TabForestPFN trained on the same synthetic datasets. Furthermore, in Figure 4 we compare AUC values per dataset, showing that there are no outlier datasets on which SoftKNN-ICL performs substantially better or worse than the current PFN architecture. Lastly, Figure 5 reports the average ranks and statistical results following Demšar (2006), demonstrating that our SoftKNN-ICL does not perform statistically differently than TabForestPFN and TabPFN.

We also conducted an ablation on using only the top-k similar datapoints from the support set (as done by Wang and Sabuncu (2023)). While performance (not surprisingly) degrades, it is better than for KNN with the same number of neighbors, and using only a fixed number of neighbors could be valuable for tasks where it is essential to be able to study which samples contribute to the prediction.



Figure 4: AUC values of SoftKNN-ICL vs. PFN. Each dot corresponds to one dataset.



Figure 5: Average rank and critical distance diagram.

# 5 Connection with kernel machines and metric learning

Before turning to the conclusion and after having presented the technical details of SoftKNN-ICL, we would like to embed our method further into the existing literature. NCA inspired our method; however, our methodological framework allows us to connect our method and the fields of metric learning and kernel learning (Bellet et al., 2013), which we briefly highlight in the following. As shown in Equation 3, our model effectively performs kernel regression and can be framed as a deep kernel learning with an exponential kernel as the base kernel (see Equation (5) in Wilson et al. (2016)). While it is known that self-attention mechanisms can be interpreted through the lens of kernel methods (Tsai et al., 2019), this connection opens up promising directions for future research. These include exploring alternative base kernels for the final layer, or gaining insight into the mechanisms of ICL by revisiting the approach of Han et al. (2024). Their work developed a theoretical and empirical framework for studying this phenomenon and its connection to kernel methods in LLMs. Our settings are more constrained than in the original work (our model is sampleorder invariant and can be made feature-order invariant using the attention mechanism proposed by den Breejen and Yun (2025)), which helps to mitigate some of the issues raised in reviews. Furthermore, the model can be reformulated as a metric learning approach by expressing the final layer (before normalization wrt support dimension) as  $\mathbf{A}^{\text{unnorm}}[\mathbf{X}^{q}[j], \mathbf{X}^{s}[i]] = exp(-||\mathbf{W}(\mathbf{E}^{q}[j] - \mathbf{W}(\mathbf{E}^{q}[j])|)$  $\mathbf{E}^{s}[i])||^{2}$ , following the formulation in (Weinberger and Tesauro, 2007). This makes the model to explicitly learn a metric between the support and query points  $d((\mathbf{X}^s, \mathbf{y}^s), (\mathbf{X}^q)) = ||\mathbf{W}(\mathbf{E}^q[j] - \mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E}^q[j])||\mathbf{W}(\mathbf{E$  $\mathbf{E}^{s}[i])||$  in the embedding space parametrized by the embedder  $f_{\theta}$  (ICL-transformer in our model) and W. Connecting to a growing body of literature that seeks to relate kernel methods and neural networks (Belkin et al., 2018; Domingos, 2020; Bell et al., 2023; Tarzanagh et al., 2023; Teo and Nguyen, 2024; Wilson, 2025; Arbel et al., 2025), our model could largely benefit from the synergy between both fields.

## 6 Conclusion and Future Work

We have demonstrated that a (soft) KNN learning task for ICL models leads to competitive performance compared to the standard learning task. The resulting SoftKNN-ICL is closely related to kernel and metric learning and can be used as a drop-in replacement for tasks requiring intelligibility. Additionally, by using SoftKNN-ICL, we overcome two limitations of traditional KNN methods: (1) the need to tune the number of neighbors, k, and the need to define a neighborhood (similarity) function manually. We hope this spurs research into interpretability methods targeted at instance-based learning methods, and that the in-context learning of a soft neighborhood is a valuable basis for distance learning, potentially even beyond tabular tasks. Furthermore, we deem future work along the following directions particularly interesting for tabular machine learning.

**Detailed empirical evaluation.** Most importantly, we plan to study how our method uses attention in noisy query sets and how different data-generating priors, used to train the ICL model, impact performance and behaviour.

Alternative architecture and learning tasks. Secondly, by extending our methodology of ICL using neighbor methods to, for example, using the NCA prediction function or training the model without the merged  $\mathbf{KV}^T$  matrix, we hope to understand better how to train an ICL nearest neighbor method in the best manner. Other possible architecture improvements include the use of cell-based attention like in TabPFN v2 (Hollmann et al., 2025) and TabICL (Qu et al., 2025b), efficient embeddings similar e.g. TabICL, and localization methods (Thomas et al., 2024; Koshil et al., 2024) to mitigate the need of ensembling and improve scaling wrt. training set.

Making use of the distance function. Finally, while we only assessed the learned distance function to make predictions, it should also be possible to use it for exploratory data analysis and metalearning. Additionally, it would be interesting to condition our method to consider as few neighbors as possible.

## Limitations

Firstly, our method inherits the limitations of the ICL model class it resembles, i.e., limited context size and slow inference speed. Secondly, it is not as powerful as TabPFN (yet); however, we expect it to improve with longer training and hyperparameter tuning. Thirdly, our evaluation of intelligibility is limited to synthetic datasets; a thorough evaluation, potentially including a user study, remains future work. Lastly, although our model's inference mechanism is transparent by explicitly combining labels of existing data points, it remains unclear why these points are chosen due to the black-box nature of transformer models.

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## A Dataset and Task IDs

Data ID	Dataset Name	Task ID
11	balance-scale	361412
14	mfeat-fourier	361414
15	breast-w	361415
16	mfeat-karhunen	361416
18	mfeat-morphological	361417
22	mfeat-zernike	361419
23	cmc	361420
29	credit-approval	363512
31	credit-g	233149
37	diabetes	361424
50	tic-tac-toe	363513
54	vehicle	361426
188	eucalyptus	363511
458	analcatdata_authorship	361437
469	analcatdata_dmft	363514
1049	pc4	363515
1050	pc3	363516
1063	kc2	361440
1068	pc1	363517
1462	banknote-authentication	361462
1464	blood-transfusion	361463
1480	ilpd	363518
1494	qsar-biodeg	361448
1510	wdbc	361442
6332	cylinder-bands	363519
23381	dresses-sales	363520
40966	MiceProtein	363521
40975	car	363522
40982	steel-plates-fault	363523
40994	climate-model	363524

Table 2: OpenML (Vanschoren et al., 2014) dataset and task IDs used for the evaluation.